

Undirected Graphical Models (at a glance!)

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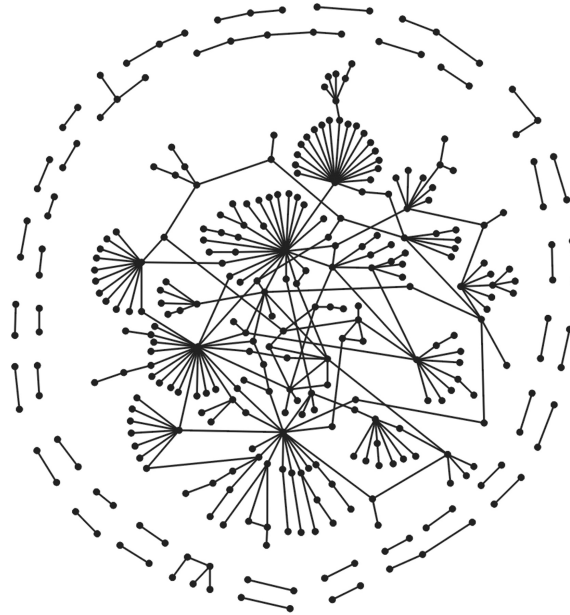
Introduction

As we already known, *graphical models* are a way of representing the relationships between features (variables). There are two main brands: **directed** and **undirected**. Here we shall focus on the latter.

Undirected graphs with attached a probabilistic semantic (i.e. undirected graphical models) come in different flavors, such as:

1. Marginal Correlation Graphs.
2. Partial Correlation Graphs.
3. Conditional Independence Graphs.

In each case, there are parametric and nonparametric versions but for the sake of these notes, we just talk about the parametric case. The figure shows an example of an undirected graph associated to protein networks from [Maslov and Sneppen \(2002\)](#).



So, let $\{\mathbf{X}_1, \dots, \mathbf{X}_n\}$ be random vector IID from some distribution $P(\cdot)$ where $\mathbf{X}_i = [X_i(1), \dots, X_i(D)]^T \in \mathbb{R}^D$.

The **vertices** (nodes) of the graph refer to the D features: each node corresponds to a single feature. **Edges** instead represent *relationships* between the features.

The graph is represented by $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ where $\mathcal{V} = \{V_1, \dots, V_D\}$ is the vertex-set and \mathcal{E} the edge-set. We can regard the edge-set \mathcal{E} as a $(D \times D)$ matrix \mathbf{E} where $\mathbf{E}(j, k) = 1$ if there is an edge between feature j and feature k and 0 otherwise. Alternatively, you can regard \mathcal{E} as a list of *unordered* pairs where $\{j, k\} \in \mathcal{E}$ if there is an edge between j and k .

As always, we write $X \perp Y$ to mean that X and Y are *independent* $\Leftrightarrow p(x, y) = p(x) \cdot p(y)$, whereas we write $(X \perp Y | Z)$ to mean that X and Y are independent given $Z \Leftrightarrow p(x, y | z) = p(x | z) p(y | z)$.

Marginal Correlation Graphs

In a **marginal correlation graph** – or *association graph* – we put an edge between V_j and V_k if

$$|\rho(j, k)| \geq \epsilon,$$

where $\rho(j, k)$ is *some* measure of *association*. Often we set $\epsilon = 0$ in which case there is an edge if and only if $\rho(j, k) \neq 0$. We also write $\rho_{j,k}$ or $\rho(X_j, X_k)$ to mean the same as $\rho(j, k)$.

The parameter $\rho(j, k)$ is required to have the following property:

$$X \perp Y \Rightarrow \rho(X, Y) = 0.$$

In general, the reverse may **not** be true. We will say that ρ is *strong* if

$$X \perp Y \Leftrightarrow \rho(X, Y) = 0.$$

We will not dig into these last type of association measures, but let's just mention here the recent work by [Bergsma and Dassios \(2014\)](#) who extended the well-known Kendall's τ – see the Appendix – into a *strong* correlation.

We would like ρ to have several properties:

1. easy to compute;
2. robust to outliers;
3. there must be some way to calculate a confidence interval for the parameter.

