Logistic Regression

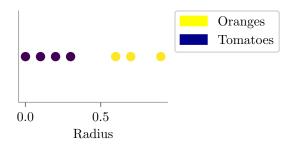
Nipun Batra

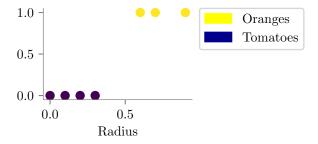
IIT Gandhinagar

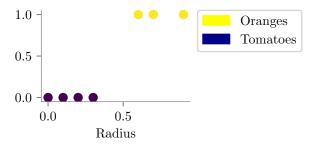
August 1, 2025

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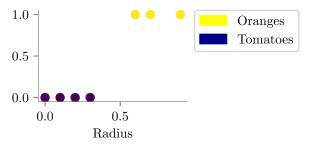
- 1. Problem Setup
- 2. Logistic/Sigmoid function
- 3. Deriving Cost Function via Maximum Likelihood Estimation
- 4. Cross Entropy Cost Function
- 5. Class Imbalance Handling
- 6. Practice and Review



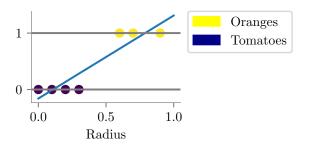




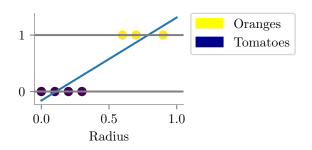
Aim: Probability(Tomatoes | Radius) ? or



Aim: Probability(Tomatoes | Radius) ? or More generally, P(y = 1|X = x)?



$$P(X = Orange | Radius) = \theta_0 + \theta_1 \times Radius$$



$$P(X = Orange|Radius) = \theta_0 + \theta_1 \times Radius$$

Generally,

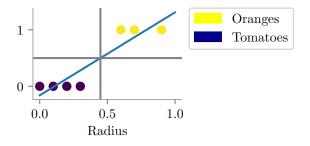
$$P(y = 1|\mathbf{x}) = \mathbf{X}\boldsymbol{\theta}$$

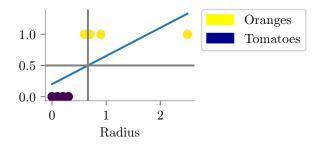
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Prediction:
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If $\theta_0 + \theta_1 \times \textit{Radius} > 0.5 \rightarrow \text{Orange}$ Else $\rightarrow \text{Tomato}$

Problem:

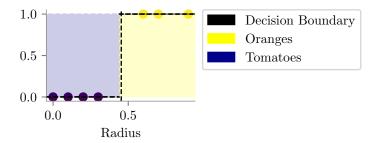
Range of $X\theta$ is $(-\infty, \infty)$ But $P(y = 1 | ...) \in [0, 1]$





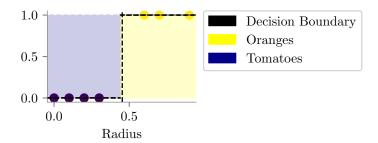
Linear regression for classification gives a poor prediction!

Ideal boundary

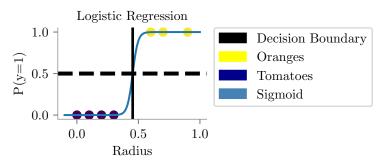


 Have a decision function similar to the above (but not so sharp and discontinuous)

Ideal boundary



- Have a decision function similar to the above (but not so sharp and discontinuous)
- Aim: use linear regression still!



