Nipun Batra and the teaching staff

July 17, 2025

IIT Gandhinagar

Setup

 $\bullet~\textsc{O/P}$ is continuous in nature.

- O/P is continuous in nature.
- Examples of linear systems:

- O/P is continuous in nature.
- Examples of linear systems:
 - *F* = *ma*

- O/P is continuous in nature.
- Examples of linear systems:
 - *F* = *ma*
 - v = u + at

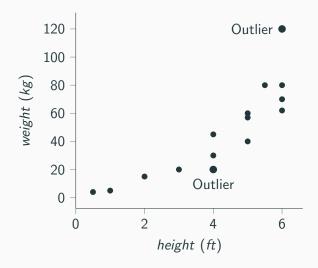
Task at hand

• TASK: Predict Weight = f(height)

Height	Weight
3	29
4	35
5	39
2	20
6	41
7	?
8	?
1	?

The first part of the dataset are the training points. The latter ones are testing points.

Scatter Plot



- $weight_1 \approx \theta_0 + \theta_1 * height_1$
- $weight_2 \approx \theta_0 + \theta_1 * height_2$
- $weight_N \approx \theta_0 + \theta_1 * height_N$

- $weight_1 \approx \theta_0 + \theta_1 * height_1$
- $weight_2 \approx \theta_0 + \theta_1 * height_2$
- $weight_N \approx \theta_0 + \theta_1 * height_N$

weight_i
$$\approx \theta_0 + \theta_1 * height_i$$

$$\begin{bmatrix} weight_1 \\ weight_2 \\ \dots \\ weight_N \end{bmatrix} = \begin{bmatrix} 1 & height_1 \\ 1 & height_2 \\ \dots & \dots \\ 1 & height_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$

$$\begin{bmatrix} weight_1 \\ weight_2 \\ \dots \\ weight_N \end{bmatrix} = \begin{bmatrix} 1 & height_1 \\ 1 & height_2 \\ \dots & \dots \\ 1 & height_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$

$$W_{N\times 1}=X_{N\times 2}\theta_{2\times 1}$$

$$\begin{bmatrix} weight_1 \\ weight_2 \\ \dots \\ weight_N \end{bmatrix} = \begin{bmatrix} 1 & height_1 \\ 1 & height_2 \\ \dots & \dots \\ 1 & height_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$

$$W_{N\times 1}=X_{N\times 2}\theta_{2\times 1}$$

ullet $heta_0$ - Bias Term/Intercept Term

$$\begin{bmatrix} weight_1 \\ weight_2 \\ \dots \\ weight_N \end{bmatrix} = \begin{bmatrix} 1 & height_1 \\ 1 & height_2 \\ \dots & \dots \\ 1 & height_N \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$

$$W_{N\times 1}=X_{N\times 2}\theta_{2\times 1}$$

- ullet $heta_0$ Bias Term/Intercept Term
- θ_1 Slope

In the previous example y = f(x), where x is one-dimensional.

In the previous example y=f(x), where x is one-dimensional. Examples in multiple dimensions.

In the previous example y = f(x), where x is one-dimensional.

Examples in multiple dimensions.

One example is to predict the water demand of the IITGN campus

In the previous example y = f(x), where x is one-dimensional.

Examples in multiple dimensions.

One example is to predict the water demand of the IITGN campus

Demand = f(# occupants, Temperature)

In the previous example y = f(x), where x is one-dimensional.

Examples in multiple dimensions.

One example is to predict the water demand of the IITGN campus

Demand = f(# occupants, Temperature)

 $\mathsf{Demand} = \mathsf{Base} \ \mathsf{Demand} + \mathit{K}_1 \ \text{*} \ \# \ \mathsf{occupants} + \mathit{K}_2 \ \text{*} \ \mathsf{Temperature}$

6

Intuition

We hope to:

- Learn f: Demand = f(#occupants, Temperature)
- From training dataset
- To predict the condition for the testing set

•
$$x_i = \begin{bmatrix} Temperature_i \\ \#Occupants_i \end{bmatrix}$$

We have

•
$$x_i = \begin{bmatrix} Temperature_i \\ \#Occupants_i \end{bmatrix}$$

• Estimated demand for i^{th} sample is

• Estimated demand for i^{th} sample is $de\hat{mand}_i = \theta_0 + \theta_1 Temperature_i + \theta_2 Occupants_i$

•
$$x_i = \begin{bmatrix} Temperature_i \\ \#Occupants_i \end{bmatrix}$$

- Estimated demand for i^{th} sample is $demand_i = \theta_0 + \theta_1 Temperature_i + \theta_2 Occupants_i$
- $demand_i = x_i'^T \theta$

