## SC301 - Numerical Linear Algebra

# Preliminaries: Linear Algebra

Aditya Tatu



January 7, 2025

### Data

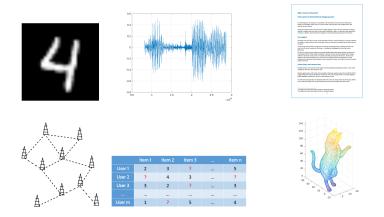


Figure: Examples of Data

• Typical representation of data, raw or feature-based is an m-tuple of real numbers, an element of  $\mathbb{R}^m$ .



#### **Dataset**

- Dataset will be a subset  $D \subset \mathbb{R}^m$ .
- Operations on  $\mathbb{R}^m$ :
  - 1. Addition (+) :  $\forall \mathbf{u} = (u_1, \dots, u_m), \forall \mathbf{v} = (v_1, \dots, v_m) \in \mathbb{R}^m, \mathbf{u} + \mathbf{v} := (u_1 + v_1, \dots, u_m + v_m).$
  - 2. Scalar Multiplication (·):  $\forall x \in \mathbb{R}, \forall \mathbf{u} = (u_1, \dots, u_m) \in \mathbb{R}^m, x \cdot \mathbf{u} := (xu_1, \dots, xu_m).$

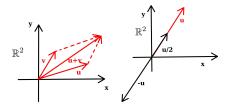


Figure: (left) Addition and (right) Scalar multiplication in  $\mathbb{R}^2$ 

### Linear Combination

- Given vectors  $\mathbf{u}, \mathbf{v} \in \mathbb{R}^m$  and  $x, y \in \mathbb{R}$ , we say that the vector  $x \cdot \mathbf{u} + y \cdot \mathbf{v} \in \mathbb{R}^m$  is a **linear combination** of  $\mathbf{u}, \mathbf{v}$ .
- In general, given vectors  $\mathbf{a}_1, \dots, \mathbf{a}_n \in \mathbb{R}^m$ , and given scalars  $x_1, \dots, x_n$ , we say that the vector  $\sum_{k=1}^n x_k \mathbf{a}_k$  is a linear combination of  $\{\mathbf{a}_1, \dots, \mathbf{a}_n\}$ .
- Explicitly in terms of the *m*-tuples,

$$\mathbf{a}_k = (a_{1,k}, a_{2,k}, \dots, a_{m,k}), k = 1, \dots, n,$$

$$\sum_{k=1}^{n} x_{k} \mathbf{a}_{k} = \begin{bmatrix} x_{1} a_{1,1} \\ x_{1} a_{2,1} \\ | \\ x_{1} a_{m,1} \end{bmatrix} + \begin{bmatrix} x_{2} a_{1,2} \\ x_{2} a_{2,2} \\ | \\ x_{2} a_{m,2} \end{bmatrix} + \dots + \begin{bmatrix} x_{n} a_{1,n} \\ x_{n} a_{2,n} \\ | \\ x_{n} a_{m,n} \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} a_{1,1} & a_{1,2} & - & a_{1,n} \\ a_{2,1} & a_{2,2} & - & a_{2,n} \\ | & | & | & | \\ a_{m,1} & a_{m,2} & - & a_{m,n} \end{bmatrix}}_{A} \underbrace{\begin{bmatrix} x_{1} \\ x_{2} \\ | \\ x_{n} \end{bmatrix}}_{X}$$

$$(4)$$

• Matrix-Vector Product:  $A_{m \times n} x_{n \times 1}$  is a linear combination of columns of A.

# Linear Dependence/Independence

- If  $\mathbf{b} = x\mathbf{u} + y\mathbf{v}$ , we say that  $\mathbf{b}$  is **linearly dependent** (or LD) on the set of vectors  $\{\mathbf{u}, \mathbf{v}\}$ .
- ▶ In general, if  $\mathbf{b} = \sum_{k=1}^{n} x_k \mathbf{a}_k$ , where  $\mathbf{a}_k \in \mathbb{R}^m, x_k \in \mathbb{R}, k = 1, \dots, n$ , we say that  $\mathbf{b}$  is linearly dependent on the set  $\{\mathbf{a}_1, \dots, \mathbf{a}_n\}$ .
- Conversely, we say that the vector **b** is **linearly independent** (or LI) of the set  $\{\mathbf{a}_1, \dots, \mathbf{a}_n\}$  if for no scalars  $x_1, \dots, x_n$ ,  $\mathbf{b} = \sum_{k=1}^n x_k \mathbf{a}_k$ .
- ullet Explicitly, since  $\mathbf{a}_k \in \mathbb{R}^m, k=1,\ldots,n$ ,

