



**ECON 7350 Applied Econometrics for Macroeconomics and Finance**

**Research Project II**

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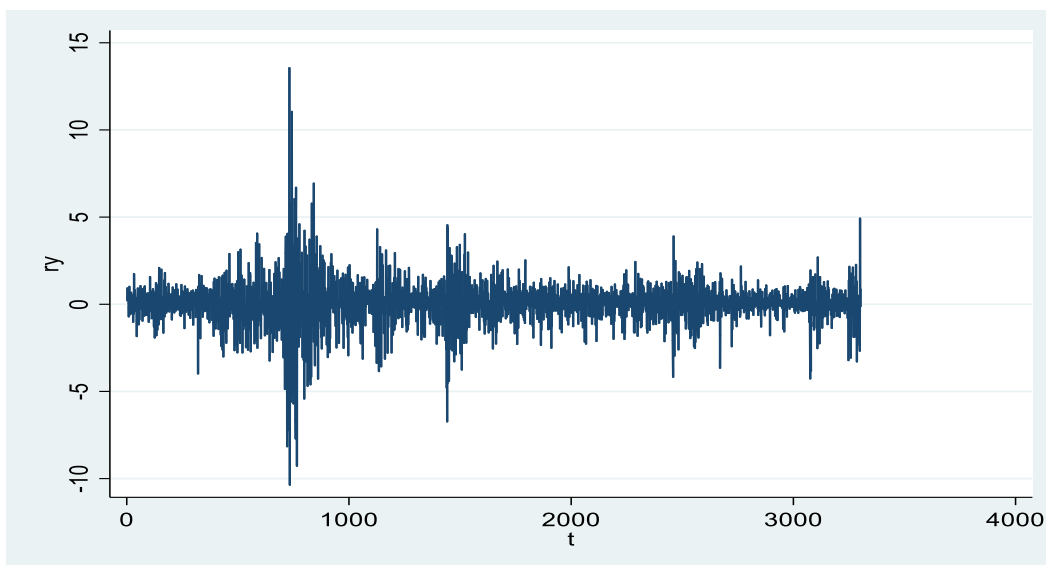
# Q1

## (A)

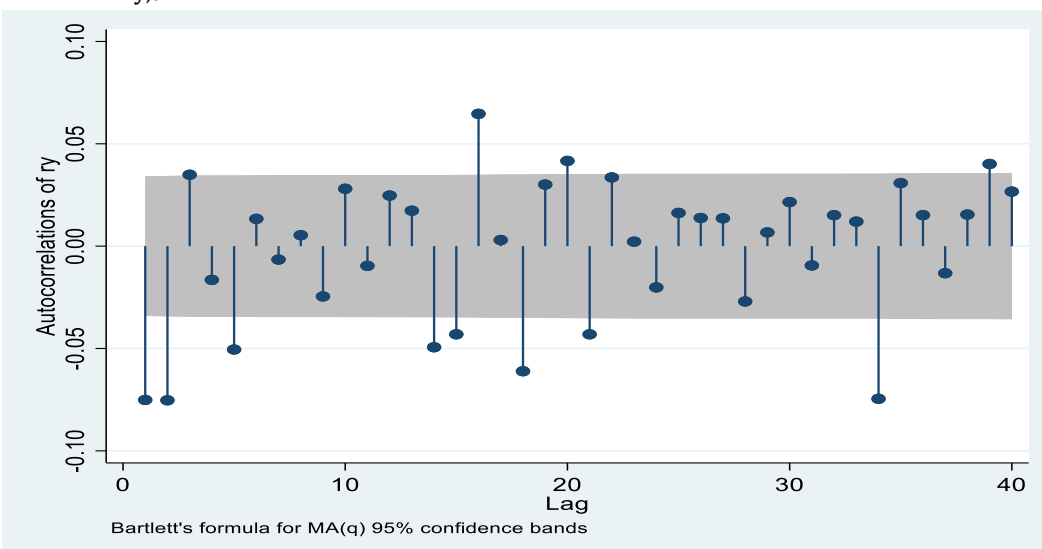
At the first glance, the time series of  $r_{y,t}$  looks like it exhibits mean reversion which is the phenomenon of stationarity. However, volatility jump/fat tailed event had happened during the early period before  $t = 1000$ . That jump will make the data highly stochastic for quite a period if we conduct subsample analysis. No matter what, we still cannot conclude that it is stationary without conducting unit root test. In addition, both ACF and PACF of  $r_{y,t}$  also show signs of mean reversion since they have reverted around 0 which is the signal of stationarity. Combining these information, we still cannot firmly indicate that  $r_{y,t}$  is stationary. Therefore, to make sure the time series has no unit root, we then run ADF test.

From the ADF test for all three kinds of equations at lag 2, we can reject the null hypothesis that  $r_{y,t}$  contains unit root at five percent significance level for all equations. In conclusion,  $r_{y,t}$  is clearly stationary.

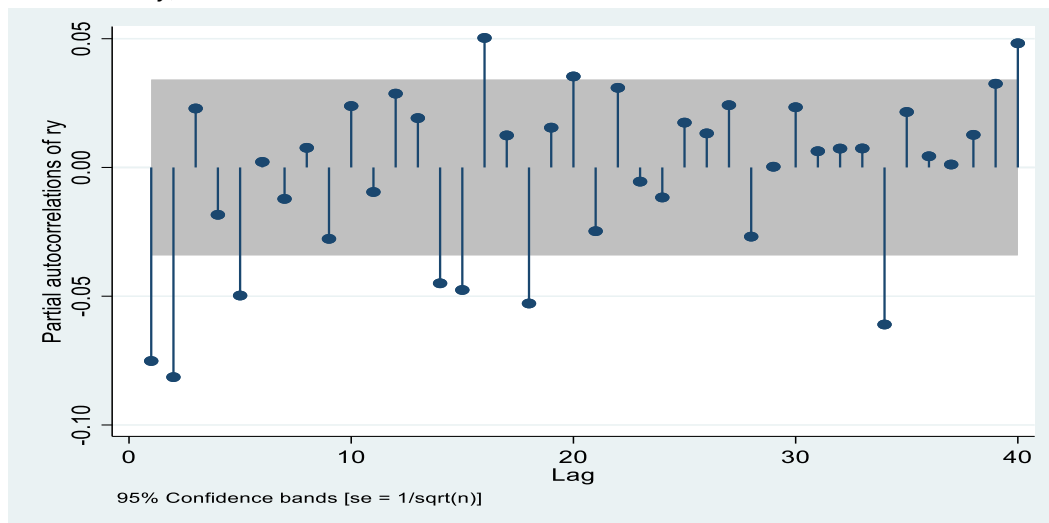
### Time Series of $r_{y,t}$



### ACF of $r_{y,t}$



### PACF of $r_{y,t}$



### ADF test of $r_{y,t}$

Ho:  $r_{y,t}$  contains unit root

Ha:  $r_{y,t}$  contains no unit root

#### The three equations of ADF test are:

Equation (1): the pure random walk model.