•
$$x_i = \begin{bmatrix} Temperature_i \\ \#Occupants_i \end{bmatrix}$$

- Estimated demand for i^{th} sample is $de\hat{mand}_i = \theta_0 + \theta_1 Temperature_i + \theta_2 Occupants_i$
- ullet where $heta=egin{bmatrix} heta_0 \ heta_1 \ heta_2 \end{bmatrix}$

•
$$x_i = \begin{bmatrix} Temperature_i \\ \#Occupants_i \end{bmatrix}$$

- Estimated demand for i^{th} sample is $de\hat{mand}_i = \theta_0 + \theta_1 Temperature_i + \theta_2 Occupants_i$
- $demand_i = x_i'^T \theta$

$$ullet$$
 where $heta=egin{bmatrix} heta_0 \ heta_1 \ heta_2 \end{bmatrix}$

• and
$$x_i' = \begin{bmatrix} 1 \\ Temperature_i \\ \#Occupants_i \end{bmatrix} = \begin{bmatrix} 1 \\ x_i \end{bmatrix}$$

We have

•
$$x_i = \begin{bmatrix} Temperature_i \\ \#Occupants_i \end{bmatrix}$$

- Estimated demand for i^{th} sample is $de\hat{mand}_i = \theta_0 + \theta_1 Temperature_i + \theta_2 Occupants_i$
- $demand_i = x_i'^T \theta$
- ullet where $heta=egin{bmatrix} heta_0 \ heta_1 \ heta_2 \end{bmatrix}$

• and
$$x_i' = \begin{bmatrix} 1 \\ Temperature_i \\ \#Occupants_i \end{bmatrix} = \begin{bmatrix} 1 \\ x_i \end{bmatrix}$$

 Notice the transpose in the equation! This is because x_i is a column vector

We can expect the following

ullet Demand increases, if # occupants increases, then $heta_2$ is likely to be positive

We can expect the following

- Demand increases, if # occupants increases, then θ_2 is likely to be positive
- \bullet Demand increases, if temperature increases, then θ_1 is likely to be positive

We can expect the following

- Demand increases, if # occupants increases, then θ_2 is likely to be positive
- \bullet Demand increases, if temperature increases, then θ_1 is likely to be positive
- Base demand is independent of the temperature and the # occupants, but, likely positive, thus θ_0 is likely positive.

Normal Equation

• Assuming *N* samples for training

- Assuming *N* samples for training
- # Features = M

- Assuming *N* samples for training
- # Features = M

- Assuming N samples for training
- # Features = M

$$\begin{bmatrix} \hat{y_1} \\ \hat{y_2} \\ \vdots \\ \hat{y_N} \end{bmatrix}_{N \times 1} = \begin{bmatrix} 1 & x_{1,1} & x_{1,2} & \dots & x_{1,M} \\ 1 & x_{2,1} & x_{2,2} & \dots & x_{2,M} \\ \vdots & \vdots & \vdots & \dots & \vdots \\ 1 & x_{N,1} & x_{N,2} & \dots & x_{N,M} \end{bmatrix}_{N \times (M+1)} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_M \end{bmatrix}_{(M+1) \times 1}$$

- Assuming N samples for training
- # Features = M

$$\begin{bmatrix} \hat{y_1} \\ \hat{y_2} \\ \vdots \\ \hat{y_N} \end{bmatrix}_{N \times 1} = \begin{bmatrix} 1 & x_{1,1} & x_{1,2} & \dots & x_{1,M} \\ 1 & x_{2,1} & x_{2,2} & \dots & x_{2,M} \\ \vdots & \vdots & \vdots & \dots & \vdots \\ 1 & x_{N,1} & x_{N,2} & \dots & x_{N,M} \end{bmatrix}_{N \times (M+1)} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_M \end{bmatrix}_{(M+1) \times 1}$$

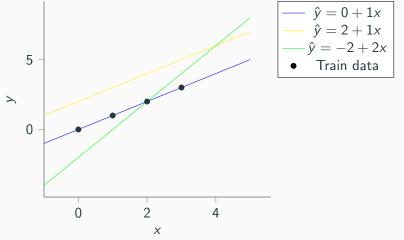
$$\hat{Y} = X\theta$$

Relationships between feature and target variables

- There could be different $\theta_0, \theta_1 \dots \theta_M$. Each of them can represents a relationship.
- Given multiples values of $\theta_0, \theta_1 \dots \theta_M$ how to choose which is the best?
- Let us consider an example in 2d

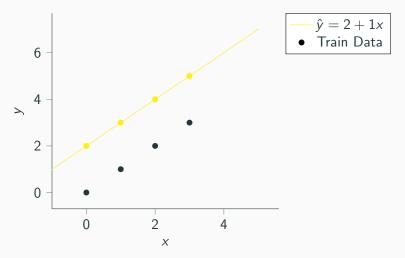
Relationships between feature and target variables

Out of the three fits, which one do we choose?



