

Seeing with Algorithms: Introduction to Object Detection

From Pixels to Predictions, and Precision to
Policy

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Why Object Detection Matters

Object Detection helps machines see!

Self-Driving Cars



Self-Driving Cars

Medical Imaging



Medical Imaging

Smart Retail

Smart Checkout

Satellite Analysis

Satellite Analysis

Image Classification

What is Image Classification?

Image Classification Goal

Identify what object is in the image

Image Classification Output

Single class label

Image Classification Question

"What is this?"

Object Detection

What is Object Detection?

Object Detection Goal

Find all objects and their locations

Object Detection Output

Class labels + bounding boxes

Object Detection Question

"What and where?"

Detection Components

What does detection give us?

Component 1: Bounding Box

$$(x_{min}, y_{min}, x_{max}, y_{max})$$

Component 2: Class Label

Dog, Cat, Car, Person

Component 3: Confidence Score

0.0 to 1.0

Detection Example

Real detection output

Class: Dog

Class: Dog

Confidence: 0.87

Confidence: 87%

Bounding Box

(120, 80, 340, 220) pixels

3-Class Detection

3-Class Detection Problem

Class 1: Dog

Dog

Class 2: Bicycle

Bicycle

Class 3: Person

Person

Detection Pipeline

Object Detection Pipeline

Pipeline Input

Single image with unknown objects

Pipeline Processing

Computer vision algorithms

Pipeline Output

List of detected objects + locations

Step 1: Feature Extraction

Feature Extraction

Input Image

416×416×3 pixels

Backbone Network

ResNet, EfficientNet, DarkNet

Feature Maps

Rich representations

Step 2: Detection Predictions

Detection Predictions

Detection Head

YOLO, R-CNN, DETR

Raw Predictions

Bounding boxes + class scores

Step 3: Post-Processing

Post-Processing

Raw Predictions

Thousands of boxes

NMS + Filtering

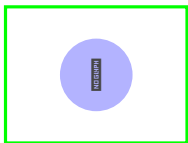
Remove duplicates

Final Detections

Clean results

Understanding Detection Outcomes

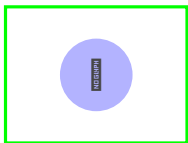
Sample Detection Results



True Positive (TP)
Correctly detected dog

Understanding Detection Outcomes

Sample Detection Results



True Positive (TP)
Correctly detected dog

False Positive: When Models Hallucinate

False Positive Example



False Positive (FP)

Model thinks there's a dog here
but there isn't!

False Positive: When Models Hallucinate

False Positive Example



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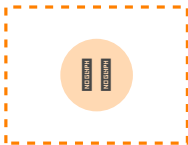


False Positive (FP)

Model thinks there's a dog here
but there isn't!

False Negative: When Models Miss Objects

False Negative Example

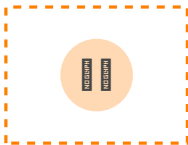


False Negative (FN)

Person exists but model missed it

False Negative: When Models Miss Objects

False Negative Example

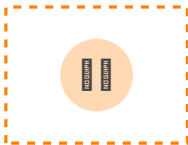


False Negative (FN)

Person exists but model missed it

False Negative: When Models Miss Objects

False Negative Example



False Negative (FN)

Person exists but model missed it

What is Precision?

"Of my detections, how many were correct?"

Precision Formula

$$\frac{TP}{TP + FP}$$

Precision Meaning

Correct ÷ All detections

What is Recall?

"Of all real objects, how many did I find?"

Recall Formula

$$\frac{TP}{TP + FN}$$

Recall Meaning

Found ÷ All real objects

What is IoU?

IoU

IoU Stands For

Intersection over Union

What Does IoU Measure?

How much boxes overlap

IoU Range

0 to 1

Example Setup

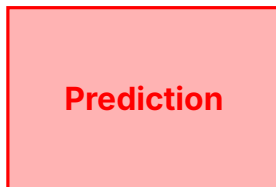
Let's work through an example step by step

Ground Truth Box

Ground Truth

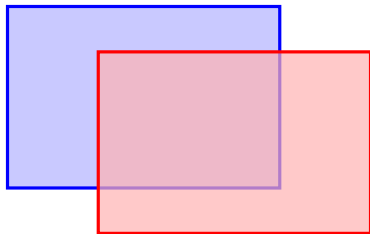
Coordinates
Ground Truth: (1,1) to (4,3)

Prediction Box



Coordinates
Prediction: (2,0.5) to (5,2.5)

Both Boxes Together



Question

Where do they overlap?

Finding Intersection - X Coordinates

Ground Truth X: 1 to 4

Prediction X: 2 to 5

Step 1

Overlap X: from $\max(1,2) = 2$ to $\min(4,5) = 4$

Finding Intersection - Y Coordinates

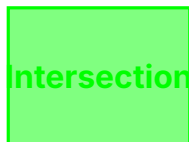
Ground Truth Y: 1 to 3

Prediction Y: 0.5 to 2.5

Step 2

Overlap Y: from $\max(1, 0.5) = 1$ to $\min(3, 2.5) = 2.5$

Intersection Rectangle



Intersection Box

From (2,1) to (4,2.5)

Calculate Intersection Width

$$\text{Width} = 4 - 2 = 2$$

Step 3

Right edge - Left edge = Width

Calculate Intersection Height

$$\text{Height} = 2.5 - 1 = 1.5$$

Step 4

Top edge - Bottom edge = Height

Calculate Intersection Area

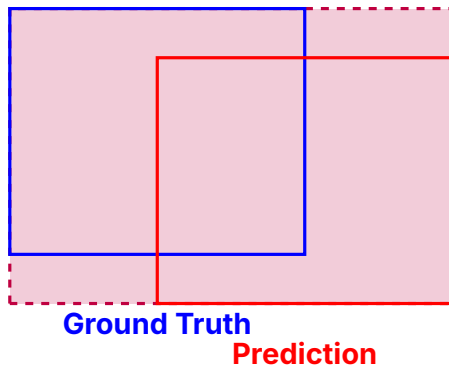
$$\text{Area} = 2 \times 1.5 = 3$$

Step 5

Width \times Height = Area

IoU: Calculating the Union

Union = Total Covered Area



Union = Area1 + Area2 - Intersection

Now Calculate Union

$$\text{Union} = \text{Area1} + \text{Area2} - \text{Intersection}$$

Why Subtract?

