Lasso Regression

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Lasso Regression

- LASSO \longrightarrow Least absolute shrinkage and selection operator
- Popular as it leads to a sparse solution.

Constructing the Objective Function

• Find a θ_{opt} such that

$$heta_{\mathsf{opt}} = rg \min_{oldsymbol{ heta}} (\mathbf{y} - \mathbf{X} oldsymbol{ heta})^\mathsf{T} (\mathbf{y} - \mathbf{X} oldsymbol{ heta}) : ||oldsymbol{ heta}||_1 < oldsymbol{s}$$
 (1)

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 (1)

Using KKT conditions

$$\theta_{\text{opt}} = \underbrace{\arg\min_{\boldsymbol{\theta}} (\mathbf{y} - \mathbf{X}\boldsymbol{\theta})^{\mathsf{T}} (\mathbf{y} - \mathbf{X}\boldsymbol{\theta}) + \delta^{2} ||\boldsymbol{\theta}||_{1}}_{\text{convex function}}$$
(2)

Solving the Objective

• Since $||\theta||_1$ is not differentiable, we cannot solve,

$$\frac{\partial (\mathbf{y} - \mathbf{X}\boldsymbol{\theta})^{\mathsf{T}} (\mathbf{y} - \mathbf{X}\boldsymbol{\theta}) + \delta^{2} ||\boldsymbol{\theta}||_{1}}{\partial \boldsymbol{\theta}} = 0$$
 (3)

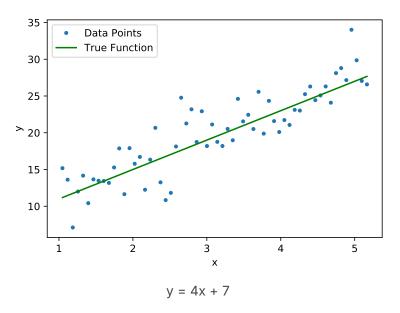
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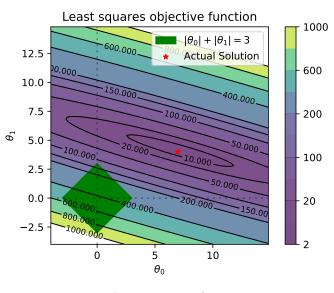
$$\frac{\partial (\mathbf{y} - \mathbf{X}\boldsymbol{\theta})^{\mathsf{T}} (\mathbf{y} - \mathbf{X}\boldsymbol{\theta}) + \delta^{2} ||\boldsymbol{\theta}||_{1}}{\partial \boldsymbol{\theta}} = 0$$
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How to Solve? Use coordinate descent!

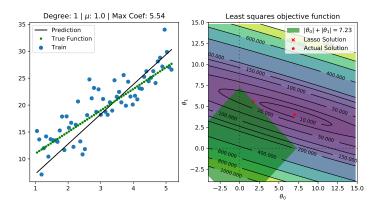
Sample Dataset



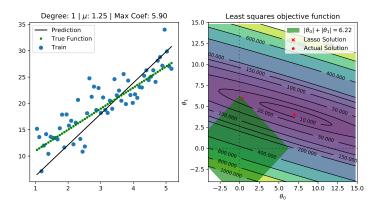
Geometric Interpretation



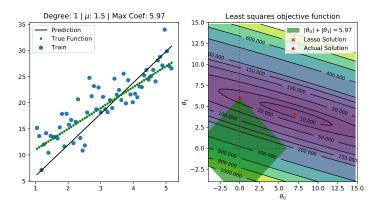
Lasso regression



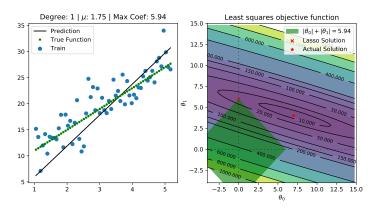
 $\mu = 1.0 \label{eq:mu}$ (on the Sample Dataset)



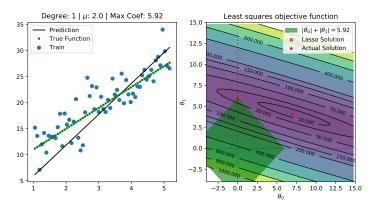
 $\mu = 1.25 \label{eq:mu}$ (on the Sample Dataset)



 $\mu = 1.5 \label{eq:mu}$ (on the Sample Dataset)



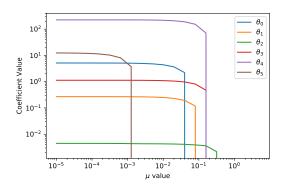
 $\mu = 1.75 \label{eq:mu}$ (on the Sample Dataset)



 $\mu = 2.0 \label{eq:mu}$ (on the Sample Dataset)

width=!,height=!,page=-

Regularization path of lasso regression



Regularization path of θ_i

LASSO and feature selection

· LASSO inherently does feature selection!