Pearson Correlation. In spite to all its weaknesses and lack of robustness to outliers – it's just an expected value – a common choice of ρ is the **Pearson correlation coefficient**:

$$\rho(X, Y) = \frac{\text{Cov}(X, Y)}{\sigma_X \cdot \sigma_Y},$$

with the associated well-known plug-in estimator given by

$$\hat{\rho}(X, Y) = \frac{\frac{1}{n} \sum_{i=1}^n (X_i - \bar{X}_n)(Y_i - \bar{Y}_n)}{S_X \cdot S_Y}.$$

Remember that in dealing with D features, to simplify notation we will write $\rho_{j,k} = \rho(j, k) \equiv \rho(X(j), X(k))$, and the corresponding sample correlation will be denoted by $\hat{\rho}_{j,k} = \hat{\rho}(j, k)$.

Statistically speaking, checking if an edge $\{j, k\}$ is in the vertex-set \mathcal{E} or not, is equivalent to test the null-hypothesis $H_0 : \rho(j, k) = 0$ versus the alternative $H_1 : \rho(j, k) \neq 0$. To this end we can use an *asymptotic* test or an *exact* test.

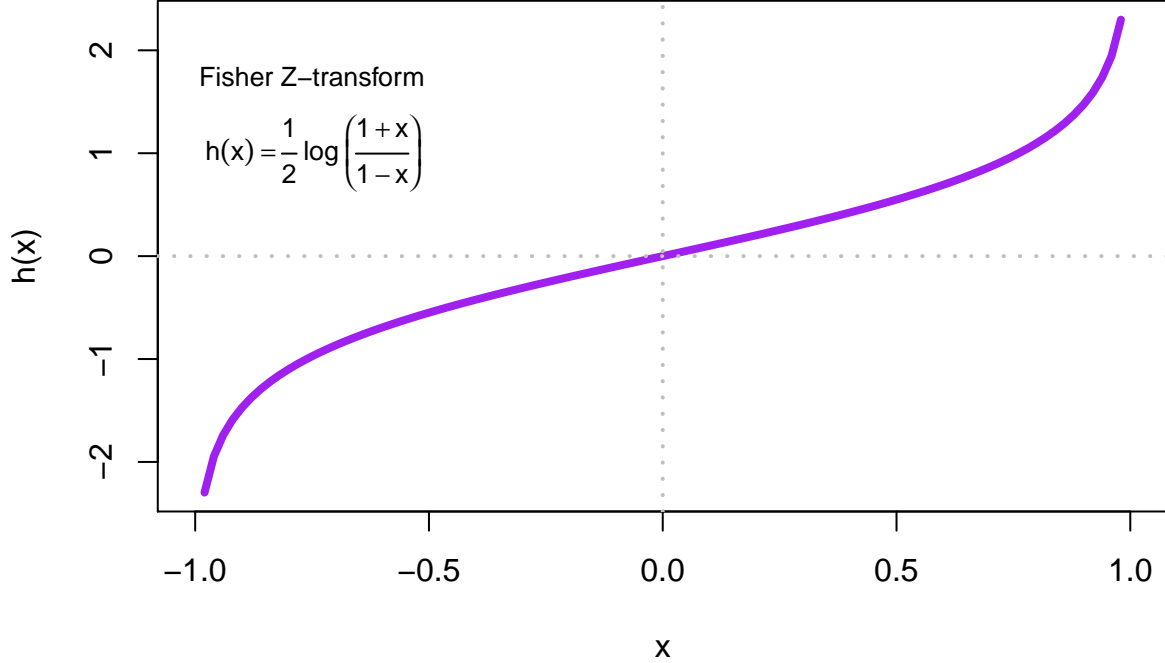
For the *asymptotic* test we'd like to invoke some sort of large sample normality of our estimator $\hat{\rho}_{j,k}$, but by definition it is constrained to live between -1 and $+1 \Rightarrow$ we need to find a suitable transformation that maps smoothly $[-1, +1]$ into \mathbb{R} , the support of a Normal. So let's define (see figure below):

$$h(x) = \frac{1}{2} \log \left(\frac{1+x}{1-x} \right) = \text{arctanh}(x) \rightsquigarrow Z_{j,k} = h(\hat{\rho}_{j,k}) = \frac{1}{2} \log \left(\frac{1+\hat{\rho}_{j,k}}{1-\hat{\rho}_{j,k}} \right).$$

