

# Linear Regression

---

Nipun Batra and the teaching staff

IIT Gandhinagar

August 1, 2025

# Table of Contents

1. Setup
2. Normal Equation
3. Basis Expansion
4. Geometric Interpretation
5. Regularization
6. Dummy Variables and Multicollinearity
7. Practice and Review

# Linear Regression

- Output is continuous in nature.

# Linear Regression

- Output is continuous in nature.
- Examples of linear systems:

# Linear Regression

- Output is continuous in nature.
- Examples of linear systems:
  - $F = ma$

# Linear Regression

- Output is continuous in nature.
- Examples of linear systems:
  - $F = ma$
  - $v = u + at$

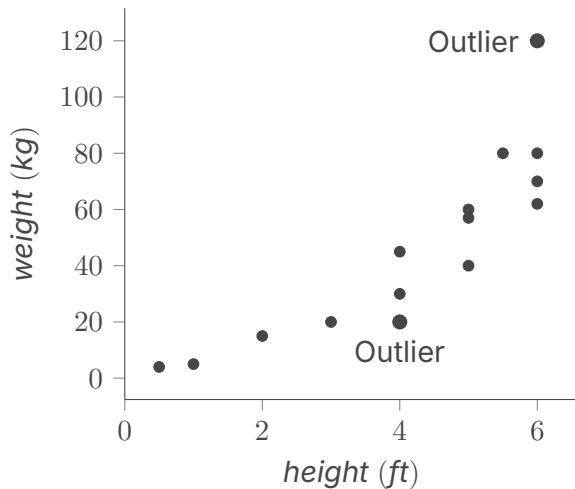
# Task at hand

- TASK: Predict Weight =  $f(\text{height})$

Height	Weight
3	29
4	35
5	39
2	20
6	41
7	?
8	?
1	?

The first part of the dataset is the training points. The latter ones are testing points.

# Scatter Plot





# Matrix representation of the expression

- $weight_1 \approx \theta_0 + \theta_1 \cdot height_1$

# Matrix representation of the expression

- $weight_1 \approx \theta_0 + \theta_1 \cdot height_1$
- $weight_2 \approx \theta_0 + \theta_1 \cdot height_2$

# Matrix representation of the expression

- $weight_1 \approx \theta_0 + \theta_1 \cdot height_1$
- $weight_2 \approx \theta_0 + \theta_1 \cdot height_2$
- $weight_N \approx \theta_0 + \theta_1 \cdot height_N$

# Matrix representation of the expression

- $weight_1 \approx \theta_0 + \theta_1 \cdot height_1$
- $weight_2 \approx \theta_0 + \theta_1 \cdot height_2$
- $weight_N \approx \theta_0 + \theta_1 \cdot height_N$

# Matrix representation of the expression

- $weight_1 \approx \theta_0 + \theta_1 \cdot height_1$
- $weight_2 \approx \theta_0 + \theta_1 \cdot height_2$
- $weight_N \approx \theta_0 + \theta_1 \cdot height_N$

$$weight_i \approx \theta_0 + \theta_1 \cdot height_i$$

## Matrix representation of the expression

$$\begin{bmatrix} weight_1 \\ weight_2 \\ \dots \\ weight_N \end{bmatrix} = \begin{bmatrix} 1 & height_1 \\ 1 & height_2 \\ \dots & \dots \\ 1 & height_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$

## Matrix representation of the expression

$$\begin{bmatrix} weight_1 \\ weight_2 \\ \dots \\ weight_N \end{bmatrix} = \begin{bmatrix} 1 & height_1 \\ 1 & height_2 \\ \dots & \dots \\ 1 & height_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$

$$\hat{\mathbf{y}}_{n \times 1} = \mathbf{X}_{n \times d} \boldsymbol{\theta}_{d \times 1}$$

# Matrix representation of the expression

$$\begin{bmatrix} weight_1 \\ weight_2 \\ \dots \\ weight_N \end{bmatrix} = \begin{bmatrix} 1 & height_1 \\ 1 & height_2 \\ \dots & \dots \\ 1 & height_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$

$$\hat{\mathbf{y}}_{n \times 1} = \mathbf{X}_{n \times d} \boldsymbol{\theta}_{d \times 1}$$

- $\theta_0$  - Bias Term/Intercept Term



# Matrix representation of the expression

$$\begin{bmatrix} weight_1 \\ weight_2 \\ \dots \\ weight_N \end{bmatrix} = \begin{bmatrix} 1 & height_1 \\ 1 & height_2 \\ \dots & \dots \\ 1 & height_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$

$$\hat{\mathbf{y}}_{n \times 1} = \mathbf{X}_{n \times d} \boldsymbol{\theta}_{d \times 1}$$

- $\theta_0$  - Bias Term/Intercept Term
- $\theta_1$  - Slope

# Extension to multiple dimensions

In the previous example  $y = f(x)$ , where  $x$  is one-dimensional.

# Extension to multiple dimensions

In the previous example  $y = f(x)$ , where  $x$  is one-dimensional.

Examples in multiple dimensions.

# Extension to multiple dimensions

In the previous example  $y = f(x)$ , where  $x$  is one-dimensional.

Examples in multiple dimensions.

One example is to predict the water demand of the IITGN campus

# Extension to multiple dimensions

In the previous example  $y = f(x)$ , where  $x$  is one-dimensional.

Examples in multiple dimensions.

One example is to predict the water demand of the IITGN campus

$$\text{Demand} = f(\text{\# occupants, Temperature})$$

# Extension to multiple dimensions

In the previous example  $y = f(x)$ , where  $x$  is one-dimensional.

Examples in multiple dimensions.

One example is to predict the water demand of the IITGN campus

$$\text{Demand} = f(\# \text{ occupants}, \text{Temperature})$$

$$\text{Demand} = \text{Base Demand} + K_1 * \# \text{ occupants} + K_2 * \text{Temperature}$$

# Intuition

We hope to:

- Learn  $f$ :  $Demand = f(\#occupants, Temperature)$

# Intuition

We hope to:

- Learn  $f$ :  $Demand = f(\#occupants, Temperature)$
- From training dataset



# Intuition

We hope to:

- Learn  $f$ :  $Demand = f(\#occupants, Temperature)$
- From training dataset
- To predict the condition for the testing set

# Linear Relationship

We have

- $x_i = \begin{bmatrix} \textit{Temperature}_i \\ \textit{\#Occupants}_i \end{bmatrix}$

# Linear Relationship

We have

- $x_i = \begin{bmatrix} \text{Temperature}_i \\ \# \text{Occupants}_i \end{bmatrix}$
- Estimated demand for  $i^{\text{th}}$  sample is  
 $\hat{\text{demand}}_i = \theta_0 + \theta_1 \text{Temperature}_i + \theta_2 \text{Occupants}_i$

# Linear Relationship

We have

- $x_i = \begin{bmatrix} Temperature_i \\ \#Occupants_i \end{bmatrix}$
- Estimated demand for  $i^{th}$  sample is  
 $\hat{demand}_i = \theta_0 + \theta_1 Temperature_i + \theta_2 Occupants_i$
- $\hat{demand}_i = x_i'^T \theta$

# Linear Relationship

We have

- $x_i = \begin{bmatrix} \text{Temperature}_i \\ \# \text{Occupants}_i \end{bmatrix}$
- Estimated demand for  $i^{\text{th}}$  sample is  
 $\hat{\text{demand}}_i = \theta_0 + \theta_1 \text{Temperature}_i + \theta_2 \text{Occupants}_i$
- $\hat{\text{demand}}_i = x_i^T \theta$
- where  $\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix}$

# Linear Relationship

We have

- $x_i = \begin{bmatrix} \text{Temperature}_i \\ \# \text{Occupants}_i \end{bmatrix}$
- Estimated demand for  $i^{\text{th}}$  sample is  
 $\hat{\text{demand}}_i = \theta_0 + \theta_1 \text{Temperature}_i + \theta_2 \text{Occupants}_i$
- $\hat{\text{demand}}_i = x_i^T \theta$
- where  $\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix}$
- and  $x'_i = \begin{bmatrix} 1 \\ \text{Temperature}_i \\ \# \text{Occupants}_i \end{bmatrix} = \begin{bmatrix} 1 \\ x_i \end{bmatrix}$

# Linear Relationship

We have

- $x_i = \begin{bmatrix} \text{Temperature}_i \\ \# \text{Occupants}_i \end{bmatrix}$
- Estimated demand for  $i^{\text{th}}$  sample is  
 $\hat{\text{demand}}_i = \theta_0 + \theta_1 \text{Temperature}_i + \theta_2 \text{Occupants}_i$
- $\hat{\text{demand}}_i = x_i'^T \theta$
- where  $\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix}$
- and  $x_i' = \begin{bmatrix} 1 \\ \text{Temperature}_i \\ \# \text{Occupants}_i \end{bmatrix} = \begin{bmatrix} 1 \\ x_i \end{bmatrix}$
- Notice the transpose in the equation! This is because  $x_i$  is a column vector

## We can expect the following

- Demand increases, if # occupants increases, then  $\theta_2$  is likely to be positive



## We can expect the following

- Demand increases, if # occupants increases, then  $\theta_2$  is likely to be positive
- Demand increases, if temperature increases, then  $\theta_1$  is likely to be positive

## We can expect the following

- Demand increases, if # occupants increases, then  $\theta_2$  is likely to be positive
- Demand increases, if temperature increases, then  $\theta_1$  is likely to be positive
- Base demand is independent of the temperature and the # occupants, but, likely positive, thus  $\theta_0$  is likely positive.

