Coordinate Descent

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• Express error as a difference of y_i and \hat{y}_i

$$\hat{y_i} = \sum_{i=0}^{d} \theta_j x_i^j = \theta_0 x_i^0 + \theta_1 x_i^1 + \theta_2 x_i^2 \dots + \theta_d x_i^d$$
 (1)

$$\epsilon_i = y_i - \hat{y}_i \tag{2}$$

$$= y_i - \theta_0 x_i^0 + \theta_1 x_i^1 + \dots + \theta_d x_i^d$$
 (3)

$$=y_i-\sum_{j=0}^d\theta_jx_i^j\tag{4}$$

$$\sum_{i=1}^{N} \epsilon^2 = RSS = \sum_{i=1}^{N} \left(y_i - \left(\theta_0 x_i^0 + \dots \quad \theta_j x_i^j + \theta_d x_i^d \right) \right)^2$$

$$\sum_{i=1}^{N} \epsilon^{2} = RSS = \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots \quad \theta_{j} x_{i}^{j} + \theta_{d} x_{i}^{d} \right) \right)^{2}$$

$$\frac{\partial \operatorname{RSS} \left(\theta_{j} \right)}{\partial \theta_{j}} = 2 \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots \quad \theta_{j} x_{i}^{j} + \dots \right) \right) \left(-x_{i}^{j} \right)$$

$$\sum_{i=1}^{N} \epsilon^{2} = RSS = \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots + \theta_{j} x_{i}^{j} + \theta_{d} x_{i}^{d} \right) \right)^{2}$$

$$\frac{\partial RSS \left(\theta_{j} \right)}{\partial \theta_{j}} = 2 \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots + \theta_{j} x_{i}^{j} + \dots \right) \right) \left(-x_{i}^{j} \right)$$

$$= 2 \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots + \theta_{d} x_{i}^{d} \right) \right) \left(-x_{i}^{j} \right) + 2 \sum_{i=1}^{N} \theta_{j} (x_{i}^{j})^{2}$$

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where:

$$\hat{\mathbf{y}_i}^{(-j)} = \theta_0 \mathbf{x}_i^0 + \ldots + \theta_d \mathbf{x}_i^d$$

is \hat{y}_i without θ_j

$$Set \frac{\partial \operatorname{RSS}(\theta_{j})}{\partial \theta_{j}} = 0$$

$$\theta_{j} = \sum_{i=1}^{N} \frac{\left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots + \dots + \theta_{d} x_{i}^{d}\right)\right) \left(x_{i}^{j}\right)}{\left(x_{i}^{j}\right)^{2}} = \frac{\rho_{j}}{z_{j}}$$

$$\rho_{j} = \sum_{i=1}^{N} x_{i}^{j} \left(y_{i} - \hat{y}_{i}^{(-j)}\right)$$

$$z_{j} = \sum_{i=1}^{N} \left(x_{i}^{j}\right)^{2}$$

 z_i is the squared of ℓ_2 norm of the j^{th} feature

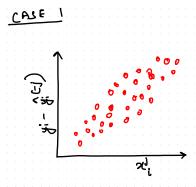
COORDINATE

UNDERSTANDING Pj IN COORDINATE DESCEN

$$p_{j} = \sum_{i=1}^{N} x_{i} \left(y_{i} - \hat{y}_{i}^{c_{j}} \right)$$

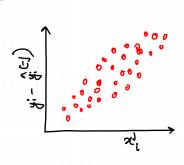
UNDERSTANDING Pj IN COORDINATE DESCENT

$$Pj = \sum_{i=1}^{N} x_i^j (y_i - y_i^i)$$



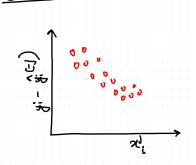
STRONG TVE CORE

UNDERSTANDING
$$P_j$$
 IN COORDINATE DESCENT
$$P_j = \sum_{i=1}^{N} \chi_i \left(y_i - \hat{y}_i \right)$$
CASE 1



jth FEATURE IS IMPT AND ITS COEFFICIENT

UNDERSTANDING Pj IN COORDINATE DESCENT
$$p_{j} = \sum_{i=1}^{N} x_{i}^{j} (y_{i} - \hat{y}_{i}^{c})$$



STRONG -VE CORR
WITH y: -y;

FEATURE IS IN

AND ITS COFF. -V

UNDERSTANDING Pj IN COORDINATE DESCEN

$$Pj = \sum_{i=1}^{N} \chi_{i} \left(y_{i} - y_{i}^{cj} \right)$$

$$\chi_{i}^{j} \text{ WEAK } \left(\text{ORR.} \right)$$

$$\chi_{i}^{j} \text{ WEAK } \left(\text{ORR.} \right)$$

$$\psi_{i} - \hat{y}_{i}^{cj}$$

$$\psi_{i} -$$

$$\frac{\partial}{\partial \theta_j}(\text{LASSO OBJECTIVE}) = -2\rho_j + 2\theta_j \mathbf{Z}_j + \delta^2 \frac{\partial}{\partial \theta_j} \left|\theta_j\right|$$

$$\frac{\partial}{\partial \theta_j} |\theta_j| = \begin{cases} 1 & \theta_j > 0 \\ [-1, 1] & \theta_j = 0 \\ -1 & \theta_j < 0 \end{cases}$$