For this particular **variance-stabilizing transformation**, [Fisher proved](#) that

$$Z_{j,k} \sim N_1 \left(\theta_{j,k}, \frac{1}{n-3} \right) \text{ where } \theta_{j,k} = h(\rho_{j,k}) = \frac{1}{2} \log \left(\frac{1+\rho_{j,k}}{1-\rho_{j,k}} \right) \rightsquigarrow \rho_{j,k} = h^{-1}(\theta_{j,k}) = \tanh(\theta_{j,k}) = \frac{e^{2\theta_{j,k}} - 1}{e^{2\theta_{j,k}} + 1}.$$

Since $h(x) = 0 \Leftrightarrow x = 0$, following the usual path, we may reject the null if $|Z_{j,k}| > z_{\frac{\alpha}{2}} \cdot \frac{1}{\sqrt{n-3}}$, where $z_{\frac{\alpha}{2}} = -\text{qnorm}(\frac{\alpha}{2}) \stackrel{\text{sym}}{=} \text{qnorm}(1 - \frac{\alpha}{2})$. So, for example, if $\alpha = 0.05$ then $z_{\frac{0.05}{2}} = -\text{qnorm}(0.025) \approx 1.96$.



The result we just obtained is of course perfectly fine in case we have only a small number of edges to check. In general though, the graphs we have to deal with are characterized by a large number of nodes and, consequently, a huge amount of edges to test: $m = \binom{D}{2}$ to be precise.

TAKE HOME MESSAGE: we necessarily need to control for **multiplicity** in order to avoid a ridiculous overflow of false discoveries! The easiest to implement – although quite conservative recipe – here is the so called **Bonferroni correction** that simply asks for testing each single hypothesis at a level equal to α/m if α is the desired overall level and m the number of hypotheses. Hence, in our case, we just reject the null if $|Z_{j,k}| > z_{\frac{\alpha}{2m}} \cdot \frac{1}{\sqrt{n-3}}$ where $m = \binom{D}{2}$.

Out of the asymptotic normality, we can also get confidence sets $C_{n,\alpha} = [L, U]$ for each *single* $\rho_{i,j}$, where

- $L = h^{-1}(Z_{j,k} - z_{\frac{\alpha}{2}}/\sqrt{n-3})$,
- $U = h^{-1}(Z_{j,k} + z_{\frac{\alpha}{2}}/\sqrt{n-3})$.

A **simultaneous** confidence set for **all** the correlations can be obtained using the **bootstrap**. This is especially important if we want to put an edge when $|\rho(j,k)| \geq \epsilon$. If we have a confidence interval $C_{n,\alpha}$ then we can put an edge whenever $[-\epsilon, +\epsilon] \cap C_{n,\alpha} = \emptyset$.

1. Let \mathbf{R} be the $(D \times D)$ matrix of **true** correlations and let $\hat{\mathbf{R}}$ be the $(D \times D)$ matrix of sample correlations with the associated Z -transformed matrix $\hat{\mathbf{Z}} = h(\hat{\mathbf{R}})$.
2. Now let $\{\mathbf{X}_1^*, \dots, \mathbf{X}_n^*\}$ denote a **bootstrap** sample and let $\hat{\mathbf{R}}^*$ and $\hat{\mathbf{Z}}^*$ be the $(D \times D)$ matrices of correlations and Z -transformed correlations from the bootstrap sample.
3. After taking B bootstrap samples we have $\{\hat{\mathbf{R}}_1^*, \dots, \hat{\mathbf{R}}_B^*\}$
4. Now, for each bootstrap sample $b \in \{1, \dots, B\}$, define the following bootstrapped replicate of a **simultaneous** test statistics

$$\Delta_b = \sqrt{n} \max_{j,k} \left| \hat{\mathbf{R}}_b^*[j,k] - \hat{\mathbf{R}}[j,k] \right|,$$

and its associated bootstrapped ECDF:

$$\hat{F}_n(t) = \frac{1}{B} \sum_{b=1}^B \mathbb{I}(\Delta_b \leq t).$$

Within the usual bootstrap analogy, for large n and B , $\hat{F}_n(t)$ should be a good approximation to

$$F_n(t) = \mathbb{P}\left(\sqrt{n} \max_{j,k} \left| \hat{\mathbf{R}}[j, k] - \mathbf{R}[j, k] \right| \leq t\right).$$