Equation (2): adds a drift term to the previous model, Equation (1).

Equation (3): adds a drift and a linear time trend to the random walk model.

#### Table of ADF test

At lag 2	Test Statistics	5% Critical Value
Equation (1)	-34.885	-1.950
Equation (2)	-34.929	-1.645
Equation (3)	-34.931	-3.410

### (B)

#### (B-1) Model Selection

I tested the ARMA models from ARMA (1,1) to ARMA (4,4). The information criterion test indicates that ARMA(3,3) has the lowest AIC and BIC; therefore, ARMA (3,3) is the best model.

#### Below is the estimated model for ARMA(3,3)

$$\begin{aligned}
 r_t = & 0.0295 - 0.1279r_{t-1} - 0.5386r_{t-2} + 0.5875r_{t-3} \\
 & (0.0197) \quad (0.0643) \quad (0.0466) \quad (0.0611) \\
 & + 0.0496\varepsilon_{t-1} + 0.4708\varepsilon_{t-2} - 0.6398\varepsilon_{t-3} + \varepsilon_t \\
 & (0.0585) \quad (0.0418) \quad (0.0531)
 \end{aligned}$$

## (B-2) Test for existence of ARCH/GARCH effects

### Breusch-Pagan LM test for existence of ARCH/GARCH effect

Ho: No ARCH effect or homoskedasticity

Ha: Existence of ARCH effect or heteroscedasticity

I then run the Breusch-Pagan type (LM) test for the errors in my ARMA(3,3) with different values of q where q=1,2,3,4. We reject the null hypothesis that variance of error term in  $r_{y,t}$  has no ARCH effect in all tests as the LM test statistics are all larger than their corresponding critical values from Chi-squared distribution at five percent significance level. Hence, the ARCH effect exists in variance of error term in  $r_{y,t}$ .

### STATA output for ARMA (3,3)

ARIMA regression

Sample: 2 - 3303	Number of obs	=	3302
	Wald chi2(6)	=	28060.65
Log likelihood = -5259.527	Prob > chi2	=	0.0000

ry		OPG		z	P> z	[95% Conf. Interval]	
		Coef.	Std. Err.				
ry	_cons	.0294687	.0196633	1.50	0.134	-.0090707	.0680081
ARMA							
	ar						
	L1.	-.1279481	.0642943	-1.99	0.047	-.2539625	-.0019336
	L2.	-.5385931	.0465675	-11.57	0.000	-.6298638	-.4473224
	L3.	.5875072	.0611044	9.61	0.000	.4677448	.7072696
	ma						
	L1.	.0495883	.0584833	0.85	0.396	-.0650369	.1642136
	L2.	.4708219	.0418494	11.25	0.000	.3887986	.5528453
	L3.	-.6398336	.053076	-12.06	0.000	-.7438606	-.5358065
/sigma		1.189877	.0060871	195.47	0.000	1.177946	1.201807

### AIC/BIC table for all tested models

Models	AIC	BIC
ARIMA (1,0,1)	10564.76	10589.17
ARIMA (1,0,2)	10559.13	10589.65
ARIMA (1,0,3)	10560.94	10597.55
ARIMA (1,0,4)	10558.12	10600.83
ARIMA (2,0,1)	10558.22	10588.74
ARIMA (2,0,2)	10559.06	10595.67
ARIMA (2,0,3)	10542.38	10585.09
ARIMA (2,0,4)	10535.47	10584.29

ARIMA (3,0,1)	10560.09	10596.71
ARIMA (3,0,2)	10555.13	10597.85
ARIMA (3,0,3)	10535.05*	10583.87*
ARIMA (3,0,4)	10537.03	10591.95
ARIMA (4,0,1)	10556.96	10599.67
ARIMA (4,0,2)	10536.01	10584.82
ARIMA (4,0,3)	10537.04	10591.96
ARIMA (4,0,4)	10538.25	10599.27

### STATA output for LM test

Source	SS	df	MS	Number of obs	=	3,301
Model	3609.48334	1	3609.48334	F(1, 3299)	=	128.64
Residual	92566.5382	3,299	28.0589689	Prob > F	=	0.0000
				R-squared	=	0.0375
				Adj R-squared	=	0.0372
Total	96176.0216	3,300	29.144249	Root MSE	=	5.2971

ehat2	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
ehat2 L1.	.193725	.0170804	11.34	0.000	.1602357	.2272143
_cons	1.141939	.0953159	11.98	0.000	.9550545	1.328823

```
. dis e(N)*e(r2) > invchi2(1, 0.95)
1
```

Source	SS	df	MS	Number of obs	=	3,300
Model	21772.6679	2	10886.3339	F(2, 3297)	=	482.40
Residual	74403.009	3,297	22.5668817	Prob > F	=	0.0000
				R-squared	=	0.2264
				Adj R-squared	=	0.2259
Total	96175.6769	3,299	29.1529787	Root MSE	=	4.7505

ehat2	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
ehat2 L1.	.1079086	.0156138	6.91	0.000	.0772949	.1385224
L2.	.4429679	.0156138	28.37	0.000	.4123541	.4735816
_cons	.6361496	.0873338	7.28	0.000	.4649157	.8073835

```
. dis e(N)*e(r2) > invchi2(2, 0.95)
1
```

Source	SS	df	MS	Number of obs	=	3,299
				F(3, 3295)	=	338.70
Model	22667.9235	3	7555.97452	Prob > F	=	0.0000
Residual	73506.2746	3,295	22.3084293	R-squared	=	0.2357
				Adj R-squared	=	0.2350
Total	96174.1981	3,298	29.16137	Root MSE	=	4.7232

ehat2	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
ehat2						
L1.	.0592843	.0173157	3.42	0.001	.0253337	.0932348
L2.	.4311167	.0156363	27.57	0.000	.4004588	.4617745
L3.	.1097659	.0173157	6.34	0.000	.0758153	.1437165
_cons	.5664768	.0875422	6.47	0.000	.3948342	.7381195

```
. dis e(N)*e(r2) > invchi2(3, 0.95) //1 means reject the null
1
```

Source	SS	df	MS	Number of obs	=	3,298
				F(3, 3294)	=	154.71
Model	11877.1877	3	3959.06257	Prob > F	=	0.0000
Residual	84295.8052	3,294	25.5907119	R-squared	=	0.1235
				Adj R-squared	=	0.1227
Total	96172.9929	3,297	29.1698492	Root MSE	=	5.0587

ehat2	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
ehat2						
L1.	.0726709	.0186265	3.90	0.000	.0361503	.1091915
L3.	.1363213	.0185175	7.36	0.000	.1000144	.1726282
L3.	0	(omitted)				
L4.	.2616511	.0168528	15.53	0.000	.2286081	.2946942
_cons	.7517762	.093696	8.02	0.000	.5680679	.9354844

```
. dis e(N)*e(r2) > invchi2(4, 0.95) //1 means reject the null
1
```

## (C)

If we also set the cap on ARCH(q) at 4 and combine with the best ARMA model from 1(B), then compare ARMA(3,3)-ARCH(1), ARMA(3,3)-ARCH(2), ARMA(3,3)-ARCH(3), and ARMA(3,3)-ARCH(4) models. We can soon find out that ARMA(3,3)-ARCH(4) model will have lowest AIC and BIC; therefore, the best q should be 4 if the cap is set at ARCH(4). Moreover, the coefficients in ARMA(3,3)-ARCH(4) are also significant. However, the above is the result with setting the cap. Now, what if we don't set a cap?

