

```
# Install YOLOv8 from the ultralytics library
!pip install ultralytics
```

```
# Install Roboflow to download the dataset
!pip install roboflow
```

```
Requirement already satisfied: tzdata>=2022.7 in /usr/local/lib/python3.10/dist-packages (from pandas>=1.1.4->ultralytics) (2024.1)
Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/python3.10/dist-packages (from requests>=2.23.0->ultralytics) (3.3.2)
Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.10/dist-packages (from requests>=2.23.0->ultralytics) (3.10)
Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/lib/python3.10/dist-packages (from requests>=2.23.0->ultralytics) (2.2.3)
Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.10/dist-packages (from requests>=2.23.0->ultralytics) (2024.7.4)
Requirement already satisfied: filelock in /usr/local/lib/python3.10/dist-packages (from torch>=1.8.0->ultralytics) (3.16.1)
Requirement already satisfied: typing-extensions>=4.8.0 in /usr/local/lib/python3.10/dist-packages (from torch>=1.8.0->ultralytics) (4.12.2)
Requirement already satisfied: networkx in /usr/local/lib/python3.10/dist-packages (from torch>=1.8.0->ultralytics) (3.4.2)
Requirement already satisfied: Jinja2 in /usr/local/lib/python3.10/dist-packages (from torch>=1.8.0->ultralytics) (3.1.4)
Requirement already satisfied: fsspec in /usr/local/lib/python3.10/dist-packages (from torch>=1.8.0->ultralytics) (2024.10.1)
Requirement already satisfied: sympy==1.13.1 in /usr/local/lib/python3.10/dist-packages (from torch>=1.8.0->ultralytics) (1.13.1)
Requirement already satisfied: mpmath<1.4,>=1.1.0 in /usr/local/lib/python3.10/dist-packages (from sympy==1.13.1) (1.3.0)
Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.10/dist-packages (from python-dateutil>=2.7->ultralytics) (1.17.0)
Requirement already satisfied: MarkupSafe>=2.0 in /usr/local/lib/python3.10/dist-packages (from Jinja2->torch>=1.8.0->ultralytics) (3.0.2)
Downloading ultralytics-8.3.43-py3-none-any.whl (898 kB)
898.4/898.4 kB 37.1 MB/s eta 0:00:00
Downloading ultralytics-thop-2.0.12-py3-none-any.whl (26 kB)
Installing collected packages: ultralytics-thop, ultralytics
Successfully installed ultralytics-8.3.43 ultralytics-thop-2.0.12
Collecting roboflow
  Downloading roboflow-1.1.49-py3-none-any.whl.metadata (9.7 kB)
Requirement already satisfied: certifi in /usr/local/lib/python3.10/dist-packages (from roboflow) (2024.8.30)
Collecting idna==3.7 (from roboflow)
  Downloading idna-3.7-py3-none-any.whl.metadata (9.9 kB)
Requirement already satisfied: cyclery in /usr/local/lib/python3.10/dist-packages (from roboflow) (0.12.1)
Requirement already satisfied: kiwisolver>=1.3.1 in /usr/local/lib/python3.10/dist-packages (from roboflow) (1.4.7)
Requirement already satisfied: matplotlib in /usr/local/lib/python3.10/dist-packages (from roboflow) (3.8.0)
Requirement already satisfied: numpy>=1.18.5 in /usr/local/lib/python3.10/dist-packages (from roboflow) (1.26.4)
Requirement already satisfied: opencv-python-headless==4.10.0.84 in /usr/local/lib/python3.10/dist-packages (from roboflow) (4.10.0.84)
Requirement already satisfied: Pillow>=7.1.2 in /usr/local/lib/python3.10/dist-packages (from roboflow) (11.0.0)
Requirement already satisfied: python-dateutil in /usr/local/lib/python3.10/dist-packages (from roboflow) (2.8.2)
Collecting python-dotenv (from roboflow)
  Downloading python_dotenv-1.0.1-py3-none-any.whl.metadata (23 kB)
Requirement already satisfied: requests in /usr/local/lib/python3.10/dist-packages (from roboflow) (2.32.3)
Requirement already satisfied: six in /usr/local/lib/python3.10/dist-packages (from roboflow) (1.17.0)
Requirement already satisfied: urllib3>=1.26.6 in /usr/local/lib/python3.10/dist-packages (from roboflow) (2.2.3)
Requirement already satisfied: tqdm>=4.41.0 in /usr/local/lib/python3.10/dist-packages (from roboflow) (4.66.6)
Requirement already satisfied: PyYAML>=5.3.1 in /usr/local/lib/python3.10/dist-packages (from roboflow) (6.0.2)
Requirement already satisfied: requests-toolbelt in /usr/local/lib/python3.10/dist-packages (from roboflow) (1.0.0)
Collecting filetype (from roboflow)
  Downloading filetype-1.2.0-py2.py3-none-any.whl.metadata (6.5 kB)
Requirement already satisfied: contourpy>=1.0.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib>=3.8.0->roboflow) (1.3.0)
Requirement already satisfied: fonttools>=4.22.0 in /usr/local/lib/python3.10/dist-packages (from matplotlib>=3.8.0->roboflow) (4.55.0)