Question. Can we still use Linear Regression? Answer. Yes! Transform $\hat{y} \rightarrow [0, 1]$

$$\begin{array}{l} \hat{y} \in (-\infty, \infty) \\ \phi = \text{Sigmoid / Logistic Function } (\sigma) \\ \phi(\hat{y}) \in [0,1] \\ \\ \sigma(z) = \frac{1}{1+e^{-z}} \\ \\ 0.5 \\ \hline 0.0 \\ \\ -10 \\ \end{array}$$



$$z \to \infty$$

 $\sigma(z) \to 1$

 $\begin{aligned} \mathbf{Z} &\to \infty \\ \sigma(\mathbf{Z}) &\to 1 \\ \mathbf{Z} &\to -\infty \end{aligned}$

$$\begin{split} \mathbf{Z} &\to \infty \\ \sigma(\mathbf{Z}) &\to 1 \\ \mathbf{Z} &\to -\infty \\ \sigma(\mathbf{Z}) &\to 0 \end{split}$$

$$\begin{split} \mathbf{Z} &\to \infty \\ \sigma(\mathbf{Z}) &\to 1 \\ \mathbf{Z} &\to -\infty \\ \sigma(\mathbf{Z}) &\to 0 \\ \mathbf{Z} &= 0 \end{split}$$

$$\begin{split} \mathbf{Z} &\to \infty \\ \sigma(\mathbf{Z}) &\to 1 \\ \mathbf{Z} &\to -\infty \\ \sigma(\mathbf{Z}) &\to 0 \\ \mathbf{Z} &= 0 \\ \sigma(\mathbf{Z}) &= 0.5 \end{split}$$

Question. Could you use some other transformation (ϕ) of \hat{y} s.t.

$$\phi(\hat{\mathbf{y}}) \in [0, 1]$$

Yes! But Logistic Regression works.

$$P(y = 1|X) = \sigma(X\theta) = \frac{1}{1 + e^{-X\theta}}$$

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$$\therefore \frac{P(y=1|X)}{1-P(y=1|X)} = e^{X\theta} \implies X\theta = \log \frac{P(y=1|X)}{1-P(y=1|X)}$$

Odds (Used in betting)

$$\frac{P(win)}{P(loss)}$$

Here,

$$Odds = \frac{P(y=1)}{P(y=0)}$$

log-odds =
$$\log \frac{P(y=1)}{P(y=0)} = \mathbf{X}\boldsymbol{\theta}$$

Logistic Regression

Q. What is decision boundary for Logistic Regression?

Logistic Regression

Q. What is decision boundary for Logistic Regression? Decision Boundary: P(y = 1|X) = P(y = 0|X)

or
$$\frac{1}{1+e^{-X heta}}=\frac{e^{-X heta}}{1+e^{-X heta}}$$
 or $e^{X heta}=1$ or $X heta=0$

Could we use cost function as:

$$J(\theta) = \sum (y_i - \hat{y}_i)^2$$
$$\hat{y}_i = \sigma(\mathbf{X}\boldsymbol{\theta})$$

Answer: No (Non-Convex)

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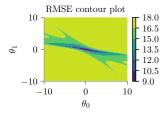
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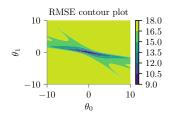
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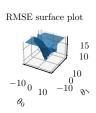
- Sigmoid $\sigma(\mathbf{z}) = \frac{1}{1+\mathbf{e}^{-\mathbf{z}}}$ is non-linear
- Composition $(\sigma(\mathbf{X}\boldsymbol{\theta}) \mathbf{y})^2$ has multiple local minima
- No guarantee gradient descent finds global optimum
- This is why we need cross-entropy loss instead!

Cost function convexity

Cost function convexity







```
Likelihood = P(D|\theta)

P(y|X,\theta) = \prod_{i=1}^{n} P(y_i|x_i,\theta)

where y = 0 or 1
```

 $\mathsf{Likelihood} = P(D|\theta)$

$$P(y|X,\theta) = \prod_{i=1}^{n} P(y_i|X_i,\theta) = \prod_{i=1}^{n} \left\{ \frac{1}{1 + e^{-X_i^T \theta}} \right\}^{y_i} \left\{ 1 - \frac{1}{1 + e^{-X_i^T \theta}} \right\}^{1 - y_i}$$

[Above: Similar to $P(D|\theta)$ for Linear Regression; Difference Bernoulli instead of Gaussian]