# Generalized Linear Regression Format

- Assuming  $N$  samples for training

# Generalized Linear Regression Format

- Assuming  $N$  samples for training
- # Features =  $M$

# Generalized Linear Regression Format

- Assuming  $N$  samples for training
- # Features =  $M$

# Generalized Linear Regression Format

- Assuming  $N$  samples for training
- # Features =  $M$

$$\begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \vdots \\ \hat{y}_N \end{bmatrix}_{N \times 1} = \begin{bmatrix} 1 & x_{1,1} & x_{1,2} & \dots & x_{1,M} \\ 1 & x_{2,1} & x_{2,2} & \dots & x_{2,M} \\ \vdots & \vdots & \vdots & \dots & \vdots \\ 1 & x_{N,1} & x_{N,2} & \dots & x_{N,M} \end{bmatrix}_{N \times (M+1)} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_M \end{bmatrix}_{(M+1) \times 1}$$

# Generalized Linear Regression Format

- Assuming  $N$  samples for training
- # Features =  $M$

$$\begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \vdots \\ \hat{y}_N \end{bmatrix}_{N \times 1} = \begin{bmatrix} 1 & x_{1,1} & x_{1,2} & \dots & x_{1,M} \\ 1 & x_{2,1} & x_{2,2} & \dots & x_{2,M} \\ \vdots & \vdots & \vdots & \dots & \vdots \\ 1 & x_{N,1} & x_{N,2} & \dots & x_{N,M} \end{bmatrix}_{N \times (M+1)} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_M \end{bmatrix}_{(M+1) \times 1}$$

$$\hat{Y} = X\theta$$

# Relationships between feature and target variables

- There could be different  $\theta_0, \theta_1 \dots \theta_M$ . Each of them can represents a relationship.



# Relationships between feature and target variables

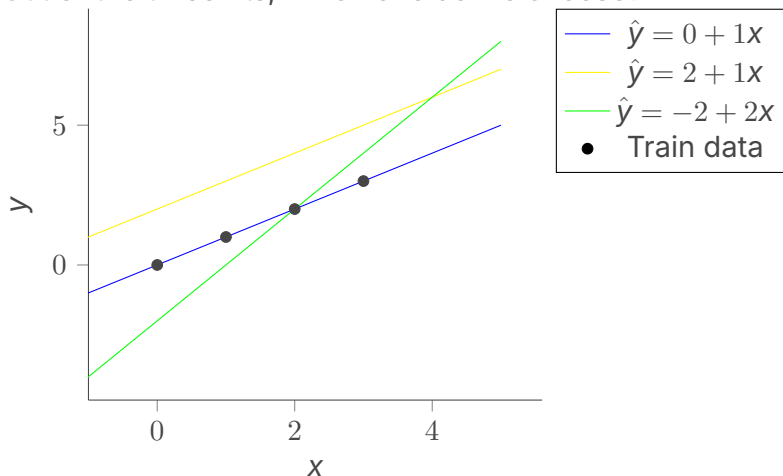
- There could be different  $\theta_0, \theta_1 \dots \theta_M$ . Each of them can represents a relationship.
- Given multiples values of  $\theta_0, \theta_1 \dots \theta_M$  how to choose which is the best?

# Relationships between feature and target variables

- There could be different  $\theta_0, \theta_1 \dots \theta_M$ . Each of them can represents a relationship.
- Given multiples values of  $\theta_0, \theta_1 \dots \theta_M$  how to choose which is the best?
- Let us consider an example in 2d

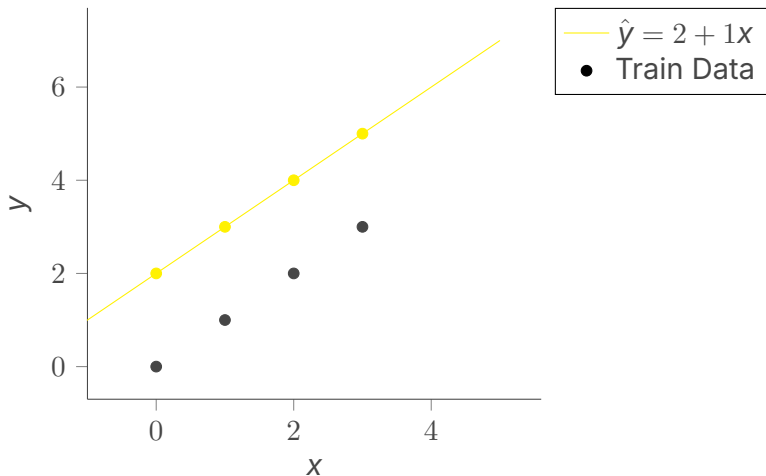
# Relationships between feature and target variables

Out of the three fits, which one do we choose?



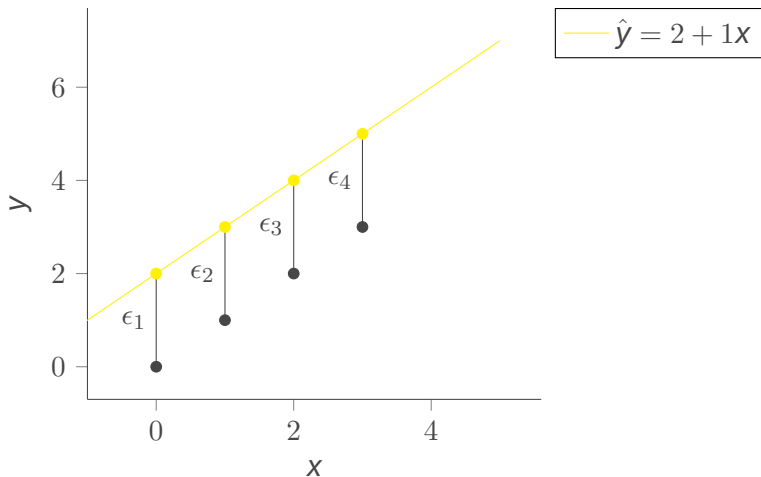
# Relationships between feature and target variables

We have  $\hat{y} = 2 + 1x$  as one relationship.



# Relationships between feature and target variables

How far is our estimated  $\hat{y}$  from ground truth  $y$ ?



# Error terms

- $y_i = \hat{y}_i + \epsilon_i$  where  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$

# Error terms

- $y_i = \hat{y}_i + \epsilon_i$  where  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- **Critical Assumption:**  $\epsilon_i$  are independent and identically distributed (i.i.d.)

# Error terms

- $y_i = \hat{y}_i + \epsilon_i$  where  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- **Critical Assumption:**  $\epsilon_i$  are independent and identically distributed (i.i.d.)
- $y_i$  denotes the ground truth for  $i^{th}$  sample



# Error terms

- $y_i = \hat{y}_i + \epsilon_i$  where  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- **Critical Assumption:**  $\epsilon_i$  are independent and identically distributed (i.i.d.)
- $y_i$  denotes the ground truth for  $i^{th}$  sample
- $\hat{y}_i$  denotes the prediction for  $i^{th}$  sample, where  $\hat{y}_i = \mathbf{x}_i^\top \boldsymbol{\theta}$

# Error terms

- $y_i = \hat{y}_i + \epsilon_i$  where  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- **Critical Assumption:**  $\epsilon_i$  are independent and identically distributed (i.i.d.)
- $y_i$  denotes the ground truth for  $i^{th}$  sample
- $\hat{y}_i$  denotes the prediction for  $i^{th}$  sample, where  $\hat{y}_i = \mathbf{x}_i^\top \boldsymbol{\theta}$
- $\epsilon_i$  denotes the error/residual for  $i^{th}$  sample

# Error terms

- $y_i = \hat{y}_i + \epsilon_i$  where  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- **Critical Assumption:**  $\epsilon_i$  are independent and identically distributed (i.i.d.)
- $y_i$  denotes the ground truth for  $i^{th}$  sample
- $\hat{y}_i$  denotes the prediction for  $i^{th}$  sample, where  $\hat{y}_i = \mathbf{x}_i^\top \boldsymbol{\theta}$
- $\epsilon_i$  denotes the error/residual for  $i^{th}$  sample
- $\theta_0, \theta_1$ : The parameters of the linear regression

