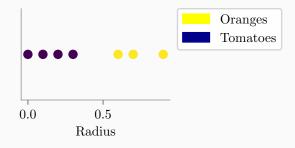
## **Logistic Regression**

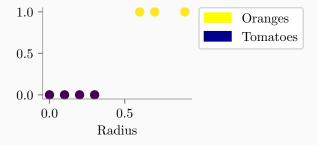
Nipun Batra

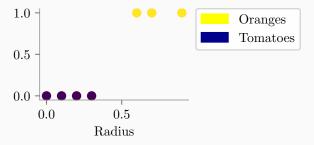
July 20, 2025

IIT Gandhinagar

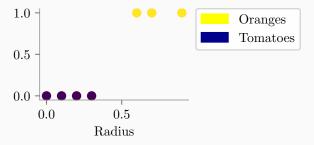
## **Problem Setup**





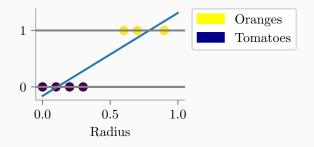


 $\label{eq:Aim: Probability (Tomatoes \mid Radius) ? or } Aim: Probability (Tomatoes \mid Radius) ? or \\$ 

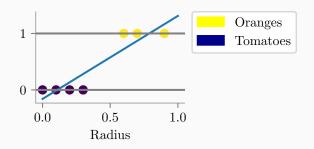


Aim: Probability(Tomatoes | Radius) ? or

More generally,  $P(y = 1 | \mathbf{X} = \mathbf{x})$ ?



$$P(X = Orange|Radius) = \theta_0 + \theta_1 \times Radius$$



$$P(X = Orange|Radius) = \theta_0 + \theta_1 \times Radius$$

Generally,

$$P(y=1|\mathbf{x})=\mathbf{X}\boldsymbol{\theta}$$

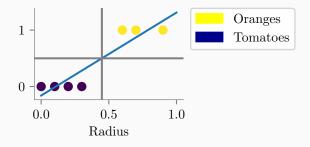
#### Prediction:

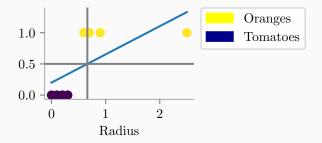
$$\begin{array}{c} \text{If } \theta_0 + \theta_1 \times \textit{Radius} > 0.5 \rightarrow \mathsf{Orange} \\ \\ \text{Else} \rightarrow \mathsf{Tomato} \end{array}$$

#### Problem:

Range of 
$$\mathbf{X}\boldsymbol{\theta}$$
 is  $(-\infty,\infty)$ 

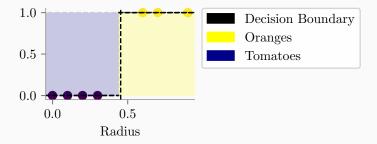
But 
$$P(y = 1 | ...) \in [0, 1]$$





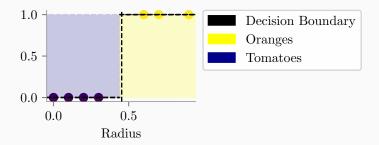
Linear regression for classification gives a poor prediction!

#### **Ideal boundary**

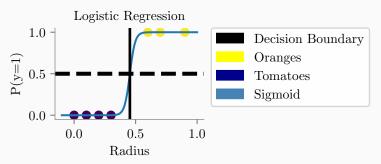


 Have a decision function similar to the above (but not so sharp and discontinuous)

#### **Ideal boundary**



- Have a decision function similar to the above (but not so sharp and discontinuous)
- Aim: use linear regression still!



Question. Can we still use Linear Regression? Answer. Yes! Transform  $\hat{y} \rightarrow [0,1]$ 

$$\hat{y} \in (-\infty, \infty)$$

$$\phi = \text{Sigmoid / Logistic Function } (\sigma)$$

$$\phi(\hat{y}) \in [0, 1]$$

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

$$0.0$$

$$0.0$$

$$0.0$$

$$0$$

$$0$$



$$z \to \infty$$
  
 $\sigma(z) \to 1$ 

$$z \to \infty$$

$$\sigma(z) \to 1$$

$$z \to -\infty$$

$$z \to \infty$$
  
 $\sigma(z) \to 1$   
 $z \to -\infty$   
 $\sigma(z) \to 0$ 

$$z \to \infty$$
 $\sigma(z) \to 1$ 
 $z \to -\infty$ 
 $\sigma(z) \to 0$ 
 $z = 0$ 

$$z \to \infty$$
 $\sigma(z) \to 1$ 
 $z \to -\infty$ 
 $\sigma(z) \to 0$ 
 $z = 0$ 
 $\sigma(z) = 0.5$ 