 $-\log P(y|\mathbf{X}, \boldsymbol{\theta}) = \mathsf{Negative\ Log\ Likelihood} = \mathsf{Cost\ function\ will\ be}$

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- Idea find MLE estimate for θ

•
$$p(H) = \theta$$
 and $p(T) = 1 - \theta$

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- Log-likelihood = $\mathcal{LL}(\theta) = n_h \log(\theta) + n_t \log(1 \theta)$
- $\frac{\partial \mathcal{LL}(\theta)}{\partial \theta} = 0 \implies \frac{n_h}{\theta} + \frac{n_t}{1-\theta} = 0 \implies \theta_{MLE} = \frac{n_h}{n_h + n_t}$

$$J(\theta) = -\log \left\{ \prod_{i=1}^{n} \left\{ \frac{1}{1 + e^{-X_i^T \theta}} \right\}^{y_i} \left\{ 1 - \frac{1}{1 + e^{-X_i^T \theta}} \right\}^{1 - y_i} \right\}$$
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This cost function is called cross-entropy.

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This cost function is called cross-entropy. Why?

What is the interpretation of the cost function?

What is the interpretation of the cost function? Let us try to write the cost function for a single example:

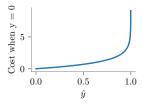
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First, assume y_i is 0, then if \hat{y}_i is 0, the loss is 0; but, if \hat{y}_i is 1, the loss tends towards infinity!



Notebook: logits-usage

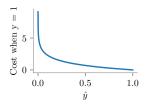
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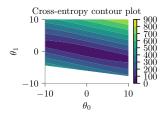
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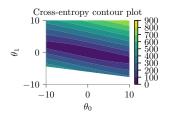
What is the interpretation of the cost function?

$$J(\theta) = -y_i \log \hat{y}_i - (1 - y_i) \log(1 - \hat{y}_i)$$

Now, assume y_i is 1, then if \hat{y}_i is 0, the loss is huge; but, if \hat{y}_i is 1, the loss is zero!







Cross-entropy surface plot



$$\frac{\partial J(\theta)}{\partial \theta_j} = -\frac{\partial}{\partial \theta_j} \left\{ \sum_{i=1}^{N} y_i log(\sigma_{\theta}(x_i)) + (1 - y_i) log(1 - \sigma_{\theta}(x_i)) \right\}$$

$$= -\sum_{i=1}^{N} \left[y_i \frac{\partial}{\partial \theta_j} \log(\sigma_{\theta}(x_i)) + (1 - y_i) \frac{\partial}{\partial \theta_j} log(1 - \sigma_{\theta}(x_i)) \right]$$

$$\frac{\partial J(\theta)}{\partial \theta_{j}} = -\sum_{i=1}^{N} \left[y_{i} \frac{\partial}{\partial \theta_{j}} \log(\sigma_{\theta}(x_{i})) + (1 - y_{i}) \frac{\partial}{\partial \theta_{j}} log(1 - \sigma_{\theta}(x_{i})) \right]$$

$$= -\sum_{i=1}^{N} \left[\frac{y_{i}}{\sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{i}} \sigma_{\theta}(x_{i}) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{i}} (1 - \sigma_{\theta}(x_{i})) \right]$$

Aside:

Aside.
$$\frac{\partial}{\partial z}\sigma(z) = \frac{\partial}{\partial z}\frac{1}{1+e^{-z}} = -(1+e^{-z})^{-2}\frac{\partial}{\partial z}(1+e^{-z})$$
$$= \frac{e^{-z}}{(1+e^{-z})^2} = \left(\frac{1}{1+e^{-z}}\right)\left(\frac{e^{-z}}{1+e^{-z}}\right) = \sigma(z)\left\{\frac{1+e^{-z}}{1+e^{-z}} - \frac{1}{1+e^{-z}}\right\}$$
$$= \sigma(z)(1-\sigma(z))$$