# Error terms

- $y_i = \hat{y}_i + \epsilon_i$  where  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- **Critical Assumption:**  $\epsilon_i$  are independent and identically distributed (i.i.d.)
- $y_i$  denotes the ground truth for  $i^{th}$  sample
- $\hat{y}_i$  denotes the prediction for  $i^{th}$  sample, where  $\hat{y}_i = \mathbf{x}_i^\top \boldsymbol{\theta}$
- $\epsilon_i$  denotes the error/residual for  $i^{th}$  sample
- $\theta_0, \theta_1$ : The parameters of the linear regression
- $\epsilon_i = y_i - \hat{y}_i$

# Error terms

- $y_i = \hat{y}_i + \epsilon_i$  where  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- **Critical Assumption:**  $\epsilon_i$  are independent and identically distributed (i.i.d.)
- $y_i$  denotes the ground truth for  $i^{th}$  sample
- $\hat{y}_i$  denotes the prediction for  $i^{th}$  sample, where  $\hat{y}_i = \mathbf{x}_i^\top \boldsymbol{\theta}$
- $\epsilon_i$  denotes the error/residual for  $i^{th}$  sample
- $\theta_0, \theta_1$ : The parameters of the linear regression
- $\epsilon_i = y_i - \hat{y}_i$
- $\epsilon_i = y_i - (\theta_0 + \mathbf{x}_i \cdot \theta_1)$

# Good fit

- $|\epsilon_1|, |\epsilon_2|, |\epsilon_3|, \dots$  should be small.

# Good fit

- $|\epsilon_1|, |\epsilon_2|, |\epsilon_3|, \dots$  should be small.
- minimize  $\epsilon_1^2 + \epsilon_2^2 + \dots + \epsilon_N^2$  -  $L_2$  Norm

# Good fit

- $|\epsilon_1|, |\epsilon_2|, |\epsilon_3|, \dots$  should be small.
- minimize  $\epsilon_1^2 + \epsilon_2^2 + \dots + \epsilon_N^2$  -  $L_2$  Norm
- minimize  $|\epsilon_1| + |\epsilon_2| + \dots + |\epsilon_n|$  -  $L_1$  Norm



# Normal Equation

# Normal Equation

$$Y = X\theta + \epsilon$$

# Normal Equation

$$Y = X\theta + \epsilon$$

To Learn:  $\theta$

# Normal Equation

$$Y = X\theta + \epsilon$$

To Learn:  $\theta$

Objective: minimize  $\epsilon_1^2 + \epsilon_2^2 + \dots + \epsilon_N^2$

# Normal Equation

$$\epsilon = \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_N \end{bmatrix}$$

# Normal Equation

$$\epsilon = \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_N \end{bmatrix}$$

Objective: Minimize  $\epsilon^T \epsilon$

# Derivation of Normal Equation

$$\boldsymbol{\epsilon} = \mathbf{y} - \mathbf{X}\boldsymbol{\theta}$$

$$\boldsymbol{\epsilon}^\top \boldsymbol{\epsilon} = (\mathbf{y} - \mathbf{X}\boldsymbol{\theta})^\top (\mathbf{y} - \mathbf{X}\boldsymbol{\theta})$$

$$= \mathbf{y}^\top \mathbf{y} - 2\mathbf{y}^\top \mathbf{X}\boldsymbol{\theta} + \boldsymbol{\theta}^\top \mathbf{X}^\top \mathbf{X}\boldsymbol{\theta}$$

This is what we wish to minimize

# Minimizing the objective function

$$\frac{\partial \epsilon^\top \epsilon}{\partial \theta} = 0$$

- $\frac{\partial}{\partial \theta} \mathbf{y}^\top \mathbf{y} = 0$

Substitute the values in the top equation



# Minimizing the objective function

$$\frac{\partial \epsilon^\top \epsilon}{\partial \theta} = 0$$

- $\frac{\partial}{\partial \theta} \mathbf{y}^\top \mathbf{y} = 0$
- $\frac{\partial}{\partial \theta} (-2\mathbf{y}^\top \mathbf{X}\theta) = -2\mathbf{X}^\top \mathbf{y}$

Substitute the values in the top equation

# Minimizing the objective function

$$\frac{\partial \epsilon^\top \epsilon}{\partial \theta} = 0$$

- $\frac{\partial}{\partial \theta} \mathbf{y}^\top \mathbf{y} = 0$
- $\frac{\partial}{\partial \theta} (-2\mathbf{y}^\top \mathbf{X}\theta) = -2\mathbf{X}^\top \mathbf{y}$
- $\frac{\partial}{\partial \theta} (\theta^\top \mathbf{X}^\top \mathbf{X}\theta) = 2\mathbf{X}^\top \mathbf{X}\theta$

Substitute the values in the top equation

# Normal Equation derivation

$$0 = -2\mathbf{X}^\top \mathbf{y} + 2\mathbf{X}^\top \mathbf{X} \boldsymbol{\theta}$$

$$\mathbf{X}^\top \mathbf{y} = \mathbf{X}^\top \mathbf{X} \boldsymbol{\theta}$$

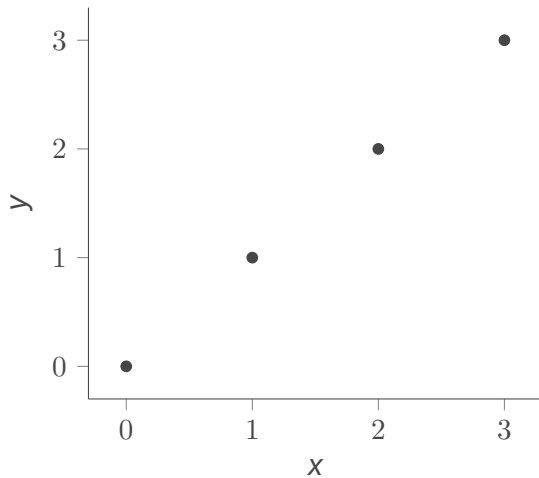
$$\hat{\boldsymbol{\theta}}_{OLS} = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}$$

## Worked out example

x	y
0	0
1	1
2	2
3	3

Given the data above, find  $\theta_0$  and  $\theta_1$ .

# Scatter Plot



## Worked out example

$$\mathbf{X} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix}$$

$$\mathbf{X}^\top = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{bmatrix}$$

$$\mathbf{X}^\top \mathbf{X} = \begin{bmatrix} 4 & 6 \\ 6 & 14 \end{bmatrix}$$

Given the data above, find  $\theta_0$  and  $\theta_1$ .

## Worked out example

$$(\mathbf{X}^\top \mathbf{X})^{-1} = \frac{1}{20} \begin{bmatrix} 14 & -6 \\ -6 & 4 \end{bmatrix}$$

$$\mathbf{X}^\top \mathbf{y} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 6 \\ 14 \end{bmatrix}$$

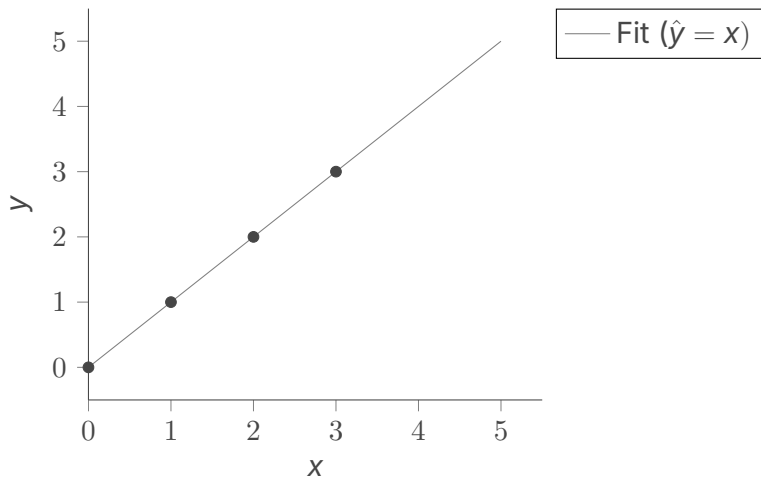
## Worked out example

$$\theta = (X^T X)^{-1} (X^T y)$$

$$\begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} = \frac{1}{20} \begin{bmatrix} 14 & -6 \\ -6 & 4 \end{bmatrix} \begin{bmatrix} 6 \\ 14 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$



# Scatter Plot

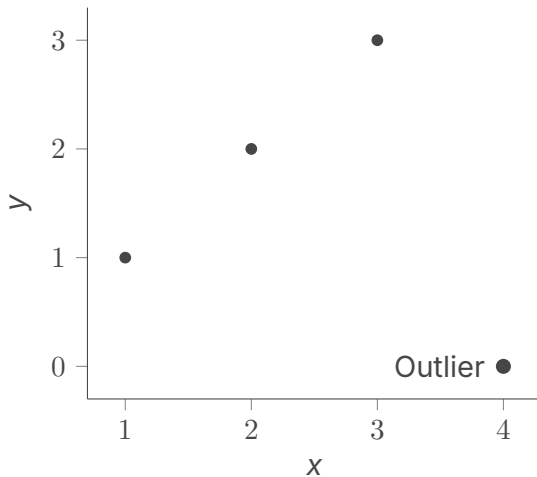


# Effect of outlier

x	y
1	1
2	2
3	3
4	0

Compute the  $\theta_0$  and  $\theta_1$ .