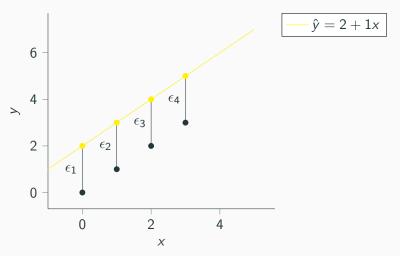
Relationships between feature and target variables

We have $\hat{y} = 2 + 1x$ as one relationship.



Relationships between feature and target variables

How far is our estimated \hat{y} from ground truth y?



•
$$y_i = \hat{y_i} + \epsilon_i$$
 where $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$

- $y_i = \hat{y}_i + \epsilon_i$ where $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- y_i denotes the ground truth for i^{th} sample

- $y_i = \hat{y}_i + \epsilon_i$ where $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- y_i denotes the ground truth for i^{th} sample
- $\hat{y_i}$ denotes the prediction for i^{th} sample, where $\hat{y_i} = x_i'^T \theta$

- $y_i = \hat{y}_i + \epsilon_i$ where $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- y_i denotes the ground truth for i^{th} sample
- $\hat{y_i}$ denotes the prediction for i^{th} sample, where $\hat{y_i} = x_i^{\prime T} \theta$
- ullet ϵ_i denotes the error/residual for i^{th} sample

- $y_i = \hat{y}_i + \epsilon_i$ where $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- y_i denotes the ground truth for i^{th} sample
- $\hat{y_i}$ denotes the prediction for i^{th} sample, where $\hat{y_i} = x_i'^T \theta$
- ϵ_i denotes the error/residual for i^{th} sample
- θ_0, θ_1 : The parameters of the linear regression

- $y_i = \hat{y}_i + \epsilon_i$ where $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- y_i denotes the ground truth for i^{th} sample
- $\hat{y_i}$ denotes the prediction for i^{th} sample, where $\hat{y_i} = x_i'^T \theta$
- ϵ_i denotes the error/residual for i^{th} sample
- θ_0, θ_1 : The parameters of the linear regression
- $\bullet \ \epsilon_i = y_i \hat{y}_i$

- $y_i = \hat{y}_i + \epsilon_i$ where $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- y_i denotes the ground truth for i^{th} sample
- $\hat{y_i}$ denotes the prediction for i^{th} sample, where $\hat{y_i} = x_i^{\prime T} \theta$
- ullet ϵ_i denotes the error/residual for i^{th} sample
- θ_0, θ_1 : The parameters of the linear regression
- $\bullet \ \epsilon_i = y_i \hat{y}_i$
- $\bullet \ \epsilon_i = y_i (\theta_0 + x_i \times \theta_1)$

Good fit

 $\bullet \ |\epsilon_1|, \ |\epsilon_2|, \ |\epsilon_3|, \ \dots \ \mbox{should be small}.$

Good fit

- $|\epsilon_1|$, $|\epsilon_2|$, $|\epsilon_3|$, ... should be small.
- ullet minimize $\epsilon_1^2+\epsilon_2^2+\cdots+\epsilon_N^2$ L_2 Norm

Good fit

- $|\epsilon_1|$, $|\epsilon_2|$, $|\epsilon_3|$, ... should be small.
- minimize $\epsilon_1^2 + \epsilon_2^2 + \cdots + \epsilon_N^2$ L_2 Norm
- minimize $|\epsilon_1| + |\epsilon_2| + \cdots + |\epsilon_n|$ L_1 Norm

$$Y = X\theta + \epsilon$$

$$Y = X\theta + \epsilon$$

To Learn: θ

$$Y = X\theta + \epsilon$$

To Learn: θ

Objective: minimize $\epsilon_1^2 + \epsilon_2^2 + \cdots + \epsilon_N^2$

$$\epsilon = \begin{bmatrix} \epsilon_1 \\ \epsilon_1 \\ \vdots \\ \epsilon_N \end{bmatrix}$$

$$\epsilon = \begin{bmatrix} \epsilon_1 \\ \epsilon_1 \\ \vdots \\ \epsilon_N \end{bmatrix}$$