Resuming from (1)

$$\begin{split} \frac{\partial J(\theta)}{\partial \theta_{j}} &= -\sum_{i=1}^{N} \left[\frac{y_{i}}{\sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{j}} \sigma_{\theta}(x_{i}) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} \frac{\partial}{\partial \theta_{j}} (1 - \sigma_{\theta}(x_{i})) \right] \\ &= -\sum_{i=1}^{N} \left[\frac{y_{i}\sigma_{\theta}(x_{i})}{\sigma_{\theta}(x_{i})} (1 - \sigma_{\theta}(x_{i})) \frac{\partial}{\partial \theta_{j}} (x_{i}\theta) + \frac{1 - y_{i}}{1 - \sigma_{\theta}(x_{i})} (1 - \sigma_{\theta}(x_{i})) \frac{\partial}{\partial \theta_{j}} (1 - \sigma_{\theta}(x_{i})) \right] \\ &= -\sum_{i=1}^{N} \left[y_{i} (1 - \sigma_{\theta}(x_{i})) x_{i}^{j} - (1 - y_{i}) \sigma_{\theta}(x_{i}) x_{i}^{j} \right] \\ &= -\sum_{i=1}^{N} \left[(y_{i} - y_{i}\sigma_{\theta}(x_{i}) - \sigma_{\theta}(x_{i}) + y_{i}\sigma_{\theta}(x_{i})) x_{i}^{j} \right] \end{split}$$

 $=\sum_{i}^{N}\left[\sigma_{\theta}(x_{i})-y_{i}\right]x_{i}^{j}$

Learning Parameters

$$\frac{\partial J(\theta)}{\theta_j} = \sum_{i=1}^{N} \left[\sigma_{\theta}(x_i) - y_i \right] x_i^j$$

Now, just use Gradient Descent!

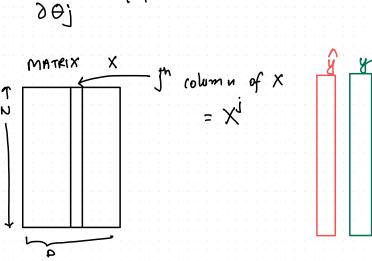
$$\frac{\partial J(\theta)}{\partial \Theta_j} = \sum_{i=1}^{N} (\hat{y_i} - \hat{y_i}) z_i^j$$

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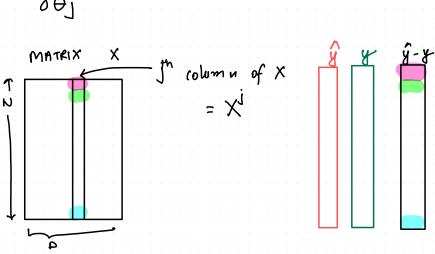
$$\frac{\partial J(\theta)}{\partial \theta j} = \sum_{i=1}^{N} (\hat{y_i} - \hat{y_i}) z_i^j$$
MATRIX X

The columns of X

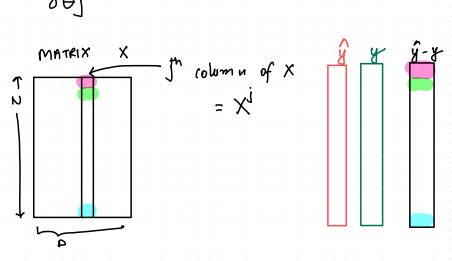


$$\frac{\partial J(\theta)}{\partial \theta_i} = \sum_{i=1}^{N} (\hat{y_i} - \hat{y_i}) z_i^j$$

$$\frac{\partial J(\theta)}{\partial \theta_i} = \sum_{i=1}^{N} (\hat{y_i} - y_i) z_i^j$$



$$\frac{\partial J(\theta)}{\partial x_i} = \sum_{i=1}^{N} (\hat{y_i} - \hat{y_i}) z_i^j = \sum_{i=1}^{N} (\hat{y_i} - \hat{y_i})$$