$$x_{1}\begin{bmatrix} a_{1,1} \\ a_{2,1} \\ | \\ a_{m,1} \end{bmatrix} + x_{2}\begin{bmatrix} a_{1,2} \\ a_{2,2} \\ | \\ a_{m,2} \end{bmatrix} + \dots + x_{n}\begin{bmatrix} a_{1,n} \\ a_{2,n} \\ | \\ a_{m,n} \end{bmatrix} = \begin{bmatrix} b_{1} \\ b_{2} \\ | \\ b_{m} \end{bmatrix}$$
(5)
$$A\mathbf{x} = \mathbf{b}$$
 (6)

## Solving Linear equations

- ullet Find  $\mathbf{x} \in \mathbb{R}^n$  such that  $A_{m \times n} \mathbf{x}_{n \times 1} = \mathbf{b}_{m \times 1}$
- Column Space of A:

$$C(A) = \{\sum_{k=1}^{n} x_k \mathbf{a}_k \mid \forall x_k \in \mathbb{R}, k = 1, \dots, n\} \subset \mathbb{R}^m.$$

▶ Solution to  $A\mathbf{x} = \mathbf{b}$  exists if and only if  $\mathbf{b} \in C(A)$ .

► Example: Let 
$$A = \begin{bmatrix} -1 & 2 \\ 2 & -1 \\ -3 & 1 \end{bmatrix}$$
,  $\mathbf{b}_1 = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$ ,  $\mathbf{b}_2 = \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$ 

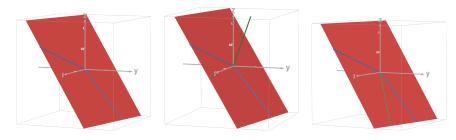


Figure: Column Space and Existence of Solution

• Example: 
$$A_1 = \begin{bmatrix} -1 & 2 \\ 2 & -1 \\ -3 & 1 \end{bmatrix}, A_2 = \begin{bmatrix} -1 & 1 \\ 2 & -2 \\ -3 & 3 \end{bmatrix}$$

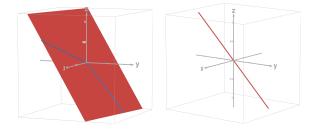


Figure: Column Space of  $A_1$  and  $A_2$ .

- ullet Properties of C(A):
- ▶  $0 \in C(A)$
- ▶ If  $\mathbf{u}, \mathbf{v} \in C(A), \forall x, y \in \mathbb{R}, x\mathbf{u} + y\mathbf{v} \in C(A)$ .

# Linearly Independent Set of vectors

- We say that  $\{a_1, \ldots, a_n\}$  is LI if none of the  $a_i$ 's can be expressed as a linear combination of the remaining  $a_k$ 's.
- ▶ Re-writing, if the set  $\{\mathbf{a}_1, \dots, \mathbf{a}_n\}$  is LD then there must be at least one vector, say  $\mathbf{a}_i$  from the set such that  $\mathbf{a}_i = \sum_{k=1, k \neq i}^n x_k \mathbf{a}_k$ . Then,

$$\sum_{k=1,k\neq i}^{n} x_k \mathbf{a}_k - \mathbf{a}_i = \mathbf{0} \tag{7}$$

$$\sum_{k=1}^{n} x_k \mathbf{a}_k = \mathbf{0}, \text{ with } x_i = -1$$
 (8)

- Thus, there is at least one non-zero scalar in the set  $\{x_1, \ldots, x_n\}$  such that  $\sum_{k=1}^n x_k \mathbf{a}_k = \mathbf{0}$ .
- ▶ So, if cols of A are LD, there exists  $\mathbf{x} \neq \mathbf{0}$  such that  $A\mathbf{x} = \mathbf{0}$ . And  $A\mathbf{0} = \mathbf{0}$ .

### LI set of Vectors

- How to verify LI of  $\{a_1, \ldots, a_n\}$ ?
- Find x such that Ax = 0.

### Nullspace

ullet For  $A \in \mathbb{R}^{m \times n}$ , its Nullspace, denoted by N(A) is defined as:

$$N(A) = \{ \mathbf{x} \in \mathbb{R}^n \mid A\mathbf{x} = \mathbf{0} \}$$

- $\bullet$  Properties of N(A):
- ▶  $\mathbf{0} \in N(A)$
- ▶ If  $\mathbf{u}, \mathbf{v} \in N(A), \forall x, y \in \mathbb{R}, x\mathbf{u} + y\mathbf{v} \in N(A)$ .