Question. Could you use some other transformation  $(\phi)$  of  $\hat{y}$  s.t.

$$\phi(\hat{y}) \in [0,1]$$

Yes! But Logistic Regression works.

$$P(y=1|\mathbf{X}) = \sigma(\mathbf{X}\boldsymbol{\theta}) = \frac{1}{1+e^{-\mathbf{X}\boldsymbol{\theta}}}$$

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$$\therefore \frac{P(y=1|X)}{1-P(y=1|X)} = e^{\mathbf{X}\boldsymbol{\theta}} \implies \mathbf{X}\boldsymbol{\theta} = \log \frac{P(y=1|X)}{1-P(y=1|X)}$$

## Odds (Used in betting)

$$\frac{P(win)}{P(loss)}$$

Here,

$$Odds = \frac{P(y=1)}{P(y=0)}$$

$$\mathsf{log} ext{-odds} = \mathsf{log}\, rac{P(y=1)}{P(y=0)} = \mathbf{X}oldsymbol{ heta}$$

#### **Logistic Regression**

 $\ensuremath{\mathsf{Q}}.$  What is decision boundary for Logistic Regression?

## **Logistic Regression**

Q. What is decision boundary for Logistic Regression? Decision Boundary: P(y=1|X)=P(y=0|X) or  $\frac{1}{1+e^{-X\theta}}=\frac{e^{-X\theta}}{1+e^{-X\theta}}$  or  $e^{X\theta}=1$  or  $X\theta=0$ 

#### **Learning Parameters**

Could we use cost function as:

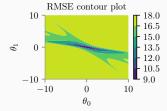
$$J(\theta) = \sum (y_i - \hat{y}_i)^2$$
$$\hat{y}_i = \sigma(\mathbf{X}\theta)$$

Answer: No (Non-Convex)
(See Jupyter Notebook)

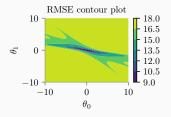
# Deriving Cost Function via Maximum Likelihood Estimation

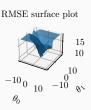
## **Cost function convexity**

## Cost function convexity



## **Cost function convexity**





## **Learning Parameters**

Likelihood = 
$$P(D|\theta)$$
  
 $P(y|X,\theta) = \prod_{i=1}^{n} P(y_i|x_i,\theta)$   
where y = 0 or 1

 $\mathsf{Likelihood} = P(D|\theta)$ 

$$P(y|X,\theta) = \prod_{i=1}^{n} P(y_i|x_i,\theta) = \prod_{i=1}^{n} \left\{ \frac{1}{1 + e^{-x_i^T \theta}} \right\}^{y_i} \left\{ 1 - \frac{1}{1 + e^{-x_i^T \theta}} \right\}^{1 - y_i}$$

[Above: Similar to  $P(D|\theta)$  for Linear Regression;

Difference Bernoulli instead of Gaussian]

 $-\log P(y|\mathbf{X}, \boldsymbol{ heta}) = ext{Negative Log Likelihood} = ext{Cost function will be minim}$ 

 Assume you have a coin and flip it ten times and get (H, H, T, T, T, H, H, T, T, T).

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- Answer 2: What is likelihood of seeing the above sequence when the p(Head)=θ?

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- ullet Idea find MLE estimate for heta

• 
$$p(H) = \theta$$
 and  $p(T) = 1 - \theta$ 

- $p(H) = \theta$  and  $p(T) = 1 \theta$
- What is the PMF for first observation  $P(D_1 = x | \theta)$ , where x = 0 for Tails and x = 1 for Heads?