Requirement already satisfied: packaging>=20.0 in /usr/local/lib/python3.10/dist-packages (from matplotlib>=3.8.0->roboflow) (24.2)
Requirement already satisfied: pyparsing>=2.3.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib>=3.8.0->roboflow) (3.2.0)
Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/python3.10/dist-packages (from requests>=2.32.3->roboflow) (3.3.2)
Downloading roboflow-1.1.49-py3-none-any.whl (80 kB)
80.9/80.9 kB 8.0 MB/s eta 0:00:00
Downloading idna-3.7-py3-none-any.whl (66 kB)
66.8/66.8 kB 7.1 MB/s eta 0:00:00
Downloading filetype-1.2.0-py2.py3-none-any.whl (19 kB)
Downloading python_dotenv-1.0.1-py3-none-any.whl (19 kB)
Installing collected packages: filetype, python-dotenv, idna, roboflow
  Attempting uninstall: idna
    Found existing installation: idna 3.10
    Uninstalling idna-3.10:
      Successfully uninstalled idna-3.10
  Successfully installed filetype-1.2.0 idna-3.7 python-dotenv-1.0.1 roboflow-1.1.49
```

```
!pip install roboflow
```

```
from roboflow import Roboflow
rf = Roboflow(api_key="cJU1zRFgpb0vH56NFSUF")
project = rf.workspace("mohamed-traore-2ekkp").project("taco-trash-annotations-in-context")
version = project.version(16)
dataset = version.download("yolov8")
```

```

Requirement already satisfied: roboflow in /usr/local/lib/python3.10/dist-packages (1.1.49)
Requirement already satisfied: certifi in /usr/local/lib/python3.10/dist-packages (from roboflow) (2024.8.30)
Requirement already satisfied: idna==3.7 in /usr/local/lib/python3.10/dist-packages (from roboflow) (3.7)
Requirement already satisfied: cyclcr in /usr/local/lib/python3.10/dist-packages (from roboflow) (0.12.1)
Requirement already satisfied: kiwisolver>=1.3.1 in /usr/local/lib/python3.10/dist-packages (from roboflow) (1.4.7)
Requirement already satisfied: matplotlib in /usr/local/lib/python3.10/dist-packages (from roboflow) (3.8.0)
Requirement already satisfied: numpy>=1.18.5 in /usr/local/lib/python3.10/dist-packages (from roboflow) (1.26.4)
Requirement already satisfied: opencv-python-headless==4.10.0.84 in /usr/local/lib/python3.10/dist-packages (from roboflow) (4.10.0.84)
Requirement already satisfied: Pillow>=7.1.2 in /usr/local/lib/python3.10/dist-packages (from roboflow) (11.0.0)
Requirement already satisfied: python-dateutil in /usr/local/lib/python3.10/dist-packages (from roboflow) (2.8.2)
Requirement already satisfied: python-dotenv in /usr/local/lib/python3.10/dist-packages (from roboflow) (1.0.1)
Requirement already satisfied: requests in /usr/local/lib/python3.10/dist-packages (from roboflow) (2.32.3)
Requirement already satisfied: six in /usr/local/lib/python3.10/dist-packages (from roboflow) (1.16.0)
Requirement already satisfied: urllib3>=1.26.6 in /usr/local/lib/python3.10/dist-packages (from roboflow) (2.2.3)
Requirement already satisfied: tqdm>=4.41.0 in /usr/local/lib/python3.10/dist-packages (from roboflow) (4.66.6)
Requirement already satisfied: PyYAML>=5.3.1 in /usr/local/lib/python3.10/dist-packages (from roboflow) (6.0.2)
Requirement already satisfied: requests-toolbelt in /usr/local/lib/python3.10/dist-packages (from roboflow) (1.0.0)
Requirement already satisfied: filetype in /usr/local/lib/python3.10/dist-packages (from roboflow) (1.2.0)
Requirement already satisfied: contourpy>=1.0.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib->roboflow) (1.0.1)
Requirement already satisfied: fonttools>=4.22.0 in /usr/local/lib/python3.10/dist-packages (from matplotlib->roboflow) (4.22.0)
Requirement already satisfied: packaging>=20.0 in /usr/local/lib/python3.10/dist-packages (from matplotlib->roboflow) (23.1)
Requirement already satisfied: pyparsing>=2.3.1 in /usr/local/lib/python3.10/dist-packages (from matplotlib->roboflow) (3.1.0)
Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/python3.10/dist-packages (from requests->roboflow) (3.3.2)
loading Roboflow workspace...
loading Roboflow project...
Downloading Dataset Version Zip in TACO:-Trash-Annotations-in-Context-Dataset-16 to yolov8:: 100%|██████████| 3323
Extracting Dataset Version Zip to TACO:-Trash-Annotations-in-Context-Dataset-16 in yolov8:: 100%|██████████| 7204/
Creating new Ultralytics Settings v0.0.6 file ☒
View Ultralytics Settings with 'yolo settings' or at '/root/.config/Ultralytics/settings.json'
Update Settings with 'yolo settings key=value', i.e. 'yolo settings runs_dir=path/to/dir'. For help see https://docs.ultralytics.com/yolo/settings/