- If  $\mathbf{w} \neq \mathbf{0}$ ,  $\mathbf{w} \in N(A)$ , cols of A are not LI.
- If  $\mathbf{y} \in \mathbb{R}^n$  satisfies/solves  $A\mathbf{x} = \mathbf{b}$ , and  $\mathbf{w} \in \mathcal{N}(A)$ , then  $\mathbf{y} + \mathbf{w}$  also solves  $A\mathbf{x} = \mathbf{b} \Rightarrow$  Multiple Solutions!
- If there are multiple solutions to  $A\mathbf{x} = \mathbf{b}$ , then what can we conclude about N(A)?

## Matrix Multiplication

• Let  $A \in \mathbb{R}^{m \times n}$ ,  $B \in \mathbb{R}^{n \times k}$ , then  $AB \in \mathbb{R}^{m \times k}$ :

$$AB = \begin{bmatrix} a_{1,1} & \dots & a_{1,n} \\ | & | & | \\ a_{m,1} & \dots & a_{m,n} \end{bmatrix} \begin{bmatrix} b_{1,1} & \dots & b_{n,1} \\ | & | & | \\ b_{n,1} & \dots & b_{n,k} \end{bmatrix}$$
(9)  
$$= \begin{bmatrix} \sum_{i=1}^{n} a_{1,i}b_{i,1} & \dots & \sum_{i=1}^{n} a_{1,i}b_{i,n} \\ | & | & | \\ \sum_{i=1}^{n} a_{m,i}b_{i,1} & \dots & \sum_{i=1}^{n} a_{m,i}b_{i,n} \end{bmatrix}$$
(10)

- ► Cols. of AB are LC of cols of A
- ightharpoonup Rows of AB are LC of rows of B
- ► Also,

$$AB = \sum_{i=1}^{n} \begin{bmatrix} a_{1,i}b_{i,1} & \dots & a_{1,i}b_{i,n} \\ | & | & | \\ a_{m,i}b_{i,1} & \dots & a_{m,i}b_{i,n} \end{bmatrix}$$

## Matrix Multiplication

• Let  $A \in \mathbb{R}^{m \times n}$ ,  $B \in \mathbb{R}^{n \times k}$ , then  $AB \in \mathbb{R}^{m \times k}$ :

$$AB = \begin{bmatrix} a_{1,1} & \dots & a_{1,n} \\ | & | & | \\ a_{m,1} & \dots & a_{m,n} \end{bmatrix} \begin{bmatrix} b_{1,1} & \dots & b_{n,1} \\ | & | & | \\ b_{n,1} & \dots & b_{n,k} \end{bmatrix}$$
(9)  
$$= \begin{bmatrix} \sum_{i=1}^{n} a_{1,i}b_{i,1} & \dots & \sum_{i=1}^{n} a_{1,i}b_{i,n} \\ | & | & | \\ \sum_{i=1}^{n} a_{m,i}b_{i,1} & \dots & \sum_{i=1}^{n} a_{m,i}b_{i,n} \end{bmatrix}$$
(10)

- ► Cols. of *AB* are LC of cols of *A*
- ► Rows of AB are LC of rows of B
- ► Also,

$$AB = \sum_{i=1}^{n} \begin{bmatrix} a_{1,i}b_{i,1} & \dots & a_{1,i}b_{i,n} \\ | & | & | \\ a_{m,i}b_{i,1} & \dots & a_{m,i}b_{i,n} \end{bmatrix} = \sum_{i=1}^{n} C_{i}$$
 (11)

#### Rank of a Matrix

- ullet The number of LI cols of a matrix A is called the Column rank of A.
- The number of LI rows of a matrix A is called the Row rank of A.
- **Assignment 1:** Try to show that they are the same.
- ▶ Notation: r(A).
- Assignment 2: Let  $A \in \mathbb{R}^{m \times 1}$ ,  $B \in \mathbb{R}^{1 \times n}$ . Find the rank of AB.

# Under & Over determined system of equations

- Let  $A \in \mathbb{R}^{m \times n}$ ,  $\mathbf{b} \in \mathbb{R}^m$ . The system  $A\mathbf{x} = \mathbf{b}$  is said to be
- ▶ Under-determined if there are fewer equations than variables, i.e., m < n.
- ▶ Over-determined if there are more equations than variables, i.e., m > n.

### Span

ullet Let  $S = \{\mathbf{a}_1, \dots, \mathbf{a}_n\} \subset \mathbb{R}^m$  be a set of vectors. Then

$$span(S) = \{\sum_{k=1}^{n} x_k \mathbf{a}_k \mid \forall x_k \in \mathbb{R}, k = 1, \dots, n\}$$

• Let  $A = [\mathbf{a}_1 \ \mathbf{a}_2 \ \dots \ \mathbf{a}_n] \in \mathbb{R}^{m \times n}$ . Then, span(S) = C(A).