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- $P(D_1, D_2, ..., D_n | \theta) = \theta^{n_h} (1 \theta)^{n_t}$
- Log-likelihood =  $\mathcal{LL}(\theta) = n_h \log(\theta) + n_t \log(1 \theta)$
- $\frac{\partial \mathcal{LL}(\theta)}{\partial \theta} = 0 \implies \frac{n_h}{\theta} + \frac{n_t}{1-\theta} = 0 \implies \theta_{MLE} = \frac{n_h}{n_h + n_t}$

# **Cross Entropy Cost Function**

$$J(\theta) = -\log \left\{ \prod_{i=1}^{n} \left\{ \frac{1}{1 + e^{-x_{i}^{T}\theta}} \right\}^{y_{i}} \left\{ 1 - \frac{1}{1 + e^{-x_{i}^{T}\theta}} \right\}^{1 - y_{i}} \right\}$$

$$J(\theta) = -\left\{\sum_{i=1}^{N} y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i))\right\}$$

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This cost function is called cross-entropy.

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Why?

What is the interpretation of the cost function?

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Let us try to write the cost function for a single example:

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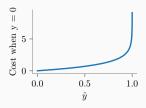
$$J(\theta) = -y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)$$

What is the interpretation of the cost function?

Let us try to write the cost function for a single example:

$$J(\theta) = -y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)$$

First, assume  $y_i$  is 0, then if  $\hat{y}_i$  is 0, the loss is 0; but, if  $\hat{y}_i$  is 1, the loss tends towards infinity!



Notebook: logits-usage

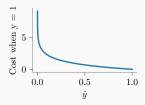
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What is the interpretation of the cost function?

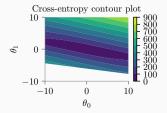
$$J(\theta) = -y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)$$

Now, assume  $y_i$  is 1, then if  $\hat{y}_i$  is 0, the loss is huge; but, if  $\hat{y}_i$  is 1, the loss is zero!

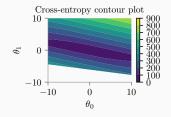


## **Cost function convexity**

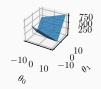
### **Cost function convexity**



### **Cost function convexity**



#### Cross-entropy surface plot



$$\begin{split} \frac{\partial J(\theta)}{\partial \theta_j} &= -\frac{\partial}{\partial \theta_j} \bigg\{ \sum_{i=1}^N y_i log(\sigma_{\theta}(x_i)) + (1 - y_i) log(1 - \sigma_{\theta}(x_i)) \bigg\} \\ &= -\sum_{i=1}^N \bigg[ y_i \frac{\partial}{\partial \theta_j} \log(\sigma_{\theta}(x_i)) + (1 - y_i) \frac{\partial}{\partial \theta_j} log(1 - \sigma_{\theta}(x_i)) \bigg] \end{split}$$

$$\frac{\partial J(\theta)}{\partial \theta_j} = -\sum_{i=1}^N \left[ y_i \frac{\partial}{\partial \theta_j} \log(\sigma_{\theta}(x_i)) + (1 - y_i) \frac{\partial}{\partial \theta_j} \log(1 - \sigma_{\theta}(x_i)) \right]$$
$$= -\sum_{i=1}^N \left[ \frac{y_i}{\sigma_{\theta}(x_i)} \frac{\partial}{\partial \theta_j} \sigma_{\theta}(x_i) + \frac{1 - y_i}{1 - \sigma_{\theta}(x_i)} \frac{\partial}{\partial \theta_j} (1 - \sigma_{\theta}(x_i)) \right]$$

Aside:

$$\frac{\partial}{\partial z}\sigma(z) = \frac{\partial}{\partial z}\frac{1}{1+e^{-z}} = -(1+e^{-z})^{-2}\frac{\partial}{\partial z}(1+e^{-z})$$

$$= \frac{e^{-z}}{(1+e^{-z})^2} = \left(\frac{1}{1+e^{-z}}\right)\left(\frac{e^{-z}}{1+e^{-z}}\right) = \sigma(z)\left\{\frac{1+e^{-z}}{1+e^{-z}} - \frac{1}{1+e^{-z}}\right\}$$

$$= \sigma(z)(1-\sigma(z))$$

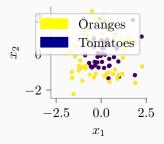
Resuming from (1)

