

view_frames Result
Recorded at time: 1588605416.433

map

odom

zed_link

zed_camera_center

zed_current_frame

base_footprint

Humidity_link

gps_link

imu_link

laser_link

left_thruster_link

right_thruster_link

temp_1_link

ultrasound1_link

ultrasound2_link

zed_left_camera_frame

zed_right_camera_frame

zed_left_camera_optical_frame

zed_right_camera_optical_frame

Broadcaster: /zed/zed_node
Average rate: 4890000.000 Hz
Most recent transform: 1588605403.315 (13.118 sec old)
Buffer length: 0.000 sec

Broadcaster: /zed/zed_node
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1588605416.433 sec old)
Buffer length: 0.000 sec

Broadcaster: /zed/zed_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1588605416.433 sec old)
Buffer length: 0.000 sec

Broadcaster: /zed/zed_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1588605416.433 sec old)
Buffer length: 0.000 sec

Broadcaster: /zed_link_to_zed_current_frame
Average rate: 10.192 Hz
Most recent transform: 1588605416.514 (-0.082 sec old)
Buffer length: 4.906 sec

Broadcaster: /robot_state_node
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1588605416.433 sec old)
Buffer length: 0.000 sec

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