## $\mathbb{R}^n$ as a Vector Space

- $lackbox{} \mathbb{R}^n$  with the set  $\mathbb{R}$ , and two binary operations, addition + and scalar multiplication  $\cdot$  satisfy:
- ▶ Closure w.r.t Addition:  $\forall u, v \in \mathbb{R}^n, u + v \in \mathbb{R}^n$
- ▶ Additive identity:  $\mathbf{0} \in \mathbb{R}^n, \forall u \in \mathbb{R}^n, u + \mathbf{0} = \mathbf{0} + u = u$
- ▶ Additive inverse:  $\forall u \in \mathbb{R}^n, \exists v \in \mathbb{R}^n, u + v = u + v = \theta$ . We will denote v by -u.
- ▶ Associativity:  $\forall u, v, w \in \mathbb{R}^n, (u+v)+w=u+(v+w).$
- **►** Commutative:  $\forall u, v \in \mathbb{R}^n, u + v = v + u$ .
- ▶ Closure w.r.t Scalar multiplication:  $\forall a \in \mathbb{R}, \forall u \in \mathbb{R}^n, a \cdot u \in \mathbb{R}^n$ .
- ▶ Scalar Multiplication identity:  $\exists 1 \in \mathbb{R}$  such that  $1 \cdot u = u, \forall u \in \mathbb{R}^n$ .
- **▶ Distributivity:**  $\forall a \in \mathbb{R}, \forall u, v \in \mathbb{R}^n, a \cdot (u + v) = a \cdot u + a \cdot v$ , and  $\forall a, b \in \mathbb{R}, \forall u \in \mathbb{R}^n, (a+b) \cdot u = a \cdot u + b \cdot u$ .
- ▶ Compatibility of multiplication of real nos. and scalar multiplication:  $\forall a, b \in \mathbb{R}, \forall u \in \mathbb{R}^n, (a \times b) \cdot u = a \cdot (b \cdot u)$ .

**Subspace:** A set  $W \subseteq \mathbb{R}^n$  is said to be a subspace of  $\mathbb{R}^n$  if W is also a vector space. A non-empty subset W of  $\mathbb{R}^n$  is a subspace iff it is closed with respect to + and  $\cdot$ .

- **Subspace:** A set  $W \subseteq \mathbb{R}^n$  is said to be a subspace of  $\mathbb{R}^n$  if W is also a vector space. A non-empty subset W of  $\mathbb{R}^n$  is a subspace iff it is closed with respect to + and  $\cdot$ .
- Examples: For  $A \in \mathbb{R}^{m \times n}$ , C(A) is a subspace of  $\mathbb{R}^m$ , while N(A) is a subspace of  $\mathbb{R}^n$ .

- **Subspace:** A set  $W \subseteq \mathbb{R}^n$  is said to be a subspace of  $\mathbb{R}^n$  if W is also a vector space. A non-empty subset W of  $\mathbb{R}^n$  is a subspace iff it is closed with respect to + and  $\cdot$ .
- Examples: For  $A \in \mathbb{R}^{m \times n}$ , C(A) is a subspace of  $\mathbb{R}^m$ , while N(A) is a subspace of  $\mathbb{R}^n$ .
- Assignment 3: Given that U, W are subspaces of  $\mathbb{R}^n$ ,
- ▶ Is  $U \cap W$  a subspace of  $\mathbb{R}^n$ ?
- ▶ Is  $U \cup W$  a subspace of  $\mathbb{R}^n$ ?
- ▶ Let  $S = {\mathbf{a}_1, ..., \mathbf{a}_n} \subset \mathbb{R}^m$ . Show that span(S) is a subspace of  $\mathbb{R}^m$ .

- **Subspace:** A set  $W \subseteq \mathbb{R}^n$  is said to be a subspace of  $\mathbb{R}^n$  if W is also a vector space. A non-empty subset W of  $\mathbb{R}^n$  is a subspace iff it is closed with respect to + and  $\cdot$ .
- Examples: For  $A \in \mathbb{R}^{m \times n}$ , C(A) is a subspace of  $\mathbb{R}^m$ , while N(A) is a subspace of  $\mathbb{R}^n$ .
- Assignment 3: Given that U, W are subspaces of  $\mathbb{R}^n$ ,
- ▶ Is  $U \cap W$  a subspace of  $\mathbb{R}^n$ ?
- ▶ Is  $U \cup W$  a subspace of  $\mathbb{R}^n$ ?
- ▶ Let  $S = \{a_1, ..., a_n\} \subset \mathbb{R}^m$ . Show that span(S) is a subspace of  $\mathbb{R}^m$ .
- **◆ Assignment 4:** Let  $w \in \mathbb{R}^3$ ,  $w \neq 0$ , and  $S = \{a \in \mathbb{R}^3 \mid \langle a, w \rangle = w^T a = 0\}$ . Is S a subspace of  $\mathbb{R}^3$ ?