Objective: Minimize $\epsilon^T \epsilon$

Derivation of Normal Equation

$$\epsilon = y - X\theta$$

$$\epsilon^{T} = (y - X\theta)^{T} = y^{T} - \theta^{T}X^{T}$$

$$\epsilon^{T}\epsilon = (y^{T} - \theta^{T}X^{T})(y - X\theta)$$

$$= y^{T}y - \theta^{T}X^{T}y - y^{T}X\theta + \theta^{T}X^{T}X\theta$$

$$= y^{T}y - 2y^{T}X\theta + \theta^{T}X^{T}X\theta$$

This is what we wish to minimize

Minimizing the objective function

$$\frac{\partial \epsilon^T \epsilon}{\partial \theta} = 0 \tag{1}$$

$$\bullet \ \frac{\partial}{\partial \theta} y^T y = 0$$

•
$$\frac{\partial}{\partial \theta} (-2y^T X \theta) = (-2y^T X)^T = -2X^T y$$

•
$$\frac{\partial}{\partial \theta} (\theta^T X^T X \theta) = 2X^T X \theta$$

Substitute the values in the top equation

Normal Equation derivation

$$0 = -2X^T y + 2X^T X \theta$$

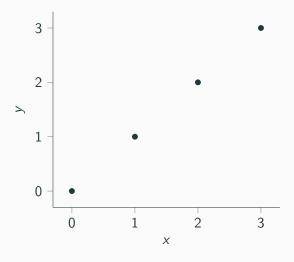
$$X^T y = X^T X \theta$$

$$\hat{\theta}_{OLS} = (X^T X)^{-1} X^T y$$

X	У
0	0
1	1
2	2
3	3

Given the data above, find θ_0 and θ_1 .

Scatter Plot



$$X = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix}$$

$$X^{T} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{bmatrix}$$

$$X^{T}X = \begin{bmatrix} 4 & 6 \\ 6 & 14 \end{bmatrix}$$
(2)

Given the data above, find θ_0 and θ_1 .

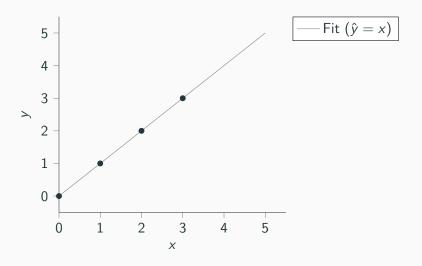
$$(X^{T}X)^{-1} = \frac{1}{20} \begin{bmatrix} 14 & -6 \\ -6 & 4 \end{bmatrix}$$

$$X^{T}y = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 6 \\ 14 \end{bmatrix}$$
(3)

$$\theta = (X^T X)^{-1} (X^T y)$$

$$\begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} = \frac{1}{20} \begin{bmatrix} 14 & -6 \\ -6 & 4 \end{bmatrix} \begin{bmatrix} 6 \\ 14 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$
(4)

Scatter Plot

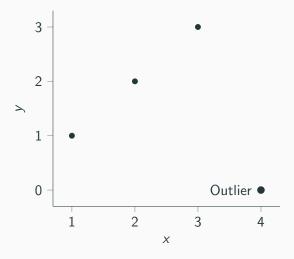


Effect of outlier

X	У
1	1
2	2
3	3
4	0

Compute the θ_0 and θ_1 .

Scatter Plot



$$X = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix}$$

$$X^{T} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$

$$X^{T}X = \begin{bmatrix} 4 & 10 \\ 10 & 30 \end{bmatrix}$$
(5)

Given the data above, find θ_0 and θ_1 .

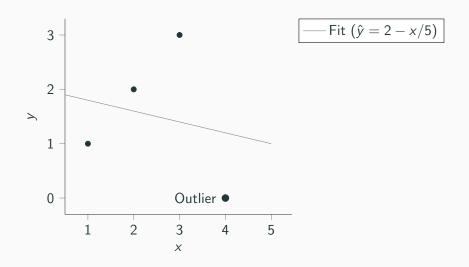
$$(X^{T}X)^{-1} = \frac{1}{20} \begin{bmatrix} 30 & -10 \\ -10 & 4 \end{bmatrix}$$

$$X^{T}y = \begin{bmatrix} 6 \\ 14 \end{bmatrix}$$
(6)

$$\theta = (X^T X)^{-1} (X^T y)$$

$$\begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} = \begin{bmatrix} 2 \\ (-1/5) \end{bmatrix}$$
(7)

Scatter Plot



Basis Expansion

Variable Transformation

Transform the data, by including the higher power terms in the feature space.

t	S
0	0
1	6
3	24
4	36

The above table represents the data before transformation

Add the higher degree features to the previous table

t	t ²	S
0	0	0
1	1	6
3	9	24
4	16	36

Add the higher degree features to the previous table

t	t ²	S
0	0	0
1	1	6
3	9	24
4	16	36

The above table represents the data after transformation

Add the higher degree features to the previous table

t	t ²	S
0	0	0
1	1	6
3	9	24
4	16	36

The above table represents the data after transformation Now, we can write $\hat{s}=f(t,t^2)$

Add the higher degree features to the previous table

t	t ²	S
0	0	0
1	1	6
3	9	24
4	16	36

The above table represents the data after transformation Now, we can write $\hat{s} = f(t, t^2)$

Other transformations: $log(x), x_1 \times x_2$

1.
$$\hat{s} = \theta_0 + \theta_1 * t$$
 is linear

¹https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression

- 1. $\hat{s} = \theta_0 + \theta_1 * t$ is linear
- 2. Is $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$ linear?