# Scatter Plot



## Worked out example

$$X = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix}$$

$$X^T = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$

$$X^T X = \begin{bmatrix} 4 & 10 \\ 10 & 30 \end{bmatrix}$$

Given the data above, find  $\theta_0$  and  $\theta_1$ .

## Worked out example

$$(\mathbf{X}^\top \mathbf{X})^{-1} = \frac{1}{20} \begin{bmatrix} 30 & -10 \\ -10 & 4 \end{bmatrix}$$

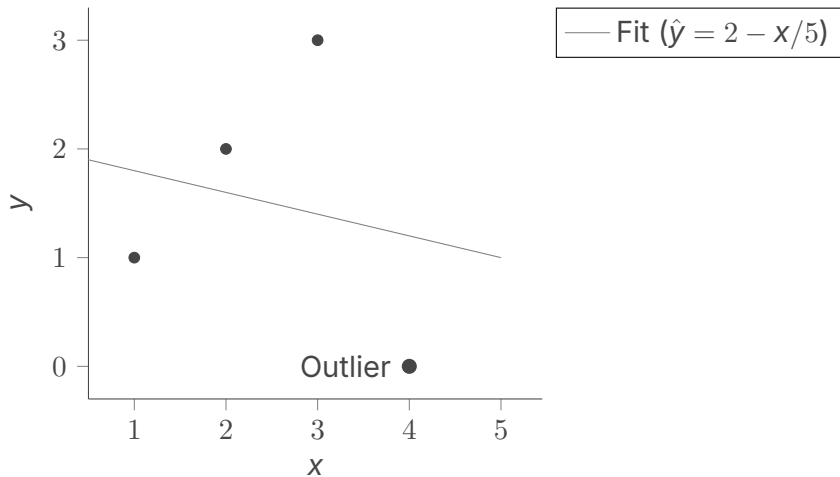
$$\mathbf{X}^\top \mathbf{y} = \begin{bmatrix} 6 \\ 14 \end{bmatrix}$$

## Worked out example

$$\boldsymbol{\theta} = (\mathbf{X}^\top \mathbf{X})^{-1} (\mathbf{X}^\top \mathbf{y})$$

$$\begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} = \begin{bmatrix} 2 \\ (-1/5) \end{bmatrix}$$

# Scatter Plot



# Variable Transformation

Transform the data, by including the higher power terms in the feature space.

t	s
0	0
1	6
3	24
4	36

The above table represents the data before transformation



# Variable Transformation

Add the higher degree features to the previous table

t	$t^2$	s
0	0	0
1	1	6
3	9	24
4	16	36

# Variable Transformation

Add the higher degree features to the previous table

t	$t^2$	s
0	0	0
1	1	6
3	9	24
4	16	36

The above table represents the data after transformation

# Variable Transformation

Add the higher degree features to the previous table

t	$t^2$	s
0	0	0
1	1	6
3	9	24
4	16	36

The above table represents the data after transformation  
Now, we can write  $\hat{s} = f(t, t^2)$

# Variable Transformation

Add the higher degree features to the previous table

t	$t^2$	s
0	0	0
1	1	6
3	9	24
4	16	36

The above table represents the data after transformation

Now, we can write  $\hat{s} = f(t, t^2)$

Other transformations:  $\log(x)$ ,  $x_1 \times x_2$

# A big caveat: Linear in what?!<sup>1</sup>

1.  $\hat{s} = \theta_0 + \theta_1 * t$  is linear

---

<sup>1</sup><https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression>

# A big caveat: Linear in what?!<sup>1</sup>

1.  $\hat{s} = \theta_0 + \theta_1 * t$  is linear
2. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$  linear?

---

<sup>1</sup><https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression>

# A big caveat: Linear in what?!<sup>1</sup>

1.  $\hat{s} = \theta_0 + \theta_1 * t$  is linear
2. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$  linear?
3. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2 + \theta_3 * \cos(t^3)$  linear?

---

<sup>1</sup><https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression>

# A big caveat: Linear in what?!<sup>1</sup>

1.  $\hat{s} = \theta_0 + \theta_1 * t$  is linear
2. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$  linear?
3. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2 + \theta_3 * \cos(t^3)$  linear?
4. Is  $\hat{s} = \theta_0 + \theta_1 * t + e^{\theta_2} * t$  linear?

---

<sup>1</sup><https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression>



# A big caveat: Linear in what?!<sup>1</sup>

1.  $\hat{s} = \theta_0 + \theta_1 * t$  is linear
2. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$  linear?
3. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2 + \theta_3 * \cos(t^3)$  linear?
4. Is  $\hat{s} = \theta_0 + \theta_1 * t + e^{\theta_2} * t$  linear?
5. All except #4 are linear models!

---

<sup>1</sup><https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression>

# A big caveat: Linear in what?!<sup>1</sup>

1.  $\hat{s} = \theta_0 + \theta_1 * t$  is linear
2. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$  linear?
3. Is  $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2 + \theta_3 * \cos(t^3)$  linear?
4. Is  $\hat{s} = \theta_0 + \theta_1 * t + e^{\theta_2} * t$  linear?
5. All except #4 are linear models!
6. Linear refers to the relationship between the parameters that you are estimating ( $\theta$ ) and the outcome

---

<sup>1</sup><https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression>

# Basis Functions

- Linear regression only refers to linear in the parameters

# Basis Functions

- Linear regression only refers to linear in the parameters
- We can perform an arbitrary nonlinear transformation  $\phi(x)$  of the inputs  $x$  and then linearly combine the components of this transformation.

# Basis Functions

- Linear regression only refers to linear in the parameters
- We can perform an arbitrary nonlinear transformation  $\phi(x)$  of the inputs  $x$  and then linearly combine the components of this transformation.
- $\phi : \mathbb{R}^D \rightarrow \mathbb{R}^K$  is called the basis function

# Basis Functions

Some examples of basis functions:

- Polynomial basis:  $\phi(x) = \{1, x, x^2, x^3, \dots\}$

# Basis Functions

Some examples of basis functions:

- Polynomial basis:  $\phi(x) = \{1, x, x^2, x^3, \dots\}$
- Fourier basis:  
 $\phi(x) = \{1, \sin(x), \cos(x), \sin(2x), \cos(2x), \dots\}$

# Basis Functions

Some examples of basis functions:

- Polynomial basis:  $\phi(x) = \{1, x, x^2, x^3, \dots\}$
- Fourier basis:  
 $\phi(x) = \{1, \sin(x), \cos(x), \sin(2x), \cos(2x), \dots\}$
- Gaussian basis:  
 $\phi(x) = \{1, \exp(-\frac{(x-\mu_1)^2}{2\sigma^2}), \exp(-\frac{(x-\mu_2)^2}{2\sigma^2}), \dots\}$



# Basis Functions

Some examples of basis functions:

- Polynomial basis:  $\phi(x) = \{1, x, x^2, x^3, \dots\}$
- Fourier basis:  
 $\phi(x) = \{1, \sin(x), \cos(x), \sin(2x), \cos(2x), \dots\}$
- Gaussian basis:  
 $\phi(x) = \{1, \exp(-\frac{(x-\mu_1)^2}{2\sigma^2}), \exp(-\frac{(x-\mu_2)^2}{2\sigma^2}), \dots\}$
- Sigmoid basis:  $\phi(x) = \{1, \sigma(x - \mu_1), \sigma(x - \mu_2), \dots\}$   
where  $\sigma(x) = \frac{1}{1+e^{-x}}$

# Linear Combination of Vectors

Let  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_j$  be vectors in  $\mathbb{R}^D$ , where  $D$  denotes the dimensions.

# Linear Combination of Vectors

Let  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_i$  be vectors in  $\mathbb{R}^D$ , where  $D$  denotes the dimensions.

A linear combination of  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_i$  is of the following form

# Linear Combination of Vectors

Let  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_j$  be vectors in  $\mathbb{R}^D$ , where  $D$  denotes the dimensions.

A linear combination of  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_j$  is of the following form

$$\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \alpha_3 \mathbf{v}_3 + \dots + \alpha_j \mathbf{v}_j$$

where  $\alpha_1, \alpha_2, \alpha_3, \dots, \alpha_j \in \mathbb{R}$

# Span of vectors

Let  $v_1, v_2, \dots, v_i$  be vectors in  $\mathbb{R}^D$ , with  $D$  dimensions.

