Coordinate Descent

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• Express error as a difference of y_i and \hat{y}_i

$$\hat{y}_i = \sum_{i=0}^d \theta_j x_i^j = \theta_0 x_i^0 + \theta_1 x_i^1 + \theta_2 x_i^2 \dots + \theta_d x_i^d \qquad (1)$$

$$\epsilon_i = y_i - \hat{y}_i \tag{2}$$

$$= y_i - \theta_0 x_i^0 + \theta_1 x_i^1 + \dots + \theta_d x_i^d$$
 (3)

$$= y_i - \sum_{i=0}^d \theta_j x_i^j \tag{4}$$

$$\sum_{i=1}^{N} \epsilon^2 = RSS = \sum_{i=1}^{N} \left(y_i - \left(\theta_0 x_i^0 + \dots \quad \theta_j x_i^j + \theta_d x_i^d \right) \right)^2$$

$$\sum_{i=1}^{N} \epsilon^{2} = RSS = \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots \quad \theta_{j} x_{i}^{j} + \theta_{d} x_{i}^{d} \right) \right)^{2}$$
$$\frac{\partial RSS(\theta_{j})}{\partial \theta_{j}} = 2 \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots \quad \theta_{j} x_{i}^{j} + \dots \right) \right) \left(-x_{i}^{j} \right)$$

$$\sum_{i=1}^{N} \epsilon^{2} = RSS = \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots \quad \theta_{j} x_{i}^{j} + \theta_{d} x_{i}^{d} \right) \right)^{2}$$

$$\frac{\partial RSS(\theta_{j})}{\partial \theta_{j}} = 2 \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots \quad \theta_{j} x_{i}^{j} + \dots \right) \right) \left(-x_{i}^{j} \right)$$

$$= 2 \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots + \theta_{d} x_{i}^{d} \right) \right) \left(-x_{i}^{j} \right) + 2 \sum_{i=1}^{N} \theta_{j} (x_{i}^{j})^{2}$$

$$\sum_{i=1}^{N} \epsilon^{2} = RSS = \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots \quad \theta_{j} x_{i}^{j} + \theta_{d} x_{i}^{d} \right) \right)^{2}$$

$$\frac{\partial RSS (\theta_{j})}{\partial \theta_{j}} = 2 \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots \quad \theta_{j} x_{i}^{j} + \dots \right) \right) \left(-x_{i}^{j} \right)$$

$$= 2 \sum_{i=1}^{N} \left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots + \theta_{d} x_{i}^{d} \right) \right) \left(-x_{i}^{j} \right) + 2 \sum_{i=1}^{N} \theta_{j} (x_{i}^{j})^{2}$$

where:

$$\hat{y_i}^{(-j)} = \theta_0 x_i^0 + \ldots + \theta_d x_i^d$$

is \hat{y}_i without θ_j

$$Set \frac{\partial \operatorname{RSS}(\theta_{j})}{\partial \theta_{j}} = 0$$

$$\theta_{j} = \sum_{i=1}^{N} \frac{\left(y_{i} - \left(\theta_{0} x_{i}^{0} + \dots + \dots + \theta_{d} x_{i}^{d}\right)\right) \left(x_{i}^{j}\right)}{\left(x_{i}^{j}\right)^{2}} = \frac{\rho_{j}}{z_{j}}$$

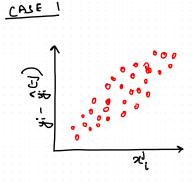
$$\rho_{j} = \sum_{i=1}^{N} x_{i}^{j} \left(y_{i} - \hat{y}_{i}^{(-j)}\right)$$

$$z_{j} = \sum_{i=1}^{N} \left(x_{i}^{j}\right)^{2}$$

 z_i is the squared of ℓ_2 norm of the j^{th} feature

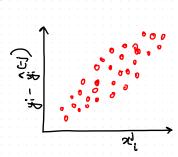
COORDINATE

UNDERSTANDING Pj IN COORDINATE DESCENT
$$Pj = \sum_{i=1}^{N} x_i^j (y_i - y_i^{(i)})$$



STRONG TVE CORP WITH Y: -Y:

UNDERSTANDING Pj IN COORDINATE DESCENT
$$Pj = \sum_{i=1}^{N} x_i^i \left(y_i - y_i^{-i} \right)$$



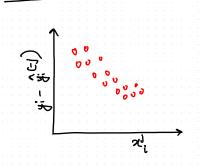
CASE

WITH y; -y;

jth FEATURE IS IMPT

AND ITS COEFFICIENT

UNDERSTANDING Pj IN COORDINATE DESCENT
$$Pj = \sum_{i=1}^{N} x_i^j \left(y_i - \hat{y}_i^{-j} \right)$$