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- Sets coefficients of "less important" features to zero.

LASSO and feature selection

- LASSO inherently does feature selection!
- Sets coefficients of "less important" features to zero.
- Sparse and memory efficient and often more interpretable models.

Subgradient

Generalises gradient to convex but non-differentiable problems

Subgradient

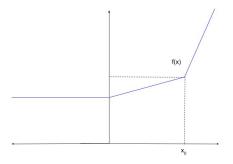
- Generalises gradient to convex but non-differentiable problems
- Examples:

Subgradient

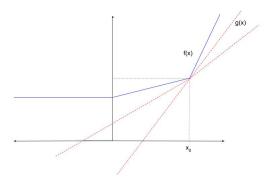
- Generalises gradient to convex but non-differentiable problems
- · Examples:
 - f(x) = |x|

Task at hand

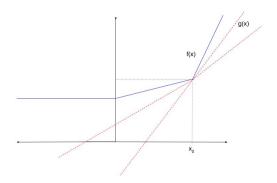
• TASK: find derivative of f(x) at $x = x_0$



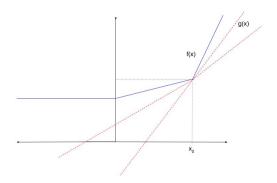
• Construct a differentiable g(x)



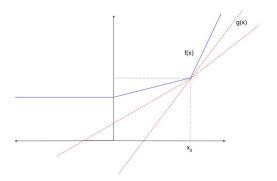
- Construct a differentiable g(x)
 - Intersecting f(x) at $x = x_0$



- Construct a differentiable g(x)
 - Intersecting f(x) at $x = x_0$
 - Below or on f(x) for all x

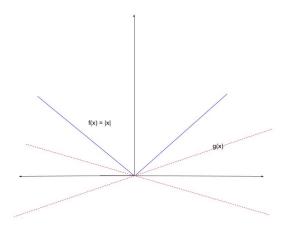


• Compute slope of g(x) at $x = x_0$



Another Example: f(x) = |x|

• Subgradient of f(x) belongs to [-1, 1]



Another optimisation method (akin to gradient descent)

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- Another optimisation method (akin to gradient descent)
- Objective: $\min_{\theta} f(\theta)$
- Key idea: Sometimes difficult to find minimum for all coordinates
- · ..., but, easy for each coordinate
- turns into a one-dimensional optimisation problem

Picking next coordinate:

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- Picking next coordinate: random, round-robin
- No step-size to choose!

Coordinate Descent

- Picking next coordinate: random, round-robin
- No step-size to choose!
- · Converges for Lasso objective

Learn $y = \theta_0 + \theta_1 x$ on following dataset, using coordinate descent where initially $(\theta_0, \theta_1) = (2, 3)$ for 2 iterations.

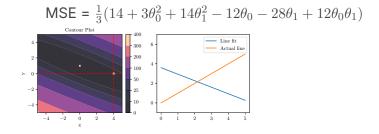
У
1
2
3

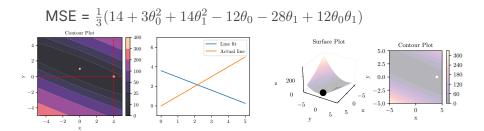
Our predictor,
$$\hat{y} = \theta_0 + \theta_1 x$$

Error for
$$i^{th}$$
 datapoint, $\epsilon_i = y_i - \hat{y}_i$
 $\epsilon_1 = 1 - \theta_0 - \theta_1$
 $\epsilon_2 = 2 - \theta_0 - 2\theta_1$
 $\epsilon_3 = 3 - \theta_0 - 3\theta_1$

$$MSE = \frac{\epsilon_1^2 + \epsilon_2^2 + \epsilon_3^2}{3} = \frac{14 + 3\theta_0^2 + 14\theta_1^2 - 12\theta_0 - 28\theta_1 + 12\theta_0\theta_1}{3}$$

$$\mathsf{MSE} = \tfrac{1}{3}(14 + 3\theta_0^2 + 14\theta_1^2 - 12\theta_0 - 28\theta_1 + 12\theta_0\theta_1)$$





