

Lab-2

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Matlab Experiment:

Matlab Code:

```
Fs = 20; % Sampling frequency (20 Hz)
T = 1/Fs; % Sampling period
t = 0:T:2-T; % Time vector for 2 seconds
f1 = 5; % Frequency of first cosine signal (5 Hz)
f2 = 8; % Frequency of second cosine signal (8 Hz)
x = cos(2*pi*f1*t) + cos(2*pi*f2*t); % Original signal (sum of cosines)

% Sampling the signal
n = 0:length(t)-1; % Sample indices
x_sampled = cos(2*pi*f1*n*T) + cos(2*pi*f2*n*T); % Sampled signal

% Low-Pass Filter (LPF) using sinc interpolation
t_reconstruct = linspace(0, 2, 1000); % High-resolution time vector
x_reconstruct = zeros(size(t_reconstruct)); % Initialize reconstructed signal

for i = 1:length(n)
    x_reconstruct = x_reconstruct + x_sampled(i) * sinc(Fs*(t_reconstruct-n(i)*T));
end

% Plotting the results
figure;
subplot(3,1,1);
plot(t, x, 'b', 'LineWidth', 1.5);
title('Original Signal');
xlabel('Time (s)');
ylabel('Amplitude');
```

```
grid on;
```

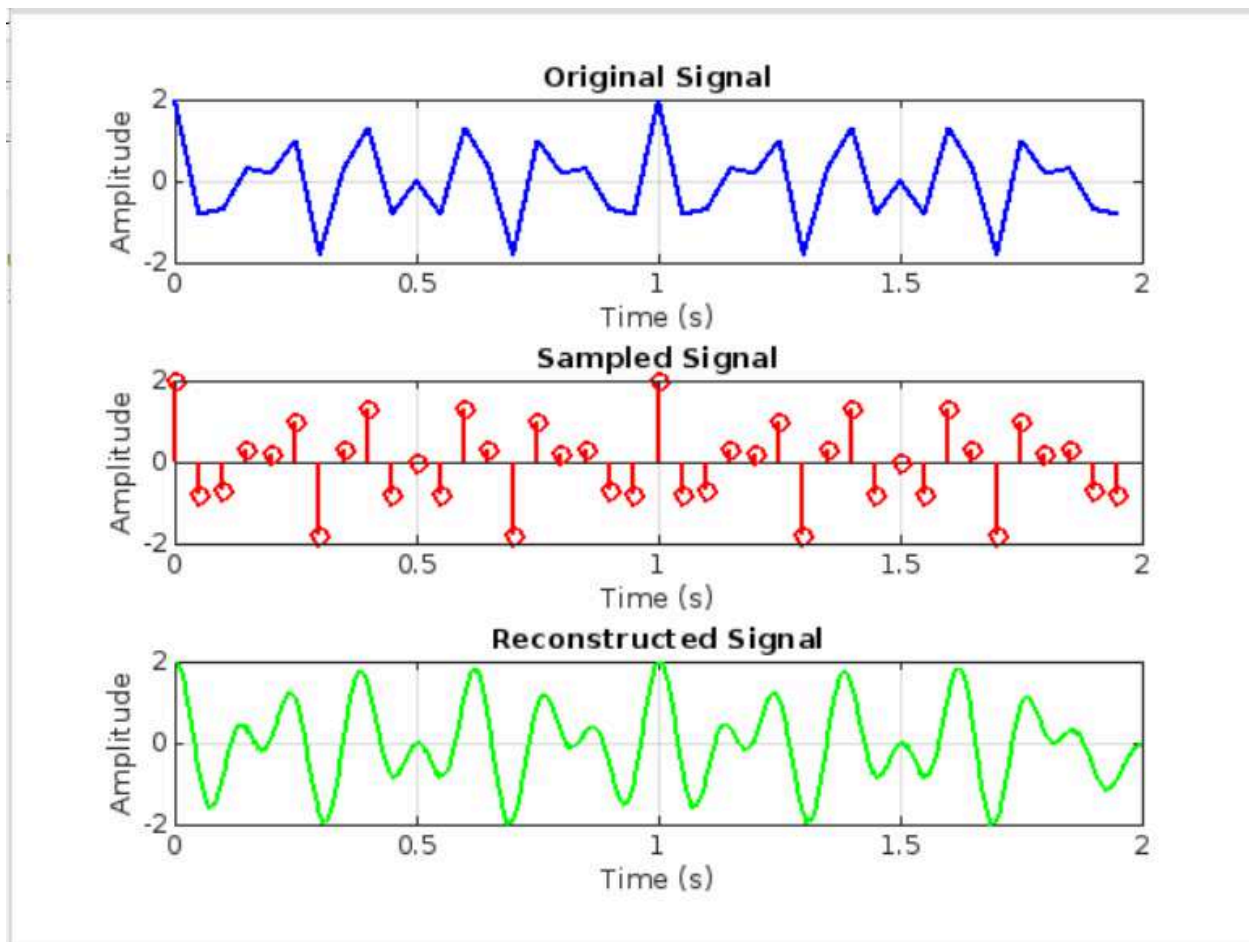
```
subplot(3,1,2);  
stem(n*T, x_sampled, 'r', 'LineWidth', 1.5);  
title('Sampled Signal');  
xlabel('Time (s)');  
ylabel('Amplitude');  
grid on;
```

```
subplot(3,1,3);  
plot(t_reconstruct, x_reconstruct, 'g', 'LineWidth', 1.5);  
title('Reconstructed Signal');  
xlabel('Time (s)');  
ylabel('Amplitude');  
grid on;
```

