



## \* Assignment No. 1 g \*

### ◦ Title:-

Given sequence  $K = k_1 < k_2 < \dots < k_n$  in sorted keys, with a search probability  $p_i$  for each key  $k_i$  build the Binary search tree that the least search cost given the access probability for each key?

### ◦ objective:-

- 1) To understand concept of OBST
- 2) To understand concept & features like extends binary search tree.

### ◦ learning outcome:-

- 1) Define class for extends binary search tree using object oriented features
- 2) Analytical working of function.

### ◦ Theory :-

An optimal binary search tree is a binary search tree for which the nodes are arranged on levels.

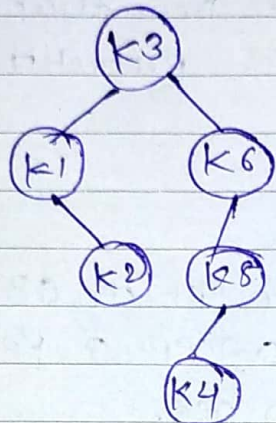
Such that the tree cost is minimum for the purpose of a better presentation of optimal binary search tree, "Which have the keys stored at their internal nodes suppose  $n$  keys  $k_1, k_2, \dots, k_n$  are stored at the internal nodes of a sorted order, so that  $k_1 < k_2 < \dots < k_n$

An extended binary search tree is obtained from the binary search tree is obtained from the binary search tree by adding null nodes to each

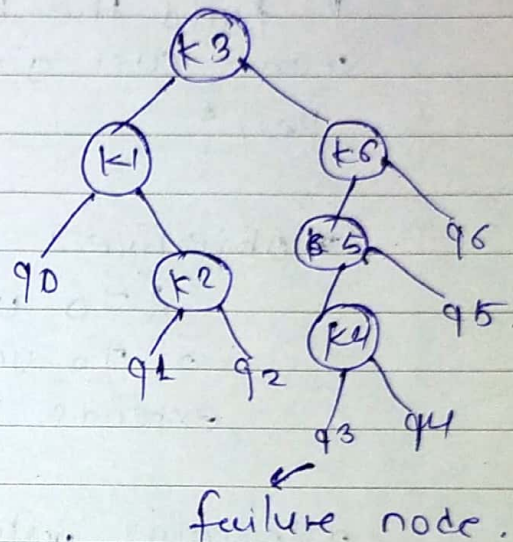




of its terminal nodes as indicated in the following by



Binary Search tree



\* In the Extended tree -

- i) The squares represent terminal nodes. These terminal nodes represent unsuccessful searches of the tree of key values. The searches did not end successfully, that is because they represent key values that are not actually stored in the tree.
- ii) The round node represents internal nodes. These are actually keys stored in the tree.
- iii) Assuming that the relative frequency with which each key value is accessed is known, weights can be assigned to each node of the extended tree ( $P_1, P_6$ ). They represent terminating at each node, that is, they mark the successful searches.





iv) If the User interface a particular key in the case 2 can occur.

i) 1- the key is found. So the corresponding weight 'p' is incremented.

ii) 2- the key is not found. So the corresponding 'q' value is incremented.

### \* Generalization :-

The terminal node is the extended tree that is the left successor of  $k_i$  can be interpreted as representing all key values that are not stored and are less than  $k_i$ . Similarly

the terminal node in the extended tree that is right successor of  $k_n$ , represents all key values not stored in the tree that are greater than  $k_n$ . The terminal node that is Successor between  $k_i$  and  $k_{i-1}$  in an inorder traversal represent all key values not stored that lie between  $k_i$  and  $k_{i-1}$ .

### \* Algorithm :-

we have the following procedures for determining  $R(i, j)$  &  $C(i, j)$  with  $0 \leq i \leq j \leq n$ ;

Procedure Compute Root ( $n, p, q, R, C$ );

begin

for  $i = 0$  to  $n$  do

$C(i, i) \leftarrow 0$ .

$W(1, i) \leftarrow q(i)$

for  $m = 0$  to  $n$  do.

for  $j = 0$  to  $(n-m)$  do.





$j \leftarrow itm$   
 $w(i, j) \leftarrow w(i, j-1) + p(j) + q(j)$   
\* find  $c(i, j)$  and  $R(i, j)$  which minimize the three cost  
end  
end.