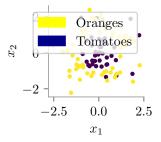
$$\frac{\partial J(\theta)}{\partial \Theta_{j}} = \sum_{i=1}^{N} (\hat{y_{i}} - \hat{y_{i}})^{2_{i}} = x_{1xN}^{T} (\hat{y_{i}} - \hat{y_{j}})$$

$$\begin{bmatrix} \frac{\partial J(\theta)}{\partial \Theta_{i}} \\ \frac{\partial J(\theta)}{\partial \Theta_{i}} \\ \vdots \\ \frac{\partial J(\theta)}{\partial \Theta_{i}} \end{bmatrix} = \begin{bmatrix} x_{1}^{T} (\hat{y_{i}} - \hat{y_{i}}) \\ x_{2}^{T} (\hat{y_{i}} - \hat{y_{i}}) \\ \vdots \\ \frac{\partial J(\theta)}{\partial \Theta_{i}} \end{bmatrix} = \begin{bmatrix} x_{1}^{T} (\hat{y_{i}} - \hat{y_{i}}) \\ \frac{\partial J(\theta)}{\partial \Theta_{i}} \\ \vdots \\ \frac{\partial J(\theta)}{\partial \Theta_{i}} \end{bmatrix}$$

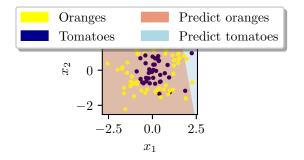
$$\frac{\partial J(\theta)}{\partial \Theta_{j}} = \sum_{i=1}^{N} (\hat{y_{i}} - y_{i}) z_{i}^{j} = x_{i}^{j} (\hat{y_{i}} - y_{j})$$

$$\begin{bmatrix}
\frac{\partial J(0)}{\partial B_{1}} \\
\frac{\partial J(0)}{\partial B_{2}} \\
\vdots \\
\frac{\partial J(0)}{\partial B_{D}}
\end{bmatrix} = \begin{bmatrix}
x^{1} (\hat{y} - \hat{y}) \\
x^{2} (\hat{y} - \hat{y})
\end{bmatrix}$$

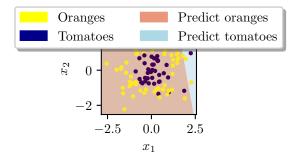
$$= \begin{bmatrix}
x^{1}(\hat{y} - \hat{y}) \\
\vdots \\
x^{D}(\hat{y} - \hat{y})
\end{bmatrix}$$



What happens if you apply logistic regression on the above data?

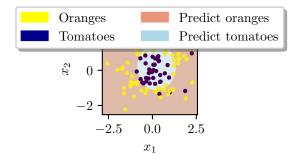


Linear boundary will not be accurate here. What is the technical name of the problem?



Linear boundary will not be accurate here. What is the technical name of the problem? Bias!

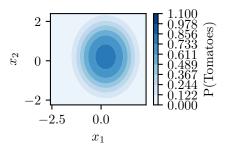
$$\phi(\mathbf{X}) = \begin{bmatrix} \phi_0(\mathbf{X}) \\ \phi_1(\mathbf{X}) \\ \vdots \\ \phi_{K-1}(\mathbf{X}) \end{bmatrix} = \begin{bmatrix} 1 \\ \mathbf{X} \\ \mathbf{X}^2 \\ \mathbf{X}^3 \\ \vdots \\ \mathbf{X}^{K-1} \end{bmatrix} \in \mathbb{R}^K$$

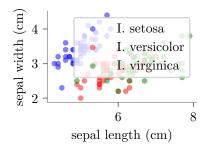


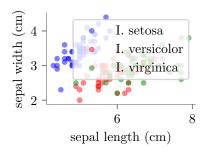
Using x_1^2, x_2^2 as additional features, we are able to learn a more accurate classifier.

How would you expect the probability contours look like?