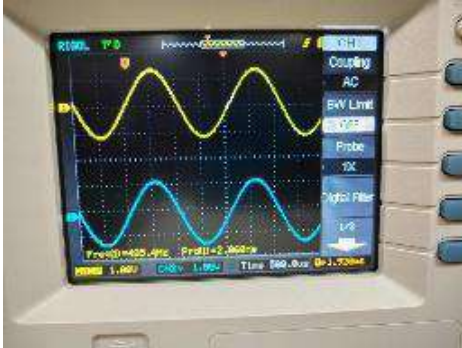
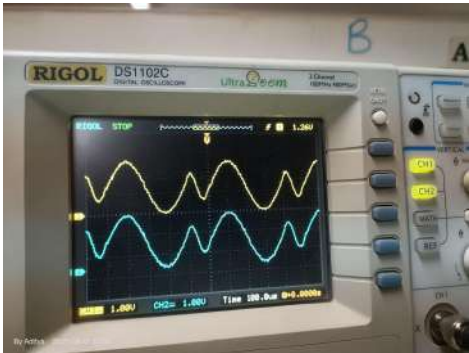
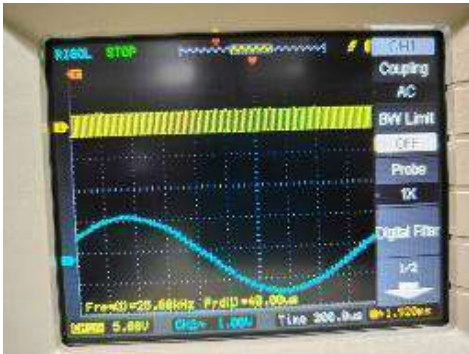
Explanation:

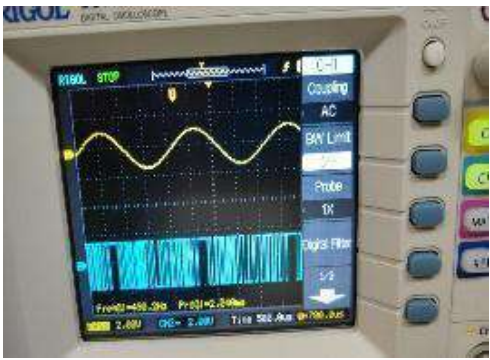


This MATLAB code samples a signal composed of two cosine waves (5 Hz and 8 Hz) at 20 Hz, reconstructs the signal using sinc interpolation (low-pass filtering), and then plots the original, sampled, and reconstructed signals for comparison.