Iteration 1

INIT: $\theta_0 = 2$ and $\theta_1 = 3$

 $\theta_1=3$ optimize for θ_0

Iteration 1

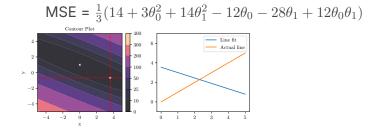
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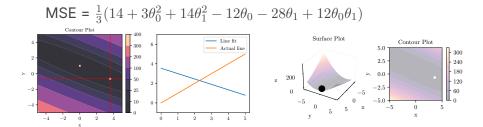
 $\theta_1=3$ optimize for θ_0

$$\frac{\partial \, \mathrm{MSE}}{\partial \theta_0} = 6\theta_0 + 24 = 0$$

$$\theta_0 = -4$$

$$\mathsf{MSE} = \tfrac{1}{3}(14 + 3\theta_0^2 + 14\theta_1^2 - 12\theta_0 - 28\theta_1 + 12\theta_0\theta_1)$$





INIT:
$$\theta_0 = -4$$
 and $\theta_1 = 3$

$$\theta_0 = -4$$
 optimize for θ_1

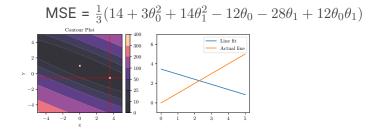
Iteration 2

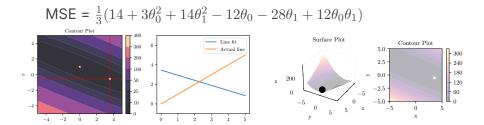
INIT: $\theta_0 = -4$ and $\theta_1 = 3$

 $\theta_0 = -4$ optimize for θ_1

 $\theta_1 = 2.7$

$$\mathsf{MSE} = \frac{1}{3}(14 + 3\theta_0^2 + 14\theta_1^2 - 12\theta_0 - 28\theta_1 + 12\theta_0\theta_1)$$





Iteration 3

INIT: $\theta_0 = -4$ and $\theta_1 = 2.7$

 $\theta_1=2.7$ optimize for θ_0

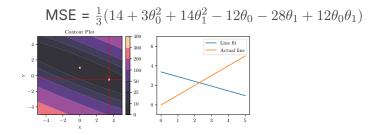
Iteration 3

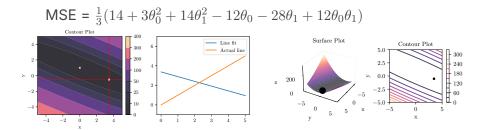
INIT: $\theta_0 = -4$ and $\theta_1 = 2.7$

 $\theta_1=2.7$ optimize for θ_0

$$\theta_0 = -3.4$$

$$\mathsf{MSE} = \frac{1}{3}(14 + 3\theta_0^2 + 14\theta_1^2 - 12\theta_0 - 28\theta_1 + 12\theta_0\theta_1)$$





• Express error as a difference of y_i and $\hat{y_i}$

$$\hat{y}_i = \sum_{j=0}^d \theta_j x_i^j = \theta_0 x_i^0 + \theta_1 x_i^1 + \theta_2 x_i^2 + \ldots + \theta_d x_i^d$$
 (4)

$$\epsilon_i = y_i - \hat{y}_i = y_i - \theta_0 x_i^0 - \theta_1 x_i^1 - \dots - \theta_d x_i^d = y_i - \sum_{j=0}^d \theta_j x_j^j$$
 (5)

$$\sum_{i=1}^{n} \epsilon^{2} = RSS = \sum_{i=1}^{n} \left(y_{i} - \left(\theta_{0} \mathbf{x}_{i}^{0} + \ldots + \theta_{j} \mathbf{x}_{i}^{j} + \theta_{d} \mathbf{x}_{i}^{d} \right) \right)^{2}$$

$$\sum_{i=1}^{n} \epsilon^{2} = RSS = \sum_{i=1}^{n} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \ldots + \theta_{j} x_{i}^{j} + \theta_{d} x_{i}^{d} \right) \right)^{2}$$
$$\frac{\partial RSS \left(\theta_{j} \right)}{\partial \theta_{j}} = 2 \sum_{i=1}^{n} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \ldots + \theta_{j} x_{i}^{j} + \ldots \right) \right) \left(-x_{i}^{j} \right)$$

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$$= 2 \sum_{i=1}^{n} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \ldots + \theta_{d} x_{i}^{d} \right) \right) \left(-x_{i}^{j} \right) + 2 \sum_{i=1}^{n} \theta_{j} (x_{i}^{j})^{2}$$