¹https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression

- 1. $\hat{s} = \theta_0 + \theta_1 * t$ is linear
- 2. Is $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$ linear?
- 3. Is $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2 + \theta_3 * \cos(t^3)$ linear?

¹https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression

- 1. $\hat{s} = \theta_0 + \theta_1 * t$ is linear
- 2. Is $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$ linear?
- 3. Is $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2 + \theta_3 * \cos(t^3)$ linear?
- 4. Is $\hat{s} = \theta_0 + \theta_1 * t + e^{\theta_2} * t$ linear?

¹https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression

- 1. $\hat{s} = \theta_0 + \theta_1 * t$ is linear
- 2. Is $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$ linear?
- 3. Is $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2 + \theta_3 * \cos(t^3)$ linear?
- 4. Is $\hat{s} = \theta_0 + \theta_1 * t + e^{\theta_2} * t$ linear?
- 5. All except #4 are linear models!

¹https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression

- 1. $\hat{s} = \theta_0 + \theta_1 * t$ is linear
- 2. Is $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2$ linear?
- 3. Is $\hat{s} = \theta_0 + \theta_1 * t + \theta_2 * t^2 + \theta_3 * \cos(t^3)$ linear?
- 4. Is $\hat{s} = \theta_0 + \theta_1 * t + e^{\theta_2} * t$ linear?
- 5. All except #4 are linear models!
- 6. Linear refers to the relationship between the parameters that you are estimating (θ) and the outcome

¹https://stats.stackexchange.com/questions/8689/what-does-linear-stand-for-in-linear-regression

Basis Functions

- Linear regression only refers to linear in the parameters
- We can perform an arbitrary nonlinear transformation $\phi(x)$ of the inputs x and then linearly combine the components of this transformation.
- $\phi: \mathbb{R}^D \to \mathbb{R}^K$ is called the basis function

Basis Functions

Some examples of basis functions:

- Polynomial basis: $\phi(x) = \{1, x, x^2, x^3, \dots\}$
- Fourier basis: $\phi(x) = \{1, \sin(x), \cos(x), \sin(2x), \cos(2x), \dots\}$
- Gaussian basis: $\phi(x) = \{1, \exp(-\frac{(x-\mu_1)^2}{2\sigma^2}), \exp(-\frac{(x-\mu_2)^2}{2\sigma^2}), \dots\}$
- Sigmoid basis: $\phi(x)=\{1,\sigma(x-\mu_1),\sigma(x-\mu_2),\dots\}$ where $\sigma(x)=\frac{1}{1+e^{-x}}$

Linear Combination of Vectors

Let $v_1, v_2, v_3, \dots, v_i$ be vectors in \mathbb{R}^D , where D denotes the dimensions.

Linear Combination of Vectors

Let $v_1, v_2, v_3, \ldots, v_i$ be vectors in \mathbb{R}^D , where D denotes the dimensions.

A linear combination of $v_1, v_2, v_3, \ldots, v_i$ is of the following form

Linear Combination of Vectors

Let $v_1, v_2, v_3, \ldots, v_i$ be vectors in \mathbb{R}^D , where D denotes the dimensions.

A linear combination of $v_1, v_2, v_3, \ldots, v_i$ is of the following form

$$\alpha_1 v_1 + \alpha_2 v_2 + \alpha_3 v_3 + \cdots + \alpha_i v_i$$

where $\alpha_1, \alpha_2, \alpha_3, \dots, \alpha_i \in \mathbb{R}$

Let v_1, v_2, \ldots, v_i be vectors in \mathbb{R}^D , with D dimensions.

Let v_1, v_2, \ldots, v_i be vectors in \mathbb{R}^D , with D dimensions. The span of v_1, v_2, \ldots, v_i is denoted by $\mathsf{SPAN}\{v_1, v_2, \ldots, v_i\}$

Let v_1, v_2, \ldots, v_i be vectors in \mathbb{R}^D , with D dimensions. The span of v_1, v_2, \ldots, v_i is denoted by $\mathsf{SPAN}\{v_1, v_2, \ldots, v_i\}$

$$\{\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \dots + \alpha_i \mathbf{v}_i \mid \alpha_1, \alpha_2, \dots, \alpha_i \in \mathbb{R}\}$$

Let v_1, v_2, \ldots, v_i be vectors in \mathbb{R}^D , with D dimensions. The span of v_1, v_2, \ldots, v_i is denoted by $\mathsf{SPAN}\{v_1, v_2, \ldots, v_i\}$

$$\{\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \dots + \alpha_i \mathbf{v}_i \mid \alpha_1, \alpha_2, \dots, \alpha_i \in \mathbb{R}\}$$

It is the set of all vectors that can be generated by linear combinations of v_1, v_2, \ldots, v_i .