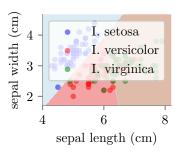
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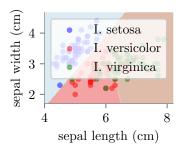




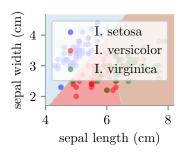


How would you learn a classifier? Or, how would you expect the classifier to learn decision boundaries?

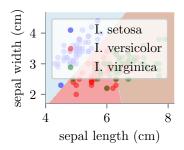




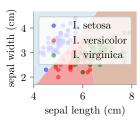
1. Use one-vs.-all on Binary Logistic Regression

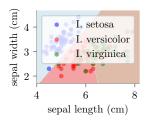


- 1. Use one-vs.-all on Binary Logistic Regression
- 2. Use one-vs.-one on Binary Logistic Regression

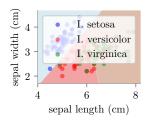


- 1. Use one-vs.-all on Binary Logistic Regression
- 2. Use one-vs.-one on Binary Logistic Regression
- 3. Extend <u>Binary</u> Logistic Regression to <u>Multi-Class</u> Logistic Regression

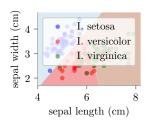




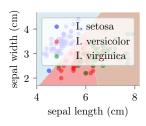
1. Learn P(setosa (class 1)) = $\mathcal{F}(\mathbf{X}\boldsymbol{\theta}_1)$



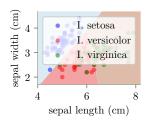
- 1. Learn P(setosa (class 1)) = $\mathcal{F}(\mathbf{X}\boldsymbol{\theta}_1)$
- 2. P(versicolor (class 2)) = $\mathcal{F}(\mathbf{X}\boldsymbol{\theta}_2)$



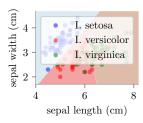
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- 3. P(virginica (class 3)) = $\mathcal{F}(\mathbf{X}\boldsymbol{\theta}_3)$

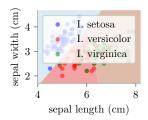


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- 4. Goal: Learn $\theta_i \forall i \in \{1, 2, 3\}$

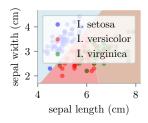


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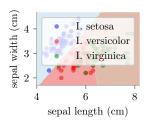




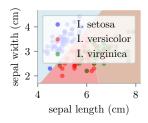
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- 3. Also $\mathcal{F}(\mathbf{z}) \in [0,1]$
- **4.** Also, $\mathcal{F}(z)$ has squashing proprties: $R \mapsto [0,1]$

Softmax

$$Z \in \mathbb{R}^d$$

$$\mathcal{F}(z_i) = \frac{e^{z_i}}{\sum_{i=1}^d e^{z_i}}$$

$$\therefore \sum \mathcal{F}(z_i) = 1$$

 $\mathcal{F}(z_i)$ refers to probability of class \underline{i}

Softmax for Multi-Class Logistic Regression

$$k = \{1, \dots, k\} \text{classes}$$

$$\theta = \begin{bmatrix} \vdots \vdots \vdots \\ \theta_1 \theta_2 \cdots \theta_k \\ \vdots \vdots \vdots \end{bmatrix}$$

$$P(y = k | X, \theta) = \frac{e^{X \theta_k}}{\sum_{k=1}^K e^{X \theta_k}}$$

Softmax for Multi-Class Logistic Regression

For K = 2 classes,

$$\begin{split} P(y=k|X,\theta) &= \frac{e^{X\theta_k}}{\sum_{k=1}^K e^{X\theta_k}} \\ P(y=0|X,\theta) &= \frac{e^{X\theta_0}}{e^{X\theta_0} + e^{X\theta_1}} \\ P(y=1|X,\theta) &= \frac{e^{X\theta_1}}{e^{X\theta_0} + e^{X\theta_1}} = \frac{e^{X\theta_1}}{e^{X\theta_1}\{1 + e^{X(\theta_0 - \theta_1)}\}} \\ &= \frac{1}{1 + e^{-X\theta'}} \\ &= \text{Sigmoid!} \end{split}$$

