

$$y_1(t) = g(T-t)$$

 $y_1(-1.5T) = g(T+1.5T)$
 $= g(2.5T)$

$$g(t) = kg(\tau - t)$$

$$= g_0(t)$$

Goff =
$$RG^{*}(f)Glf e^{-j2\pi fT} = R|Glf l^{2}e^{-j2\pi fT}$$
 $go(T) = \int_{0}^{\infty} Goff)e^{j2\pi fT} df = R\int_{0}^{\infty} [Gff]^{2} df$

Let $\int_{0}^{\infty} Goff)e^{j2\pi fT} df = R\int_{0}^{\infty} [Gff]^{2} df$

We know from Rayleigh's theorem

$$E = \int_{0}^{\infty} g(t) dt = \int_{0}^{\infty} [Gff]^{2} df$$

Hence, $go(T) = RE$

$$E = \int_{0}^{\infty} g^{2}t dt$$

$$E[\pi^{2}tt] = \frac{N_{0}}{2} R^{2} \int_{0}^{\infty} [Gff]^{2} df = R^{2}NoG_{12}^{2}$$

(Study linear feltering of WN from Haylan | Couch | Madhow)

Peall pulse signal power to mouse power vatio

MF has completely asomoved the dependence on the WF of the gH). The ability of the MF receiver to combat AWN (Additie white newse), we find that all signals that have the same energy are equally effective.

We know that the MF is the optimum detector of a known pulse in AWN, home We can now study the error rate due to noise in a binary PCM system.

Convider a binary PCM system based en polar NRZ signalling

1

A To

Tb t

W(t): Channel noise (AWGN) of zeromeant PSD No/2. In the signalling interval $0 \le t \le T_b$, Rxd. sig. is thus written as

 $x(t) = \begin{cases} +A + w(t), & \text{if symbol 1 is Sent} \\ -A + w(t), & \text{if } o \text{ is Sent} \end{cases}$

The bit duration & A -> Txd. pulse amplitude

- -) Assumption: DTx. takes place over infinite BW chammel; i.e., chammel right now is not B.L. _> no 1.S.I.
 - 2 ex has acquired knowledge of the starting & ending times of each Txd. Julse. Barically, Julse shape is known, but polarity is unknown.

probi Gwen the newry signal xH), the fxis regd: to make a decision in each signalling interval as to whother the txd. Symbolis Dor I. showmen S(t)

T)

Decision

Device

Sample

at t=Tb

wan with

let y denote the sample value obtained at the end of a signalling interval.