We subtract intersection to avoid counting it twice

Ground Truth Area

$$\text{Area1} = 3 \times 2 = 6$$

Step 6

Ground Truth: Width 3, Height 2

Prediction Area

$$\text{Area2} = 3 \times 2 = 6$$

Step 7

Prediction: Width 3, Height 2

Calculate Union

$$\text{Union} = 6 + 6 - 3 = 9$$

Step 8

$$\text{Area1} + \text{Area2} - \text{Intersection} = \text{Union}$$

IoU: The Formula

$$\text{IoU} = \frac{\text{Intersection}}{\text{Union}}$$

Simple Division

Take the overlapping area and divide by the total covered area

Final IoU Calculation

$$\text{IoU} = \frac{3}{9}$$

Step 9

Intersection ÷ Union

Do the Division

$$\frac{3}{9} = 0.33$$

Final Answer

IoU = 0.33 (33

IoU Threshold: 0.5

$$\text{IoU} \geq 0.5$$

Standard Rule

If IoU is 0.5 or higher, we call it a True Positive

IoU Below Threshold

$$\text{IoU} < 0.5$$

False Positive

If IoU is below 0.5, we call it a False Positive

Pop Quiz #1

Quiz #1

Given this detection scenario:

- Ground Truth: 5 dogs in image

What are TP, FP, FN, Precision, and Recall?

Pop Quiz #1

Quiz #1

Given this detection scenario:

- Ground Truth: 5 dogs in image
- Model detections: 8 boxes predicted as "dog"

What are TP, FP, FN, Precision, and Recall?

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Given this detection scenario:

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- 4 detections have $\text{IoU} \geq 0.5$ with ground truth

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What are TP, FP, FN, Precision, and Recall?

A) TP=4, FP=4, FN=1, Precision=0.5, Recall=0.8

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What are TP, FP, FN, Precision, and Recall?

- A) TP=4, FP=4, FN=1, Precision=0.5, Recall=0.8
- B) TP=5, FP=3, FN=0, Precision=0.63, Recall=1.0

Pop Quiz #1

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Given this detection scenario:

- Ground Truth: 5 dogs in image
- Model detections: 8 boxes predicted as "dog"
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- A) TP=4, FP=4, FN=1, Precision=0.5, Recall=0.8
- B) TP=5, FP=3, FN=0, Precision=0.63, Recall=1.0
- C) TP=4, FP=1, FN=4, Precision=0.8, Recall=0.5

Pop Quiz #1

Quiz #1

Given this detection scenario:

- Ground Truth: 5 dogs in image
- Model detections: 8 boxes predicted as "dog"
- 4 detections have IoU ≥ 0.5 with ground truth

What are TP, FP, FN, Precision, and Recall?

- A) TP=4, FP=4, FN=1, Precision=0.5, Recall=0.8
- B) TP=5, FP=3, FN=0, Precision=0.63, Recall=1.0
- C) TP=4, FP=1, FN=4, Precision=0.8, Recall=0.5
- D) TP=8, FP=0, FN=0, Precision=1.0, Recall=1.0

The Answer

A)

Correct Answer

TP=4, FP=4, FN=1, Precision=0.5, Recall=0.8

Step 1: Find TP

$$TP = 4$$

Explanation

4 detections have $\text{IoU} \geq 0.5$ with ground truth

Step 2: Find FP

$$FP = 8 - 4 = 4$$

Explanation

8 total detections - 4 correct = 4 false alarms

Step 3: Find FN

$$FN = 5 - 4 = 1$$

Explanation

5 ground truth dogs - 4 detected = 1 missed

Step 4: Calculate Precision

$$\frac{4}{4+4} = \frac{4}{8} = 0.5$$

Precision Formula

$$TP \div (TP + FP)$$

Step 5: Calculate Recall

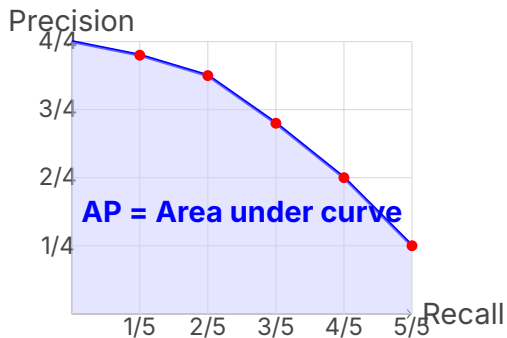
$$\frac{4}{4+1} = \frac{4}{5} = 0.8$$

Recall Formula

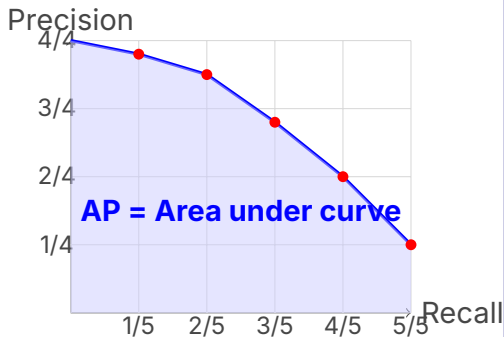
$$TP \div (TP + FN)$$

Precision-Recall Curve

Precision-Recall Curve

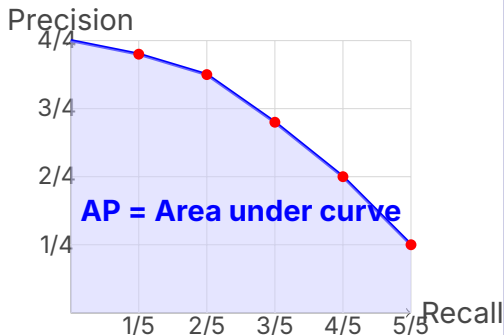


Precision-Recall Curve



PR Curve Interpretation

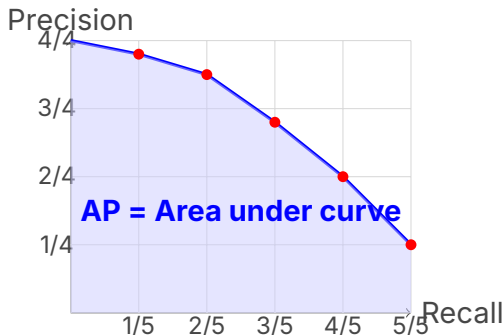
Precision-Recall Curve



PR Curve Interpretation

- **High precision at low recall:**
Easy detections first

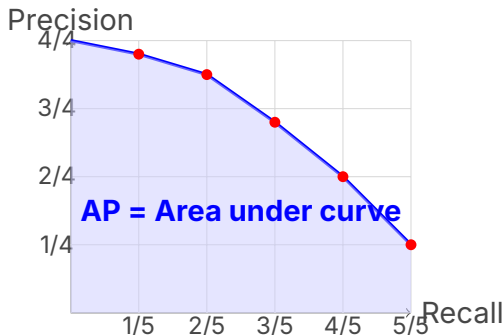
Precision-Recall Curve



PR Curve Interpretation

- **High precision at low recall:**
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- **Curve drops:**
As we include more detections, precision falls