```

```
from ultralytics import YOLO
```

```
# Step 1: Load a pre-trained YOLOv8 model (choose 'n', 's', 'm', 'l', or 'x' for different sizes)
model = YOLO("yolov8n.pt") # yolov8n = nano, yolov8s = small, yolov8m = medium, etc.
```

```
# Step 2: Train the model
```

```
model.train(
    data=f"{dataset.location}/data.yaml", # Path to the downloaded dataset's data.yaml
    epochs=50,                           # Number of epochs to train
    imgsz=640,                           # Image size
    batch=16,                            # Batch size
    workers=2                             # Number of workers (adjust based on your environment)
)
```



0.46844,	0.46832,	0.4672,	0.46666,	0.46548,	0.4648,	0.46252,	0.46252,	0.46844,
0.46252,	0.46154,	0.46154,	0.46154,	0.46154,	0.46015,	0.4587,		
	0.45613,	0.45464,	0.45266,	0.45168,	0.45168,	0.45168,	0.45168,	0.45137,
0.451,	0.45069,	0.45069,	0.45037,	0.4497,	0.44927,	0.44876,	0.44872,	0.44872,
0.44872,	0.44872,	0.44816,	0.44773,	0.44763,	0.44675,			
	0.44675,	0.44675,	0.44675,	0.44675,	0.44576,	0.44576,	0.44576,	0.44477,
0.44335,	0.44181,	0.43984,	0.43984,	0.43984,	0.43984,	0.43905,	0.43886,	
0.43886,	0.43886,	0.43754,	0.43688,	0.43688,	0.43688,	0.43688,		
	0.43688,	0.43543,	0.43491,	0.43491,	0.43491,	0.43491,	0.43393,	0.43393,
0.43393,	0.43389,	0.43321,	0.43214,	0.43195,	0.43195,	0.43097,	0.43049,	
0.42999,	0.42998,	0.42998,	0.42998,	0.42998,	0.42998,	0.42792,		
	0.42725,	0.42635,	0.42604,	0.42604,	0.42529,	0.42505,	0.42505,	0.42406,
0.42406,	0.42406,	0.42386,	0.42209,	0.42209,	0.42209,	0.42209,	0.42209,	
0.42209,	0.42209,	0.4211,	0.42012,	0.42012,	0.41913,	0.41819,		
	0.41815,	0.41716,	0.41716,	0.41716,	0.41508,	0.4142,	0.4142,	0.4142,
0.4142,	0.41382,	0.41342,	0.41321,	0.41321,	0.41321,	0.41321,	0.41223,	0.41223,
0.41223,	0.41223,	0.41147,	0.41124,	0.41124,	0.41124,			
	0.41124,	0.41124,	0.41026,	0.41026,	0.41026,	0.41026,	0.41026,	0.40828,
0.40828,	0.40828,	0.40828,	0.40828,	0.40828,	0.40828,	0.40828,	0.40828,	
0.40828,	0.40828,	0.40828,	0.40828,	0.40828,	0.40828,	0.40828,		
	0.40828,	0.40828,	0.40828,	0.40828,	0.40828,	0.40828,	0.40828,	0.40828,
0.40828,	0.40828,	0.40828,	0.40828,	0.40761,	0.4073,	0.40633,	0.40631,	
0.40594,	0.40557,	0.40533,	0.40533,	0.40533,	0.40533,	0.40533,		
	0.40485,	0.40435,	0.40377,	0.40335,	0.40335,	0.40335,	0.40305,	0.40255,
0.40138,	0.40138,	0.40039,	0.40039,	0.40039,	0.40025,	0.39975,	0.39941,	
0.39941,	0.39941,	0.39941,	0.39941,	0.39906,	0.39855,	0.39743,		
	0.39645,	0.39645,	0.39637,	0.39546,	0.39546,	0.39546,	0.39546,	0.39546,
0.39519,	0.39461,	0.39448,	0.39448,	0.39448,	0.39448,	0.39448,	0.39448,	

```
# Evaluate the model on the validation set
results = model.val()
```

```
# Print validation results
print(results)
```



```

0.19348, 0.19252, 0.18988, 0.1882, 0.18701, 0.18646, 0.18588, 0.18535,
0.17025, 0.16864, 0.16715, 0.16623, 0.16543, 0.16473, 0.16144, 0.15951,
0.132, 0.13024, 0.1267, 0.12538, 0.12368, 0.12296, 0.12261, 0.12215,
0.093545, 0.092404, 0.089731, 0.089136, 0.087212, 0.085403, 0.081909, 0.07969,
0.057012, 0.056582, 0.056037, 0.054405, 0.052656, 0.051647, 0.049197, 0.048423,
0.023175, 0.022785, 0.0212, 0.019665, 0.017519, 0.014659, 0.014314, 0.013969,
0.001969, 0.0018674, 0.0017658, 0.0016641, 0.0015625, 0.0014609, 0.0013593, 0.0012576,
0, 0, 0, 0, 0, 0, 0, 0,
fitness: 0.3652012656780426
keys: ['metrics/precision(B)', 'metrics/recall(B)', 'metrics/mAP50(B)', 'metrics/mAP50-95(B)']
maps: array([ 0.35097])
names: {0: 'trash'}
plot: True
results_dict: {'metrics/precision(B)': 0.7611350285025342, 'metrics/recall(B)': 0.39644970414201186, 'metrics/mAP50(B)': 0.35097, 'metrics/mAP50-95(B)': 0.31293036546994213}
save_dir: PosixPath('runs/detect/train2')
speed: {'preprocess': 0.31293036546994213, 'inference': 4.748849964460801, 'loss': 0.001631452885758518, 'postprocess': 0.0012576}
task: 'detect'