# Span of vectors

Let  $v_1, v_2, \dots, v_i$  be vectors in  $\mathbb{R}^D$ , with  $D$  dimensions.  
The span of  $v_1, v_2, \dots, v_i$  is denoted by  
 $\text{SPAN}\{v_1, v_2, \dots, v_i\}$

# Span of vectors

Let  $v_1, v_2, \dots, v_i$  be vectors in  $\mathbb{R}^D$ , with  $D$  dimensions.  
The span of  $v_1, v_2, \dots, v_i$  is denoted by  
 $\text{SPAN}\{v_1, v_2, \dots, v_i\}$

$$\{\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_i v_i \mid \alpha_1, \alpha_2, \dots, \alpha_i \in \mathbb{R}\}$$

# Span of vectors

Let  $v_1, v_2, \dots, v_j$  be vectors in  $\mathbb{R}^D$ , with  $D$  dimensions.  
The span of  $v_1, v_2, \dots, v_j$  is denoted by  
 $\text{SPAN}\{v_1, v_2, \dots, v_j\}$

$$\{\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_j v_j \mid \alpha_1, \alpha_2, \dots, \alpha_j \in \mathbb{R}\}$$

It is the set of all vectors that can be generated by linear combinations of  $v_1, v_2, \dots, v_j$ .



# Span of vectors

Let  $v_1, v_2, \dots, v_i$  be vectors in  $\mathbb{R}^D$ , with  $D$  dimensions.  
The span of  $v_1, v_2, \dots, v_i$  is denoted by  
 $\text{SPAN}\{v_1, v_2, \dots, v_i\}$

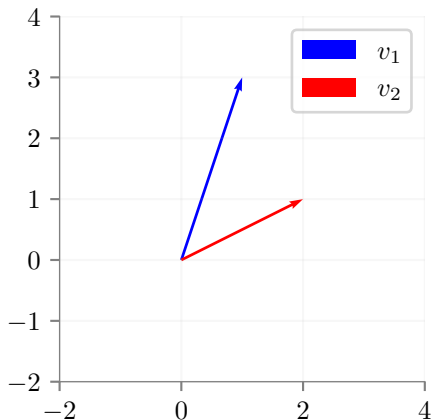
$$\{\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_i v_i \mid \alpha_1, \alpha_2, \dots, \alpha_i \in \mathbb{R}\}$$

It is the set of all vectors that can be generated by linear combinations of  $v_1, v_2, \dots, v_i$ .

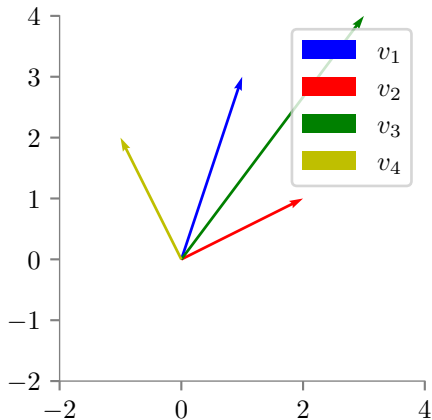
If we stack the vectors  $v_1, v_2, \dots, v_i$  as columns of a matrix  $V$ , then the span of  $v_1, v_2, \dots, v_i$  is given as  $V\alpha$  where  $\alpha \in \mathbb{R}^i$

# Example

Find the span of  $\left( \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right)$



# Example

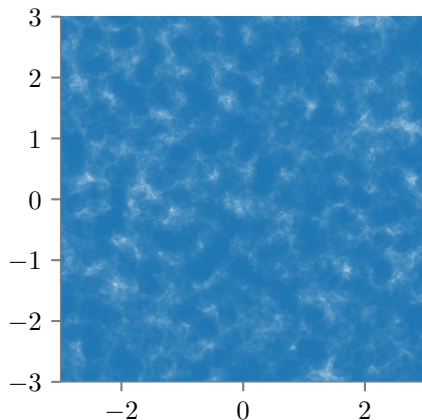


We have  $v_3 = v_1 + v_2$

We have  $v_4 = v_1 - v_2$

# Example

Simulating the above example in python using different values of  $\alpha_1$  and  $\alpha_2$



$\text{Span}((v_1, v_2)) \in \mathcal{R}^2$

## Example

Find the span of  $\left( \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix} \right)$

# Example

Find the span of  $\left( \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix} \right)$

Can we obtain a point  $(x, y)$  s.t.  $x = 3y$ ?

# Example

Find the span of  $\left( \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix} \right)$

Can we obtain a point  $(x, y)$  s.t.  $x = 3y$ ?

No

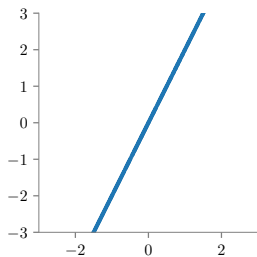
## Example

Find the span of  $\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix}\right)$

Can we obtain a point  $(x, y)$  s.t.  $x = 3y$ ?

No

Span of the above set is along the line  $y = 2x$



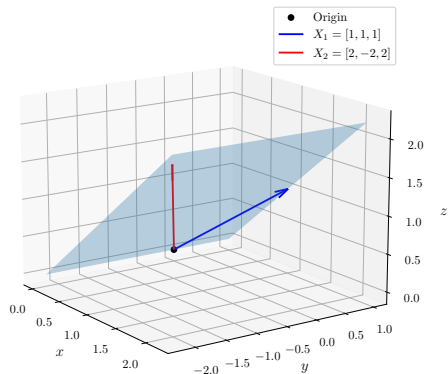


## Example

Find the span of  $\left( \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 2 \end{bmatrix} \right)$

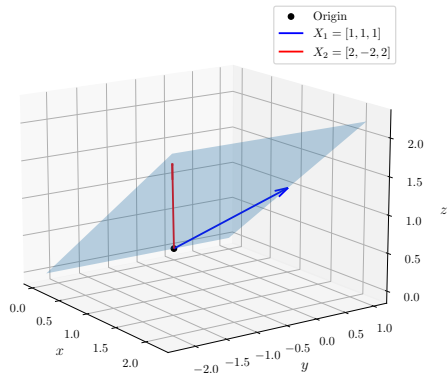
# Example

Find the span of  $\left( \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 2 \end{bmatrix} \right)$



# Example

Find the span of  $\left( \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 2 \end{bmatrix} \right)$



The span is the plane  $z = x$  or  $x_3 = x_1$

# Geometric Interpretation

Consider  $\mathbf{X}$  and  $\mathbf{y}$  as follows.

$$\mathbf{X} = \begin{pmatrix} 1 & 2 \\ 1 & -2 \\ 1 & 2 \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} 8.8957 \\ 0.6130 \\ 1.7761 \end{pmatrix}$$

- We are trying to learn  $\theta$  for  $\hat{\mathbf{y}} = \mathbf{X}\theta$  such that  $\|\mathbf{y} - \hat{\mathbf{y}}\|_2$  is minimised

# Geometric Interpretation

Consider  $\mathbf{X}$  and  $\mathbf{y}$  as follows.

$$\mathbf{X} = \begin{pmatrix} 1 & 2 \\ 1 & -2 \\ 1 & 2 \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} 8.8957 \\ 0.6130 \\ 1.7761 \end{pmatrix}$$

- We are trying to learn  $\theta$  for  $\hat{\mathbf{y}} = \mathbf{X}\theta$  such that  $\|\mathbf{y} - \hat{\mathbf{y}}\|_2$  is minimised
- Consider the two columns of  $\mathbf{X}$ . Can we write  $\mathbf{X}\theta$  as the span of  $\left( \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 2 \end{bmatrix} \right)$ ?

# Geometric Interpretation

Consider  $\mathbf{X}$  and  $\mathbf{y}$  as follows.