Precision-Recall Curve



PR Curve Interpretation

- **High precision at low recall:**
Easy detections first
- **Curve drops:**
As we include more detections, precision falls
- **Area Under Curve:**
Average Precision (AP)

Computing AP: Step-by-Step Example

Dog Detection Results (Sorted by Confidence)

Detection	Confidence	IoU	TP/FP	Precision	Recall
1	0.95	0.8	TP	1/1 = 1.00	1/3 = 0.33
2	0.89	0.3	FP	1/2 = 0.50	1/3 = 0.33
3	0.76	0.7	TP	2/3 = 0.67	2/3 = 0.67
4	0.65	0.6	TP	3/4 = 0.75	3/3 = 1.00
5	0.43	0.2	FP	3/5 = 0.60	3/3 = 1.00

Key Points

Ground Truth: 3 dogs in image

AP Calculation (using trapezoidal rule):

$$AP = \frac{1}{2}[(1.00 + 0.67) \times 0.34 + (0.67 + 0.75) \times 0.33 + (0.75 + 0.60) \times 0.33] \quad (1)$$

From AP to mAP: Multi-Class Evaluation

3-Class Example: Computing Individual APs

Class	Ground Truth Count	Average Precision (AP)
Dog	12 objects	AP = 0.73
Bicycle	8 objects	AP = 0.65
Person	15 objects	AP = 0.81

Mean Average Precision (mAP)

$$\text{mAP} = \frac{1}{C} \sum_{c=1}^C \text{AP}_c$$

For our example:

$$\text{mAP} = \frac{1}{3}(0.73 + 0.65 + 0.81) = \frac{2.19}{3} = 0.73$$

From AP to mAP: Multi-Class Evaluation

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mAP Variants: @50, @75, @[.5:.95]

mAP@50

IoU threshold = 0.5

mAP@75

IoU threshold = 0.75

mAP@[.5:.95]

Average over IoU 0.5 to 0.95

Example Results Comparison

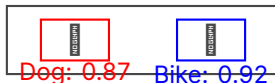
Metric	Value	Interpretation
mAP@50	0.73	Good localization (loose)
mAP@75	0.52	Moderate localization (strict)
mAP@[.5:.95]	0.61	COCO-style evaluation

Class-Agnostic mAP

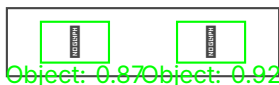
What is Class-Agnostic Detection?

Instead of predicting specific classes, we just ask: **"Is there any object here?"**

Regular Detection



Class-Agnostic Detection



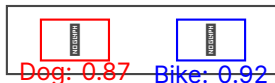
Use Cases for Class-Agnostic mAP

Class-Agnostic mAP

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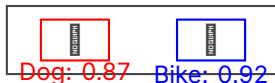
Use Cases for Class-Agnostic mAP

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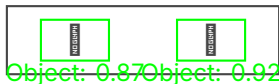
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Class-Agnostic Detection

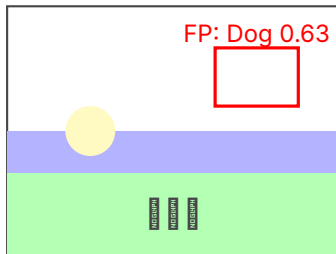


Use Cases for Class-Agnostic mAP

Negative Set Evaluation

Challenge: What about images with NO objects?

Negative Image (No Objects)



Results:

TP = 0 (no ground truth)

FP = 1 (false detection)

FN = 0 (no ground truth)

Precision = $\frac{0}{0+1} = 0$

Recall = undefined

Key Points

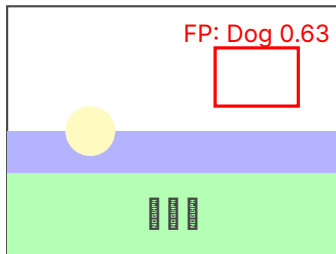
Negative Set Metrics:

False Positive Rate: FP detections per negative

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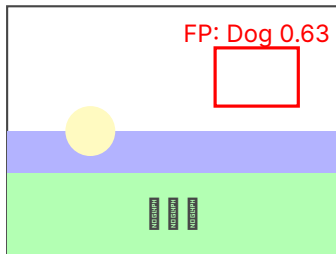
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Key Points

Negative Set Metrics:

False Positive Rate: FP detections per negative

Localization vs Classification Errors

Ground Truth



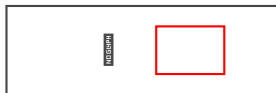
Dog

Classification Error



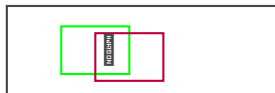
Cat (IoU=0.8)

Localization Error



Dog (IoU=0.3)

Duplicate Detection



Dog 0.9
Dog 0.7

Error Types

- **Localization Error:** Right class, wrong location (IoU < threshold)

Localization vs Classification Errors

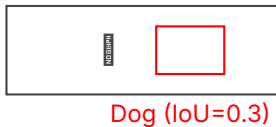
Ground Truth



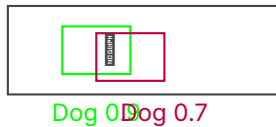
Classification Error



Localization Error



Duplicate Detection



Error Types

- **Localization Error:** Right class, wrong location ($\text{IoU} < \text{threshold}$)
- **Classification Error:** Right location, wrong class

Localization vs Classification Errors

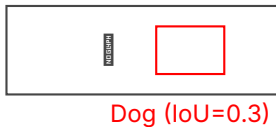
Ground Truth



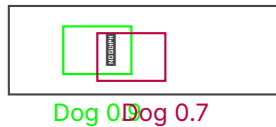
Classification Error



Localization Error



Duplicate Detection



Error Types

- **Localization Error:** Right class, wrong location (IoU < threshold)
- **Classification Error:** Right location, wrong class
- **Duplicate Detection:** Multiple boxes for same

Pop Quiz #2

Quiz #2

You have a dataset with:

- 100 images total

Your model detects:

What is the Precision and Recall for the Dog class?

Pop Quiz #2

Quiz #2

You have a dataset with:

- 100 images total
- 50 images with dogs (300 dog instances total)

Your model detects:

What is the Precision and Recall for the Dog class?

Pop Quiz #2

Quiz #2

You have a dataset with:

- 100 images total
- 50 images with dogs (300 dog instances total)
- 50 negative images (no objects)

Your model detects:

What is the Precision and Recall for the Dog class?

Pop Quiz #2

Quiz #2

You have a dataset with:

- 100 images total
- 50 images with dogs (300 dog instances total)
- 50 negative images (no objects)

Your model detects:

- 250 dogs correctly ($\text{IoU} \geq 0.5$)

What is the Precision and Recall for the Dog class?