- **Basis:** Let V be a subspace of  $\mathbb{R}^n$ . A set  $\beta \subset V$  is said to be a **basis** of V if (1)  $span(\beta) = V$ , and (2)  $\beta$  is a set of linearly independent vectors.
- Assignment 5: A subset  $\beta = \{\mathbf{b}_1, \dots, \mathbf{b}_k\}$  of V is a basis of V if and only if every  $\mathbf{v} \in V$  can be uniquely written as  $\mathbf{v} = x_1\mathbf{b}_1 + x_2\mathbf{b}_2 + \dots + x_k\mathbf{b}_k, x_i \in \mathbb{R}, i = 1, \dots, k$ .

- **Basis:** Let V be a subspace of  $\mathbb{R}^n$ . A set  $\beta \subset V$  is said to be a **basis** of V if (1)  $span(\beta) = V$ , and (2)  $\beta$  is a set of linearly independent vectors.
- **Assignment 5:** A subset  $\beta = \{\mathbf{b}_1, \dots, \mathbf{b}_k\}$  of V is a basis of V if and only if every  $\mathbf{v} \in V$  can be uniquely written as

$$\mathbf{v} = x_1 \mathbf{b}_1 + x_2 \mathbf{b}_2 + \ldots + x_k \mathbf{b}_k, x_i \in \mathbb{R}, i = 1, \ldots, k.$$

▶ The vector 
$$\begin{bmatrix} x_1 \\ x_2 \\ | \\ x_k \end{bmatrix}$$
 of coefficients, denoted by  $[\mathbf{v}]_\beta$  is called the

representation of v in basis  $\beta$ .

- **Basis:** Let V be a subspace of  $\mathbb{R}^n$ . A set  $\beta \subset V$  is said to be a **basis** of V if (1)  $span(\beta) = V$ , and (2)  $\beta$  is a set of linearly independent vectors.
- Assignment 5: A subset  $\beta = \{\mathbf{b}_1, \dots, \mathbf{b}_k\}$  of V is a basis of V if and only if every  $\mathbf{v} \in V$  can be uniquely written as  $\mathbf{v} = x_1\mathbf{b}_1 + x_2\mathbf{b}_2 + \dots + x_k\mathbf{b}_k, x_i \in \mathbb{R}, i = 1, \dots, k$ .

$$\mathbf{v} = x_1 \mathbf{b}_1 + x_2 \mathbf{b}_2 + \dots + x_k \mathbf{b}_k, x_i \in \mathbb{R}, i = 1, \dots, k.$$

$$\mathbf{b} \quad \text{The vector} \begin{bmatrix} x_1 \\ x_2 \\ | \\ x_k \end{bmatrix} \text{ of coefficients, denoted by } [\mathbf{v}]_\beta \text{ is called the}$$

representation of v in basis  $\beta$ .

**◆ Assignment 6:** Let  $\beta_1, \beta_2$  be two basis of V. Then, show that  $|\beta_1| = |\beta_2|$ .



- **Basis:** Let V be a subspace of  $\mathbb{R}^n$ . A set  $\beta \subset V$  is said to be a **basis** of V if (1)  $span(\beta) = V$ , and (2)  $\beta$  is a set of linearly independent vectors.
- Assignment 5: A subset  $\beta = \{\mathbf{b}_1, \dots, \mathbf{b}_k\}$  of V is a basis of V if and only if every  $\mathbf{v} \in V$  can be uniquely written as  $\mathbf{v} = x_1\mathbf{b}_1 + x_2\mathbf{b}_2 + \dots + x_k\mathbf{b}_k, x_i \in \mathbb{R}, i = 1, \dots, k$ .
- ► The vector  $\begin{bmatrix} x_1 \\ x_2 \\ | \\ x_k \end{bmatrix}$  of coefficients, denoted by  $[\mathbf{v}]_\beta$  is called the

representation of v in basis  $\beta$ .

- **Assignment 6:** Let  $\beta_1, \beta_2$  be two basis of V. Then, show that  $|\beta_1| = |\beta_2|$ .
- **Dimension:** Let  $V \subset \mathbb{R}^n$  be a subspace with basis  $\beta$ . Then dimension of V, denoted by dim(V), is  $dim(V) = |\beta|$ .