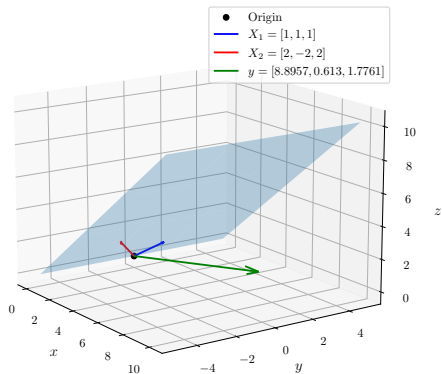
$$\mathbf{X} = \begin{pmatrix} 1 & 2 \\ 1 & -2 \\ 1 & 2 \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} 8.8957 \\ 0.6130 \\ 1.7761 \end{pmatrix}$$

- We are trying to learn  $\theta$  for  $\hat{\mathbf{y}} = \mathbf{X}\theta$  such that  $\|\mathbf{y} - \hat{\mathbf{y}}\|_2$  is minimised
- Consider the two columns of  $\mathbf{X}$ . Can we write  $\mathbf{X}\theta$  as the span of  $\left( \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 2 \end{bmatrix} \right)$ ?
- We wish to find  $\hat{\mathbf{y}}$  such that

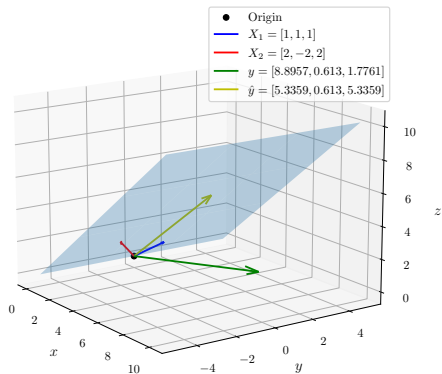
$$\arg \min_{\hat{\mathbf{y}} \in \text{SPAN}\{\bar{x}_1, \bar{x}_2, \dots, \bar{x}_D\}} \|\mathbf{y} - \hat{\mathbf{y}}\|_2$$

# Geometric Interpretation

Span of  $\left( \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -2 \\ 2 \end{bmatrix} \right)$



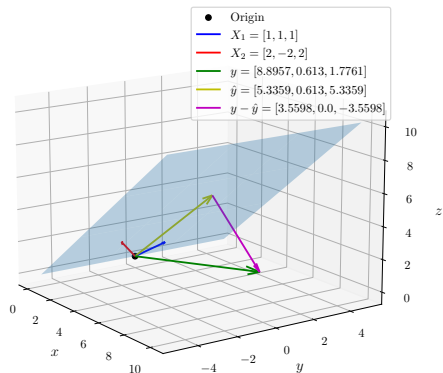
# Geometric Interpretation



- We seek a  $\hat{y}$  in the span of the columns of  $X$  such that it is closest to  $y$

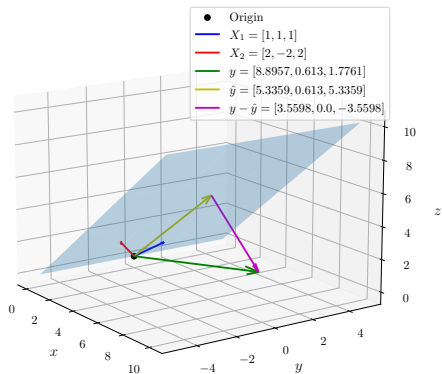


# Geometric Interpretation



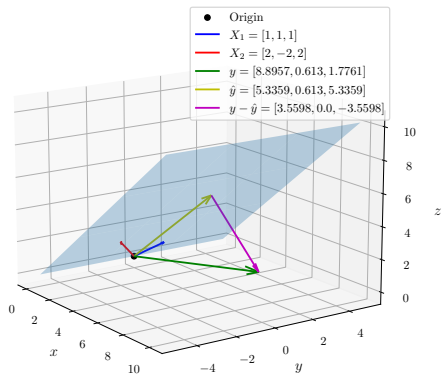
- This happens when  $y - \hat{y} \perp x_j \forall j$  or  $x_j^\top (y - \hat{y}) = 0$

# Geometric Interpretation



- This happens when  $y - \hat{y} \perp x_j \forall j$  or  $x_j^\top (y - \hat{y}) = 0$
- $\mathbf{X}^\top (y - \mathbf{X}\theta) = 0$

# Geometric Interpretation



- This happens when  $y - \hat{y} \perp x_j \forall j$  or  $x_j^\top (y - \hat{y}) = 0$
- $X^\top (y - X\theta) = 0$
- $X^\top y = X^\top X\theta$  or  $\hat{\theta} = (X^\top X)^{-1} X^\top y$

# The Problem: Overfitting

- Linear regression can overfit with:

# The Problem: Overfitting

- Linear regression can overfit with:
  - Too many features relative to data points

# The Problem: Overfitting

- Linear regression can overfit with:
  - Too many features relative to data points
  - Highly correlated features (multicollinearity)

# The Problem: Overfitting

- Linear regression can overfit with:
  - Too many features relative to data points
  - Highly correlated features (multicollinearity)
  - Noisy data with complex models

# The Problem: Overfitting

- Linear regression can overfit with:
  - Too many features relative to data points
  - Highly correlated features (multicollinearity)
  - Noisy data with complex models
- **Solution:** Add penalty term to control model complexity



# The Problem: Overfitting

- Linear regression can overfit with:
  - Too many features relative to data points
  - Highly correlated features (multicollinearity)
  - Noisy data with complex models
- **Solution:** Add penalty term to control model complexity
- This prevents coefficients from becoming too large

# Ridge Regression (L2 Regularization)

**Objective Function:**

$$J(\theta) = \text{MSE} + \lambda \sum_{j=1}^n \theta_j^2$$

- $\lambda \geq 0$  is the **regularization parameter**

# Ridge Regression (L2 Regularization)

## Objective Function:

$$J(\theta) = \text{MSE} + \lambda \sum_{j=1}^n \theta_j^2$$

- $\lambda \geq 0$  is the **regularization parameter**
- Larger  $\lambda \rightarrow$  more regularization  $\rightarrow$  simpler model

# Ridge Regression (L2 Regularization)

## Objective Function:

$$J(\theta) = \text{MSE} + \lambda \sum_{j=1}^n \theta_j^2$$

- $\lambda \geq 0$  is the **regularization parameter**
- Larger  $\lambda \rightarrow$  more regularization  $\rightarrow$  simpler model
- **Effect:** Shrinks coefficients toward zero

# Ridge Regression (L2 Regularization)

## Objective Function:

$$J(\theta) = \text{MSE} + \lambda \sum_{j=1}^n \theta_j^2$$

- $\lambda \geq 0$  is the **regularization parameter**
- Larger  $\lambda \rightarrow$  more regularization  $\rightarrow$  simpler model
- **Effect:** Shrinks coefficients toward zero
- **Closed-form solution:**  $\theta = (\mathbf{X}^\top \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^\top \mathbf{y}$

# Ridge Regression (L2 Regularization)

## Objective Function:

$$J(\theta) = \text{MSE} + \lambda \sum_{j=1}^n \theta_j^2$$

- $\lambda \geq 0$  is the **regularization parameter**
- Larger  $\lambda \rightarrow$  more regularization  $\rightarrow$  simpler model
- **Effect:** Shrinks coefficients toward zero
- **Closed-form solution:**  $\theta = (\mathbf{X}^\top \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^\top \mathbf{y}$
- **Note:**  $(\mathbf{X}^\top \mathbf{X} + \lambda \mathbf{I})$  is always invertible for  $\lambda > 0$

# Lasso Regression (L1 Regularization)

## Objective Function:

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(\mathbf{x}^{(i)}) - y^{(i)})^2 + \lambda \sum_{j=1}^n |\theta_j|$$

- Uses absolute value penalty instead of squared penalty

# Lasso Regression (L1 Regularization)

## Objective Function:

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(\mathbf{x}^{(i)}) - y^{(i)})^2 + \lambda \sum_{j=1}^n |\theta_j|$$

- Uses absolute value penalty instead of squared penalty
- **Key Property:** Can set coefficients exactly to zero



# Lasso Regression (L1 Regularization)

## Objective Function:

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(\mathbf{x}^{(i)}) - y^{(i)})^2 + \lambda \sum_{j=1}^n |\theta_j|$$

- Uses absolute value penalty instead of squared penalty
- **Key Property:** Can set coefficients exactly to zero
- **Automatic Feature Selection:** Eliminates irrelevant features

# Lasso Regression (L1 Regularization)

## Objective Function:

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(\mathbf{x}^{(i)}) - y^{(i)})^2 + \lambda \sum_{j=1}^n |\theta_j|$$

- Uses absolute value penalty instead of squared penalty
- **Key Property:** Can set coefficients exactly to zero
- **Automatic Feature Selection:** Eliminates irrelevant features
- No closed-form solution → requires iterative optimization

# Lasso Regression (L1 Regularization)

## Objective Function:

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(\mathbf{x}^{(i)}) - y^{(i)})^2 + \lambda \sum_{j=1}^n |\theta_j|$$

- Uses absolute value penalty instead of squared penalty
- **Key Property:** Can set coefficients exactly to zero
- **Automatic Feature Selection:** Eliminates irrelevant features
- No closed-form solution  $\rightarrow$  requires iterative optimization
- **Use Case:** When you suspect many features are irrelevant

# Ridge vs Lasso: Geometric Intuition

- **Ridge (L2):** Constraint region is a circle

# Ridge vs Lasso: Geometric Intuition

- **Ridge (L2):** Constraint region is a circle
  - Smooth boundary  $\rightarrow$  coefficients shrink smoothly