UNDERSTANDING Pj IN COORDINATE DESCEN

$$Pj = \sum_{i=1}^{N} \chi_{i}^{j} (y_{i} - y_{i}^{c}))$$

$$\chi_{i}^{j} \text{ WEAK } (ORR. WITH } y_{i}^{j} - y_{i}^{c})$$

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Minimize
$$\underbrace{\sum_{i=1}^{N} \epsilon^2 + \delta^2 \left\{ |\theta_0| + |\theta_1| + \dots |\theta_j| + \dots |\theta_d| \right\}}_{LASSO\ OBJECTIVE}$$

$$\frac{\partial}{\partial \theta_j}(\text{LASSO OBJECTIVE}) = -2\rho_j + 2\theta_j z_j + \delta^2 \frac{\partial}{\partial \theta_j} \left|\theta_j\right|$$

$$\frac{\partial}{\partial \theta_j} |\theta_j| = \begin{cases} 1 & \theta_j > 0 \\ [-1, 1] & \theta_j = 0 \\ -1 & \theta_j < 0 \end{cases}$$

• Case 1: $\theta_j > 0$

$$2\rho_j + 2\theta_j z_j + \delta^2 = 0$$

$$\theta_j = \frac{\rho_j - \frac{\delta^2}{2}}{z_j}$$

$$\rho_j > \frac{\delta^2}{2} \Rightarrow \theta_j = \frac{\rho_j - \frac{\delta^2}{2}}{z_j}$$

• Case 1: $\theta_j > 0$

$$2\rho_j + 2\theta_j z_j + \delta^2 = 0$$

$$\theta_j = \frac{\rho_j - \frac{\delta^2}{2}}{z_j}$$

$$\rho_j > \frac{\delta^2}{2} \Rightarrow \theta_j = \frac{\rho_j - \frac{\delta^2}{2}}{z_j}$$

• Case 2: $\theta_i < 0$

$$\rho_j < \frac{\delta^2}{2} \Rightarrow \theta_j = \frac{\rho_j + \delta^2/2}{z_j} \tag{5}$$

• Case 3: $\theta_j = 0$

$$\begin{split} \frac{\partial}{\partial \theta_j} (\text{LASSO OBJECTIVE}) &= -2\rho_j + 2\theta_j z_j + \delta^2 \underbrace{\frac{\partial}{\partial \theta_j} |\theta_j|}_{\text{[-1,1]}} \\ &\epsilon \underbrace{[-2\rho_j - \delta^2, -2\rho_j + \delta^2]}_{\text{\{0\} lies in this range}} \end{split}$$

$$-2\rho_j - \delta^2 \le 0 \text{ and } -2\rho_j - \delta^2 \le 0$$

 $-\frac{\delta^2}{2} \le \rho_j \le \frac{\delta^2}{2} \Rightarrow \theta_j = 0$

Summary of Lasso Regression

$$\theta_{j} = \begin{bmatrix} \frac{\rho_{j} + \frac{\delta^{2}}{2}}{z_{j}} & \text{if} & \rho_{j} < -\frac{\delta^{2}}{2} \\ 0 & \text{if} & -\frac{\delta^{2}}{2} \leq \rho_{j} \leq \frac{\delta^{2}}{2} \\ \frac{\rho_{j} - \frac{\delta^{2}}{2}}{z_{j}} & \text{if} & \rho_{j} > \frac{\delta^{2}}{2} \end{bmatrix}$$
(6)

$$(p_1 + S_{12}^2)$$
 if

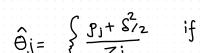
ASSO (SOFT) THRESHOLDING
$$\hat{\Theta}_{j} = \begin{cases} \frac{p_{j} + \hat{S}_{/2}^{2}}{Z_{j}} & \text{if} \end{cases}$$

θ

Asso (SOF7) MRESHULLING
$$\hat{A}_{i} = \begin{cases} p_{j} + S_{2}^{2} & \text{if} \\ \frac{1}{2} & \text{otherwise} \end{cases}$$

$$\hat{\Theta}_{j} = \begin{cases} \frac{p_{j} + \hat{S}_{/2}^{2}}{Z_{i}} & \text{if} \end{cases}$$

$$\hat{\Theta}_{j} = \begin{cases} \frac{p_{j} + S_{12}^{2}}{Z_{i}} & \text{if} \end{cases}$$



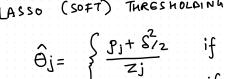
SSO (SOFT) THRESHOLDING
$$\hat{\Theta}_{i} = \begin{cases} \frac{p_{i} + S_{i}^{2}}{Z_{i}} & \text{if} \end{cases}$$

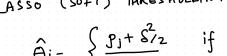
 $-\frac{s^2}{2} \leq \mathcal{I}$ 95 - 52/2

$$\hat{\Theta}_{i} = \begin{cases} \frac{p_{i} + s^{2}}{2} & \text{if} \\ \frac{1}{2} & \text{if} \end{cases}$$

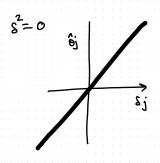
LASSO (SOFT) THRESHOLDING
$$\hat{\Theta}_{j} = \begin{cases} \frac{p_{j} + S^{2}_{12}}{z_{j}} & \text{if} \end{cases}$$

LASSO (SOFT) THRESHOLDING
$$\hat{A}:= \left\{\begin{array}{cc} p_j + S^2/2 & \text{if} \end{array}\right.$$





LASSO (SOFT) THRESHOLDING



NO REGULARISATION

LASSO (SOFT) THRESHOLDING