The following function builds an optimal binary search tree.

```
function constructor(R, i, j)
begin
  * build a new internal node N labeled (i, j)
  if  $i = k$  then
    * build a new leaf node 'N' labeled (i, i)
  else
     $N \leftarrow \text{constructor}(R, i, k)$ 
    * N is the left child of N labeled (j, j)
  else
     $N \leftarrow \text{constructor}(R, k+1, j)$ 
    N is the right child of node N
  return N
```

• Complexity analysis :-

The algorithm requires  $O(n^2)$  time and  $O(n^2)$  storage. Therefore, as 'n' increases it will run out of storage even before it runs out of time.

• Input :-

- i) No. of element.
- ii) Key values.
- iii) Key probability.





\* Output:

Create binary search tree having optimal search cost.

• Example:

Int.

$w(w_1, w_2, w_3, w_4) = (\text{do}, \text{if}, \text{else}, \text{while})$

$p(p_1, p_2, p_3, p_4) = (3, 3, 1, 1)$

$q(q_0, q_1, q_2, q_3, q_4) = (2, 3, 1, 1, 1)$

Identifiers:

	0	1	2	3	4	5	6
0	d	o	o				
1	i	f					
2	i	n	t				
3	w	h	i	e			
4							
5							
6							

probability  $p$ 

3	3	1	1	
---	---	---	---	--

  
                                  1 2 3 4 5

failure  $q$ 

2	3	1	1	1	
---	---	---	---	---	--

  
                                  0 1 2 3 4 5

$w_{00} = 2$	$w_{11} = 3$	$w_{22} = 1$	$w_{33} = 1$	$w_{44} = 1$
$c_{00} = 0$	$c_{11} = 0$	$c_{22} = 0$	$c_{33} = 0$	$c_{44} = 0$
$r_{00} = 0$	$r_{11} = 0$	$r_{22} = 0$	$r_{33} = 0$	$r_{44} = 0$





$$w[i][j] = q[i]$$

$$c[i][i] = r[i][i] = 0.$$

$$w[i][i+1] = q[i] + q[i+1] + p[i+1].$$

$$r[i][i+1] = i+1;$$

$$c[i][i+1] = q[i] + q[i+1] + p[i+1].$$

$$j-i = 1, i=0, j=1.$$

$$w[i][i] = q[i] + q[i+1] + p[i+1].$$

$$w(0,1) = p(1) + q(1) + w(0,0).$$

$$= 3 + 3 + 2.$$

$$w(0,1) = 8$$

$$c(1,1) = \min.$$

$$c[i][i+1] = q[i] + q[i+1] + p[i+1].$$

$$c[0][1] = q[0] + q[1] + p[1]$$

$$= 2 + 3 + 3.$$

$$c[0][1] = 8$$

$$r(0,1) = 1$$

$$i=1, j=2.$$

$$w[i][2] = q[i] + q[2] + p[2]$$

$$= 3 + 1 + 1$$

$$w(1,2) = 7$$

$$c(1)(2) = q[1] + q[2] + p[2].$$

$$= 3 + 1 + 3$$

$$c(1,2) = 7.$$

$$r(1,2) = 2$$

$$i=2, j=3$$





$$i=2, j=3.$$

$$w(2,3) = q[2] + q[3] + p[3]$$

$$= 1 + 1 + 1$$

$$w(2,3) = \underline{\underline{3}}$$

$$c[2,3] = q[2] + q[3] + p[3]$$

$$= 1 + 1 + 1$$

$$c[2,3] = \underline{\underline{3}}$$

$$i=3, j=4 \quad w[3,4] = q[3] + q[4] + p[4]$$

$$= 1 + 1 + 1 = 3$$

$$c[3][4] = q[3] + q[4] + p[4]$$

$$= 1 + 1 + 1 = \underline{\underline{3}}$$

$$\underline{\underline{w(3,4) = 4}}$$

$$i=4, j=5$$

$$w(4,5) = q[4] + p[5] + q[5]$$

$$= 1 + 0 + 0$$

$$r(4,5) = \underline{\underline{5}}, \quad w(4,5) = \underline{\underline{1}}$$

	0	1	2	3	4	5	6
0	2	8	12	14	16		
1		3	7	9	11		
2			1	3	5		
3				1	3		
4					1	1	
5							
6							





	0	1	2	3	4	5	6
0	0	8	14	25	22		
1		0	7	12	19		
2			0	3	8		
3				0	3		
Cost (C)	4				0	1	
5							
6							

	0	1	2	3	4	5	6
0	0	1	1	2	2		
1		0	2	2	2		
root (r)	2		0	3	3		
3				0	4		
4					0	5	
5							
6							

\* Conclusion:

This program gives us the knowledge  
OBST Extended binary search tree.