The problem is that if we test  $q > 4$ , we will find that AIC/BIC becomes smaller as q gets larger. Also, some coefficients will not be significant. This is the common phenomenon of over-

parameterization which will cause undesired outcome. The consequence is that adding more lags to q will reduce the sum of squares of the estimated residuals, but it will result in estimation of more coefficients and suffer from loss of degrees of freedom.

### STATA output of ARMA(3,3)-ARCH(4)

ARCH family regression -- ARMA disturbances

Sample: 2 - 3303	Number of obs	=	3,302
Distribution: Gaussian	Wald chi2(6)	=	24771.48
Log likelihood = -4415.494	Prob > chi2	=	0.0000

ry		OPG		z	P> z	[95% Conf. Interval]	
		Coef.	Std. Err.				
ry							
	_cons	.0831714	.0096426	8.63	0.000	.0642722	.1020706
ARMA							
	ar						
	L1.	.1385098	.064744	2.14	0.032	.0116138	.2654057
	L2.	-.518805	.0401265	-12.93	0.000	-.5974515	-.4401584
	L3.	.7468258	.0626941	11.91	0.000	.6239476	.869704
	ma						
	L1.	-.1959665	.0573787	-3.42	0.001	-.3084267	-.0835063
	L2.	.4863421	.0351008	13.86	0.000	.4175458	.5551385
	L3.	-.7948217	.0549922	-14.45	0.000	-.9026045	-.6870389
ARCH							
	arch						
	L1.	.1047661	.013174	7.95	0.000	.0789456	.1305867
	L2.	.2478873	.0235981	10.50	0.000	.2016358	.2941388
	L3.	.2235611	.0189321	11.81	0.000	.1864548	.2606674
	L4.	.2715865	.0182428	14.89	0.000	.2358313	.3073417
	_cons	.2796734	.0107399	26.04	0.000	.2586237	.3007232

**AIC/BIC table for ARMA-ARCH(q) models**

Models	AIC	BIC
ARMA(3,3)-ARCH(1)	9862.591	9917.511
ARMA(3,3)-ARCH(2)	9305.719	9366.742
ARMA(3,3)-ARCH(3)	9072.369	9139.494
ARMA(3,3)-ARCH(4)	8854.989*	8928.216*
<b>Below shows the AIC/BIC after ARMA(3,3)-ARCH(4)</b>		
ARMA(3,3)-ARCH(5)	8797.464	8876.794
ARMA(3,3)-ARCH(6)	8755.904	8841.336
ARMA(3,3)-ARCH(7)	8730.150	8821.684
ARMA(3,3)-ARCH(8)	8697.787	8795.424
ARMA(3,3)-ARCH(9)	8670.068	8773.807
ARMA(3,3)-ARCH(10)	8652.177	8762.018
ARMA(3,3)-ARCH(11)	8645.007	8760.951*
ARMA(3,3)-ARCH(12)	8646.814	8768.860
ARMA(3,3)-ARCH(13)	8648.752	8776.900
ARMA(3,3)-ARCH(14)	8645.582	8779.832
ARMA(3,3)-ARCH(15)	8642.157*	8782.509
ARMA(3,3)-ARCH(16)	8643.987	8790.442
ARMA(3,3)-ARCH(17)	8644.812	8797.369
ARMA(3,3)-ARCH(18)	8646.81	8805.469
ARMA(3,3)-ARCH(19)	8648.317	8813.079
ARMA(3,3)-ARCH(20)	8649.779	8820.643

**(D)**

I compare several candidate models: ARMA(3,3)-GARCH(1,1), ARMA(3,3)-GARCH(1,2), ARMA(3,3)-GARCH(1,3), ARMA(3,3)-GARCH(2,1), ARMA(3,3)-GARCH(2,2). Among them, ARMA(3,3)-GARCH(1,1) is preferred because it has the lowest BIC.

**The estimated model for ARMA(3,3)-GARCH(1,1) can be shown as:**

$$r_t = 0.0761 + 0.1875r_{t-1} - 0.4894r_{t-2} + 0.8028r_{t-3} - 0.2337\varepsilon_{t-1} + 0.4597\varepsilon_{t-2} - 0.8420\varepsilon_{t-3} + \varepsilon_t$$

(0.0108)
(0.0779)
(0.0484)
(0.0770)  
(0.0686)
(0.0425)
(0.0671)

$$\varepsilon_t = v_t \sqrt{h_t}$$

$$h_t = 0.0237 + 0.1261\varepsilon_{t-1}^2 + 0.8548h_{t-1}$$

(0.0024)
(0.0087)
(0.0095)



## BIC table ARMA-GARCH(p,q) models

Models	BIC
ARMA(3,3)-GARCH(1,1)	8714.184*
ARMA(3,3)-GARCH(1,2)	9007.388
ARMA(3,3)-GARCH(1,3)	8915.182
ARMA(3,3)-GARCH(2,1)	8756.743
ARMA(3,3)-GARCH(2,2)	8859.561

## STATA output for ARMA(3,3)-GARCH(1,1)

ARCH family regression -- ARMA disturbances

Sample: 2 - 3303                      Number of obs    =        3,302  
Distribution: Gaussian                Wald chi2(6)       =       36877.42  
Log likelihood = -4316.581            Prob > chi2        =       0.0000

ry	OPG					
	Coef.	Std. Err.	z	P> z	[95% Conf. Interval]	
ry						
_cons	.0761292	.0107808	7.06	0.000	.0549991	.0972593
ARMA						
ar						
L1.	.1874695	.0778793	2.41	0.016	.0348289	.3401102
L2.	-.4893534	.0484142	-10.11	0.000	-.5842436	-.3944633
L3.	.8028334	.0770069	10.43	0.000	.6519027	.9537641
ma						
L1.	-.2336743	.068604	-3.41	0.001	-.3681357	-.099213
L2.	.4596667	.0425058	10.81	0.000	.3763569	.5429766
L3.	-.8419535	.0671245	-12.54	0.000	-.9735151	-.7103919
ARCH						
arch						
L1.	.1260865	.0087495	14.41	0.000	.1089379	.1432352
garch						
L1.	.8547735	.0094542	90.41	0.000	.8362437	.8733033
_cons	.0237462	.0023515	10.10	0.000	.0191373	.0283551

## (E)

The threshold coefficient is -0.2489 and is significantly different from 0. Hence, the t-test result provides strong evidence for the existence of leverage effect which means that volatility has tendency to decline when  $r_{y,t}$  goes up and to elevate when  $r_{y,t}$  goes down.