$$\frac{\partial J(\theta)}{\partial \theta_{j}} = -\sum_{i=1}^{N} \left[ \frac{y_{i}}{\sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{j}} \sigma_{\theta}(x_{i}) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{j}} (1 - \sigma_{\theta}(x_{i})) \right] 
= -\sum_{i=1}^{N} \left[ \frac{y_{i}\sigma_{\theta}(x_{i})}{\sigma_{\theta}(x_{i})} (1 - \sigma_{\theta}(x_{i})) \frac{\partial}{\partial \theta_{j}} (x_{i}\theta) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} (1 - \sigma_{\theta}(x_{i})) \frac{\partial}{\partial \theta_{j}} (1 - \sigma_{\theta}(x_{i})) \right] 
= -\sum_{i=1}^{N} \left[ y_{i} (1 - \sigma_{\theta}(x_{i})) x_{i}^{j} - (1 - y_{i}) \sigma_{\theta}(x_{i}) x_{i}^{j} \right] 
= -\sum_{i=1}^{N} \left[ (y_{i} - y_{i}\sigma_{\theta}(x_{i}) - \sigma_{\theta}(x_{i}) + y_{i}\sigma_{\theta}(x_{i})) x_{i}^{j} \right] 
= \sum_{i=1}^{N} \left[ \sigma_{\theta}(x_{i}) - y_{i} \right] x_{i}^{j}$$

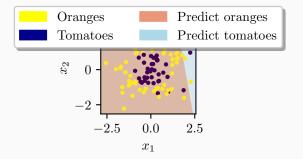
$$\frac{\partial J(\theta)}{\theta_j} = \sum_{i=1}^{N} \left[ \sigma_{\theta}(x_i) - y_i \right] x_i^j$$

Now, just use Gradient Descent!

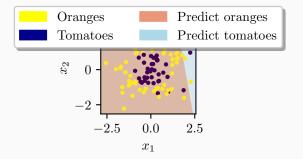
null



What happens if you apply logistic regression on the above data?

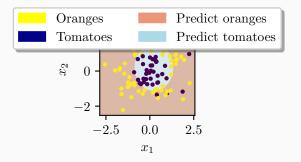


Linear boundary will not be accurate here. What is the technical name of the problem?



Linear boundary will not be accurate here. What is the technical name of the problem? Bias!

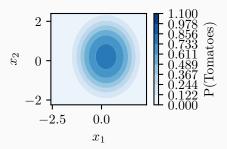
$$\phi(x) = \begin{bmatrix} \phi_0(x) \\ \phi_1(x) \\ \vdots \\ \phi_{K-1}(x) \end{bmatrix} = \begin{bmatrix} 1 \\ x \\ x^2 \\ x^3 \\ \vdots \\ x^{K-1} \end{bmatrix} \in \mathbb{R}^K$$

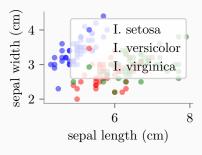


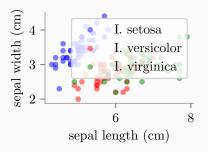
Using  $x_1^2, x_2^2$  as additional features, we are able to learn a more accurate classifier.

How would you expect the probability contours look like?

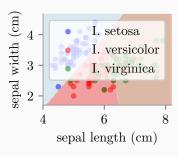
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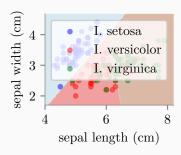




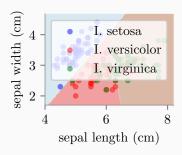


How would you learn a classifier? Or, how would you expect the classifier to learn decision boundaries?

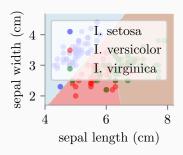




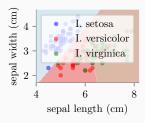
1. Use one-vs.-all on  $\underline{\mathsf{Binary}}$  Logistic Regression

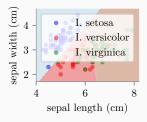


- 1. Use one-vs.-all on  $\underline{\mathsf{Binary}}$  Logistic Regression
- 2. Use one-vs.-one on  $\underline{\mathsf{Binary}}$  Logistic Regression

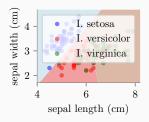


- 1. Use one-vs.-all on Binary Logistic Regression
- 2. Use one-vs.-one on Binary Logistic Regression
- 3. Extend <u>Binary</u> Logistic Regression to <u>Multi-Class</u> Logistic Regression

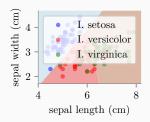




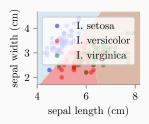
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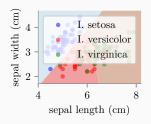
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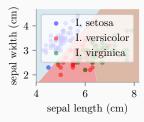
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- 3.  $P(\text{virginica (class 3)}) = \mathcal{F}(\mathbf{X}\theta_3)$

