



# Linux For Embedded Systems

## *For Arabs*

## Course 101:

### Introduction to Embedded Linux

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# Lecture 3:

## Selecting the Proper OS

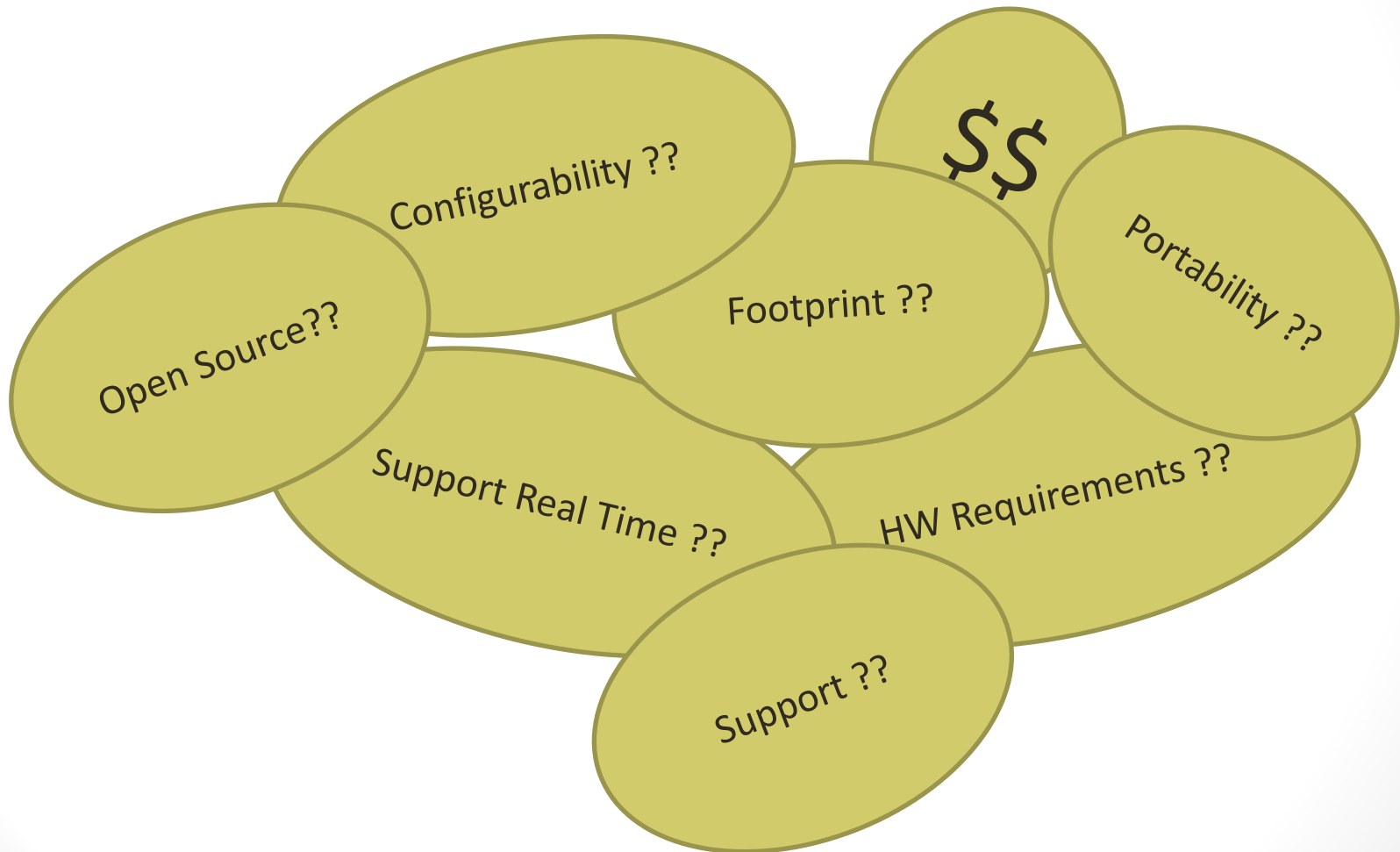
# Do We Have to Have an OS ?

*Out of our Scope*



- Not really
- Very simple embedded systems don't need an operating system, and development happens directly on the hardware
- Also, code for a bootloader or a kernel does not assume an OS
- Development is normally done in assembly language and sometimes in C as well
- No support of multiple tasks, or multiple processes, a simple loop runs the different functionality back to back
- No support of Timers... just some delay loops
- Storing info in the flash is done in a very primitive way
- These systems are very limited in functionality