### ARMA-TARCH leverage effect ( $\lambda$ ) test

Ho:  $\lambda = 0$

Ha:  $\lambda > 0$

The estimated model for this ARMA-TARCH can be shown as:

$$r_t = 0.0351 - 1.0067r_{t-1} - 0.7401r_{t-2} - 0.6879r_{t-3} \\ (0.0132) \quad (0.2035) \quad (0.2400) \quad (0.1361) \\ + 0.9724\varepsilon_{t-1} + 0.6968\varepsilon_{t-2} + 0.6899\varepsilon_{t-3} + \varepsilon_t \\ (0.2029) \quad (0.2321) \quad (0.1380)$$

$$\varepsilon_t = v_t \sqrt{h_t}$$

$$h_t = 0.0257 + 0.2267\varepsilon_{t-1}^2 - 0.2489d_{t-1}\varepsilon_{t-1}^2 + 0.8714h_{t-1} \\ (0.0021) \quad (0.0163) \quad (0.0173) \quad (0.0091)$$

### STATA output for ARMA(3,3)-TARCH model

ARCH family regression -- ARMA disturbances

Sample: 2 - 3303	Number of obs	=	3,302
Distribution: Gaussian	Wald chi2(6)	=	2471.86
Log likelihood = -4241.674	Prob > chi2	=	0.0000

ry	Coef.	OPG Std. Err.	z	P> z	[95% Conf. Interval]	
ry						
_cons	.0351308	.0132038	2.66	0.008	.0092518	.0610097
ARMA						
ar						
L1.	-1.00669	.2034746	-4.95	0.000	-1.405493	-.6078873
L2.	-.7401432	.2400422	-3.08	0.002	-1.210617	-.2696692
L3.	-.6879237	.1360943	-5.05	0.000	-.9546636	-.4211838
ma						
L1.	.9723864	.2029096	4.79	0.000	.5746908	1.370082
L2.	.6968229	.2320916	3.00	0.003	.2419317	1.151714
L3.	.6899381	.1379915	5.00	0.000	.4194796	.9603965
ARCH						
arch						
L1.	.2266948	.0163396	13.87	0.000	.1946697	.2587198
tarch						
L1.	-.2488891	.0173478	-14.35	0.000	-.2828902	-.214888
garch						
L1.	.8713512	.0090755	96.01	0.000	.8535636	.8891389
_cons	.0256514	.0021439	11.96	0.000	.0214495	.0298534

## (F)

This GARCH-M model with a GARCH(2,1) parameterization is not favourable to the existence of a time-varying risk premium as the coefficient on  $h_t$  in the conditional mean model is not significant at five percent significance level. Therefore, we cannot conclude that the increased expected return is caused by the conditional variance.

### GARCH-M time-varying risk premium ( $\lambda$ ) test

Ho:  $\lambda = 0$

Ha:  $\lambda > 0$

The estimated model for this GARCH-M with GARCH(2,1) can be shown as:

$$r_t = 0.0581 + 0.0278h_t + \varepsilon_t$$

(0.0166)    (0.0156)

$$\varepsilon_t = v_t \sqrt{h_t}$$

$$h_t = 0.0197 + 0.0979\varepsilon_{t-1}^2 + 1.1927h_{t-1} - 0.3064h_{t-2}$$

(0.0025)    (0.0111)            (0.0981)            (0.0872)

### STATA output for GARCH-M model

ARCH family regression

Sample: 2 - 3303	Number of obs	=	3,302
Distribution: Gaussian	Wald chi2(1)	=	3.18
Log likelihood = -4327.446	Prob > chi2	=	0.0747

ry	OPG					
	Coef.	Std. Err.	z	P> z	[95% Conf. Interval]	
ry						
_cons	.0581438	.0165553	3.51	0.000	.0256961	.0905915
ARCHM						
sigma2	.0277773	.0155832	1.78	0.075	-.0027652	.0583198
ARCH						
arch						
L1.	.0979044	.0110715	8.84	0.000	.0762046	.1196043
garch						
L1.	1.192714	.0980694	12.16	0.000	1.000502	1.384927
L2.	-.3063752	.0871774	-3.51	0.000	-.4772398	-.1355105
_cons	.01971	.0024847	7.93	0.000	.0148402	.0245799

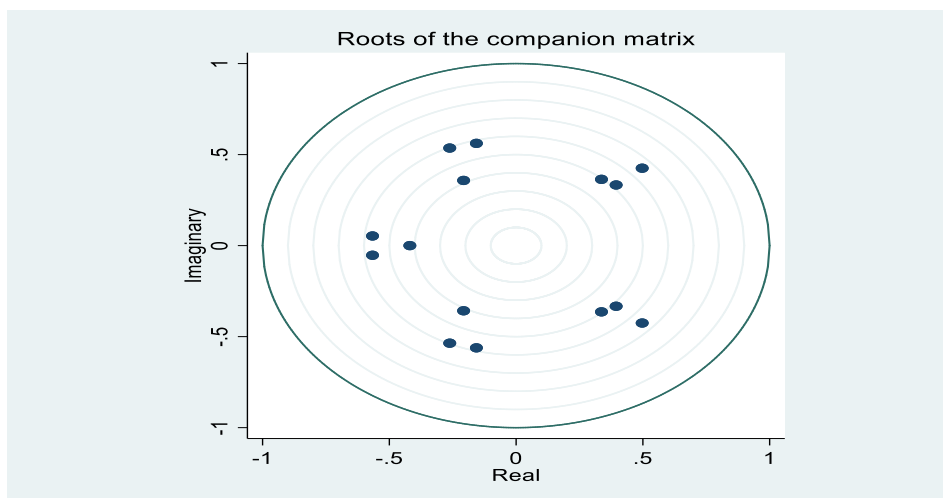


## STATA output of LM test

Lagrange-multiplier test

lag	chi2	df	Prob > chi2
1	6.8290	9	0.65492
2	11.8910	9	0.21953
3	9.0051	9	0.43681
4	16.0774	9	0.06528
5	8.0389	9	0.53023
6	5.8186	9	0.75792
7	18.2391	9	0.03250
8	18.6395	9	0.02844
9	17.8694	9	0.03672
10	23.7967	9	0.00463
11	5.0263	9	0.83201
12	13.3923	9	0.14564

## STATA unit circle graph for checking VAR stability



(C)

The advantage of companion representation is that it is useful in analysing VAR(p) model as the stationarity of the dynamic system can be assessed by checking the eigenvalues of the matrix.