Output:



Experiment 1:


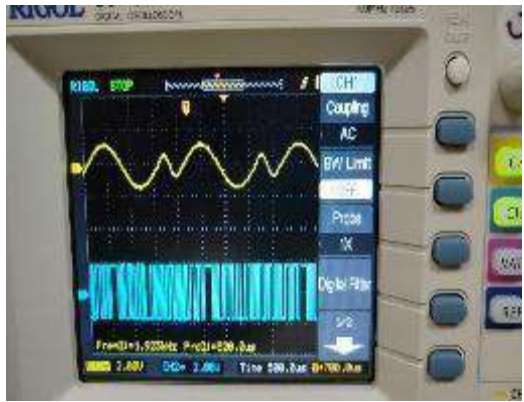
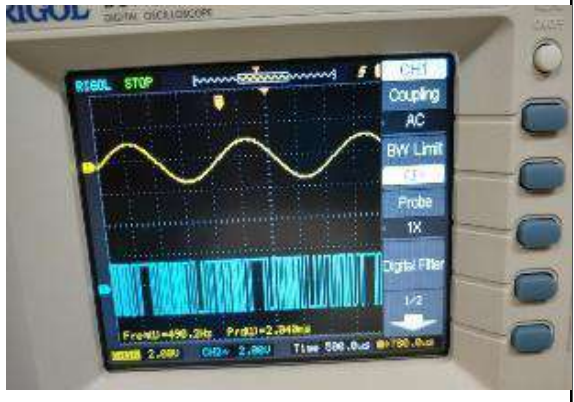
Sr.no	Input signal and freq.	Sampling freq.	Input and Output signals
Sine/500 Hz	Channel1	-	
Arbitrary /1.5 KHz	Channel2	-	
Sine/500 Hz	Channel1	8 KHz	

Sine/500 Hz	Channel1	8 KHz	
Arbitrary /500 Hz	Channel2	8 KHz	
Arbitrary /500 Hz	Channel2	8 KHz	

Conclusion:

- Through this experiment, we learned how different input signal frequencies and sampling rates influence the signals observed in the oscilloscope.
- We learned that adjusting the sampling frequency is crucial for representing the original signal accurately.


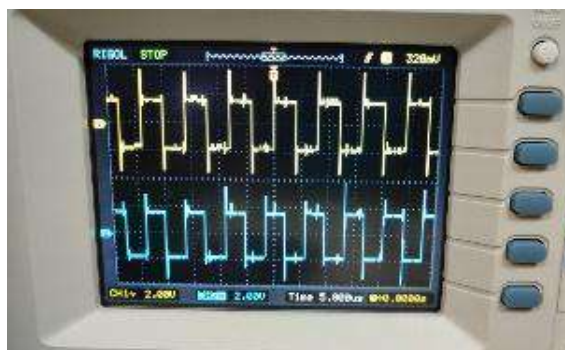
Experiment-2:


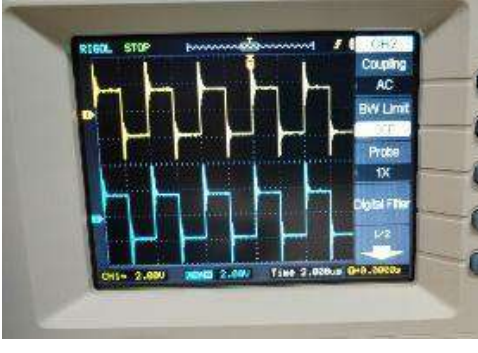
Sr.no	Input signal and freq.	Sampling freq.	Input and Output signals
Sine/500 Hz	Channel1	8 KHz	
Arbitrary/500 Hz	Channel1	8 KHz	
Sine /500 Hz	Channel2	8 KHz	

Conclusion:

- Through this experiment, we showed that the line speed frequency directly impacts the PCM clock and the PCM output.
- Changes in the line speed directly affected the timing and quality of the PCM output signal.