5. Finally, to build our simultaneous confidence set, consider the sample quantile at level α of the bootstrapped distribution $\hat{F}_n(t)$, say $t_\alpha = \hat{F}_n^{-1}(\alpha)$, and set

$$C_{j,k}(\alpha) = \left[\hat{\mathbf{R}}[j, k] - \frac{t_\alpha}{\sqrt{n}}, \hat{\mathbf{R}}[j, k] + \frac{t_\alpha}{\sqrt{n}} \right].$$

Theorem. If $D = o(\exp(n^{1/6}))$, then

$$\mathbb{P}(\mathbf{R}[j, k] \in C_{j,k}(\alpha) \text{ for all } (j, k)) \xrightarrow{n} 1 - \alpha$$

Partial Correlation Graphs

Let X, Y be random variables and \mathbf{Z} be a random vector. The partial correlation between X and Y , given \mathbf{Z} , is a measure of association between X and Y after removing the effect of \mathbf{Z} . Specifically, $\rho(X, Y | \mathbf{Z})$ is the correlation between the *residuals* ϵ_X and ϵ_Y where

$$\epsilon_X = X - \Pi_{\mathbf{Z}}(X) \quad \text{and} \quad \epsilon_Y = Y - \Pi_{\mathbf{Z}}(Y),$$

Here, $\Pi_{\mathbf{Z}}(X)$ is the *projection* of X onto the linear space spanned by \mathbf{Z} . That is $\Pi_{\mathbf{Z}}(X) = \hat{\beta}^T \mathbf{Z}$ where

$$\hat{\beta} = \underset{\text{All } \beta}{\operatorname{argmin}} \mathbb{E}[Y - \beta^T \mathbf{Z}].$$

In other words, $\Pi_{\mathbf{Z}}(X)$ is the *linear regression* of X on \mathbf{Z} . Similarly, for $\Pi_{\mathbf{Z}}(Y)$. We will give an explicit formula for the partial correlation shortly.

Now let's go back to graphs. Let $\mathbf{X} = [X(1), \dots, X(D)]^T$ and let $\rho_{j,k}^{(p)}$ denote this time the partial correlation between $X(j)$ and $X(k)$ **given all** the other variables. Let $\mathbf{R}_{(p)} = [\rho_{j,k}^{(p)}]_{j,k}$ be the $(D \times D)$ matrix of partial correlations. Then we have:

Theorem. The matrix $\mathbf{R}_{(p)}$ is given by

$$\mathbf{R}_{(p)}[j, k] = -\frac{\Lambda_{j,k}}{\sqrt{\Lambda_{j,j} \cdot \Lambda_{k,k}}},$$

where $\Lambda = \Sigma^{-1}$ is the precision matrix associated to the covariance matrix Σ .

The partial correlation graph \mathcal{G} has an edge between j and k when $\rho_{j,k}^{(p)} \neq 0$.

In the **low-dimensional** setting ($D \ll n$), we can estimate $\mathbf{R}_{(p)}$ as follows. Let $\hat{\Sigma}_n$ be the sample covariance, and $\hat{\Lambda} = \hat{\Sigma}_n^{-1}$ its inverse. Then define

$$\hat{\mathbf{R}}_{(p)}[j, k] = \hat{\rho}_{j,k}^{(p)} = -\frac{\hat{\Lambda}_{j,k}}{\sqrt{\hat{\Lambda}_{j,j} \cdot \hat{\Lambda}_{k,k}}}.$$

The easiest and reliable way to construct the graph is then to get **simultaneous** confidence intervals $C_{j,k}(\alpha)$ using **bootstrap** (again), and put in an edge $\{j, k\}$ if $0 \notin C_{j,k}(\alpha)$.

There is also a *Normal approximation* similar to correlations. Define once again

$$Z_{j,k} = h(\hat{\rho}_{j,k}^{(p)}) = \frac{1}{2} \log \left(\frac{1 + \hat{\rho}_{j,k}^{(p)}}{1 - \hat{\rho}_{j,k}^{(p)}} \right) \quad \text{then} \quad Z_{j,k} \sim N_1 \left(\theta_{j,k}, \frac{1}{n-g-3} \right)$$

where $\theta_{j,k} = h(\rho_{j,k}^{(p)})$ and $g = (D - 2)$.