**The VAR(5) can be expressed as:**

$$R_t = a_0 + \sum_{j=1}^5 A_j R_{t-j} + e_t$$

**The companion form of this model is expressed as:**

$$\begin{pmatrix} R_t \\ R_{t-1} \\ R_{t-2} \\ R_{t-3} \\ R_{t-4} \end{pmatrix} = \begin{pmatrix} a_0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} A_1 & A_2 & A_3 & A_4 & A_5 \\ I_3 & 0 & 0 & 0 & 0 \\ 0 & I_3 & 0 & 0 & 0 \\ 0 & 0 & I_3 & 0 & 0 \\ 0 & 0 & 0 & I_3 & 0 \end{pmatrix} \begin{pmatrix} R_{t-1} \\ R_{t-2} \\ R_{t-3} \\ R_{t-4} \\ R_{t-5} \end{pmatrix} + \begin{pmatrix} e_t \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

Specifically, VAR(p) is stable if the eigenvalues of the companion matrix have modules less than 1.

$$\tilde{A}_1 = \begin{pmatrix} A_1 & A_2 & A_3 & A_4 & A_5 \\ I_3 & 0 & 0 & 0 & 0 \\ 0 & I_3 & 0 & 0 & 0 \\ 0 & 0 & I_3 & 0 & 0 \\ 0 & 0 & 0 & I_3 & 0 \end{pmatrix}$$

**(D)**

**The structural form of VAR model is shown below as:**

$$\Theta R_t = \Omega_0 + \sum_{i=1}^n \Theta_i R_{t-i} + U_t$$

Where  $\Theta$  is coefficient matrix of  $R_t$  and its diagonal elements are all one.  $\Omega_0$  is a parameter vector.  $U_t$  represents the structural disturbance.

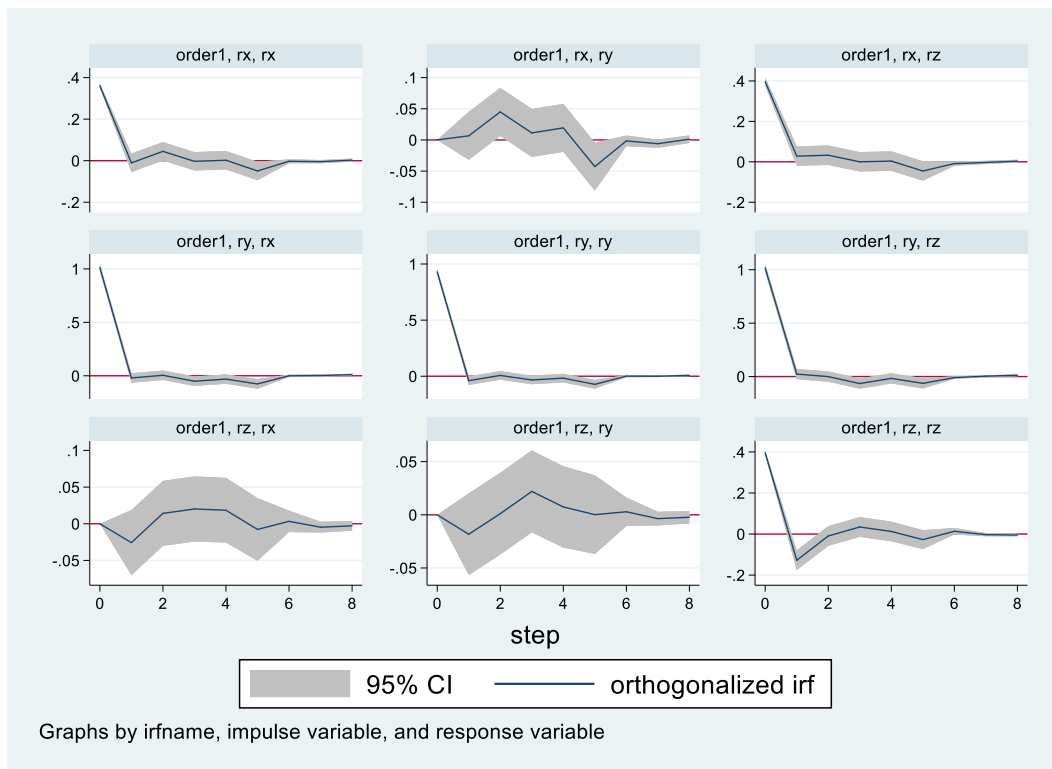
Panel of  $R_t$  that exhibits the relationship between the reduced form errors and the structural disturbances is shown below: (Note: X is the coefficient to be estimated)

$$\begin{pmatrix} \text{Ury} \\ \text{Urx} \\ \text{Urz} \end{pmatrix} \begin{pmatrix} 1 & \square & \square \\ X & 1 & \square \\ X & X & 1 \end{pmatrix} = \begin{pmatrix} 1 & \square & \square \\ \square & 1 & \square \\ \square & \square & 1 \end{pmatrix} \begin{pmatrix} \varepsilon_{ry} \\ \varepsilon_{rx} \\ \varepsilon_{rz} \end{pmatrix}$$

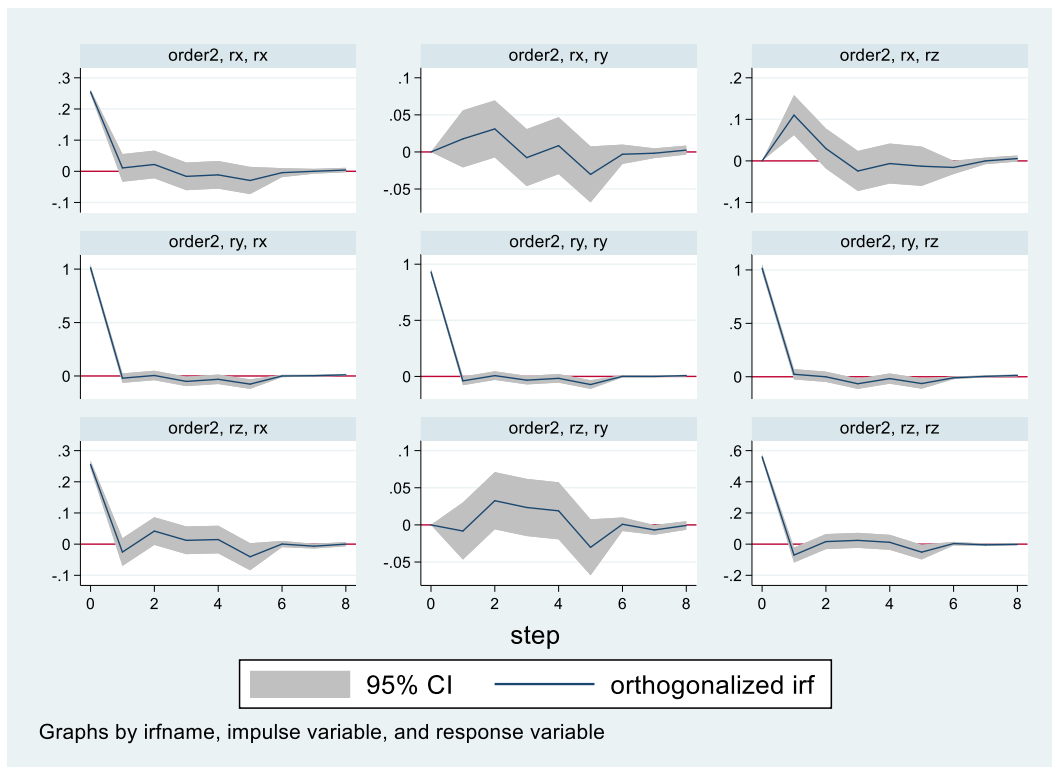
**(D-1)**

Below is the STATA output of all the ordering where ry denotes  $r_{y,t}$ , rx denotes  $r_{x,t}$ , and rz denotes  $r_{z,t}$ . The system appears to be sensitive to ordering because direction, shape, and persistence of impulse response to the same shock can be quite diverse under different ordering.