Experiment-3:


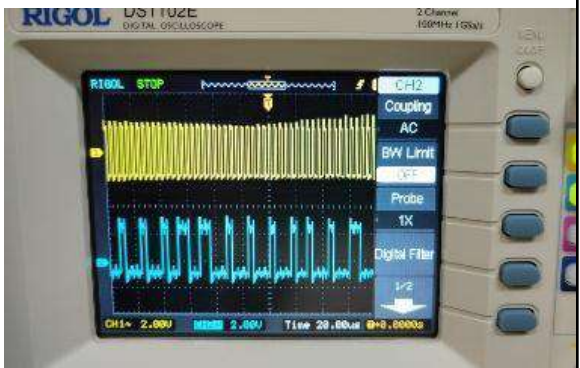
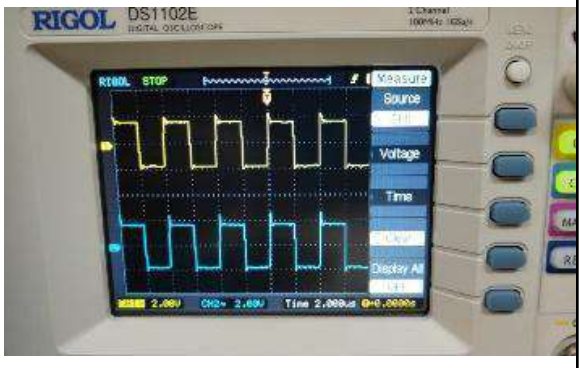
Sr.no	Input signal and freq.	Sampling freq.	Input and Output signals
Sine/500 Hz	Both	8KHz	
Sine/500 Hz	Both	8 KHz	

Sine/500 Hz	Both	8 KHz	
Sine/500 Hz	Both	8 KHz	

Conclusion:

- Through this experiment, we learned how a 17 bit multiplexed output frame is structured with a framing pulse.
- The framing pulse is added for synchronization of frames.
- They help maintain alignment of channels within the frame.

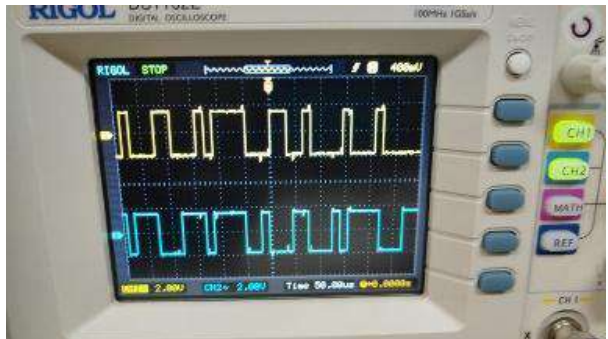
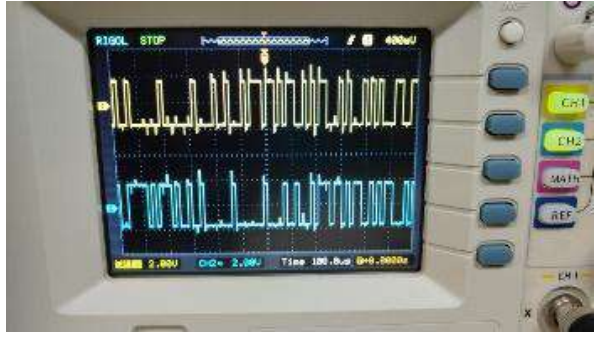
Experiment-4:

Sr.no	Input signal and freq.	Sampling freq.	Input and Output signals
Sine/500 Hz	Both	8KHz	
Sine/500 Hz	Both	8 KHz	
Sine/500 Hz	Both	8 KHz	

Conclusion:

- Through this experiment, we learned how detecting the framing pulse enables the system to correctly synchronize and output a 16 bit frame.
- It helps us understand the critical role of the framing pulse in ensuring that the data is accurately aligned and transmitted in intended format.