Assume our prediction and ground truth for the three classes for i^{th} point is:

$$\hat{y_i} = \begin{bmatrix} 0.1\\0.8\\0.1 \end{bmatrix} = \begin{bmatrix} \hat{y}_i^1\\\hat{y}_i^2\\\hat{y}_i^3 \end{bmatrix}$$

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meaning the true class is Class #2

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Assume our prediction and ground truth for the three classes for i^{th} point is:

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meaning the true class is Class #2 Let us calculate $-\sum_{k=1}^3 y_i^k \log \hat{y}_i^k = -(0 \times \log(0.1) + 1 \times \log(0.4) + 0 \times \log(0.1))$ High number! Huge penalty for misclassification!

For 2 class we had:

$$J(\theta) = -\left\{ \sum_{i=1}^{N} y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i)) \right\}$$

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Extend to K-class:

$$J(\theta) = -\left\{\sum_{i=1}^{N} \sum_{k=1}^{K} y_i^k \log(\hat{y}_i^k)\right\}$$

Now:

$$\frac{\partial J(\theta)}{\partial \theta_k} = \sum_{i=1}^{N} \left[x_i \left\{ I(y_i = k) - P(y_i = k | x_i, \theta) \right\} \right]$$

Hessian Matrix

The Hessian matrix of f(.) with respect to θ , written $\nabla^2_{\theta} f(\theta)$ or simply as \mathbb{H} , is the $d \times d$ matrix of partial derivatives,

$$\nabla^2_{\theta} f(\theta) = \begin{bmatrix} \frac{\partial^2 f(\theta)}{\partial \theta_1^2} \frac{\partial^2 f(\theta)}{\partial \theta_1 \partial \theta_2} \cdots \frac{\partial^2 f(\theta)}{\partial \theta_1 \partial \theta_n} \\ \frac{\partial^2 f(\theta)}{\partial \theta_2 \partial \theta_1} \frac{\partial^2 f(\theta)}{\partial \theta_2^2} \cdots \frac{\partial^2 f(\theta)}{\partial \theta_2 \partial \theta_n} \\ \vdots & \vdots \\ \frac{\partial^2 f(\theta)}{\partial \theta_n \partial \theta_1} \frac{\partial^2 f(\theta)}{\partial \theta_n \partial \theta_2} \cdots \frac{\partial^2 f(\theta)}{\partial \theta_n^2} \end{bmatrix}$$

Newton's Algorithm

The most basic second-order optimization algorithm is Newton's algorithm, which consists of updates of the form,

$$\theta_{k+1} = \theta_k - \mathbb{H}^1_k g_k$$

where g_k is the gradient at step k. This algorithm is derived by making a second-order Taylor series approximation of $f(\theta)$ around θ_k :

$$f_{quad}(\theta) = f(\theta_k) + g_k^{\mathsf{T}}(\theta - \theta_k) + \frac{1}{2}(\theta - \theta_k)^{\mathsf{T}} \mathbb{H}_k(\theta - \theta_k)$$

differentiating and equating to zero to solve for θ_{k+1} .

Learning Parameters

Now assume:

$$g(\theta) = \sum_{i=1}^{N} \left[\sigma_{\theta}(x_i) - y_i \right] x_i^j = \mathbf{X}^{\top} (\sigma_{\theta}(X) - y)$$

$$\pi_i = \sigma_{ heta}({\sf X}_i)$$
 Let ${\mathbb H}$ represent the Hessian of $J(heta)$

$$\mathbb{H} = \frac{\partial}{\partial \theta} g(\theta) = \frac{\partial}{\partial \theta} \sum_{i=1}^{N} \left[\sigma_{\theta}(x_i) - y_i \right] x_i^j$$