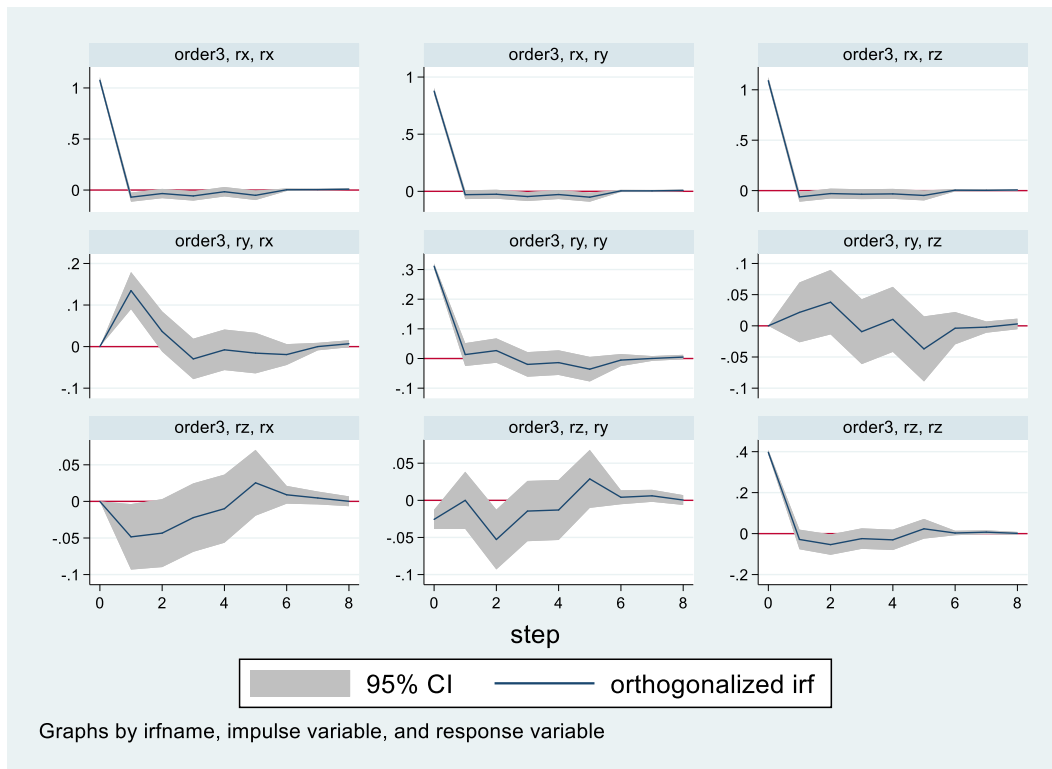
## Order 1(ry rx rz)



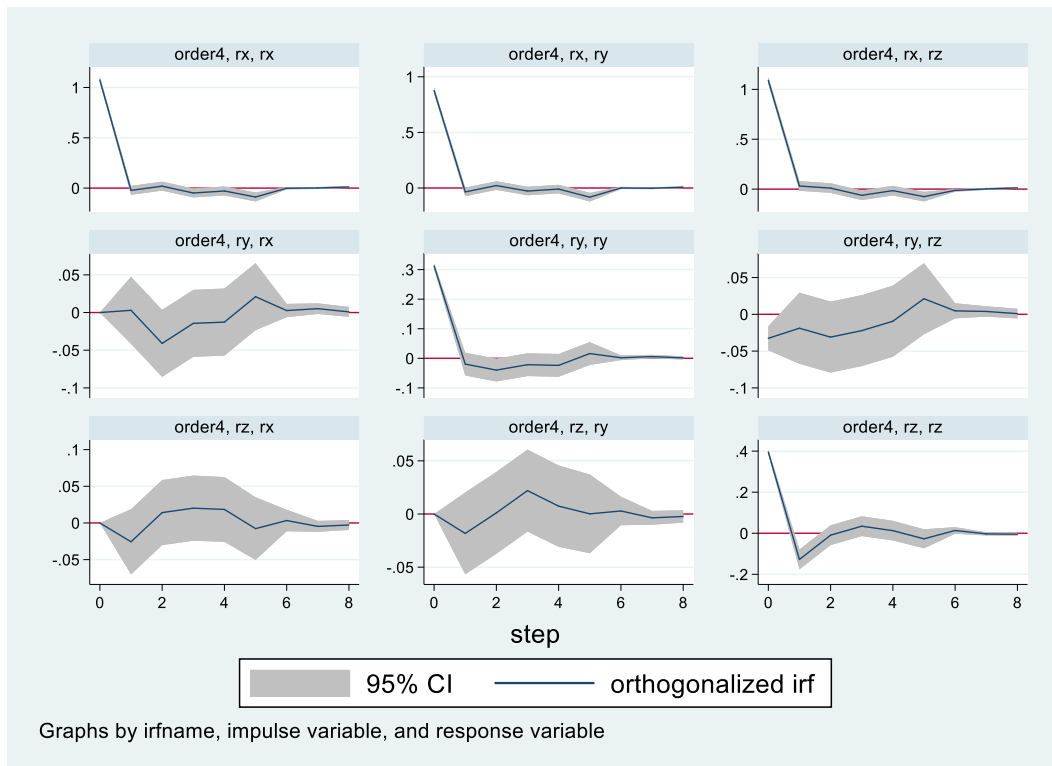
## Order 2(ry rz rx)