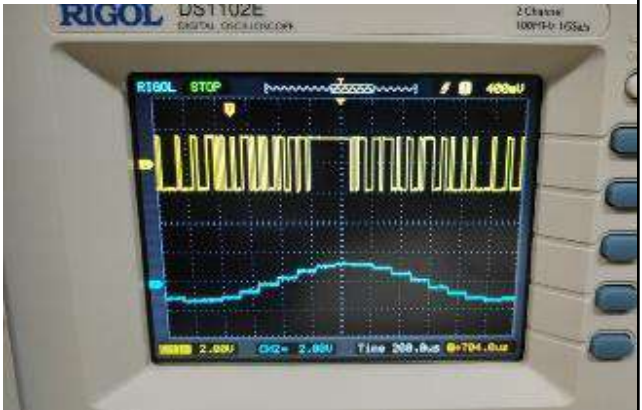
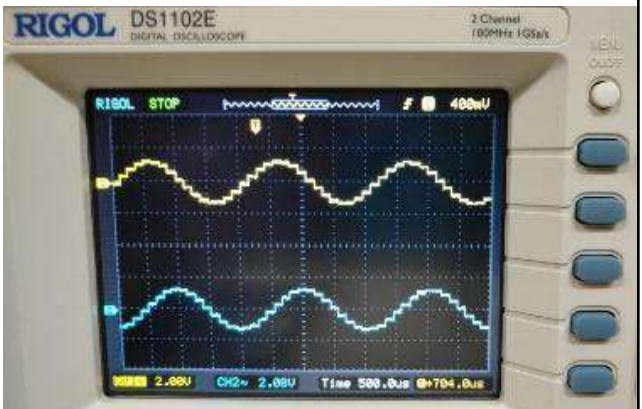
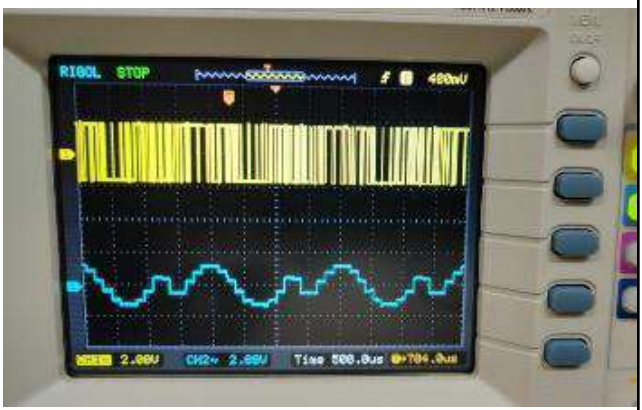
Experiment-5:

Sr.no	Input signal and freq.	Sampling freq.	Input and Output signals
Sine/500 Hz	Channel1	8KHz	
Arbitrary /500 Hz	Channel2	8KHz	

Conclusion:

- Through this experiment, we learned how PCM output was accurately separated into individual channels after demultiplexing.
- The framing pulse plays a key role in ensuring that each channel's signal was correctly identified and retrieved.
- This ensures integrity of original input signals throughout the process.