- **Basis:** Let V be a subspace of  $\mathbb{R}^n$ . A set  $\beta \subset V$  is said to be a **basis** of V if (1)  $span(\beta) = V$ , and (2)  $\beta$  is a set of linearly independent vectors.
- Assignment 5: A subset  $\beta = \{\mathbf{b}_1, \dots, \mathbf{b}_k\}$  of V is a basis of V if and only if every  $\mathbf{v} \in V$  can be uniquely written as  $\mathbf{v} = x_1\mathbf{b}_1 + x_2\mathbf{b}_2 + \dots + x_k\mathbf{b}_k, x_i \in \mathbb{R}, i = 1, \dots, k$ .

▶ The vector 
$$\begin{bmatrix} x_1 \\ x_2 \\ | \\ x_k \end{bmatrix}$$
 of coefficients, denoted by  $[\mathbf{v}]_\beta$  is called the

representation of v in basis  $\beta$ .

- Assignment 6: Let  $\beta_1, \beta_2$  be two basis of V. Then, show that  $|\beta_1| = |\beta_2|$ .
- **Dimension:** Let  $V \subset \mathbb{R}^n$  be a subspace with basis  $\beta$ . Then dimension of V, denoted by dim(V), is  $dim(V) = |\beta|$ .
- Rank-Nullity Theorem: For any matrix  $A \in \mathbb{R}^{m \times n}$ , r(A) + dim(N(A)) = n. dim(N(A)) is called the **nullity** of A.



• Geometric interpretation - measure of length of a vector.

- Geometric interpretation measure of length of a vector.
- lacksquare Example:  $orall \mathbf{u} \in \mathbb{R}^n, ||\mathbf{u}|| = \sqrt{\sum_{k=1}^n u_k^2}$  Euclidean norm.

- Geometric interpretation measure of length of a vector.
- lacksquare Example:  $orall \mathbf{u} \in \mathbb{R}^n, ||\mathbf{u}|| = \sqrt{\sum_{k=1}^n u_k^2}$  Euclidean norm.
- ► Example:  $\forall \mathbf{u} \in \mathbb{R}^n, ||\mathbf{u}|| = \sum_{k=1}^n |u_k| I_1$  norm.

- Geometric interpretation measure of length of a vector.
- ▶ Example:  $\forall \mathbf{u} \in \mathbb{R}^n, ||\mathbf{u}|| = \sqrt{\sum_{k=1}^n u_k^2}$  Euclidean norm.
- ► Example:  $\forall \mathbf{u} \in \mathbb{R}^n$ ,  $||\mathbf{u}|| = \sum_{k=1}^n |u_k| l_1$  norm.
- ▶ Example:  $\forall \mathbf{u} \in \mathbb{R}^n, ||\mathbf{u}|| = \max_{1 \le k \le n} |u_k|$  max norm.

- Geometric interpretation measure of length of a vector.
- ▶ Example:  $\forall \mathbf{u} \in \mathbb{R}^n, ||\mathbf{u}|| = \sqrt{\sum_{k=1}^n u_k^2}$  Euclidean norm.
- ► Example:  $\forall \mathbf{u} \in \mathbb{R}^n$ ,  $||\mathbf{u}|| = \sum_{k=1}^n |u_k| l_1$  norm.
- ► Example:  $\forall \mathbf{u} \in \mathbb{R}^n, ||\mathbf{u}|| = \max_{1 \le k \le n} |u_k|$  max norm.

• Geometric interpretation - measures angle between vectors.

- Geometric interpretation measures angle between vectors.
- ► Example:  $\forall \mathbf{u}, \mathbf{v} \in \mathbb{R}^n, \langle \mathbf{u}, \mathbf{v} \rangle = \mathbf{v}^T \mathbf{u} = \sum_{k=1}^n v_i u_i$ .