```

```

# Use the trained model to make predictions on test images
model.predict(
    source=f"{dataset.location}/test/images", # Path to test images
    save=True, # Save prediction images with bounding boxes
    conf=0.5 # Confidence threshold
)

```



```
...,
[[121, 119, 119],
 [122, 120, 120],
 [114, 114, 114],
....
```

# Save the trained model to Google Drive

```
!cp runs/detect/train/weights/best.pt /content/drive/MyDrive/best.pt
```



```
-----
NotImplementedError                                Traceback (most recent call last)
<ipython-input-7-817df71dd55e> in <cell line: 2>()
      1 # Save the trained model to Google Drive
----> 2 get_ipython().system('cp runs/detect/train/weights/best.pt /content/drive/MyDrive/best.pt')
```

2 frames

```
/usr/local/lib/python3.10/dist-packages/google/colab/_system_commands.py in _run_command(cmd,
clear_streamed_output)
    166     locale_encoding = locale.getpreferredencoding()
    167     if locale_encoding != _ENCODING:
--> 168         raise NotImplementedError(
    169             'A UTF-8 locale is required. Got {}'.format(locale_encoding)
    170         )
```

**NotImplementedError:** A UTF-8 locale is required. Got ANSI\_X3.4-1968

Next steps: [Explain error](#)

```
# Export the model in various formats, e.g., ONNX, CoreML, TensorRT
model.export(format="onnx", dynamic=True)
```

```
import cv2
from ultralytics import YOLO
from PIL import Image
import matplotlib.pyplot as plt
```

```
model = YOLO("yolov8n.pt") # Replace with the path to your trained YOLOv8 model
```

```
import cv2
from ultralytics import YOLO
import matplotlib.pyplot as plt
```