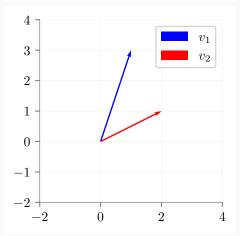
Let v_1, v_2, \ldots, v_i be vectors in \mathbb{R}^D , with D dimensions. The span of v_1, v_2, \ldots, v_i is denoted by $\mathsf{SPAN}\{v_1, v_2, \ldots, v_i\}$

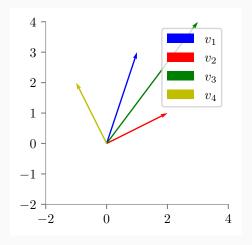
$$\{\alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \dots + \alpha_i \mathbf{v}_i \mid \alpha_1, \alpha_2, \dots, \alpha_i \in \mathbb{R}\}$$

It is the set of all vectors that can be generated by linear combinations of v_1, v_2, \ldots, v_i .

If we stack the vectors v_1, v_2, \ldots, v_i as columns of a matrix V, then the span of v_1, v_2, \ldots, v_i is given as $V\alpha$ where $\alpha \in \mathbb{R}^i$

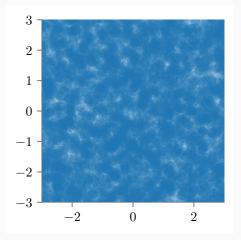






We have $v_3 = v_1 + v_2$ We have $v_4 = v_1 - v_2$

Simulating the above example in python using different values of α_1 and α_2



$$\mathsf{Span}((v_1,v_2)) \in \mathcal{R}^2$$

Find the span of
$$\begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$
)

Find the span of
$$\begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

Can we obtain a point (x, y) s.t. x = 3y?

Find the span of
$$\begin{bmatrix} 1 \\ 2 \end{bmatrix}$$
, $\begin{bmatrix} 2 \\ 4 \end{bmatrix}$)
Can we obtain a point (x, y) s.t. $x = 3y$?

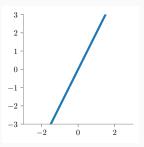
No

Find the span of $\begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix}$)

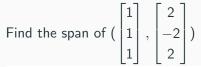
Can we obtain a point (x, y) s.t. x = 3y?

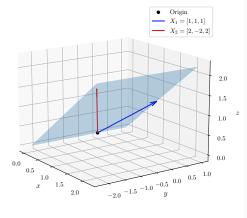
No

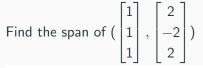
Span of the above set is along the line y=2x

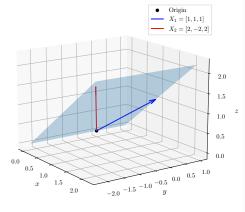


Find the span of
$$\begin{bmatrix} 1\\1\\1 \end{bmatrix}$$
, $\begin{bmatrix} 2\\-2\\2 \end{bmatrix}$)









The span is the plane z = x or $x_3 = x_1$

Consider X and y as follows.

$$\mathbf{X} = \begin{pmatrix} 1 & 2 \\ 1 & -2 \\ 1 & 2 \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} 8.8957 \\ 0.6130 \\ 1.7761 \end{pmatrix}$$

• We are trying to learn θ for $\hat{y} = X\theta$ such that $||y - \hat{y}||_2$ is minimised

Consider X and y as follows.

$$\mathbf{X} = \begin{pmatrix} 1 & 2 \\ 1 & -2 \\ 1 & 2 \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} 8.8957 \\ 0.6130 \\ 1.7761 \end{pmatrix}$$

- We are trying to learn θ for $\hat{y} = X\theta$ such that $||y \hat{y}||_2$ is minimised
- ullet Consider the two columns of X. Can we write X heta as the span

of
$$\begin{bmatrix} 1\\1\\1 \end{bmatrix}$$
, $\begin{bmatrix} 2\\-2\\2 \end{bmatrix}$)?

Consider X and y as follows.

$$\mathbf{X} = \begin{pmatrix} 1 & 2 \\ 1 & -2 \\ 1 & 2 \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} 8.8957 \\ 0.6130 \\ 1.7761 \end{pmatrix}$$

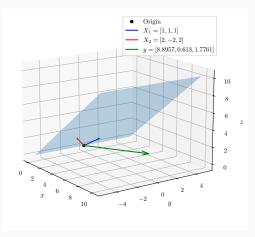
- We are trying to learn θ for $\hat{y} = X\theta$ such that $||y \hat{y}||_2$ is minimised
- ullet Consider the two columns of X. Can we write X heta as the span

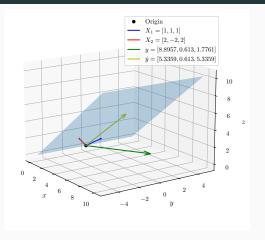
of
$$\begin{bmatrix} 1\\1\\1 \end{bmatrix}$$
, $\begin{bmatrix} 2\\-2\\2 \end{bmatrix}$)?