- Geometric interpretation measures angle between vectors.
- ► Example:  $\forall \mathbf{u}, \mathbf{v} \in \mathbb{R}^n, \langle \mathbf{u}, \mathbf{v} \rangle = \mathbf{v}^T \mathbf{u} = \sum_{k=1}^n v_i u_i$ .
- Norm induced by inner-product:  $||\mathbf{u}||^2 = \langle \mathbf{u}, \mathbf{u} \rangle$ .
- ► Angle between vectors:  $\cos \theta = \frac{\langle \mathbf{u}, \mathbf{v} \rangle}{||\mathbf{u}||||\mathbf{v}||}$ .
- ► Cauchy-Schwartz Inequality:  $|\cos \theta| \le 1$

- Geometric interpretation measures angle between vectors.
- ► Example:  $\forall \mathbf{u}, \mathbf{v} \in \mathbb{R}^n, \langle \mathbf{u}, \mathbf{v} \rangle = \mathbf{v}^T \mathbf{u} = \sum_{k=1}^n v_i u_i$ .
- ▶ Norm induced by inner-product:  $||\mathbf{u}||^2 = \langle \mathbf{u}, \mathbf{u} \rangle$ .
- ► Angle between vectors:  $\cos \theta = \frac{\langle \mathbf{u}, \mathbf{v} \rangle}{||\mathbf{u}||||\mathbf{v}||}$ .
- ► Cauchy-Schwartz Inequality:  $|\cos \theta| \le 1 \Rightarrow |\langle \mathbf{u}, \mathbf{v} \rangle| \le ||\mathbf{u}|| ||\mathbf{v}||$ .
- **Orthogonal vectors:** For  $\mathbf{u}, \mathbf{v} \in \mathbb{R}^n$ , if  $\langle \mathbf{u}, \mathbf{v} \rangle = 0$ , the vectors  $\mathbf{u}$  and  $\mathbf{v}$  are said to be orthogonal.
- ▶ Orthogonal vectors: The set of vectors  $\{\mathbf{a}_1,\ldots,\mathbf{a}_k\}\subset\mathbb{R}^n$  is said to be orthogonal if  $\langle \mathbf{a}_i,\mathbf{a}_j\rangle=0, \forall 1\leq i\neq j\leq k$ .
- ▶ Orthonormal vectors: The set of vectors  $\{a_1, \ldots, a_k\} \subset \mathbb{R}^n$  is said to be orthonormal if apart from being orthogonal, they are all unit vectors, i.e.,  $\langle \mathbf{a}_i, \mathbf{a}_i \rangle = 1, \forall 1 \leq i \leq k$ .
- Orthogonal Matrix: A matrix  $A \in \mathbb{R}^{n \times n}$  is called Orthogonal if its columns are orthonormal.
- Orthonormal basis: For a subspace  $V \subseteq \mathbb{R}^n$ , an orthonormal set of vectors  $\beta$  that also forms a basis of V is called an Orthonormal basis (ONB).
- **Assignment 7:** What is the advantage of having an ONB? [Hint: Finding representation of a vector in that basis is easy].



# Eigenvalues and Eigenvectors

- **Eigenvalues & Eigenvectors:** Let  $A \in \mathbb{R}^{n \times n}$ . If  $A\mathbf{v} = \lambda \mathbf{v}$  for some  $\lambda \in \mathbb{R}, \mathbf{v} \neq \mathbf{0} \in \mathbb{R}^n$ , then  $\lambda, \mathbf{v}$  is said to be eigenvalue-eigenvector pair.
- ► Computing eigenvalues and eigenvectors (in theory)  $A\mathbf{v} = \lambda \mathbf{v}$ .
- For  $A \in \mathbb{R}^{n \times n}$ , if there are n linearly independent eigenvectors, say  $\mathbf{e}_1, \dots, \mathbf{e}_n$  with corresponding eigenvalues  $\lambda_1, \dots, \lambda_n$ , then:
- $ightharpoonup \{e_1,\ldots,e_n\}$  forms a basis of  $\mathbb{R}^n$ , and
- ► Matrix diagonalization:

$$A[\mathbf{e}_1 \ \mathbf{e}_2 \ \dots \ \mathbf{e}_n] = [A\mathbf{e}_1 \ A\mathbf{e}_2 \ \dots \ A\mathbf{e}_n]$$
 (12)

$$= [\lambda_1 \mathbf{e}_1 \ \lambda_2 \mathbf{e}_2 \ \dots \ \lambda_n \mathbf{e}_n] \tag{13}$$

$$= [\mathbf{e}_1 \ \mathbf{e}_2 \ \dots \ \mathbf{e}_n] diag(\lambda_1, \lambda_2, \dots, \lambda_n)$$

$$\Rightarrow AF = F\Lambda$$
(14)