## Order 3(rx rz ry)

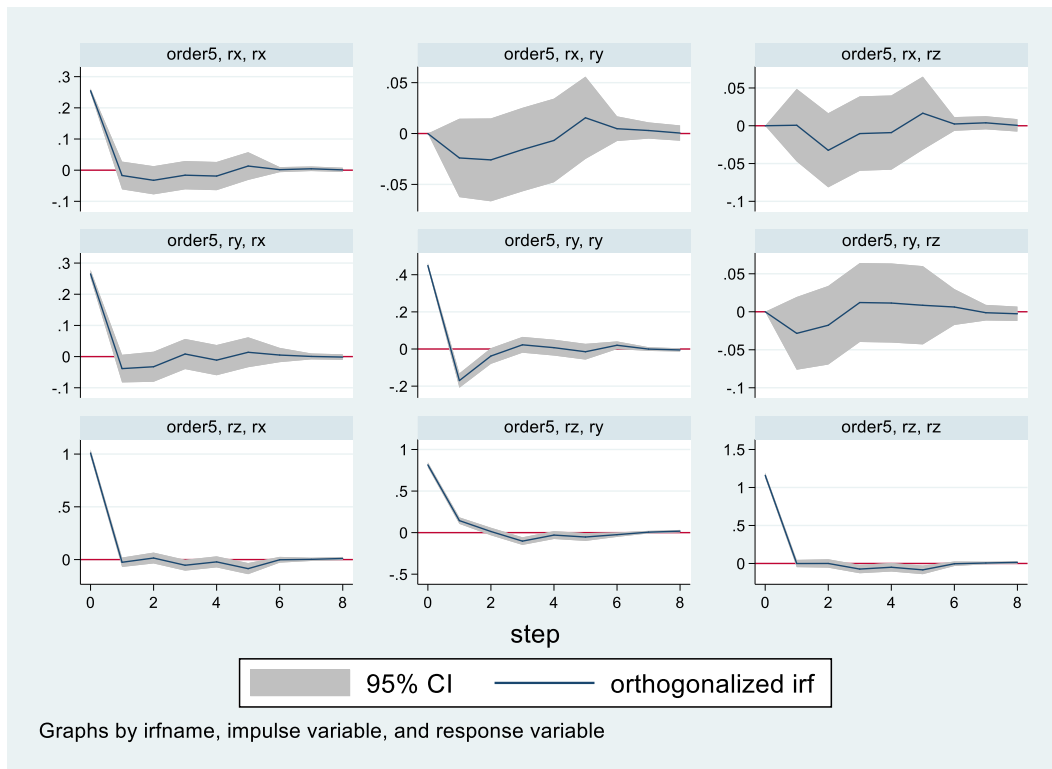


## Order 4(rx ry rz)

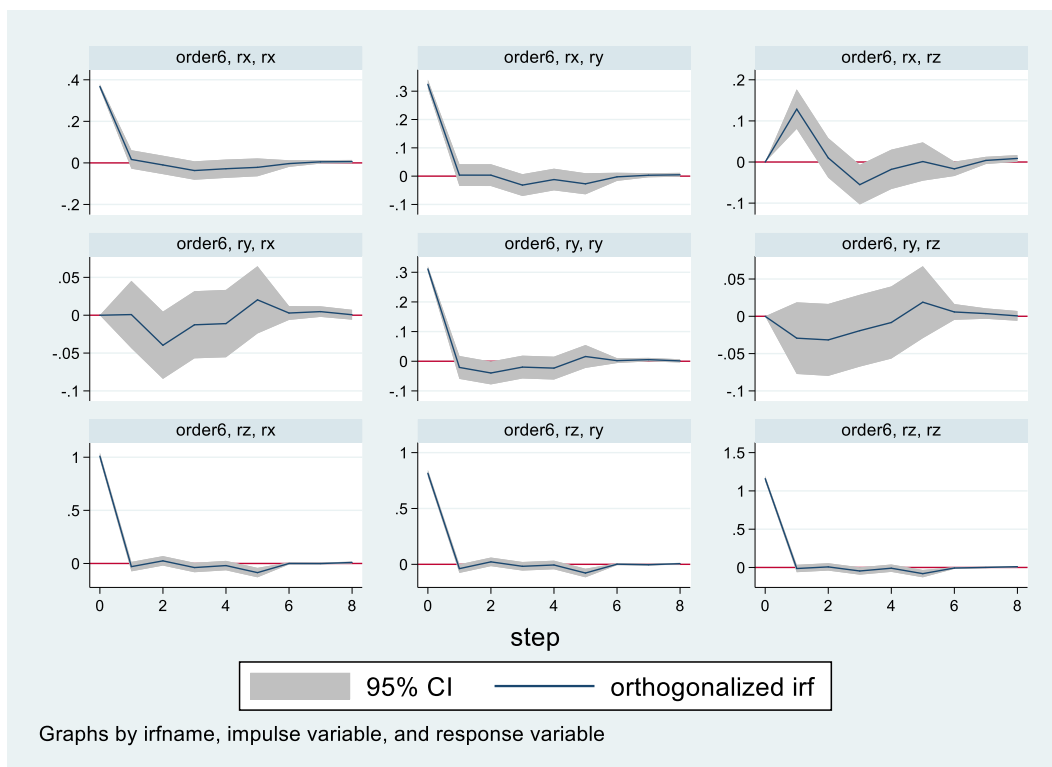




## Order 5(rz ry rx)



## Order 6(rz rx ry)



## **(D-2)**

### **Round I**

#### **ry rx rz vs ry rz rx**

Patterns are all very similar. Nevertheless, the response of rz to exogenous shock in rx is larger when the order is (ry rx rz) but response of rx to unexpected shock in rz is greater when the order is (ry rz rx). The response of rx to exogenous shock in itself is more significant when the order is (ry rx rz) while the response of rz to surprise change in itself is larger when the order is (ry rz rx). At this point, they are tied. Since rz is more sensitive to exogenous shock in rx when rx comes before rz, the order (ry rx rz) makes more sense. Overall, the order (ry rx rz) is a better model.

#### **rx rz ry vs rx ry rz**

The order (rx rz ry) is clearly better. The response of rz to exogenous shock in ry is stronger four periods after the initial shock when the order is (rx rz ry). The response of rx to shock in ry is stronger when the order is (rx rz ry). The response of ry to shock in rz is stronger when the order is (rx rz ry). The response of rx to unexpected change in rz is greater when the order is (rx rz ry). Others are either tied or order (rx ry rz) only has two sets that have stronger actions. In sum, all of the above conditions indicate that the model with order (rx rz ry) is more sound.

#### **rz ry rx vs rz rx ry**

At the first glance, their patterns look quite even. However, the response of ry to exogenous shock in rx is much more significant under the order (rz rx ry). The response of ry to unexpected change in rz is also slightly more significant under the order (rz rx ry). The response of rz to sudden and unexpected change in rx is also greater under the order (rz rx ry). The response of rx to surprise change in itself is slightly larger under the order (rz rx ry). In contrast, only the response of rx to shock in ry and the response of ry to unexpected change in itself are clearly more significant under order (rz ry rx). Apparently, the better model is with the order (rz rx ry).

### **Round II**

#### **ry rx rz vs rx rz ry vs rz rx ry**

I then compare the winners which are orders (ry rx rz), (rx rz ry), and (rz rx ry) from the round I comparison. The order (rx rz ry) is eliminated because it is clearly the worst out of three orders due to lower responses in most cases except for the responses to exogenous shock in rx.