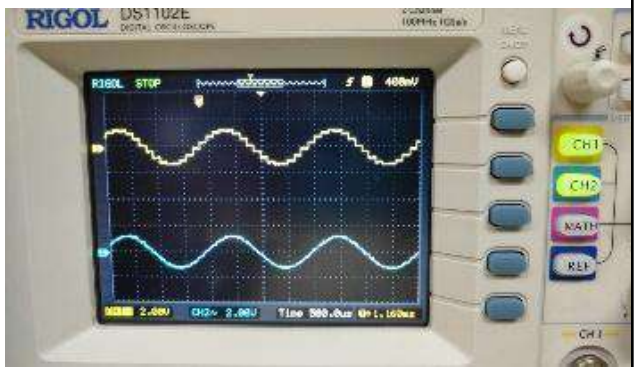
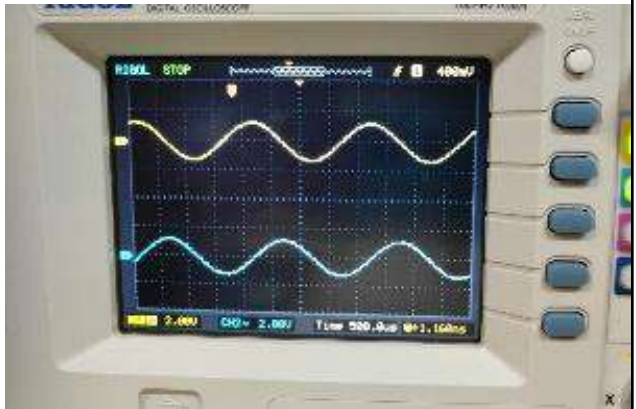
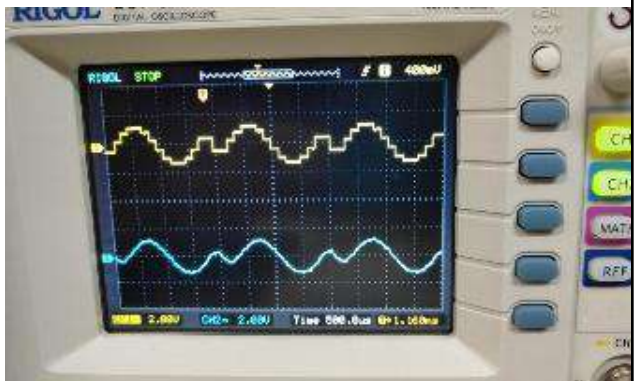
Experiment-6:

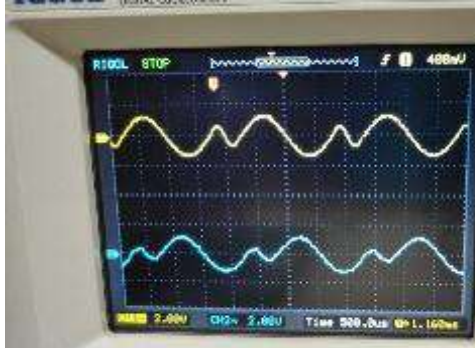
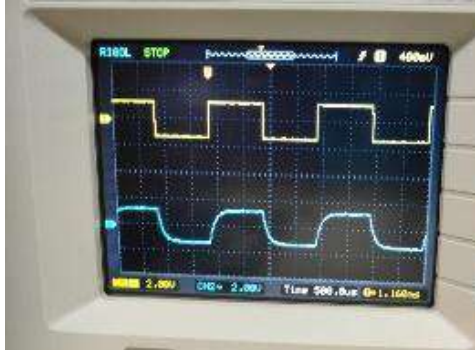
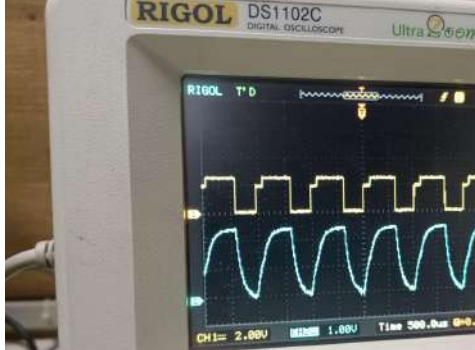
Sr.no	Input signal and freq.	Sampling freq.	Input and Output signals
Sine/500 Hz	Channel1	8KHz	
Sine/500 Hz	Channel1	8 KHz	
Arbitrary/500 Hz	Channel2	8 KHz	