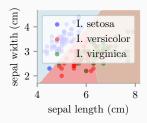


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- 4. Goal: Learn  $\theta_i \forall i \in \{1, 2, 3\}$

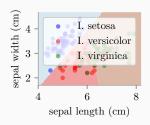


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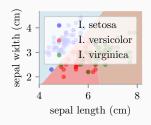




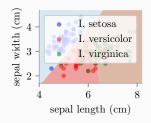
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- 2. Property:  $\sum_{i=1}^{3} \mathcal{F}(\mathbf{X}\boldsymbol{\theta}_i) = 1$
- 3. Also  $\mathcal{F}(z) \in [0,1]$
- 4. Also,  $\mathcal{F}(z)$  has squashing proprties:  $R\mapsto [0,1]$

### Softmax

$$Z \in \mathbb{R}^d$$
 $\mathcal{F}(z_i) = \frac{e^{z_i}}{\sum_{i=1}^d e^{z_i}}$ 
 $\therefore \sum \mathcal{F}(z_i) = 1$ 

 $\mathcal{F}(z_i)$  refers to probability of class <u>i</u>

# Softmax for Multi-Class Logistic Regression

$$k = \{1, \dots, k\} \text{classes}$$
 
$$\theta = \begin{bmatrix} \vdots \vdots \vdots \\ \theta_1 \theta_2 \cdots \theta_k \\ \vdots \vdots \vdots \end{bmatrix}$$

 $P(y = k|X, \theta) = \frac{e^{X\theta_k}}{\sum_{k=1}^{K} e^{X\theta_k}}$ 

# Softmax for Multi-Class Logistic Regression

For K = 2 classes,

$$P(y = k|X, \theta) = \frac{e^{\mathbf{X}\theta_k}}{\sum_{k=1}^{K} e^{\mathbf{X}\theta_k}}$$

$$P(y = 0|X, \theta) = \frac{e^{\mathbf{X}\theta_0}}{e^{\mathbf{X}\theta_0} + e^{\mathbf{X}\theta_1}}$$

$$P(y = 1|X, \theta) = \frac{e^{\mathbf{X}\theta_1}}{e^{\mathbf{X}\theta_0} + e^{\mathbf{X}\theta_1}} = \frac{e^{\mathbf{X}\theta_1}}{e^{\mathbf{X}\theta_1}\{1 + e^{X(\theta_0 - \theta_1)}\}}$$

$$= \frac{1}{1 + e^{-\mathbf{X}\theta'}}$$

$$= \text{Sigmoid!}$$

Assume our prediction and ground truth for the three classes for  $i^{th}$  point is:

$$\hat{y}_i = \begin{bmatrix} 0.1\\0.8\\0.1 \end{bmatrix} = \begin{bmatrix} \hat{y}_i^1\\\hat{y}_i^2\\\hat{y}_i^3 \end{bmatrix}$$

$$y_i = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} y_i^1 \\ y_i^2 \\ y_i^3 \end{bmatrix}$$

meaning the true class is Class #2

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Tends to zero

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$$= -(0 \times \log(0.1) + 1 \times \log(0.4) + 0 \times \log(0.1))$$

High number! Huge penalty for misclassification!

For 2 class we had:

$$J(\theta) = -\left\{\sum_{i=1}^{N} y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i))\right\}$$

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Extend to K-class:

$$J(\theta) = -\left\{ \sum_{i=1}^{N} \sum_{k=1}^{K} y_{i}^{k} \log(\hat{y}_{i}^{k}) \right\}$$

#### Now:

$$\frac{\partial J(\theta)}{\partial \theta_k} = \sum_{i=1}^N \left[ x_i \left\{ I(y_i = k) - P(y_i = k | x_i, \theta) \right\} \right]$$