As before, via a Bonferroni correction we reject $H_0 : \rho_{j,k}^{(p)} = 0$ if $|Z_{j,k}| > z_{\frac{\alpha}{2m}} \cdot \frac{1}{\sqrt{n-g-3}}$ where $m = \binom{D}{2}$.

An implementation of this method is provided by the function `sinUG()` in the package R package **SIN**. The only difference is that, instead of Bonferroni, it adopts a **finer correction** for multiplicity.

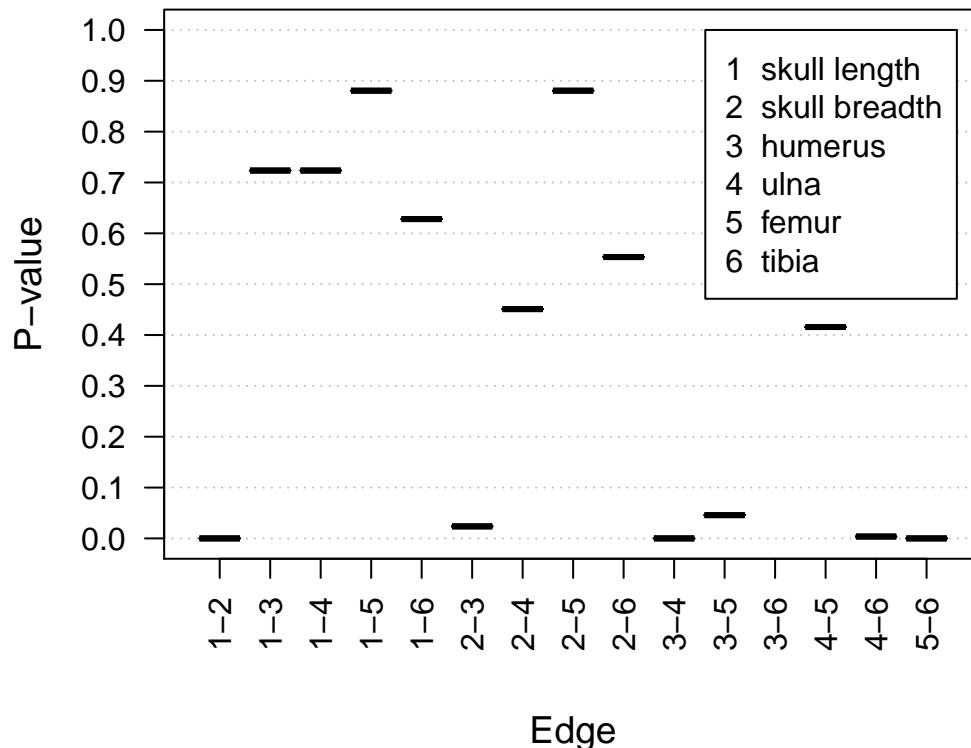
```
# Package
library(SIN); library(help = SIN); ?sinUG

# Some data: are there dependencies between biometric measurements?
data(fowlbones)
?fowlbones

# Run & take a look
out <- sinUG(fowlbones$corr,fowlbones$n)
round(out,3) # estimated partial correlation matrix
```

```
##          skull length skull breadth humerus ulna femur tibia
## skull length          NA          0.000  0.723 0.723 0.880 0.628
## skull breadth        0.000           NA  0.024 0.451 0.880 0.553
## humerus              0.723          0.024   NA 0.000 0.046 0.723
## ulna                 0.723          0.451  0.000   NA 0.416 0.004
## femur                0.880          0.880  0.046 0.416   NA 0.000
## tibia                0.628          0.553  0.723 0.004 0.000   NA
```

```
plotUGpvalues(out) # take a look at the p-values
```



```
# Get the graph associated to a specific confidence level
library(igraph)
```

```
par(mfrow = c(1,2))
alpha = 0.05
E.SIN = getgraph(out, alpha)
print(E.SIN)
```

