# **Coordinate Descent**

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• Express error as a difference of  $y_i$  and  $\hat{y}_i$ 

$$\hat{y_i} = \sum_{i=0}^{d} \theta_j x_i^j = \theta_0 x_i^0 + \theta_1 x_i^1 + \theta_2 x_i^2 \dots + \theta_d x_i^d$$
 (1)

$$\epsilon_i = y_i - \hat{y}_i \tag{2}$$

$$= y_i - \theta_0 x_i^0 + \theta_1 x_i^1 + \dots + \theta_d x_i^d$$
 (3)

$$=y_i-\sum_{j=0}^d\theta_jx_i^j\tag{4}$$

$$\sum_{i=1}^{N} \epsilon^2 = RSS = \sum_{i=1}^{N} \left( y_i - \left( \theta_0 x_i^0 + \dots \quad \theta_j x_i^j + \theta_d x_i^d \right) \right)^2$$

$$\sum_{i=1}^{N} \epsilon^{2} = RSS = \sum_{i=1}^{N} \left( y_{i} - \left( \theta_{0} x_{i}^{0} + \dots \quad \theta_{j} x_{i}^{j} + \theta_{d} x_{i}^{d} \right) \right)^{2}$$

$$\frac{\partial \operatorname{RSS} \left( \theta_{j} \right)}{\partial \theta_{j}} = 2 \sum_{i=1}^{N} \left( y_{i} - \left( \theta_{0} x_{i}^{0} + \dots \quad \theta_{j} x_{i}^{j} + \dots \right) \right) \left( -x_{i}^{j} \right)$$

$$\sum_{i=1}^{N} \epsilon^{2} = RSS = \sum_{i=1}^{N} \left( y_{i} - \left( \theta_{0} x_{i}^{0} + \dots + \theta_{j} x_{i}^{j} + \theta_{d} x_{i}^{d} \right) \right)^{2}$$

$$\frac{\partial RSS \left( \theta_{j} \right)}{\partial \theta_{j}} = 2 \sum_{i=1}^{N} \left( y_{i} - \left( \theta_{0} x_{i}^{0} + \dots + \theta_{j} x_{i}^{j} + \dots \right) \right) \left( -x_{i}^{j} \right)$$

$$= 2 \sum_{i=1}^{N} \left( y_{i} - \left( \theta_{0} x_{i}^{0} + \dots + \theta_{d} x_{i}^{d} \right) \right) \left( -x_{i}^{j} \right) + 2 \sum_{i=1}^{N} \theta_{j} (x_{i}^{j})^{2}$$

$$\sum_{i=1}^{N} \epsilon^{2} = RSS = \sum_{i=1}^{N} \left( y_{i} - \left( \theta_{0} x_{i}^{0} + \dots + \theta_{j} x_{i}^{j} + \theta_{d} x_{i}^{d} \right) \right)^{2}$$

$$\frac{\partial RSS \left( \theta_{j} \right)}{\partial \theta_{j}} = 2 \sum_{i=1}^{N} \left( y_{i} - \left( \theta_{0} x_{i}^{0} + \dots + \theta_{j} x_{i}^{j} + \dots \right) \right) \left( -x_{i}^{j} \right)$$

$$= 2 \sum_{i=1}^{N} \left( y_{i} - \left( \theta_{0} x_{i}^{0} + \dots + \theta_{d} x_{i}^{d} \right) \right) \left( -x_{i}^{j} \right) + 2 \sum_{i=1}^{N} \theta_{j} (x_{i}^{j})^{2}$$

where:

$$\hat{\mathbf{y}_i}^{(-j)} = \theta_0 \mathbf{x}_i^0 + \ldots + \theta_d \mathbf{x}_i^d$$

is  $\hat{y}_i$  without  $\theta_j$ 

$$Set \frac{\partial \operatorname{RSS}(\theta_{j})}{\partial \theta_{j}} = 0$$

$$\theta_{j} = \sum_{i=1}^{N} \frac{\left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots + \dots + \theta_{d} x_{i}^{d}\right)\right) \left(x_{i}^{j}\right)}{\left(x_{i}^{j}\right)^{2}} = \frac{\rho_{j}}{z_{j}}$$

$$\rho_{j} = \sum_{i=1}^{N} x_{i}^{j} \left(y_{i} - \hat{y}_{i}^{(-j)}\right)$$

$$z_{j} = \sum_{i=1}^{N} \left(x_{i}^{j}\right)^{2}$$

 $z_i$  is the squared of  $\ell_2$  norm of the  $j^{th}$  feature

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$$\frac{\partial}{\partial \theta_j}(\text{LASSO OBJECTIVE}) = -2\rho_j + 2\theta_j \mathbf{Z}_j + \delta^2 \frac{\partial}{\partial \theta_j} \left|\theta_j\right|$$

$$\frac{\partial}{\partial \theta_j} |\theta_j| = \begin{cases} 1 & \theta_j > 0 \\ [-1, 1] & \theta_j = 0 \\ -1 & \theta_j < 0 \end{cases}$$

• Case 1:  $\theta_{j} > 0$ 

$$2\rho_{j} + 2\theta_{j}Z_{j} + \delta^{2} = 0$$

$$\theta_{j} = \frac{\rho_{j} - \frac{\delta^{2}}{2}}{Z_{j}}$$

$$\rho_{j} > \frac{\delta^{2}}{2} \Rightarrow \theta_{j} = \frac{\rho_{j} - \frac{\delta^{2}}{2}}{Z_{j}}$$

• Case 1:  $\theta_{j} > 0$ 

$$2\rho_{j} + 2\theta_{j}Z_{j} + \delta^{2} = 0$$

$$\theta_{j} = \frac{\rho_{j} - \frac{\delta^{2}}{2}}{Z_{j}}$$

$$\rho_{j} > \frac{\delta^{2}}{2} \Rightarrow \theta_{j} = \frac{\rho_{j} - \frac{\delta^{2}}{2}}{Z_{j}}$$

• Case 2:  $\theta_{i} < 0$ 

$$\rho_j < \frac{\delta^2}{2} \Rightarrow \theta_j = \frac{\rho_j + \delta^2/2}{z_j} \tag{5}$$

• Case 3:  $\theta_{i} = 0$ 

$$\frac{\partial}{\partial \theta_{j}}(\text{LASSO OBJECTIVE}) = -2\rho_{j} + 2\theta_{j}\mathbf{z}_{j} + \delta^{2}\underbrace{\frac{\partial}{\partial \theta_{j}}\left|\theta_{j}\right|}_{\text{[-1,1]}}$$
 
$$\underbrace{\epsilon\underbrace{\left[-2\rho_{j} - \delta^{2}, -2\rho_{j} + \delta^{2}\right]}_{\{0\} \text{ lies in this range}}}$$

$$-2\rho_j - \delta^2 \le 0 \text{ and } -2\rho_j - \delta^2 \le 0$$
$$-\frac{\delta^2}{2} \le \rho_j \le \frac{\delta^2}{2} \Rightarrow \theta_j = 0$$

#### Summary of Lasso Regression

$$\theta_{j} = \begin{bmatrix} \frac{\rho_{j} + \frac{\delta^{2}}{2}}{z_{j}} & \text{if} & \rho_{j} < -\frac{\delta^{2}}{2} \\ 0 & \text{if} & -\frac{\delta^{2}}{2} \leq \rho_{j} \leq \frac{\delta^{2}}{2} \\ \frac{\rho_{j} - \frac{\delta^{2}}{2}}{z_{j}} & \text{if} & \rho_{j} > \frac{\delta^{2}}{2} \end{bmatrix}$$
(6)

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