# Ridge vs Lasso: Geometric Intuition

- **Ridge (L2):** Constraint region is a circle
  - Smooth boundary  $\rightarrow$  coefficients shrink smoothly
  - Rarely sets coefficients exactly to zero

# Ridge vs Lasso: Geometric Intuition

- **Ridge (L2):** Constraint region is a circle
  - Smooth boundary  $\rightarrow$  coefficients shrink smoothly
  - Rarely sets coefficients exactly to zero
- **Lasso (L1):** Constraint region is a diamond

# Ridge vs Lasso: Geometric Intuition

- **Ridge (L2):** Constraint region is a circle
  - Smooth boundary  $\rightarrow$  coefficients shrink smoothly
  - Rarely sets coefficients exactly to zero
- **Lasso (L1):** Constraint region is a diamond
  - Sharp corners at axes  $\rightarrow$  coefficients can become exactly zero



# Ridge vs Lasso: Geometric Intuition

- **Ridge (L2):** Constraint region is a circle
  - Smooth boundary → coefficients shrink smoothly
  - Rarely sets coefficients exactly to zero
- **Lasso (L1):** Constraint region is a diamond
  - Sharp corners at axes → coefficients can become exactly zero
  - Performs automatic feature selection

# Ridge vs Lasso: Geometric Intuition

- **Ridge (L2):** Constraint region is a circle
  - Smooth boundary  $\rightarrow$  coefficients shrink smoothly
  - Rarely sets coefficients exactly to zero
- **Lasso (L1):** Constraint region is a diamond
  - Sharp corners at axes  $\rightarrow$  coefficients can become exactly zero
  - Performs automatic feature selection
- **Elastic Net:** Combines both penalties

$$J(\theta) = \text{MSE} + \lambda_1 \sum |\theta_j| + \lambda_2 \sum \theta_j^2$$

# Choosing Regularization Parameter $\lambda$

- $\lambda = 0$ : No regularization (standard linear regression)

# Choosing Regularization Parameter $\lambda$

- $\lambda = 0$ : No regularization (standard linear regression)
- $\lambda$  **very small**: Minimal regularization

# Choosing Regularization Parameter $\lambda$

- $\lambda = 0$ : No regularization (standard linear regression)
- $\lambda$  **very small**: Minimal regularization
- $\lambda$  **very large**: Heavy regularization (underfitting)

# Choosing Regularization Parameter $\lambda$

- $\lambda = 0$ : No regularization (standard linear regression)
- $\lambda$  **very small**: Minimal regularization
- $\lambda$  **very large**: Heavy regularization (underfitting)
- **Selection Methods:**

# Choosing Regularization Parameter $\lambda$

- $\lambda = 0$ : No regularization (standard linear regression)
- $\lambda$  **very small**: Minimal regularization
- $\lambda$  **very large**: Heavy regularization (underfitting)
- **Selection Methods:**
  - Cross-validation (most common)

# Choosing Regularization Parameter $\lambda$

- $\lambda = 0$ : No regularization (standard linear regression)
- $\lambda$  **very small**: Minimal regularization
- $\lambda$  **very large**: Heavy regularization (underfitting)
- **Selection Methods:**
  - Cross-validation (most common)
  - Information criteria (AIC, BIC)



# Choosing Regularization Parameter $\lambda$

- $\lambda = 0$ : No regularization (standard linear regression)
- $\lambda$  **very small**: Minimal regularization
- $\lambda$  **very large**: Heavy regularization (underfitting)
- **Selection Methods:**
  - Cross-validation (most common)
  - Information criteria (AIC, BIC)
  - Validation curves

# Choosing Regularization Parameter $\lambda$

- $\lambda = 0$ : No regularization (standard linear regression)
- $\lambda$  **very small**: Minimal regularization
- $\lambda$  **very large**: Heavy regularization (underfitting)
- **Selection Methods:**
  - Cross-validation (most common)
  - Information criteria (AIC, BIC)
  - Validation curves
- **Critical Insight:**  $\lambda$  controls bias-variance tradeoff

# Multi-collinearity

There can be situations where inverse of  $X^T X$  is not computable.

# Multi-collinearity

There can be situations where inverse of  $X^T X$  is not computable.

This condition arises when the  $|X^T X| = 0$ .

$$X = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 4 \\ 1 & 3 & 6 \end{bmatrix} \quad (1)$$

# Multi-collinearity

There can be situations where inverse of  $X^T X$  is not computable.

This condition arises when the  $|X^T X| = 0$ .

$$X = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 4 \\ 1 & 3 & 6 \end{bmatrix} \quad (1)$$

The matrix  $X$  is not full rank.

# Multi-collinearity

It arises when one or more predictor variables/features in  $X$  can be expressed as a linear combination of others

How to tackle it?

- Regularize

# Multi-collinearity

It arises when one or more predictor variables/features in  $X$  can be expressed as a linear combination of others

How to tackle it?

- Regularize
- Drop variables

# Multi-collinearity

It arises when one or more predictor variables/features in  $X$  can be expressed as a linear combination of others

How to tackle it?

- Regularize
- Drop variables
- Avoid dummy variable trap



# Dummy variables

Say Pollution in Delhi =  $P$

# Dummy variables

Say Pollution in Delhi = P

$$P = \theta_0 + \theta_1 * \text{\#Vehicles} + \theta_2 * \text{Wind speed} + \theta_3 * \text{Wind Direction}$$

# Dummy variables

Say Pollution in Delhi = P

$$P = \theta_0 + \theta_1 * \#Vehicles + \theta_2 * \text{Wind speed} + \theta_3 * \text{Wind Direction}$$

But, wind direction is a categorical variable.

# Dummy variables

Say Pollution in Delhi = P

$$P = \theta_0 + \theta_1 * \#Vehicles + \theta_2 * Wind\ speed + \theta_3 * Wind\ Direction$$

But, wind direction is a categorical variable.  
It is denoted as follows {N:0, E:1, W:2, S:3 }

# Dummy variables

Say Pollution in Delhi =  $P$

$$P = \theta_0 + \theta_1 * \#Vehicles + \theta_2 * Wind\ speed + \theta_3 * Wind\ Direction$$

But, wind direction is a categorical variable.  
It is denoted as follows {N:0, E:1, W:2, S:3 }

Can we use the direct encoding?

# Dummy variables

Say Pollution in Delhi =  $P$

$$P = \theta_0 + \theta_1 * \#Vehicles + \theta_2 * Wind\ speed + \theta_3 * Wind\ Direction$$

But, wind direction is a categorical variable.  
It is denoted as follows {N:0, E:1, W:2, S:3 }

Can we use the direct encoding?  
Then this implies that  $S > W > E > N$

# Dummy Variables

N-1 Variable encoding

	Is it N?	Is it E?	Is it W?
N	1	0	0
E	0	1	0
W	0	0	1
S	0	0	0

# Dummy Variables

N Variable encoding

	Is it N?	Is it E?	Is it W?	Is it S?
N	1	0	0	0
E	0	1	0	0
W	0	0	1	0
S	0	0	0	1



# Dummy Variables

Which is better N variable encoding or N-1 variable encoding?

# Dummy Variables

Which is better N variable encoding or N-1 variable encoding?

The N-1 variable encoding is better because the N variable encoding can cause multi-collinearity.

# Dummy Variables

Which is better N variable encoding or N-1 variable encoding?

The N-1 variable encoding is better because the N variable encoding can cause multi-collinearity.

Is it  $S = 1 - (\text{Is it N} + \text{Is it W} + \text{Is it E})$

# Binary Encoding

N	00
E	01
W	10
S	11

# Binary Encoding

N	00
E	01
W	10
S	11

W and S are related by one bit.

# Binary Encoding

N	00
E	01
W	10
S	11

W and S are related by one bit.

This introduces dependencies between them, and this can cause confusion in classifiers.

# Interpreting Dummy variables

Gender	height
F	...
F	...
F	...
M	...
M	...

# Interpreting Dummy variables

Gender	height
F	...
F	...
F	...
M	...
M	...

Encoding



# Interpreting Dummy variables

Gender	height
F	...
F	...
F	...
M	...
M	...

Encoding

Is Female	height
1	...
1	...
1	...
0	...
0	...

# Interpreting Dummy Variables

# Interpreting Dummy Variables

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

# Interpreting Dummy Variables

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$height_i = \theta_0 + \theta_1 * (\text{Is Female}) + \epsilon_i$$

# Interpreting Dummy Variables

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$height_i = \theta_0 + \theta_1 * (\text{Is Female}) + \epsilon_i$$

We get  $\theta_0 = 5.9$  and  $\theta_1 = -0.7$

# Interpreting Dummy Variables

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$height_i = \theta_0 + \theta_1 * (\text{Is Female}) + \epsilon_i$$

We get  $\theta_0 = 5.9$  and  $\theta_1 = -0.7$

$\theta_0$  = Avg height of Male = 5.9

# Interpreting Dummy Variables

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$height_i = \theta_0 + \theta_1 * (\text{Is Female}) + \epsilon_i$$

We get  $\theta_0 = 5.9$  and  $\theta_1 = -0.7$

$\theta_0$  = Avg height of Male = 5.9

$\theta_0 + \theta_1$  is chosen based (equal to) on 5, 5.2, 5.4 (for three records).