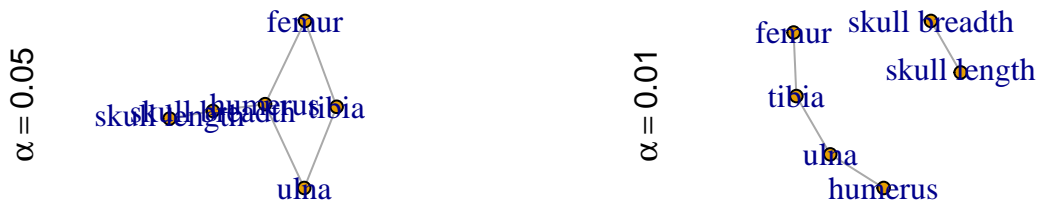
```
##           skull length skull breadth humerus ulna femur tibia
## skull length           0             1       0   0     0     0
## skull breadth          1             0       1   0     0     0
## humerus                0             1       0   1     1     0
## ulna                   0             0       1   0     0     1
## femur                  0             0       1   0     0     1
## tibia                   0             0       0   1     1     0
```

```
G.SIN = graph.adjacency(E.SIN, mode = "undirected")
plot(G.SIN, ylab = expression(alpha == 0.05))
```

```
alpha = 0.01
E.SIN = getgraph(out, alpha)
print(E.SIN)
```

```
##           skull length skull breadth humerus ulna femur tibia
## skull length           0             1       0   0     0     0
## skull breadth          1             0       0   0     0     0
## humerus                0             0       0   1     0     0
## ulna                   0             0       1   0     0     1
## femur                  0             0       0   0     0     1
## tibia                   0             0       0   1     1     0
```

```
G.SIN = graph.adjacency(E.SIN, mode = "undirected")
plot(G.SIN, ylab = expression(alpha == 0.01))
```



In high-dimensions, this protocol will **not** work since $\hat{\Sigma}_n$ is **not** invertible. In fact one can show that

$$\text{Var}(\hat{\rho}_{j,k}^{(p)}) \approx \frac{1}{n - D},$$

and this blows up when D is close to, or even larger than, n .

In such a bad situation, we have at least three exit strategies:

1. Compute a **correlation graph** instead. This is easy, works well, and often reveals similar dependence structures.
2. Apply some **shrinkage** (statistical lingo) or **regularization** (more math inclined) scheme to “fix” the ill-conditioned matrix $\hat{\Sigma}_n$ and make it non-singular + bootstrap on the entries of the resulting matrix. See, for example, [Schager and Strimmer \(2005\)](#) and [Ledoit and Wolf \(2004\)](#).
3. Use the *graphical lasso* ([glasso package](#)). **Warning!** The reliability of the graphical lasso depends on lots of non-trivial, uncheckable assumptions.

Conditional Independence Graphs

The strongest type of undirected graph is a **conditional independence graph**. In this case, we omit the edge between j and k if $X(j)$ is independent of $X(k)$ given the *rest* of the variables. We write this as

$$(X(j) \perp X(k) \mid \text{rest})$$

Conditional independence graphs are the most informative undirected graphs but they are also the hardest to estimate! This final type of undirected graphical models is treated in some details in *Ch.18* and *Ch.19* of the [purple book](#), so we are not going much further.

Here we just mention an interesting fact related to the so called **Gaussian Random Fields** (i.e. undirected graphical models over Normal random vectors). In fact, in the special case of Normality, conditional independence graphs are equivalent to partial correlation graphs.

More specifically we have the following result.

Theorem: Suppose that

$$\mathbf{X} = [X(1), \dots, X(D)]^T \sim N_D(\boldsymbol{\mu}, \Sigma).$$

Let $\Lambda = \Sigma^{-1}$ be the precision matrix. Then $X(j)$ is independent of $X(k)$ given the rest, if and only if $\Lambda_{j,k} = 0$. So, in the Normal case, we are back to partial correlations.

