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July 29, 2025

Used for constrained optimization of the form

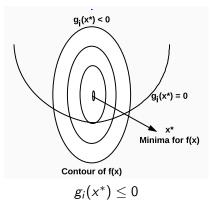
Minimize f(x), where $x \in \mathbb{R}^k$ such that

$$h_i(x) = 0$$
, $\forall i = 1, ..., m$ (m equalities) $g_j(x) \leq 0$, $\forall j = 1, ..., n$ (n inequalities)

Minimize $L(x, \lambda, \mu)$ w.rt. $x \implies \nabla_x L(x, \lambda, \mu) = 0$ Gives k equations

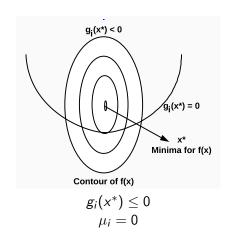
Minimize $L(x, \lambda, \mu)$ w.rt. $\lambda \implies \nabla_{\lambda} L(x, \lambda, \mu) = 0$ Gives m equations

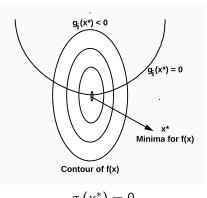
In both cases, $\mu_i g_i(x^*) = 0$



$$g_i(x^*) \le 0$$
$$\mu_i = 0$$

In both cases, $\mu_i g_i(x^*) = 0$

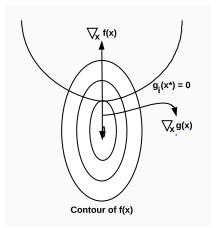




$$g_i(x^*)=0$$

In both cases, $\mu_i g_i(x^*) = 0$

Constraint on μ_i 's



$$min_x L(x, \lambda, \mu) \implies \nabla_x f(x) + \nabla_x \mu_i g_i(x) = 0$$

$$\mu_i = \frac{\nabla_x f(x)}{\nabla_x \mu_i g_i(x)} = +ve$$

Stationarity (For minimization)
$$\nabla_{x} f(x) + \sum_{i=1}^{m} \nabla_{x} \lambda_{i} h_{i}(x) + \sum_{i=1}^{n} \nabla_{x} \mu_{i} g_{i}(x) = 0$$

Stationarity (For minimization)
$$\nabla_{x} f(x) + \sum_{i=1}^{m} \nabla_{x} \lambda_{i} h_{i}(x) + \sum_{i=1}^{n} \nabla_{x} \mu_{i} g_{i}(x) = 0$$

Equality Constraints

$$\nabla_{\lambda} f(x) + \sum_{i=1}^{m} \nabla_{\lambda} \lambda_{i} h_{i}(x) + \sum_{i=1}^{n} \nabla_{\lambda} \mu_{i} g_{i}(x) = 0$$
$$\sum_{i=1}^{m} \nabla_{\lambda} \lambda_{i} h_{i}(x) = 0$$

Stationarity (For minimization)

$$\nabla_x f(x) + \sum_{i=1}^m \nabla_x \lambda_i h_i(x) + \sum_{i=1}^n \nabla_x \mu_i g_i(x) = 0$$

Equality Constraints

$$\nabla_{\lambda} f(x) + \sum_{i=1}^{m} \nabla_{\lambda} \lambda_{i} h_{i}(x) + \sum_{i=1}^{n} \nabla_{\lambda} \mu_{i} g_{i}(x) = 0$$
$$\sum_{i=1}^{m} \nabla_{\lambda} \lambda_{i} h_{i}(x) = 0$$

Inequality Constraints (Complementary Slackness)

$$\mu_i g_i(x) = 0 \forall i = 1, \dots, n$$

 $\mu_i \ge 0$

Minimize
$$x^2+y^2$$
 such that,
$$x^2+y^2 \leq 5 \\ x+2y=4 \\ x,y \geq 0$$

$$f(x,y) = x^2 + y^2$$

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 $h(x,y) = x + 2y - 4$

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$$h(x,y) = x + 2y - 4$$

$$g_{1}(x,y) = x^{2} + y^{2} - 5$$

$$f(x,y) = x^{2} + y^{2}$$

$$h(x,y) = x + 2y - 4$$

$$g_{1}(x,y) = x^{2} + y^{2} - 5$$

$$g_{2}(x,y) = -x$$

$$f(x,y) = x^{2} + y^{2}$$

$$h(x,y) = x + 2y - 4$$

$$g_{1}(x,y) = x^{2} + y^{2} - 5$$

$$g_{2}(x,y) = -x$$

$$g_{3}(x,y) = -y$$

$$f(x,y) = x^{2} + y^{2}$$

$$h(x,y) = x + 2y - 4$$

$$g_{1}(x,y) = x^{2} + y^{2} - 5$$

$$g_{2}(x,y) = -x$$

$$g_{3}(x,y) = -y$$

$$L(x, y, \lambda, \mu_1, \mu_2, \mu_3) = x^2 + y^2 + \lambda(x + 2y - 4) + \mu_1(x^2 + y^2 - 5) + \mu_2(-x) + \mu_3(-y)$$

Stationarity

$$\nabla_{x}L(x,y,\lambda,\mu_{1},\mu_{2},\mu_{3})=0$$

$$\implies 2x+\lambda+2\mu_{1}x-\mu_{2}=0......(1)$$

$$\nabla_{y}L(x,y,\lambda,\mu_{1},\mu_{2},\mu_{3})=0$$

$$\implies 2y+2\lambda+2\mu_{1}y-\mu_{3}=0.....(2)$$

Stationarity

$$\nabla_{x}L(x,y,\lambda,\mu_{1},\mu_{2},\mu_{3})=0$$

$$\Rightarrow 2x+\lambda+2\mu_{1}x-\mu_{2}=0......(1)$$

$$\nabla_{y}L(x,y,\lambda,\mu_{1},\mu_{2},\mu_{3}) = 0$$

$$\implies 2y + 2\lambda + 2\mu_{1}y - \mu_{3} = 0 \dots (2)$$

Equality Constraint

$$x + 2y = 4 \dots (3)$$

Stationarity

$$\nabla_x L(x, y, \lambda, \mu_1, \mu_2, \mu_3) = 0$$

$$\implies 2x + \lambda + 2\mu_1 x - \mu_2 = 0 \dots (1)$$

$$\nabla_{y}L(x,y,\lambda,\mu_{1},\mu_{2},\mu_{3})=0$$

$$\implies 2y+2\lambda+2\mu_{1}y-\mu_{3}=0.....(2)$$

Equality Constraint

$$x + 2y = 4 \dots (3)$$

Slackness

$$\mu_1(x^2+y^2-5)=0.....(4)$$

$$\mu_2 x = 0 \dots (5)$$

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From (6), \mu_3=0 or y=0 But if, y=0, then x=4 according to (3) . This violates (1). Hence, y\neq 0 and \mu_3=0
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From (5),
$$\mu_1=0$$
 or $x=0$
If $x=0$, $y=2$, which implies $x^2+y^2=4(\le 5)$
Since $(x,y)=(0,2)$ gives smaller x^2+y^2 terms than 5, Using (4), $\mu_1=0$

On further solving we get, x = 0.8 y = 1.6