# Interpreting Dummy Variables

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$height_i = \theta_0 + \theta_1 * (\text{Is Female}) + \epsilon_i$$

We get  $\theta_0 = 5.9$  and  $\theta_1 = -0.7$

$\theta_0$  = Avg height of Male = 5.9

$\theta_0 + \theta_1$  is chosen based (equal to) on 5, 5.2, 5.4 (for three records).

$\theta_1$  is chosen based on 5-5.9, 5.2-5.9, 5.4-5.9



# Interpreting Dummy Variables

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$height_i = \theta_0 + \theta_1 * (\text{Is Female}) + \epsilon_i$$

We get  $\theta_0 = 5.9$  and  $\theta_1 = -0.7$

$\theta_0$  = Avg height of Male = 5.9

$\theta_0 + \theta_1$  is chosen based (equal to) on 5, 5.2, 5.4 (for three records).

$\theta_1$  is chosen based on  $5-5.9$ ,  $5.2-5.9$ ,  $5.4-5.9$   $\theta_1$  = Avg. female height  $(5+5.2+5.4)/3$  - Avg. male height(5.9)

# Interpreting Dummy Variables

Alternatively, instead of a 0/1 coding scheme, we could create a dummy variable

# Interpreting Dummy Variables

Alternatively, instead of a 0/1 coding scheme, we could create a dummy variable

$$x_i = \begin{cases} 1 & \text{if } i \text{ th person is female} \\ -1 & \text{if } i \text{ th person is male} \end{cases}$$

# Interpreting Dummy Variables

Alternatively, instead of a 0/1 coding scheme, we could create a dummy variable

$$x_i = \begin{cases} 1 & \text{if } i \text{ th person is female} \\ -1 & \text{if } i \text{ th person is male} \end{cases}$$

$$y_i = \theta_0 + \theta_1 x_i + \epsilon_i = \begin{cases} \theta_0 + \theta_1 + \epsilon_i & \text{if } i \text{ th person is female} \\ \theta_0 - \theta_1 + \epsilon_i & \text{if } i \text{ th person is male.} \end{cases}$$

# Interpreting Dummy Variables

Alternatively, instead of a 0/1 coding scheme, we could create a dummy variable

$$x_i = \begin{cases} 1 & \text{if } i \text{ th person is female} \\ -1 & \text{if } i \text{ th person is male} \end{cases}$$

$$y_i = \theta_0 + \theta_1 x_i + \epsilon_i = \begin{cases} \theta_0 + \theta_1 + \epsilon_i & \text{if } i \text{ th person is female} \\ \theta_0 - \theta_1 + \epsilon_i & \text{if } i \text{ th person is male.} \end{cases}$$

Now,  $\theta_0$  can be interpreted as average person height.  $\theta_1$  as the amount that female height is above average and male height is below average.

# Pop Quiz: Linear Regression

1. What is the geometric interpretation of least squares?

# Pop Quiz: Linear Regression

1. What is the geometric interpretation of least squares?

# Pop Quiz: Linear Regression

1. What is the geometric interpretation of least squares?
2. When does the normal equation have a unique solution?



# Pop Quiz: Linear Regression

1. What is the geometric interpretation of least squares?
2. When does the normal equation have a unique solution?

# Pop Quiz: Linear Regression

1. What is the geometric interpretation of least squares?
2. When does the normal equation have a unique solution?
3. How do polynomial features help with non-linear relationships?

# Pop Quiz: Linear Regression

1. What is the geometric interpretation of least squares?
2. When does the normal equation have a unique solution?
3. How do polynomial features help with non-linear relationships?

# Pop Quiz: Linear Regression

1. What is the geometric interpretation of least squares?
2. When does the normal equation have a unique solution?
3. How do polynomial features help with non-linear relationships?
4. What are the assumptions behind linear regression?

# Critical Assumptions of Linear Regression

**Before using linear regression, verify these assumptions:**

- **Linearity:** Relationship between  $x$  and  $y$  is linear

# Critical Assumptions of Linear Regression

**Before using linear regression, verify these assumptions:**

- **Linearity:** Relationship between  $x$  and  $y$  is linear
- **Independence:** Observations are independent of each other

# Critical Assumptions of Linear Regression

**Before using linear regression, verify these assumptions:**

- **Linearity:** Relationship between  $x$  and  $y$  is linear
- **Independence:** Observations are independent of each other
- **Homoscedasticity:** Error variance is constant across all values of  $x$

# Critical Assumptions of Linear Regression

**Before using linear regression, verify these assumptions:**

- **Linearity:** Relationship between  $x$  and  $y$  is linear
- **Independence:** Observations are independent of each other
- **Homoscedasticity:** Error variance is constant across all values of  $x$
- **Normality:** Errors are normally distributed (for inference)



# Critical Assumptions of Linear Regression

**Before using linear regression, verify these assumptions:**

- **Linearity:** Relationship between  $x$  and  $y$  is linear
- **Independence:** Observations are independent of each other
- **Homoscedasticity:** Error variance is constant across all values of  $x$
- **Normality:** Errors are normally distributed (for inference)
- **No Multicollinearity:** Features are not highly correlated

# Critical Assumptions of Linear Regression

**Before using linear regression, verify these assumptions:**

- **Linearity:** Relationship between  $x$  and  $y$  is linear
- **Independence:** Observations are independent of each other
- **Homoscedasticity:** Error variance is constant across all values of  $x$
- **Normality:** Errors are normally distributed (for inference)
- **No Multicollinearity:** Features are not highly correlated

# Critical Assumptions of Linear Regression

**Before using linear regression, verify these assumptions:**

- **Linearity:** Relationship between  $x$  and  $y$  is linear
- **Independence:** Observations are independent of each other
- **Homoscedasticity:** Error variance is constant across all values of  $x$
- **Normality:** Errors are normally distributed (for inference)
- **No Multicollinearity:** Features are not highly correlated

**Violation Consequences:**

- Biased coefficient estimates

# Critical Assumptions of Linear Regression

**Before using linear regression, verify these assumptions:**

- **Linearity:** Relationship between  $x$  and  $y$  is linear
- **Independence:** Observations are independent of each other
- **Homoscedasticity:** Error variance is constant across all values of  $x$
- **Normality:** Errors are normally distributed (for inference)
- **No Multicollinearity:** Features are not highly correlated

**Violation Consequences:**

- Biased coefficient estimates
- Invalid confidence intervals

# Critical Assumptions of Linear Regression

**Before using linear regression, verify these assumptions:**

- **Linearity:** Relationship between  $x$  and  $y$  is linear
- **Independence:** Observations are independent of each other
- **Homoscedasticity:** Error variance is constant across all values of  $x$
- **Normality:** Errors are normally distributed (for inference)
- **No Multicollinearity:** Features are not highly correlated

**Violation Consequences:**

- Biased coefficient estimates
- Invalid confidence intervals
- Poor prediction performance

# Key Takeaways

- **Linear Model:** Assumes linear relationship between features and target

# Key Takeaways

- **Linear Model:** Assumes linear relationship between features and target
- **Least Squares:** Minimizes sum of squared residuals

# Key Takeaways

- **Linear Model:** Assumes linear relationship between features and target
- **Least Squares:** Minimizes sum of squared residuals
- **Normal Equation:** Closed-form solution when  $\mathbf{X}^T \mathbf{X}$  is invertible



# Key Takeaways

- **Linear Model:** Assumes linear relationship between features and target
- **Least Squares:** Minimizes sum of squared residuals
- **Normal Equation:** Closed-form solution when  $\mathbf{X}^T \mathbf{X}$  is invertible
- **Geometric View:** Projection onto column space of design matrix

# Key Takeaways

- **Linear Model:** Assumes linear relationship between features and target
- **Least Squares:** Minimizes sum of squared residuals
- **Normal Equation:** Closed-form solution when  $\mathbf{X}^T \mathbf{X}$  is invertible
- **Geometric View:** Projection onto column space of design matrix
- **Feature Engineering:** Basis expansion enables non-linear modeling

# Key Takeaways

- **Linear Model:** Assumes linear relationship between features and target
- **Least Squares:** Minimizes sum of squared residuals
- **Normal Equation:** Closed-form solution when  $\mathbf{X}^T \mathbf{X}$  is invertible
- **Geometric View:** Projection onto column space of design matrix
- **Feature Engineering:** Basis expansion enables non-linear modeling
- **Foundation:** Building block for more complex models