Appendix: Other measures of association

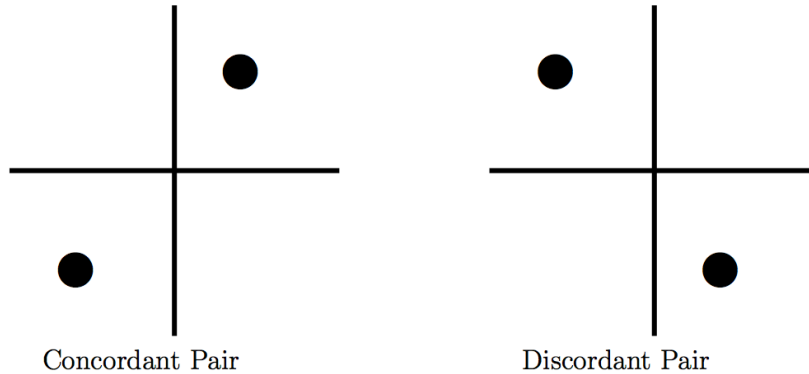
Kendall's τ . The Pearson correlation is **not** very robust to outliers. A more robust measure of association is Kendall's τ .

So consider a random vector (X, Y) with joint distribution $F_{X,Y}(\cdot)$, and denote by (X', Y') an *independent* copy of (X, Y) – in other words (X, Y) and (X', Y') are independent and identically distributed.

We say that (X, Y) and (X', Y') are **concordant** if

$$(X - X')(Y - Y') \geq 0$$

and **discordant** otherwise.



Kendall's τ is defined as:

$$\tau(X, Y) = \mathbb{P}(\text{concordant}) - \mathbb{P}(\text{discordant}) = \mathbb{P}((X - X')(Y - Y') \geq 0) - \mathbb{P}((X - X')(Y - Y') < 0).$$

After some algebra it can be shown that

$$\tau(X, Y) = \mathbb{E}[\text{sign}((X - X')(Y - Y'))],$$

so that an obvious estimator is given by

$$\hat{\tau}(X, Y) = \frac{1}{\binom{n}{2}} \sum_{j,k} \left[\text{sign}((X_j - X_k)(Y_j - Y_k)) \right].$$

A statistics of this form is called a **U-statistics**, and there's a corpus of dedicated literature that gives us all the relevant information about its (asymptotic) sampling distribution.

In particular, going back to checking the presence of a $\{j, k\}$ edge in our marginal association graph, under the null hypothesis $H_0 : \tau_{j,k} = 0$ we know that asymptotically

$$\hat{\tau}_{j,k} \dot{\sim} N(0, (4/9) \cdot n),$$

so we reject when

$$|\hat{\tau}_{j,k}| > z_{\frac{\alpha}{2m}} \cdot \frac{2}{3\sqrt{n}}.$$

A finite sample alternative would be a permutation test.

Distance Correlation. There are various other nonparametric measures of association. The most common are the **distance correlation** and the RKHS correlation (from **Reproducing Kernel Hilbert Space**).

Let's briefly focus on **distance correlation**. So the **squared distance covariance** between two random vectors \mathbf{X} and \mathbf{Y} is defined by (Szekely et al. 2007)

$$\gamma^2(\mathbf{X}, \mathbf{Y}) = \mathbb{Cov}(\|\mathbf{X} - \mathbf{X}'\|, \|\mathbf{Y} - \mathbf{Y}'\|) - 2 \mathbb{Cov}(\|\mathbf{X} - \mathbf{X}'\|, \|\mathbf{Y} - \mathbf{Y}''\|),$$

where (\mathbf{X}, \mathbf{Y}) , $(\mathbf{X}', \mathbf{Y}')$ and $(\mathbf{X}'', \mathbf{Y}'')$ are independent copies, and $\|\cdot\|$ denotes the **Euclidean norm** or any other suitable norm.

The *squared distance correlation* is then

$$\rho^2(\mathbf{X}, \mathbf{Y}) = \frac{\gamma^2(\mathbf{X}, \mathbf{Y})}{\sqrt{\gamma^2(\mathbf{X}, \mathbf{X}) \gamma^2(\mathbf{Y}, \mathbf{Y})}}.$$

An important result is the following

Theorem. We have that $\rho(\mathbf{X}, \mathbf{Y}) \in [0, 1]$ and $\rho(\mathbf{X}, \mathbf{Y}) = 0 \Leftrightarrow \mathbf{X} \perp \mathbf{Y}$.

Estimation and testing are of course possible but a bit more involved than for the other association measures.