



Checklist of information to be provided by the team		Land requirements & milestones		Water requirements & milestones		Space requirements & milestones			
Name of the project		Emergency killswitch		Emergency killswitch		Emergency killswitch			
Team members name & roles		Emergency Siren (within 3 seconds of emergency)		Emergency Siren (within 3 seconds of emergency)		Emergency Siren (within 3 seconds of emergency)			
Category entered		Fail-safe mechanism to immobilize		Fail-safe mechanism to immobilize		Fail-safe mechanism to stop propulsion and or deploy chute			
Abstract		Is not operated in a road open to circulation		Navigation lights (red, green, white)		Use only lightweight, non metal parts, for the nose, body, and fins of the aircraft			
Timeline				Is not operated in a body of water where it could be in contact or proximity of humans		Aircraft launching zone should be at least 60m wide			
Budget						Starting system should have safety interlock and switch should return to off when released			
Specifications						Launcher will have a deflector below the aircraft			
Description									Tick (✓) all the points in the checklist and requirements
Scorecard		Travel 500m	M	Buoyant for all the time of operation (at least 15 minutes)	M	Reach at least 100m of altitude from take-off	M		Do NOT submit your entry if any security requirement isn't ticked.
Proofs (photos, videos, telemetry,...)		Autonomous navigation (including obstacles detection and adaptation)	M	Autonomous navigation (including obstacles detection and adaptation)	M	Capture flight data	M		
Code repo link (forked from template)		Terrain adaptation	M	Can remain stationary	M	Land undamaged and can be relaunched	M		Circle (O) all the milestones you've reached
Is an original creation - and building started after the announcement of the challenge		Can return to its starting point and charge itself	M	Can autonomously depart from and dock to quay	M	Land autonomously in a designated area	M		
Submit at https://robotshop.typeform.com/to/ZruvXz		Can transport a cargo of at least 25% of the total weight of the robot	M	Can transport a cargo of at least 50% of the total weight of the robot	M	Can transport a cargo of 30g	M		