Pop Quiz #2

Quiz #2

You have a dataset with:

- 100 images total
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Your model detects:

- 250 dogs correctly ($\text{IoU} \geq 0.5$)
- 30 false positive dogs in positive images

What is the Precision and Recall for the Dog class?

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Your model detects:

- 250 dogs correctly ($\text{IoU} \geq 0.5$)
- 30 false positive dogs in positive images
- 20 false positive dogs in negative images

What is the Precision and Recall for the Dog class?

Pop Quiz #2

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Your model detects:

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- 30 false positive dogs in positive images
- 20 false positive dogs in negative images

What is the Precision and Recall for the Dog class?

A) Precision=0.83, Recall=0.83

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- 30 false positive dogs in positive images
- 20 false positive dogs in negative images

What is the Precision and Recall for the Dog class?

A) Precision=0.83, Recall=0.83

B) Precision=0.89, Recall=0.75

Pop Quiz #2

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You have a dataset with:

- 100 images total
- 50 images with dogs (300 dog instances total)
- 50 negative images (no objects)

Your model detects:

- 250 dogs correctly ($\text{IoU} \geq 0.5$)
- 30 false positive dogs in positive images
- 20 false positive dogs in negative images

What is the Precision and Recall for the Dog class?

A) Precision=0.83, Recall=0.83

B) Precision=0.89, Recall=0.75

Pop Quiz #2 - Answer

Answer: A) Precision=0.83, Recall=0.83

Step-by-Step Calculation

Given:

- TP = 250 (correctly detected dogs)

Calculations:

$$\text{Precision} = \frac{\text{TP}}{\text{TP} + \text{FP}} = \frac{250}{250 + 50} = \frac{250}{300} = 0.83 \quad (3)$$

$$\text{Recall} = \frac{\text{TP}}{\text{TP} + \text{FN}} = \frac{250}{250 + 50} = \frac{250}{300} = 0.83 \quad (4)$$

Pop Quiz #2 - Answer

Answer: A) Precision=0.83, Recall=0.83

Step-by-Step Calculation

Given:

- TP = 250 (correctly detected dogs)
- FP = 30 + 20 = 50 (false positives in positive + negative images)

Calculations:

$$\text{Precision} = \frac{\text{TP}}{\text{TP} + \text{FP}} = \frac{250}{250 + 50} = \frac{250}{300} = 0.83 \quad (3)$$

$$\text{Recall} = \frac{\text{TP}}{\text{TP} + \text{FN}} = \frac{250}{250 + 50} = \frac{250}{300} = 0.83 \quad (4)$$

Pop Quiz #2 - Answer

Answer: A) Precision=0.83, Recall=0.83

Step-by-Step Calculation

Given:

- TP = 250 (correctly detected dogs)
- FP = 30 + 20 = 50 (false positives in positive + negative images)
- FN = 300 - 250 = 50 (ground truth dogs - detected dogs)

Calculations:

$$\text{Precision} = \frac{\text{TP}}{\text{TP} + \text{FP}} = \frac{250}{250 + 50} = \frac{250}{300} = 0.83 \quad (3)$$

$$\text{Recall} = \frac{\text{TP}}{\text{TP} + \text{FN}} = \frac{250}{250 + 50} = \frac{250}{300} = 0.83 \quad (4)$$

What is AP?

AP

Average Precision

One Class

AP measures performance for one single class

What is mAP?

mAP

Mean Average Precision

All Classes

mAP is the average of AP across all classes

mAP Example Setup

Let's calculate mAP for 3 classes

AP for Dogs

$$\text{AP}_{\text{dogs}} = 0.8$$

Given

Dog class achieved 80

AP for Cats

$$\text{AP_cats} = 0.6$$

Given
Cat class achieved 60

$$\text{AP_cars} = 0.9$$

Given

Car class achieved 90

Add Them Up

$$0.8 + 0.6 + 0.9 = 2.3$$

Step 1

Sum all the AP values

Divide by Number of Classes

$$\frac{2.3}{3} = 0.77$$

Final Answer

mAP = 0.77 (77

mAP@50

mAP@50

Standard Evaluation

Uses IoU threshold of 0.5

Specialized mAP Variants

Class-Agnostic mAP

Ignores class labels

Just asks: "Is there an object?"

Useful for weakly supervised learning

Size-Specific mAP

Separate evaluation for

small, medium, large objects

COCO provides mAP_S, mAP_M, mAP_L

That's It!

Key Point

Object detection uses mAP to measure performance

Detection Fundamentals: Key Takeaways

Object Detection = Classification + Localization

mAP is the gold standard for model comparison

IoU thresholds matter - stricter = lower scores

Negative images crucial for real deployment

Context matters - choose metrics for your use case

Remember

Perfect metrics don't guarantee perfect real-world performance. Always test in your target domain!

Real-World Considerations

Beyond the Metrics

Perfect mAP doesn't guarantee perfect real-world performance!

Real-World Considerations

Beyond the Metrics

Perfect mAP doesn't guarantee perfect real-world performance!

Model Selection

Real-World Considerations

Beyond the Metrics

Perfect mAP doesn't guarantee perfect real-world performance!

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- **Speed vs Accuracy:** YOLOv8 vs R-CNN

Real-World Considerations

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- **Speed vs Accuracy:** YOLOv8 vs R-CNN
- **Memory constraints:** Mobile deployment

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- **Speed vs Accuracy:** YOLOv8 vs R-CNN
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Deployment Issues

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- **Domain shift:**
Training vs real data

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- **Speed vs Accuracy:** YOLOv8 vs R-CNN
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- **Domain shift:** Training vs real data
- **Edge cases:** Unusual lighting, angles

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Perfect mAP doesn't guarantee perfect real-world performance!

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- **Speed vs Accuracy:** YOLOv8 vs R-CNN
- **Memory constraints:** Mobile deployment
- **Class imbalance:** Rare vs common

Deployment Issues

- **Domain shift:** Training vs real data
- **Edge cases:** Unusual lighting, angles
- **Ethical considerations:** Bias, privacy

Demo Time & Further Reading

Try These Demos!