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where:

$$\hat{\mathbf{y}_i}^{(-j)} = \theta_0 \mathbf{x}_i^0 + \ldots + \theta_d \mathbf{x}_i^d$$

is \hat{y}_i without θ_j

$$\operatorname{Set} \frac{\partial \operatorname{RSS} \left(\theta_{j} \right)}{\partial \theta_{j}} = 0$$

$$\theta_{j} = \sum_{i=1}^{n} \frac{\left(y_{i} - \left(\theta_{0} \boldsymbol{x}_{i}^{0} + \ldots + \theta_{d} \boldsymbol{x}_{i}^{d} \right) \right) \left(\boldsymbol{x}_{i}^{j} \right)}{\left(\boldsymbol{x}_{i}^{j} \right)^{2}} = \frac{\rho_{j}}{z_{j}}$$

$$\rho_{j} = \sum_{i=1}^{n} \boldsymbol{x}_{i}^{j} \left(y_{i} - \hat{\boldsymbol{y}}_{i}^{(-j)} \right) \quad \text{and} \quad z_{j} = \sum_{i=1}^{n} \left(\boldsymbol{x}_{i}^{j} \right)^{2}$$

 z_j is the squared of ℓ_2 norm of the j^{th} feature

$$\begin{split} & \text{Minimise} \underbrace{\sum_{i=1}^{n} \epsilon^2 + \delta^2 \left\{ |\theta_0| + |\theta_1| + \dots \left| \theta_j \right| + \dots \left| \theta_d \right| \right\}}_{\text{LASSO OBJECTIVE}} \\ & \frac{\partial}{\partial \theta_j} (\text{LASSO OBJECTIVE}) = -2\rho_j + 2\theta_j \mathbf{Z}_j + \delta^2 \frac{\partial}{\partial \theta_j} \left| \theta_j \right| \\ & \frac{\partial}{\partial \theta_j} \left| \theta_j \right| = \left\{ \begin{array}{cc} 1 & \theta_j > 0 \\ [-1,1] & \theta_j = 0 \\ -1 & \theta_i < 0 \end{array} \right. \end{split}$$

• Case 1:
$$\theta_j > 0$$

$$-2\rho_j + 2\theta_j \mathbf{Z}_j + \delta^2 = 0$$

$$\theta_j = \frac{\rho_j - \frac{\delta^2}{2}}{\mathbf{Z}_j}$$

$$\rho_j > \frac{\delta^2}{2} \Rightarrow \theta_j = \frac{\rho_j - \frac{\delta^2}{2}}{\mathbf{Z}_i}$$

• Case 1: $\theta_j>0$ $-2\rho_j+2\theta_j\mathbf{Z}_j+\delta^2=0$ $\theta_j=\frac{\rho_j-\frac{\delta^2}{2}}{\mathbf{Z}_j}$

$$\rho_j > \frac{\delta^2}{2} \Rightarrow \theta_j = \frac{\rho_j - \frac{\delta^2}{2}}{\mathsf{z}_j}$$

• Case 2: $\theta_{i} < 0$

$$\rho_j < \frac{\delta^2}{2} \Rightarrow \theta_j = \frac{\rho_j + \delta^2/2}{z_j} \tag{6}$$

• Case 3: $\theta_i = 0$

$$\frac{\partial}{\partial \theta_j}(\text{LASSO OBJECTIVE}) = -2\rho_j + 2\theta_j \mathbf{z}_j + \delta^2 \underbrace{\frac{\partial}{\partial \theta_j} \left|\theta_j\right|}_{\text{[-1,1]}}$$

$$\in \underbrace{[-2\rho_j - \delta^2, -2\rho_j + \delta^2]}_{\{0\} \text{ lies in this range}}$$

$$-2\rho_j - \delta^2 \leq 0 \text{ and } -2\rho_j + \delta^2 \geq 0$$

$$-\frac{\delta^2}{2} \leq \rho_j \leq \frac{\delta^2}{2} \Rightarrow \theta_j = 0$$

Summary of Lasso Regression

$$\theta_{j} = \begin{bmatrix} \frac{\rho_{j} + \frac{\delta^{2}}{2}}{z_{j}} & \text{if} & \rho_{j} < -\frac{\delta^{2}}{2} \\ 0 & \text{if} & -\frac{\delta^{2}}{2} \leq \rho_{j} \leq \frac{\delta^{2}}{2} \\ \frac{\rho_{j} - \frac{\delta^{2}}{2}}{z_{j}} & \text{if} & \rho_{j} > \frac{\delta^{2}}{2} \end{bmatrix}$$

$$(7)$$