# Which OS Should We Use ??



# Cost ....



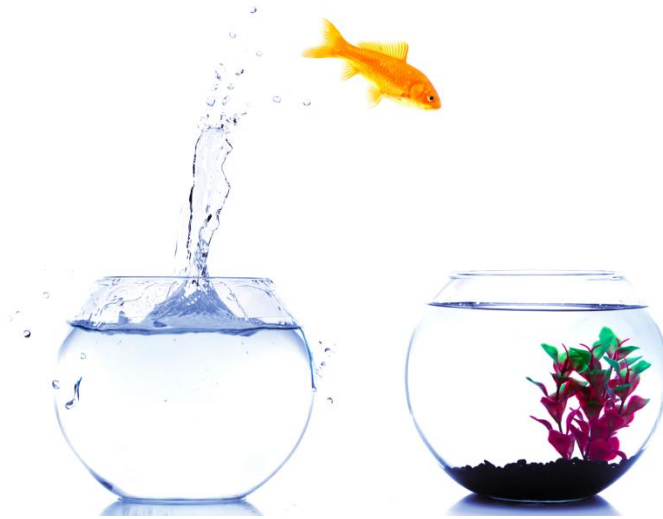
- Commercial OS's
  - Different cost models:
    - Fixed price for OS License
      - Per device type or family
      - Per processor
      - Per device line
    - Per seat license for associated tools
    - License fee per unit (Royalty cost )
    - Others.....
- Free OS's
  - No direct cost for using the OS and plenty of tools
  - Sometimes there is indirect costs such as
    - Support
    - Special services
    - Special versions (more reliability, or better performance)
    - Some associated tools
  - With time more and more free tools
  - Examples include Linux, uClinux, Ecos,...

# Hardware Requirements



- Each OS has its own hardware requirements
  - Some OS's require 32 bit processors, others are OK with 8 bits
  - Some OS's require a processor with MMU, others are fine without it
  - Each OS has its own minimum memory and storage requirements
- Also, the embedded platform may have some requirements
  - Does it need a USB 2.0 Support ?
  - Does it need TCP/IP support ?

# Portability



- We may need to migrate to a different Hardware Platform
  - Each OS has its own list of supported architectures
- We may need to migrate our code to a different OS
  - Software portability can be achieved by support of APIs (such as POSIX)

# Footprint



- Footprint is the required size of storage and memory required to start and operate the OS
- Some OS's require very small footprint (as low as 2 KB), while others require much bigger size (Several Mega Bytes)
- The size of the embedded device and its storage resources may dictate which OS to use



# Support of Real Time



- Embedded Applications usually come with real time constraints
- This require support for Real Time in the OS
- Real Time Operating System = RTOS
- Real time support does not mean fast response only, it means **Predictable Response** also

# Support of Real Time



- Fast Response does not necessary mean Predictable response
- RTOS requires Predictable response, to make sure tasks meet the target hard real time constraints
- This means,
  - No background tasks that startup in random fashion and affect response time
  - Scheduling provides some guarantees
  - Short Interrupt Latency
  - Fast Context Switch

# Configurability



- Some embedded OS's come with the option to be configurable
- This means that some of their features are optional, and can be carved out if not needed by the embedded application or the hardware
- This way we can customize our OS to the needs of the application
- Accordingly, we reach a smaller footprint and proper functionality support

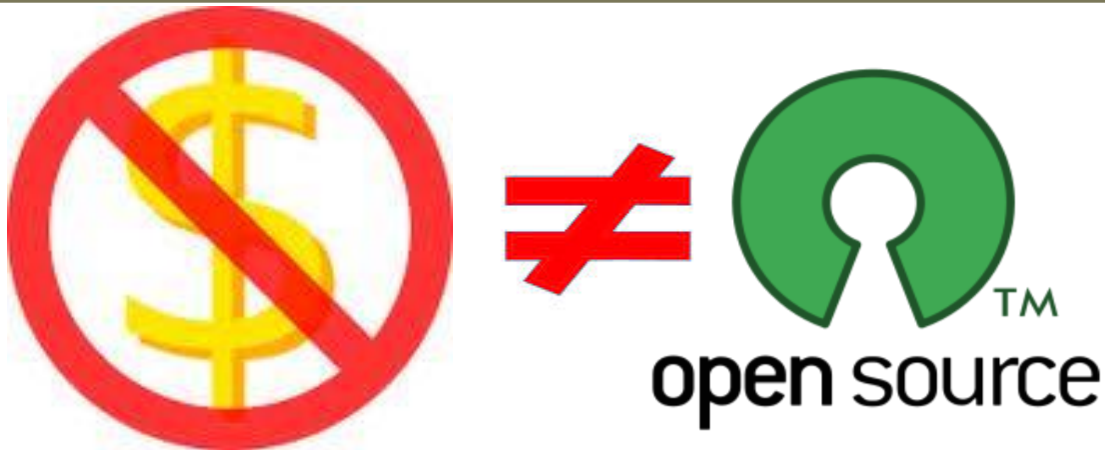
# Support



- One important aspect of choosing an OS is the level of support for that OS
- Is it only offered by the vendor ?
- Do we have strong community support ?
- Availability of Documentation

# Source Code

- Closed Source OS's (Proprietary)
- Open Sources OS's
- Partially Open Source OS's



# Summary



open source  
initiative





# Linux 4

## Embedded Systems

<http://Linux4EmbeddedSystems.com>