- YOLOv8 Demo:
<https://docs.ultralytics.com/>

Essential Papers

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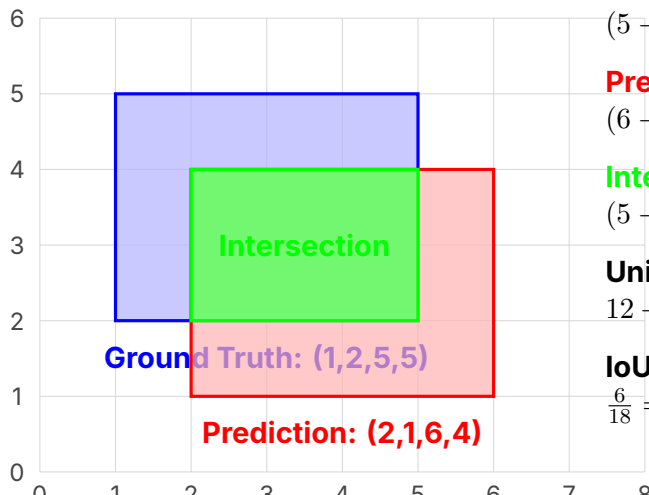
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Complete IoU Calculation Example



Ground Truth: (1,2,5,5)

Prediction: (2,1,6,4)

Step-by-Step Calculation

Ground Truth Area:

$$(5 - 1) \times (5 - 2) = 12$$

Prediction Area:

$$(6 - 2) \times (4 - 1) = 12$$

Intersection Area:

$$(5 - 2) \times (4 - 2) = 6$$

Union Area:

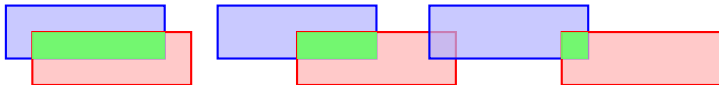
$$12 + 12 - 6 = 18$$

IoU:

$$\frac{6}{18} = 0.333$$

Multiple IoU Examples with Different Overlaps

High IoU = 0.8 Medium IoU = 0.4 Low IoU = 0.1



Intersection=1.25, Union=1.5 Intersection=0.75, Union=1.75 Intersection=0.25, Union=2.75

No Overlap IoU = 0



Perfect IoU = 1.0



Intersection=0, Union=6 Identical boxes

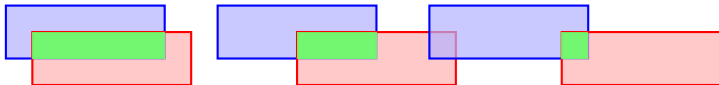
Key Points

Key Insights:

- **$\text{IoU} \geq 0.5$** : Generally considered good localization

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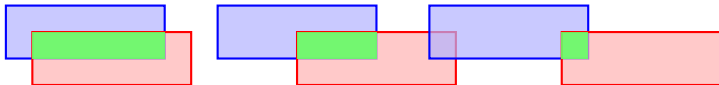
Key Points

Key Insights:

- **IoU ≥ 0.5 :** Generally considered good localization
- **IoU ≥ 0.7 :** High-quality detection

Multiple IoU Examples with Different Overlaps

High IoU = 0.8 Medium IoU = 0.4 Low IoU = 0.1



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Perfect IoU = 1.0



Intersection=0, Union=6 Identical boxes

Key Points

Key Insights:

- **$\text{IoU} \geq 0.5$** : Generally considered good localization
- **$\text{IoU} \geq 0.7$** : High-quality detection
- **$\text{IoU} = 1.0$** : Perfect alignment (rare in practice)

Comprehensive Precision-Recall Example

Scenario: Dog Detection in 5 Images

Ground Truth: 8 dogs total across all images

Model Predictions: 12 detections sorted by confidence

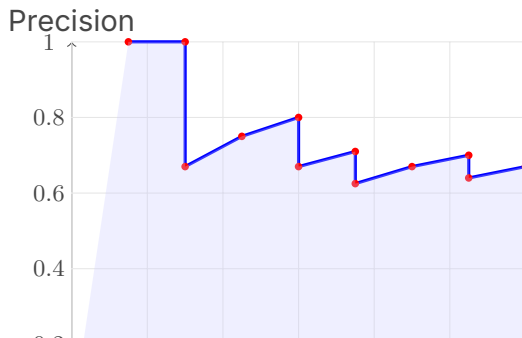
Det	Conf	IoU	TP/FP	Cum TP	Cum FP	Precision	Re
1	0.95	0.9	TP	1	0	1.0	0.125
2	0.9	0.85	TP	2	0	1.0	0.25
3	0.85	0.8	FP	2	1	0.667	0.375
4	0.8	0.75	FP	2	2	0.5	0.5
5	0.75	0.7	FP	2	3	0.4	0.625
6	0.7	0.65	FP	2	4	0.333	0.75
7	0.65	0.6	FP	2	5	0.286	0.875
8	0.6	0.55	FP	2	6	0.25	1.0
9	0.55	0.5	FP	2	7	0.222	1.0
10	0.5	0.45	FP	2	8	0.2	1.0
11	0.45	0.4	FP	2	9	0.182	1.0
12	0.4	0.35	FP	2	10	0.167	1.0

Cumulative Calculations

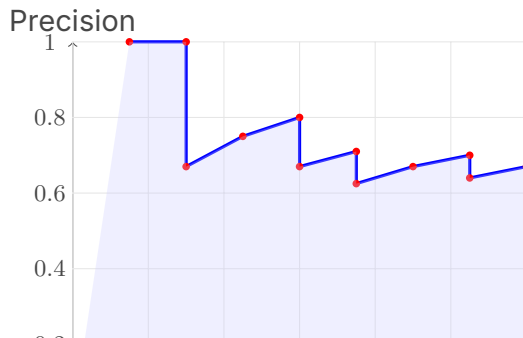
Cumulative TP: Running count of true positives (IoU

Plotting the Precision-Recall Curve

Plotting the Precision-Recall Curve



Plotting the Precision-Recall Curve



AP Calculation

Using trapezoidal rule:

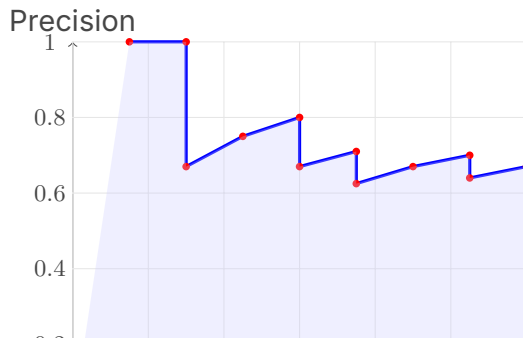
$$AP = \sum_i \frac{1}{2} (P_i + P_{i+1}) \times \Delta R_i \quad (5)$$

Result: $AP \approx 0.74$

Key Points

Observations:

Plotting the Precision-Recall Curve



AP Calculation

Using trapezoidal rule:

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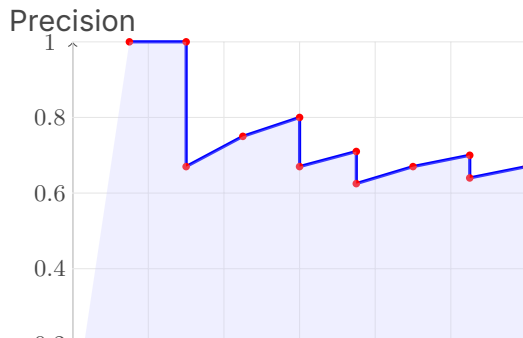
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Key Points