### **Round III**

#### **ry rx rz vs rz rx ry**

The response of rx to change to itself is greater under the order (ry rx rz). The response of rz to unexpected change in rx is more significant under the order (ry rx rz). The response of rx to unexpected shock in ry is larger under the order (ry rx rz). The response of rz to sudden change in ry is larger under the order (ry rx rz). The response of ry to unexpected change in itself is larger under the order (ry rx rz).

In contrast, the response of ry to unexpected change in rx is clearly greater under the order (rz rx ry). The response of rx to exogenous shock in rz is stronger under the order (rz rx ry). The response of ry to surprise change in rz is larger under the order (rz rx ry). The response of rz to surprise shock in itself is greater under the order (rz rx ry).

Putting everything together, the order (ry rx rz) is a slightly better model. Therefore, the large cap index (ry) should be the strongest mover, followed by mid cap (rx), and small cap (rz).

## **Conclusion**

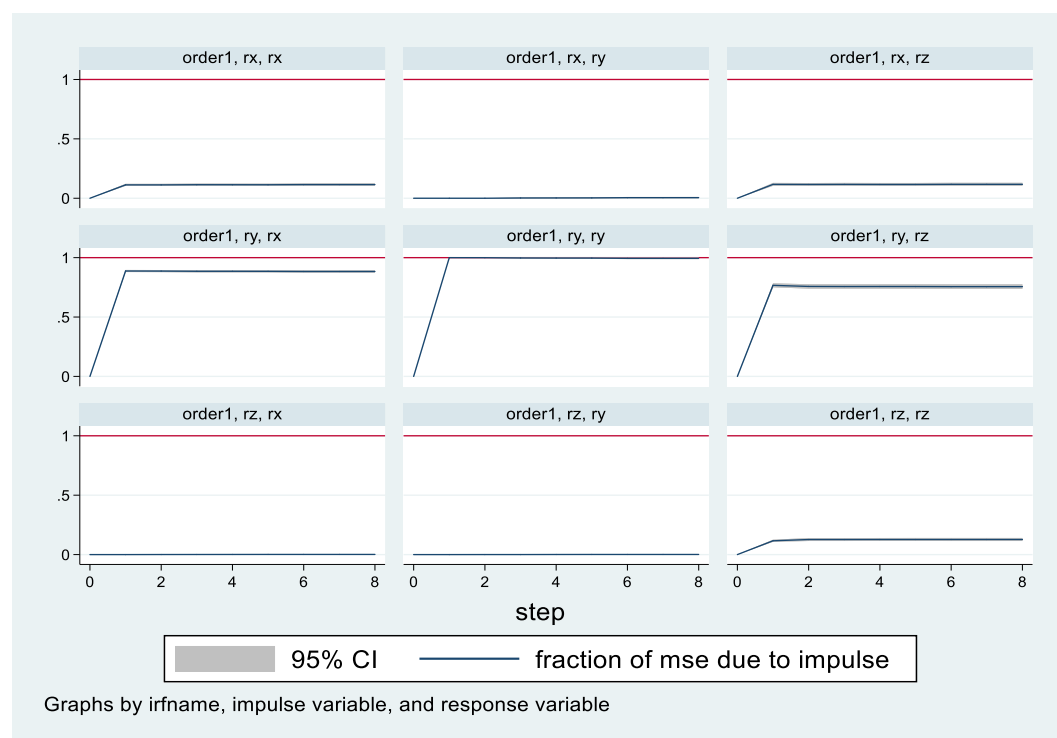
Stocks or companies belong to S&P 500 large cap or SPY tend to have much larger liquidity and is being tracked by more institutional investors including traders of proprietary trading desk at investment bank, commercial bank, long-only fund, and quantitative trading fund. In addition, traders at large banks are blocked from trading small cap stocks by middle office risk managers because large banks usually set very high limit regarding liquidity risk unless he/she belongs to market making desk for mid/small equities. Therefore, the large cap should be the first in the order and the order (ry rx rz) is inevitably the best model of all.

## **(D-3)**

### **The forecast error variance decomposition (FEVD):**

1. Most of the forecast error variances in the return of rx are not explained by changes in itself but by changes in ry. Thus, rx is not exogenous.
2. The entire forecast error of variance in the return of ry is due to change in changes in itself. Thus, ry is exogenous.
3. Most of the forecast error of variances in the return of rz are not due to changes in itself but by changes in ry followed by changes in rx. Hence, rz is not exogenous because it can be explained by other two variables.

### **STATA graph of forecast error variance decomposition**



(E)

We can use Granger causality Wald test to determine whether lags of one variable Granger cause other variables. From the Granger causality Wald test, we fail to reject most of them at the five percent significance level excepts “MDY Granger cause SLY” at five percent significance level with five lags. Besides, the test also shows that all Granger cause SLY at five percent significance level with ten lags. To interpret, we can say that lags of MDY Granger cause lags of SLY in the system. MDY is said to Granger-cause a variable SLY if, given the past values of SLY, past values of MDY are useful for predicting SLY.

**A three-variable causal model can be expressed as:**

$$X_t = a_1(U) X_t + b_1(U) Y_t + c_1(U) Z_t + \varepsilon_{1,t}$$

$$Y_t = a_2(U) X_t + b_2(U) Y_t + c_2(U) Z_t + \varepsilon_{2,t}$$

$$Z_t = a_3(U) X_t + b_3(U) Y_t + c_3(U) Z_t + \varepsilon_{3,t}$$

Where  $a_i(U)$  are polynomials in  $U$ , the shift operator.  $\varepsilon_{i,t}$  are uncorrelated, white-noise series and denote the variance  $\varepsilon_{i,t} = \sigma_i^2$ .

**Granger causality Wald test**

Ho: No Granger causality

Ha: Granger causality exists

**Table of Granger causality Wald test**

Equation	Excluded	$\chi^2$	df	Prob. > $\chi^2$	Decision
ry	rx	6.4427	5	0.265	MDY not Granger cause SPY at 5% significance level
ry	rz	2.3076	5	0.805	SLY not Granger cause SPY at 5% significance level
rx	ry	4.6154	5	0.465	SPY not Granger cause MDY at 5% significance level
rx	rz	3.1617	5	0.675	SLY not Granger cause MDY at 5% significance level
rz	ry	5.4575	5	0.363	SPY not Granger cause SLY at 5% significance level
rz	rx	24.644	5	0.000	MDY Granger cause SLY at 5% significance level

**STATE output of Granger causality Wald test**

Granger causality Wald tests

Equation	Excluded	chi2	df	Prob > chi2
ry	rx	6.4427	5	0.265
ry	rz	2.3076	5	0.805
ry	ALL	13.488	10	0.198
rx	ry	4.6154	5	0.465
rx	rz	3.1617	5	0.675
rx	ALL	8.0142	10	0.627
rz	ry	5.4575	5	0.363
rz	rx	24.644	5	0.000
rz	ALL	38.027	10	0.000