• We wish to find \hat{y} such that

$$\underset{\hat{y} \in SPAN\{\bar{x_1}, \bar{x_2}, \dots, \bar{x_D}\}}{\arg \min} ||y - \hat{y}||_2$$

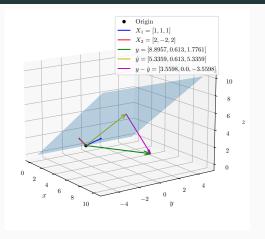
Span of
$$\begin{bmatrix} 1\\1\\1 \end{bmatrix}$$
, $\begin{bmatrix} 2\\-2\\2 \end{bmatrix}$)





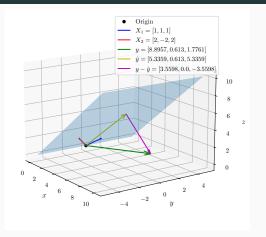
• We seek a \hat{y} in the span of the columns of X such that it is closest to y

Geometric Interpretation



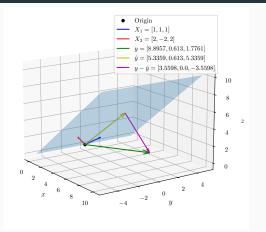
• This happens when $y - \hat{y} \perp x_j \forall j$ or $x_j^T (y - \hat{y}) = 0$

Geometric Interpretation



- This happens when $y \hat{y} \perp x_j \forall j$ or $x_j^T (y \hat{y}) = 0$
- $X^T(y X\theta) = 0$

Geometric Interpretation



- This happens when $y \hat{y} \perp x_j \forall j$ or $x_j^T (y \hat{y}) = 0$
- $\bullet \ X^T(y-X\theta)=0$
- $X^T y = X^T X \theta$ or $\hat{\theta} = (X^T X)^{-1} X^T y$

Dummy Variables and Multicollinearity

There can be situations where inverse of X^TX is not computable.

There can be situations where inverse of X^TX is not computable. This condition arises when the $|X^TX| = 0$.

$$X = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 4 \\ 1 & 3 & 6 \end{bmatrix} \tag{8}$$

There can be situations where inverse of X^TX is not computable. This condition arises when the $|X^TX| = 0$.

$$X = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 4 \\ 1 & 3 & 6 \end{bmatrix} \tag{8}$$

The matrix X is not full rank.

It arises when one or more predictor varibale/feature in X can be expressed as a linear combinations of others

How to tackle it?

• Regularize

It arises when one or more predictor varibale/feature in X can be expressed as a linear combinations of others

How to tackle it?

- Regularize
- Drop variables

It arises when one or more predictor varibale/feature in X can be expressed as a linear combinations of others

How to tackle it?

- Regularize
- Drop variables
- Avoid dummy variable trap

Say Pollution in Delhi = P

Say Pollution in Delhi = P

$$P = \theta_0 \, + \, \theta_1 \text{*\#Vehicles} \, + \, \theta_1 \text{* Wind speed} \, + \, \theta_3 \text{* Wind Direction}$$

Say Pollution in Delhi = P

$$P = \theta_0 + \theta_1 *\# Vehicles + \theta_1 *\ Wind\ speed + \theta_3 *\ Wind\ Direction$$

But, wind direction is a categorical variable.

Say Pollution in Delhi = P

$$P = \theta_0 + \theta_1 *\# Vehicles + \theta_1 *\ Wind\ speed + \theta_3 *\ Wind\ Direction$$

But, wind direction is a categorical variable.

It is denoted as follows {N:0, E:1, W:2, S:3 }

Say Pollution in Delhi = P

$$P = \theta_0 + \theta_1 *\# Vehicles + \theta_1 *\ Wind\ speed + \theta_3 *\ Wind\ Direction$$

But, wind direction is a categorical variable.

It is denoted as follows {N:0, E:1, W:2, S:3 }

Can we use the direct encoding?

Say Pollution in Delhi = P

$$P = \theta_0 + \theta_1 * \# Vehicles + \theta_1 * Wind speed + \theta_3 * Wind Direction$$

But, wind direction is a categorical variable.

It is denoted as follows {N:0, E:1, W:2, S:3 }

Can we use the direct encoding? Then this implies that S>W>E>N

N-1 Variable encoding

	Is it N?	Is it E?	Is it W?
N	1	0	0
Ε	0	1	0
W	0	0	1
S	0	0	0

N Variable encoding

	Is it N?	Is it E?	Is it W?	Is it S?
N	1	0	0	0
E	0	1	0	0
W	0	0	1	0
S	0	0	0	1

Which is better N variable encoding or N-1 variable encoding?