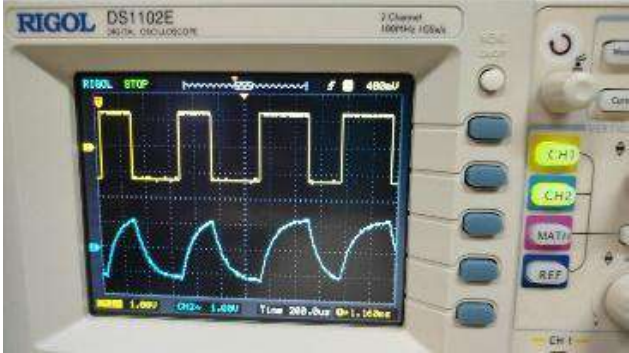
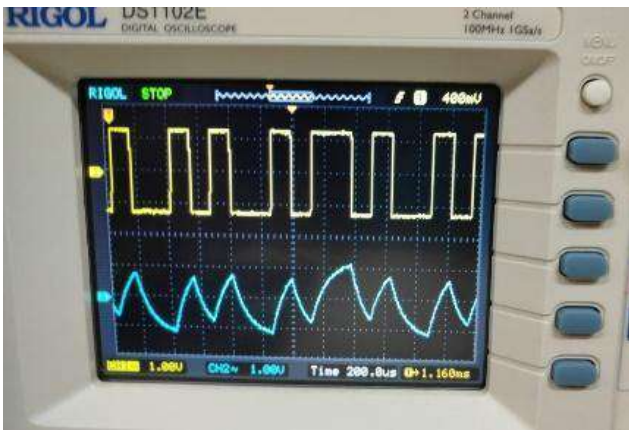
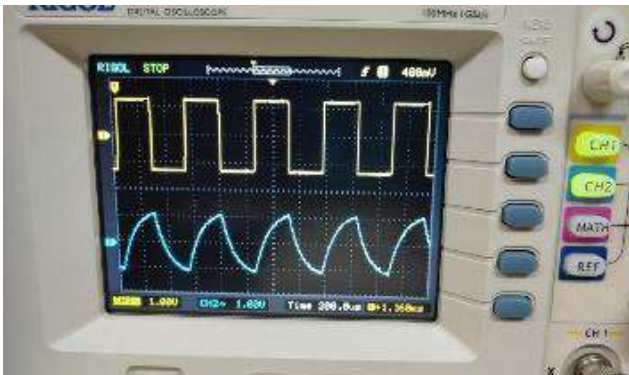
Conclusion:

- Through this experiment, we learned how demodulated output from a TDM-PCM system accurately reconstructs the original input signal.
- By observing the signal at various points, we observe how the system effectively separates and retrieves each channel's data.

Experiment-7:

Sr.no	Input signal and freq.	Sampling freq.	Input and Output signals
Sine/500 Hz	Channel1	8KHz	
Sine/500 Hz	Channel1	8 KHz	
Arbitrary/500 Hz	Channel2	8 KHz	

Arbitrary/500 Hz	Channel2	8 KHz	
Square/500 Hz	Channel1	8KHz	
Square/1 KHz	Channel1	8KHz	

Square / 1.5KHz	Channel1	8KHz	
Square / 3 KHz	Channel1	8kHz	
Square / 2 KHz	Channel1	8kHz	

Conclusion:

- Through this experiment, we learned how the low pass filter effectively smoothes out the demodulated signal.
- It then converts the original square wave into a more rounded waveform due to the LPF's RC characteristics.