Observations:

- High precision at low recall

Plotting the Precision-Recall Curve



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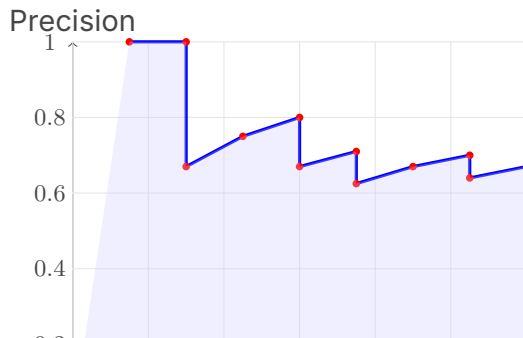
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Key Points

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Multi-Class mAP Calculation Detailed Example

3-Class Detection Results

Dataset: 100 images with Dogs, Cats, and Cars

Class 1: Dogs	Class 2: Cats	Class 3: Cars
Ground Truth: 45 objects	Ground Truth: 38 objects	Ground Truth: 17 objects
AP = 0.82	AP = 0.76	AP = 0.89

mAP Calculation:

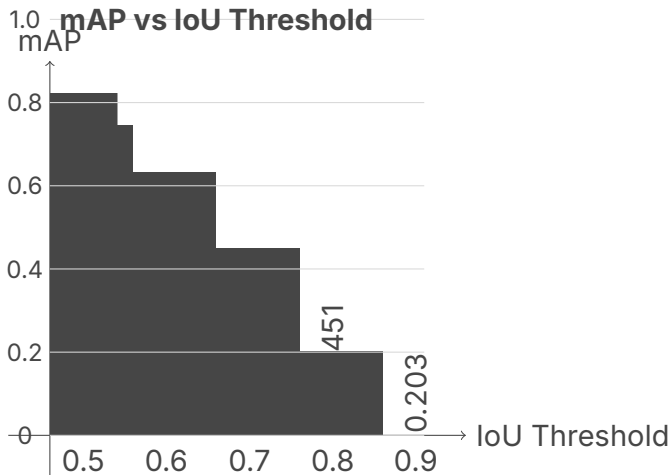
$$\text{mAP} = \frac{1}{3}(\text{AP}_{\text{Dogs}} + \text{AP}_{\text{Cats}} + \text{AP}_{\text{Cars}})$$

$$\text{mAP} = \frac{1}{3}(0.82 + 0.76 + 0.89) = \frac{2.47}{3} = 0.823$$

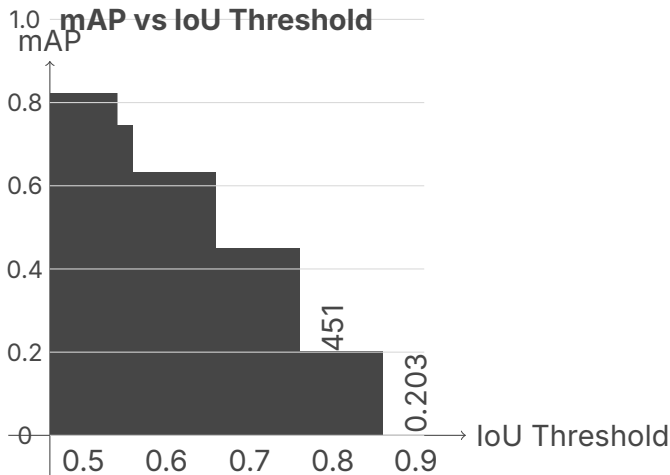
Class-wise Performance Analysis:

- **Cars (AP=0.89):** Best performing class - likely larger, more distinct
- **Dogs (AP=0.82):** Good performance - varied poses but distinct

mAP@Different IoU Thresholds: Complete Analysis

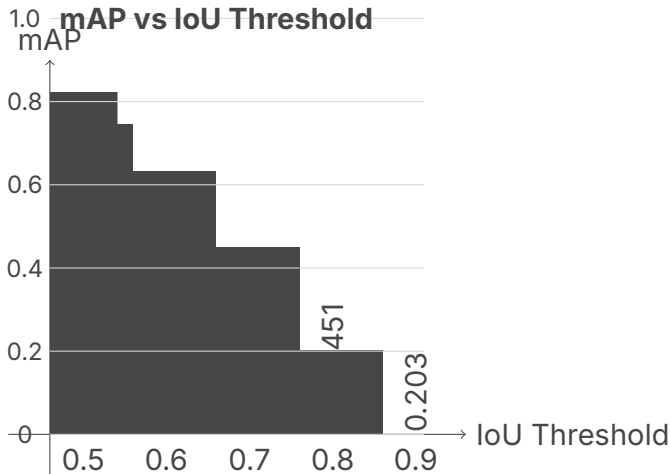


mAP@Different IoU Thresholds: Complete Analysis



mAP@[.5:.95] Calculation

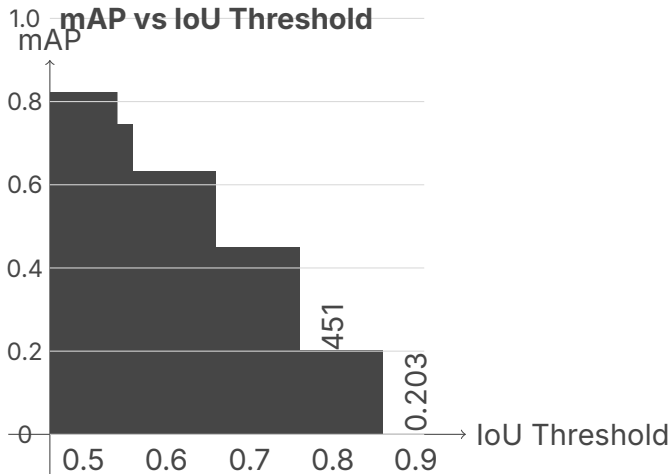
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mAP@[.5:.95] Calculation