# Step 1: Set the path to the test image

```
image_path = "/content/TACO:-Trash-Annotations-in-Context-Dataset-16/test/images/000004_jpg.rf.f220eaab0f36226385a34eb0"
```

# Step 2: Load YOLOv8 model

```
model = YOLO("yolov8n.pt") # Ensure that this is the path to your trained YOLOv8 model
```

# Step 3: Load the test image using OpenCV

```
img = cv2.imread(image_path)
```

# Step 4: Make predictions on the test image

```
results = model.predict(img, conf=0.5) # Adjust confidence threshold as needed
```

# Step 5: Annotate the image with bounding boxes and category labels

```
annotated_img = results[0].plot()
```

# Step 6: Convert to RGB format for display using matplotlib

```
annotated_img_rgb = cv2.cvtColor(annotated_img, cv2.COLOR_BGR2RGB)
```

# Step 7: Display the image with bounding boxes and category labels

```
plt.imshow(annotated_img_rgb)
plt.axis('off') # Hide axis for cleaner view
plt.show()
```

```
# Optional: Save the annotated image
cv2.imwrite("annotated_test_image.jpg", annotated_img)
```



0: 640x640 1 tv, 17.5ms  
Speed: 2.2ms preprocess, 17.5ms inference, 1.7ms postprocess per image at shape (1, 3, 640, 640)



True

```
import cv2
from ultralytics import YOLO
import matplotlib.pyplot as plt

# Step 1: Set the path to the test image
image_path = "/content/TACO:-Trash-Annotations-in-Context-Dataset-16/test/images/000006_jpg.rf.65db7183891046d795545fe"

# Step 2: Load YOLOv8 model
model = YOLO("yolov8n.pt") # Ensure that this is the path to your trained YOLOv8 model

# Step 3: Load the test image using OpenCV
img = cv2.imread(image_path)

# Step 4: Make predictions on the test image
results = model.predict(img, conf=0.5) # Adjust confidence threshold as needed

# Step 5: Annotate the image with bounding boxes and category labels
annotated_img = results[0].plot()

# Step 6: Convert to RGB format for display using matplotlib
annotated_img_rgb = cv2.cvtColor(annotated_img, cv2.COLOR_BGR2RGB)

# Step 7: Display the image with bounding boxes and category labels
plt.imshow(annotated_img_rgb)
plt.axis('off') # Hide axis for cleaner view
plt.show()

# Optional: Save the annotated image
cv2.imwrite("annotated_test_image.jpg", annotated_img)
```



0: 640x640 1 car, 9.5ms

Speed: 1.7ms preprocess, 9.5ms inference, 1.3ms postprocess per image at shape (1, 3, 640, 640)



True

```
import cv2
from ultralytics import YOLO
import matplotlib.pyplot as plt

# Step 1: Set the path to the test image
image_path = "/content/TACO:-Trash-Annotations-in-Context-Dataset-16/test/images/000074_JPG.rf.1394c939daf3a1345ce9447"

# Step 2: Load YOLOv8 model
model = YOLO("yolov8n.pt") # Ensure that this is the path to your trained YOLOv8 model

# Step 3: Load the test image using OpenCV
img = cv2.imread(image_path)

# Step 4: Make predictions on the test image
results = model.predict(img, conf=0.5) # Adjust confidence threshold as needed

# Step 5: Annotate the image with bounding boxes and category labels
annotated_img = results[0].plot()

# Step 6: Convert to RGB format for display using matplotlib
annotated_img_rgb = cv2.cvtColor(annotated_img, cv2.COLOR_BGR2RGB)

# Step 7: Display the image with bounding boxes and category labels
plt.imshow(annotated_img_rgb)
plt.axis('off') # Hide axis for cleaner view
plt.show()

# Optional: Save the annotated image
cv2.imwrite("annotated_test_image.jpg", annotated_img)
```





0: 640x640 (no detections), 13.0ms

Speed: 2.1ms preprocess, 13.0ms inference, 0.9ms postprocess per image at shape (1, 3, 640, 640)



True

```
# # You can upload a test image manually in Colab using the file upload widget:
# from google.colab import files
# uploaded = files.upload()

# # Load the test image (the uploaded image's file name will be the key)
# image = imageio.imread(uploaded['image.jpg'])
```