$$\begin{split} & = \sum_{i=1}^{N} \left[\frac{\partial}{\partial \theta} \sigma_{\theta}(\mathbf{X}_{i}) \mathbf{X}_{i}^{j} - \frac{\partial}{\partial \theta} \mathbf{Y}_{i} \mathbf{X}_{i}^{j} \right] = \sum_{i=1}^{N} \sigma_{\theta}(\mathbf{X}_{i}) (1 - \sigma_{\theta}(\mathbf{X}_{i})) \mathbf{X}_{i} \mathbf{X}_{i}^{T} \\ & = \mathbf{X}^{\top} \mathsf{diag}(\sigma_{\theta}(\mathbf{X}_{i}) (1 - \sigma_{\theta}(\mathbf{X}_{i}))) \mathbf{X} \end{split}$$

Iteratively reweighted least squares (IRLS)

For binary logistic regression, recall that the gradient and Hessian of the negative log-likelihood are given by:

$$\begin{split} g(\theta)_k &= \mathbf{X}^\top (\pi_k - \mathbf{y}) \\ \mathbf{H}_k &= \mathbf{X}^\top \mathbf{S}_k \mathbf{X} \\ \mathbf{S}_k &= diag(\pi_{1k}(1 - \pi_{1k}), \dots, \pi_{nk}(1 - \pi_{nk})) \\ \pi_{ik} &= sigm(\mathbf{x}_i \theta_k) \end{split}$$

The Newton update at iteraion k + 1 for this model is as follows:

$$\begin{split} \theta_{k+1} &= \theta_k - \mathbb{H}^{-1} g_k = \theta_k + (X^T S_k X)^{-1} X^T (y - \pi_k) \\ &= (X^T S_k X)^{-1} [(X^T S_k X) \theta_k + X^T (y - \pi_k)] = (X^T S_k X)^{-1} X^T [S_k X \theta_k + y - \pi_k] \end{split}$$

Regularized Logistic Regression

Unregularised:

$$J_1(\theta) = -\left\{\sum_{i=1}^N y_i \log(\sigma_{\theta}(x_i)) + (1 - y_i) \log(1 - \sigma_{\theta}(x_i))\right\}$$

L2 Regularization:

$$J(\theta) = J_1(\theta) + \lambda \theta^{\mathsf{T}} \theta$$

L1 Regularization:

$$J(\theta) = J_1(\theta) + \lambda |\theta|$$

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- Naive approach fails: Predicting all samples as majority class

With 99% class 0, 1% class 1:

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- Need: Better evaluation metrics and techniques

Solution 1: Weighted Loss Function

Modify the cost function to penalize minority class errors more:

$$J(\boldsymbol{\theta}) = -\sum_{i=1}^{N} w_i \left[y_i \log(\sigma(\boldsymbol{\theta}^{\top} \mathbf{x}_i)) + (1 - y_i) \log(1 - \sigma(\boldsymbol{\theta}^{\top} \mathbf{x}_i)) \right]$$

• Class weights: $w_i = w_0$ if $y_i = 0$, $w_i = w_1$ if $y_i = 1$

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- Common choice: $w_1 = \frac{N_0}{N_1}$ (inverse frequency)
- Effect: Forces model to pay attention to minority class

Solution 1: Weighted Loss Function

Modify the cost function to penalize minority class errors more:

$$J(\boldsymbol{\theta}) = -\sum_{i=1}^{N} w_i \left[y_i \log(\sigma(\boldsymbol{\theta}^{\top} \mathbf{x}_i)) + (1 - y_i) \log(1 - \sigma(\boldsymbol{\theta}^{\top} \mathbf{x}_i)) \right]$$

- Class weights: $w_i = w_0$ if $y_i = 0$, $w_i = w_1$ if $y_i = 1$
- Common choice: $w_1 = \frac{N_0}{N_1}$ (inverse frequency)
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- Implementation: Available in most ML libraries (sklearn: class_weight='balanced')

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- Trade-off: Lower threshold → higher recall, lower precision

Modify the training data distribution:

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 - More sophisticated than simple duplication

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- PR-AUC: Area under precision-recall curve (better for imbalanced data)

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