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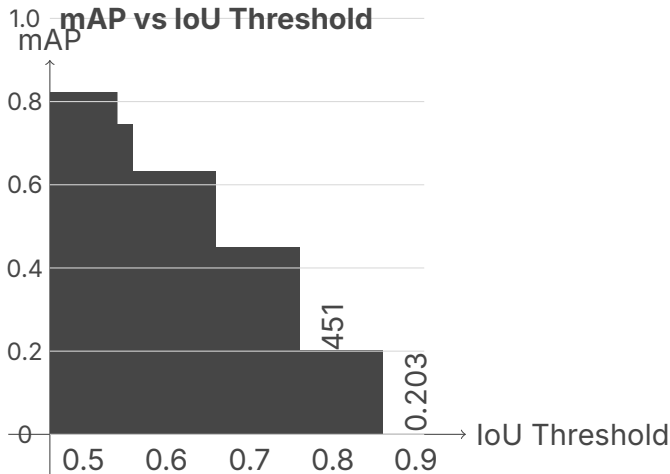
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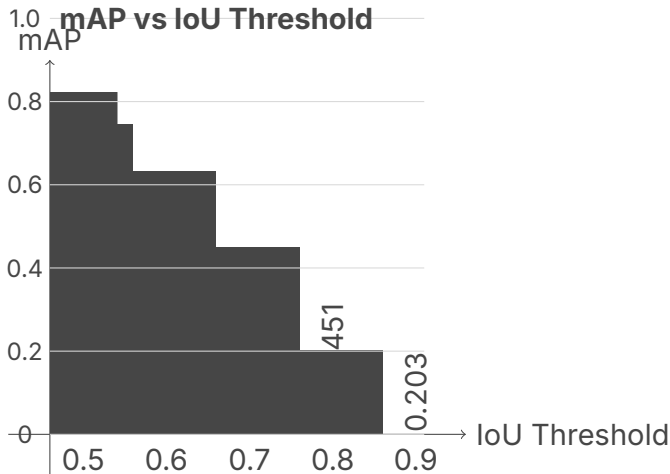
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Key Insights

mAP@Different IoU Thresholds: Complete Analysis



mAP@[.5:.95] Calculation

Key Insights

Pop Quiz #3: Advanced mAP Calculation

Quiz #3

You're evaluating a 2-class detector (Cat, Dog) on a dataset:

Cat Class Results:

- Ground truth: 20 cats

Dog Class Results:

Pop Quiz #3: Advanced mAP Calculation

Quiz #3

You're evaluating a 2-class detector (Cat, Dog) on a dataset:

Cat Class Results:

- Ground truth: 20 cats
- Detections: 15 correct ($\text{IoU} \geq 0.5$), 8 false positives

Dog Class Results:

Pop Quiz #3: Advanced mAP Calculation

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- Ground truth: 30 dogs

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- Ground truth: 30 dogs
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Dog Class Results:

- Ground truth: 30 dogs
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- Detections: 25 correct ($\text{IoU} \geq 0.5$), 5 false positives
- $\text{AP@0.5} = 0.83$

Pop Quiz #3 - Answer

Answer: A) mAP = 0.79, Dog has better precision (0.83 > 0.65)

Step-by-Step Solution

1. Calculate mAP:

$$\text{mAP} = \frac{\text{AP}_{\text{Cat}} + \text{AP}_{\text{Dog}}}{2} = \frac{0.75 + 0.83}{2} = 0.79$$

2. Calculate Precision for each class:

- **Cat Precision:** $\frac{15}{15+8} = \frac{15}{23} = 0.65$

3. Compare: Dog class has higher precision (0.83 > 0.65)

Key Points

Pop Quiz #3 - Answer

Answer: A) mAP = 0.79, Dog has better precision (0.83 > 0.65)

Step-by-Step Solution

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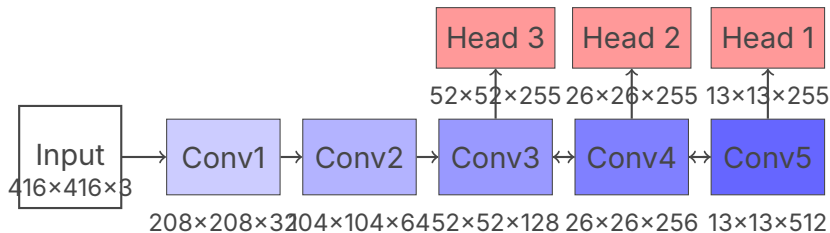
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3. Compare: Dog class has higher precision (0.83 > 0.65)

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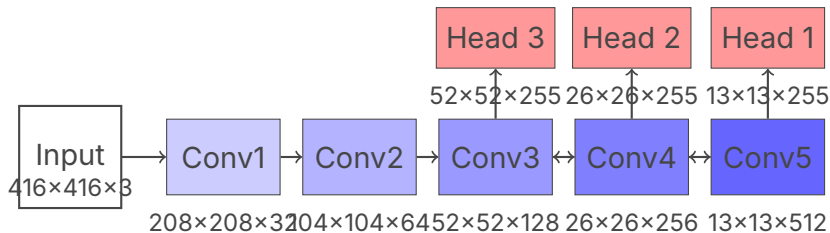
YOLO Architecture Deep Dive



YOLO Key Features

- **Single Shot:** One forward pass for detection

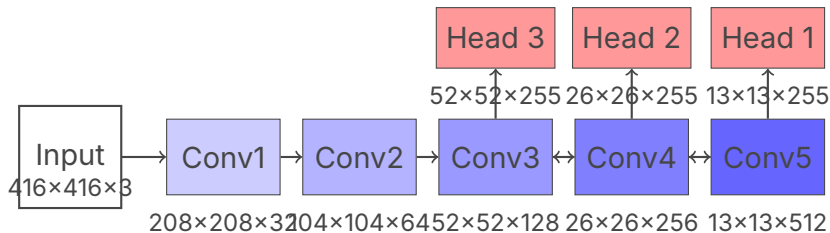
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- **Single Shot:** One forward pass for detection
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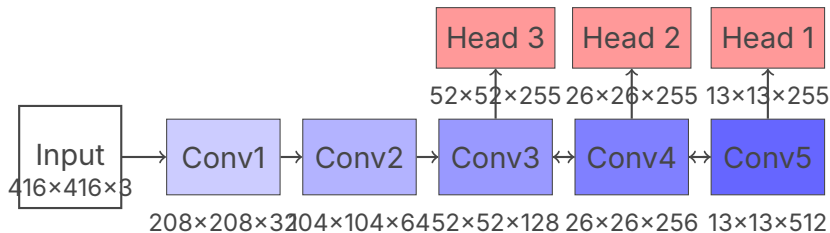
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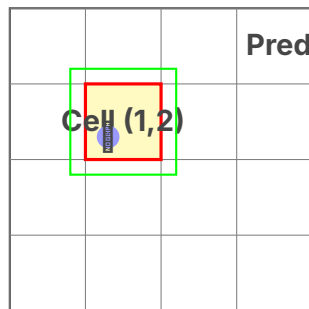
YOLO Architecture Deep Dive



YOLO Key Features

- **Single Shot:** One forward pass for detection
- **Multi-Scale:** 3 detection heads for different object sizes
- **Anchor-based:** Predefined anchor boxes for each grid cell
- **255 channels:** $(4 + 1 + 80) \times 3 = 255$ (bbox + conf)