# Eigenvalues and Eigenvectors

- **Eigenvalues & Eigenvectors:** Let  $A \in \mathbb{R}^{n \times n}$ . If  $A\mathbf{v} = \lambda \mathbf{v}$  for some  $\lambda \in \mathbb{R}, \mathbf{v} \neq \mathbf{0} \in \mathbb{R}^n$ , then  $\lambda, \mathbf{v}$  is said to be eigenvalue-eigenvector pair.
- ► Computing eigenvalues and eigenvectors (in theory)  $A\mathbf{v} = \lambda \mathbf{v}$ .
- For  $A \in \mathbb{R}^{n \times n}$ , if there are n linearly independent eigenvectors, say  $\mathbf{e}_1, \dots, \mathbf{e}_n$  with corresponding eigenvalues  $\lambda_1, \dots, \lambda_n$ , then:
- ▶  $\{e_1, ..., e_n\}$  forms a basis of  $\mathbb{R}^n$ , and
- ► Matrix diagonalization:

$$A[\mathbf{e}_1 \ \mathbf{e}_2 \ \dots \ \mathbf{e}_n] = [A\mathbf{e}_1 \ A\mathbf{e}_2 \ \dots \ A\mathbf{e}_n]$$
 (12)

$$= [\lambda_1 \mathbf{e}_1 \ \lambda_2 \mathbf{e}_2 \ \dots \ \lambda_n \mathbf{e}_n] \tag{13}$$

$$= [\mathbf{e}_1 \ \mathbf{e}_2 \ \dots \ \mathbf{e}_n] diag(\lambda_1, \lambda_2, \dots, \lambda_n)$$
 (14)

$$\Rightarrow AE = E\Lambda \Rightarrow A = E\Lambda E^{-1} \tag{15}$$

• Let 
$$A = \begin{bmatrix} 2.8 & -2.4 \\ -2.4 & -0.8 \end{bmatrix}$$
.

• Using basis  $\left\{ \begin{bmatrix} 1\\0 \end{bmatrix}, \begin{bmatrix} 0\\1 \end{bmatrix} \right\}$ ,

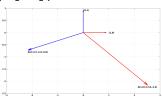


Figure: Usual basis

• Using eigenbasis  $\left\{ \begin{bmatrix} 0.44 \\ 0.89 \end{bmatrix}, \begin{bmatrix} 0.89 \\ -0.44 \end{bmatrix} \right\}$ ,

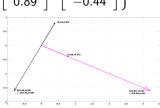


Figure: Figenbasis

# Eigenbasis

Do all matrices yield an eigenbasis?

► No, examples: 
$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$
,  $A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ ,  $\theta \neq k\pi$ ,  $k \in \mathbb{Z}$ .

- **Spectral Theorem for Real-Symmetric Matrices:** Let  $A \in \mathbb{R}^{n \times n}$  be any real-symmetric matrix, i.e.,  $A^T = A$ . Then,
- ▶ its eigenvalues are real,and
- ► *A* has *n*-orthogonal eigenvectors.
- **Symmetric Positive-Definite Matrix:** A matrix  $A \in \mathbb{R}^{n \times n}$  is said to be Symmetric Positive-Definite (SPD), if (1)  $A^T = A$ , and (2)  $x^T Ax > 0, \forall x \neq 0, x \in \mathbb{R}^n$ .
- ► For a SPD matrix, all eigenvalues are strictly positive.
- ▶ A matrix  $A \in \mathbb{R}^{n \times n}$  is **Symmetric Positive-Semidefinite** if (1)  $A^T = A$ , and (2)  $x^T A x \ge 0, \forall x \ne 0, x \in \mathbb{R}^n$ .

# Singular Value Decomposition

- For  $A \in \mathbb{R}^{m \times n}$  with r(A) = r.
- ▶  $A^TA \in \mathbb{R}^{n \times n}$  and  $AA^T \in \mathbb{R}^{m \times m}$  are real-symmetric positive semi-definite matrices.
- ▶ **Assignment 8:** Show that  $A^TA$  and  $AA^T$  have the same non-zero eigenvalues.
- ▶  $A^TA = V^T\Lambda_n V$  and  $AA^T = U^T\Lambda_m U$ , where  $U \in \mathbb{R}^{m \times m}$ ,  $V \in \mathbb{R}^{n \times n}$  are orthogonal matrices, and  $\Lambda_n = diag(\lambda_1, \dots, \lambda_r, 0, \dots, 0) \in \mathbb{R}^{m \times n}$ ,  $\Lambda_m = diag(\lambda_1, \dots, \lambda_r, 0, \dots, 0) \in \mathbb{R}^{m \times m}$ .
- Then  $A = U\Sigma V^T$ , with

$$\Sigma = diag(\sqrt{\lambda_1}, \sqrt{\lambda_2}, \dots, \sqrt{\lambda_r}, 0, \dots, 0) \in \mathbb{R}^{m \times n}$$
. Notation:

 $\sigma_k = \sqrt{\overline{\lambda_k}}, k = 1, \dots, r$  are called the **Singular values**.