Which is better N variable encoding or N-1 variable encoding? The N-1 variable encoding is better because the N variable encoding can cause multi-collinearity.

Which is better N variable encoding or N-1 variable encoding? The N-1 variable encoding is better because the N variable encoding can cause multi-collinearity.

Is it
$$S = 1$$
 - (Is it $N + Is$ it $W + Is$ it E)

Binary Encoding

N	00
Е	01
W	10
S	11

Binary Encoding

N	00
Е	01
W	10
S	11

 $\ensuremath{\mathsf{W}}$ and $\ensuremath{\mathsf{S}}$ are related by one bit.

Binary Encoding

N	00
E	01
W	10
S	11

W and S are related by one bit.

This introduces dependencies between them, and this can confusion in classifiers.

Gender	height
F	
F	
F	
М	
М	

Gender	height
F	
F	
F	
M	
М	

Encoding

Gender	height
F	
F	
F	
M	
M	

Encoding

Is Female	height
1	
1	
1	
0	
0	

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$\textit{height}_i = \theta_0 + \theta_1 * (\text{Is Female}) + \epsilon_i$$

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$\textit{height}_i = \theta_0 + \theta_1 * (\text{Is Female}) + \epsilon_i$$

We get
$$\theta_0=5.8$$
 and $\theta_0=6$

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$\textit{height}_i = \theta_0 + \theta_1 * (\text{Is Female}) + \epsilon_i$$

We get
$$\theta_0 = 5.8$$
 and $\theta_0 = 6$
 $\theta_0 = \text{Avg height of Male} = 5.9$

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$\textit{height}_i = \theta_0 + \theta_1 * (\text{Is Female}) + \epsilon_i$$

We get $\theta_0 = 5.8$ and $\theta_0 = 6$

 $\theta_0 = \text{Avg height of Male} = 5.9$

 $\theta_0 + \theta_1$ is chosen based (equal to) on 5, 5.2, 5.4 (for three records).

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$height_i = \theta_0 + \theta_1 * (Is Female) + \epsilon_i$$

We get $\theta_0=5.8$ and $\theta_0=6$

 $heta_0 = \mathsf{Avg} \; \mathsf{height} \; \mathsf{of} \; \mathsf{Male} = 5.9$

 $\theta_0 + \theta_1$ is chosen based (equal to) on 5, 5.2, 5.4 (for three records).

 θ_1 is chosen based on 5-5.9, 5.2-5.9, 5.4-5.9

Is Female	height
1	5
1	5.2
1	5.4
0	5.8
0	6

$$height_i = \theta_0 + \theta_1 * (Is Female) + \epsilon_i$$

We get $\theta_0=5.8$ and $\theta_0=6$ $\theta_0=$ Avg height of Male =5.9 $\theta_0+\theta_1$ is chosen based (equal to) on 5, 5.2, 5.4 (for three records). θ_1 is chosen based on 5-5.9, 5.2-5.9, 5.4-5.9 $\theta_1=$ Avg. female height (5+5.2+5.4)/3 - Avg. male height(5.9)

Alternatively, instead of a $0/1\ \text{coding}$ scheme, we could create a dummy variable

Alternatively, instead of a 0/1 coding scheme, we could create a dummy variable

$$x_i = \begin{cases} 1 & \text{if } i \text{ th person is female} \\ -1 & \text{if } i \text{ th person is male} \end{cases}$$

Alternatively, instead of a 0/1 coding scheme, we could create a dummy variable

$$x_i = \begin{cases} 1 & \text{if } i \text{ th person is female} \\ -1 & \text{if } i \text{ th person is male} \end{cases}$$

$$y_i = \theta_0 + \theta_1 x_i + \epsilon_i = \begin{cases} \theta_0 + \theta_1 + \epsilon_i & \text{if } i \text{ th person is female} \\ \theta_0 - \theta_1 + \epsilon_i & \text{if } i \text{ th person is male.} \end{cases}$$

Alternatively, instead of a 0/1 coding scheme, we could create a dummy variable

$$x_i = \begin{cases} 1 & \text{if } i \text{ th person is female} \\ -1 & \text{if } i \text{ th person is male} \end{cases}$$

$$y_i = \theta_0 + \theta_1 x_i + \epsilon_i = \begin{cases} \theta_0 + \theta_1 + \epsilon_i & \text{if } i \text{ th person is female} \\ \theta_0 - \theta_1 + \epsilon_i & \text{if } i \text{ th person is male.} \end{cases}$$

Now, θ_0 can be interpreted as average person height. θ_1 as the amount that female height is above average and male height is below average.