YOLO Prediction Format Explained



Anchor 1: $[t_x, t_y, t_w, t_h, conf, p_1, p_2, \dots, p_{80}]$
Anchor 2: $[t_x, t_y, t_w, t_h, conf, p_1, p_2, \dots, p_{80}]$
Anchor 3: $[t_x, t_y, t_w, t_h, conf, p_1, p_2, \dots, p_{80}]$

Where:

t_x, t_y : Box center offsets

t_w, t_h : Box width/height

$conf$: Objectness confidence

p_i : Class probabilities

Decoding YOLO Predictions

$$b_x = \sigma(t_x) + c_x \quad (6)$$

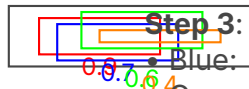
$$b_y = \sigma(t_y) + c_y \quad (7)$$

Non-Maximum Suppression (NMS) Detailed

Step 1: Sort by confidence

Red (0.9) > Blue (0.7) > Green (0.6) > Orange (0.4)

Before NMS **Step 2:** Pick Highest Confidence (Red)



Step 3: Remove boxes with IoU > threshold

- Blue: $\text{IoU}(\text{Red}, \text{Blue}) = 0.6 > 0.5 \rightarrow \text{Remove}$

- Green: $\text{IoU}(\text{Red}, \text{Green}) = 0.4 < 0.5 \rightarrow \text{Keep}$

- Orange: $\text{IoU}(\text{Red}, \text{Orange}) = 0.3 < 0.5 \rightarrow \text{Keep}$

After NMS



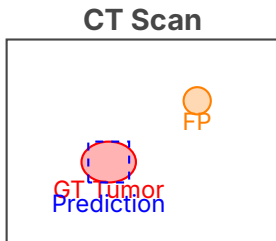
Step 4: Repeat with remaining boxes

NMS Parameters

IoU Threshold: Typically 0.5 (higher = more suppression)

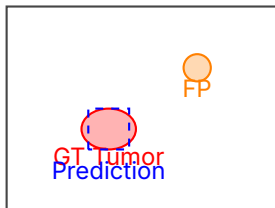
Case Study 1: Medical Imaging - Tumor Detection

Case Study 1: Medical Imaging - Tumor Detection



Case Study 1: Medical Imaging - Tumor Detection

CT Scan



Results Analysis

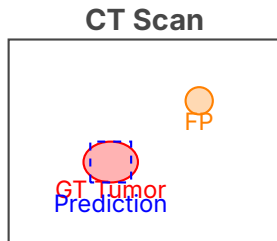
Challenge: High precision needed

IoU: 0.65 (good localization)

Issue: False positive rate too high

Medical Considerations

Case Study 1: Medical Imaging - Tumor Detection



Results Analysis

Challenge: High precision needed

IoU: 0.65 (good localization)

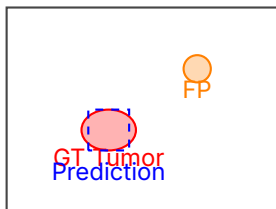
Issue: False positive rate too high

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- **High Recall** crucial (can't miss tumors)

Case Study 1: Medical Imaging - Tumor Detection

CT Scan



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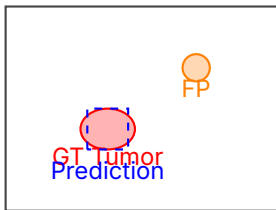
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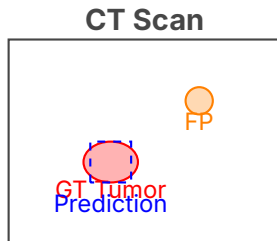
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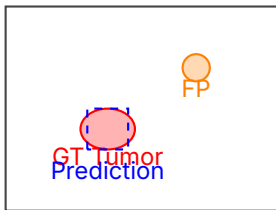
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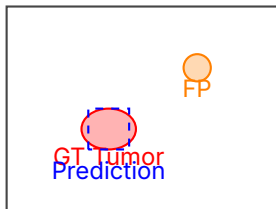
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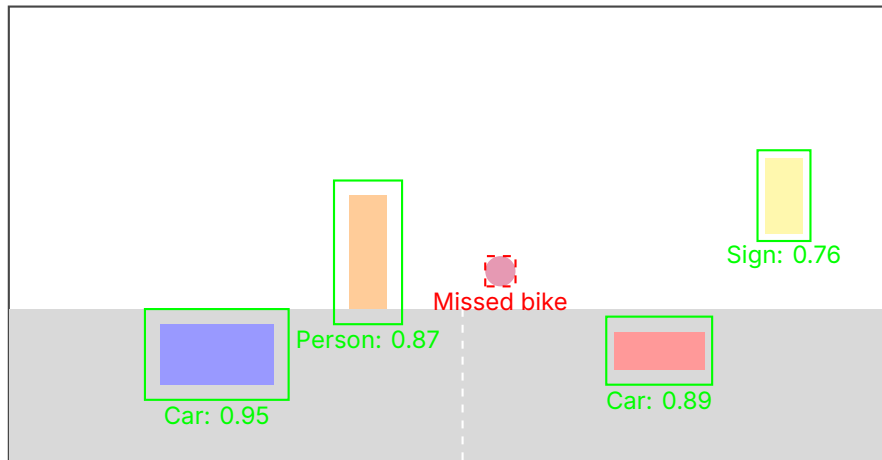
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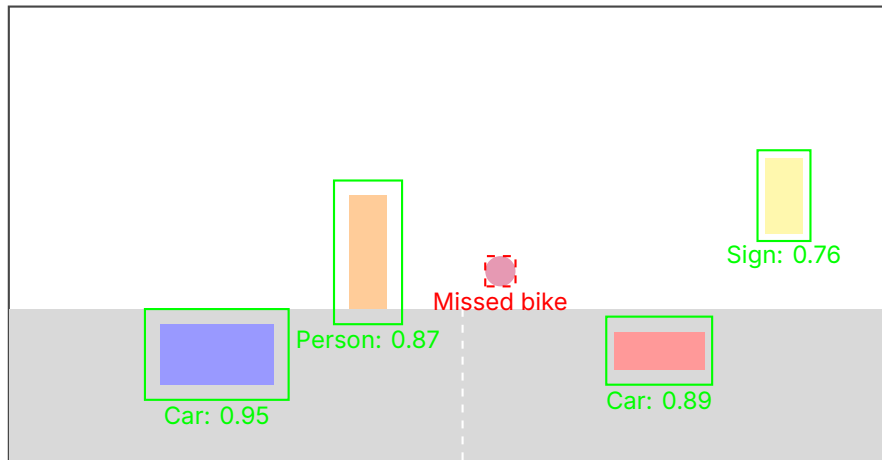
Case Study 2: Autonomous Driving - Multi-Object Scene

Autonomous Vehicle Camera View



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