• Case 1: $\theta_{j} > 0$

$$2\rho_j + 2\theta_j \mathbf{Z}_j + \delta^2 = 0$$
$$\theta_j = \frac{\rho_j - \frac{\delta^2}{2}}{\mathbf{Z}_j}$$
$$\rho_j > \frac{\delta^2}{2} \Rightarrow \theta_j = \frac{\rho_j - \frac{\delta^2}{2}}{\mathbf{Z}_j}$$

• Case 1: $\theta_{j} > 0$

$$2\rho_{j} + 2\theta_{j}Z_{j} + \delta^{2} = 0$$

$$\theta_{j} = \frac{\rho_{j} - \frac{\delta^{2}}{2}}{Z_{j}}$$

$$\rho_{j} > \frac{\delta^{2}}{2} \Rightarrow \theta_{j} = \frac{\rho_{j} - \frac{\delta^{2}}{2}}{Z_{j}}$$

• Case 2: $\theta_{i} < 0$

$$\rho_j < \frac{\delta^2}{2} \Rightarrow \theta_j = \frac{\rho_j + \delta^2/2}{z_j} \tag{5}$$

• Case 3: $\theta_{i} = 0$

$$\frac{\partial}{\partial \theta_{j}}(\text{LASSO OBJECTIVE}) = -2\rho_{j} + 2\theta_{j}\mathbf{z}_{j} + \delta^{2}\underbrace{\frac{\partial}{\partial \theta_{j}}\left|\theta_{j}\right|}_{\text{[-1,1]}}$$

$$\underbrace{\epsilon\underbrace{\left[-2\rho_{j} - \delta^{2}, -2\rho_{j} + \delta^{2}\right]}_{\{0\} \text{ lies in this range}}}$$

$$-2\rho_j - \delta^2 \le 0 \text{ and } -2\rho_j - \delta^2 \le 0$$
$$-\frac{\delta^2}{2} \le \rho_j \le \frac{\delta^2}{2} \Rightarrow \theta_j = 0$$

Summary of Lasso Regression

$$\theta_{j} = \begin{bmatrix} \frac{\rho_{j} + \frac{\delta^{2}}{2}}{z_{j}} & \text{if} & \rho_{j} < -\frac{\delta^{2}}{2} \\ 0 & \text{if} & -\frac{\delta^{2}}{2} \leq \rho_{j} \leq \frac{\delta^{2}}{2} \\ \frac{\rho_{j} - \frac{\delta^{2}}{2}}{z_{j}} & \text{if} & \rho_{j} > \frac{\delta^{2}}{2} \end{bmatrix}$$
(6)

SSO (SOFT) THRESHOLDING
$$\left(P_1 + \frac{2}{5}\right)^2 \quad \text{if} \quad \frac{1}{5}$$

$$(9.+ 5^2)$$

LASSO (SOFT) THRESHOLDING
$$\hat{\Theta}_{j} = \begin{cases} \frac{p_{j} + \hat{S}_{12}^{2}}{Z_{j}} & \text{if} \\ \frac{1}{2} & \text{if} \end{cases}$$

$$\hat{\Theta}_{j} = \begin{cases} \frac{p_{j} + \hat{S}_{/2}^{2}}{z_{j}} & \text{if} \end{cases}$$

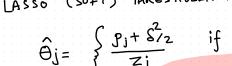
θ

LASSO (SOFT) THRES HOLDING
$$\hat{\Theta}_{i} = \begin{cases} \frac{p_{j} + S^{2}}{2} & \text{if} \end{cases}$$

$$\hat{\Theta}_{i} = \begin{cases} \frac{p_{i} + \hat{S}_{i}^{2}}{7!} & \text{if} \end{cases}$$

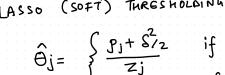
ASSO (SOFT) THRESHOLDING
$$\hat{\Theta}_{i} = \begin{cases} \frac{p_{j} + S^{2}}{2} & \text{if} \end{cases}$$

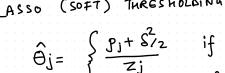
 $-\frac{8^2}{2} \leq f$ 95 = 52/2



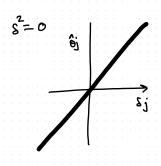
LASSO (SOFT) THRESHOLDING
$$\hat{\Theta}_{j} = \begin{cases} \frac{p_{j} + S_{/2}^{2}}{Z_{j}} & \text{if} \\ \frac{1}{Z_{j}} & \text{if} \end{cases}$$

LASSO (SOFT) THRESHOLDING
$$\hat{A}:= \left\{\begin{array}{cc} p_j + S^2/2 & \text{if} \end{array}\right.$$





LASSO (SOFT) THRESHOLDING



NO REGULARISATION

LASSO (SOFT) THRESHOLDING