#### **Hessian Matrix**

The Hessian matrix of f(.) with respect to  $\theta$ , written  $\nabla^2_{\theta} f(\theta)$  or simply as  $\mathbb{H}$ , is the  $d \times d$  matrix of partial derivatives,

$$\nabla_{\theta}^{2} f(\theta) = \begin{bmatrix} \frac{\partial^{2} f(\theta)}{\partial \theta_{1}^{2}} \frac{\partial^{2} f(\theta)}{\partial \theta_{1} \partial \theta_{2}} \cdots \frac{\partial^{2} f(\theta)}{\partial \theta_{1} \partial \theta_{n}} \\ \frac{\partial^{2} f(\theta)}{\partial \theta_{2} \partial \theta_{1}} \frac{\partial^{2} f(\theta)}{\partial \theta_{2}^{2}} \cdots \frac{\partial^{2} f(\theta)}{\partial \theta_{2} \partial \theta_{n}} \\ \vdots & \vdots & \vdots \\ \frac{\partial^{2} f(\theta)}{\partial \theta_{n} \partial \theta_{1}} \frac{\partial^{2} f(\theta)}{\partial \theta_{n} \partial \theta_{2}} \cdots \frac{\partial^{2} f(\theta)}{\partial \theta_{n}^{2}} \end{bmatrix}$$

#### **Newton's Algorithm**

The most basic second-order optimization algorithm is Newton's algorithm, which consists of updates of the form,

$$\theta_{k+1} = \theta_k - \mathbb{H}^1_k g_k$$

where  $g_k$  is the gradient at step k. This algorithm is derived by making a second-order Taylor series approximation of  $f(\theta)$  around  $\theta_k$ :

$$f_{quad}(\theta) = f(\theta_k) + g_k^T(\theta - \theta_k) + \frac{1}{2}(\theta - \theta_k)^T \mathbb{H}_k(\theta - \theta_k)$$

differentiating and equating to zero to solve for  $\theta_{k+1}$ .

## **Learning Parameters**

Now assume:

$$g(\theta) = \sum_{i=1}^{N} \left[ \sigma_{\theta}(x_i) - y_i \right] x_i^j = \mathbf{X}^{\mathsf{T}} (\sigma_{\theta}(\mathbf{X}) - \mathbf{y})$$
$$\pi_i = \sigma_{\theta}(x_i)$$

Let  $\mathbb{H}$  represent the Hessian of  $J(\theta)$ 

$$\mathbb{H} = \frac{\partial}{\partial \theta} g(\theta) = \frac{\partial}{\partial \theta} \sum_{i=1}^{N} \left[ \sigma_{\theta}(x_i) - y_i \right] x_i^j$$

$$= \sum_{i=1}^{N} \left[ \frac{\partial}{\partial \theta} \sigma_{\theta}(x_i) x_i^j - \frac{\partial}{\partial \theta} y_i x_i^j \right] = \sum_{i=1}^{N} \sigma_{\theta}(x_i) (1 - \sigma_{\theta}(x_i)) x_i x_i^T$$

$$= \mathbf{X}^{\mathsf{T}} diag(\sigma_{\theta}(x_i) (1 - \sigma_{\theta}(x_i))) \mathbf{X}$$

## Iteratively reweighted least squares (IRLS)

For binary logistic regression, recall that the gradient and Hessian of the negative log-likelihood are given by:

$$g(\theta)_k = \mathbf{X}^{\mathsf{T}}(\pi_{\mathbf{k}} - \mathbf{y})$$
 $\mathbf{H}_k = \mathbf{X}^{\mathsf{T}}S_k\mathbf{X}$ 
 $\mathbf{S}_k = diag(\pi_{1k}(1 - \pi_{1k}), \dots, \pi_{nk}(1 - \pi_{nk}))$ 
 $\pi_{ik} = sigm(\mathbf{x_i}\theta_{\mathbf{k}})$ 

The Newton update at iteraion k + 1 for this model is as follows:

$$\theta_{k+1} = \theta_k - \mathbb{H}^{-1} g_k = \theta_k + (X^T S_k X)^{-1} X^T (y - \pi_k)$$

$$= (X^T S_k X)^{-1} [(X^T S_k X) \theta_k + X^T (y - \pi_k)] = (X^T S_k X)^{-1} X^T [S_k X \theta_k + y - \pi_k]$$

## Regularized Logistic Regression

Unregularised:

$$J_1(\theta) = -\left\{\sum_{i=1}^N y_i \log(\sigma_{\theta}(x_i)) + (1-y_i) \log(1-\sigma_{\theta}(x_i))\right\}$$

L2 Regularization:

$$J(\theta) = J_1(\theta) + \lambda \theta^T \theta$$

L1 Regularization:

$$J(\theta) = J_1(\theta) + \lambda |\theta|$$