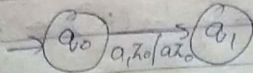


# PDA



$$\delta(q_0, a, z_0) = (q_1, a z_0)$$

↓  
next new state
↓  
push operation

$$\delta(q_0, \epsilon, z_0) = (q_1, z_0)$$

↓  
empty I/P string
↓  
initial symbol of stack

$$\delta(q_1, a, z_0) = (q_2, \epsilon)$$

↓  
pop operation

$$\delta(q_0, a, a) = (q_1, aa) \Rightarrow \text{push}$$

$$\delta(q_0, a, z_0) = (q_0, a z_0) \Rightarrow \text{push}$$

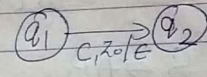
$$\delta(q_0, b, z_0) = (q_0, b z_0) \Rightarrow \text{push}$$

$$\delta(q_1, c, z_0) = (q_2, \epsilon)$$

$$\delta(q_1, a, a) = (q_2, \epsilon)$$

$$\delta(q_1, b, b) = (q_2, \epsilon)$$

$$\delta(q_1, \epsilon, z_0) = (q_2, z_0)$$



pop

$$L = \{ w c w^R \mid w \in (a+b)^* \}$$

check if  
palindrome or  
not.

$$\delta(q_0, abbcbba, z_0)$$

of string

Till middle symbol, push the symbol on top of stack

$$\delta(q_0, abbcbba, a z_0)$$

$$\delta(q_0, bcbba, b a z_0)$$

$$\delta(q_0, cbba, b b a z_0)$$

$$\delta(q_1, bba, b b a z_0)$$

$$\delta(q_1, ba, b a z_0)$$

$$\delta(q_1, a, a z_0)$$

$$\delta(q_1, \epsilon, z_0)$$

Transition Function

$$\delta(q_0, a, z_0) = (q_0, a z_0)$$

$$\delta(q_0, b, z_0) = (q_0, b z_0)$$

$$\delta(q_0, a, a) = (q_0, aa)$$

$$\delta(q_0, a, b) = (q_0, ab)$$

$$\delta(q_0, b, a) = (q_0, ba)$$

$$\delta(q_0, b, b) = (q_0, bb)$$

$$\delta(q_1, c, z_0) = (q_1, z_0)$$

$$\delta(q_1, a, z_0) = (q_1, z_0)$$

$$\delta(q_1, b, z_0) = (q_1, z_0)$$



PDA is used to design CFG

$$\begin{aligned}\delta(q_1, a, a) &= (q_1, \epsilon) \\ \delta(q_1, b, b) &= (q_1, \epsilon) \\ \delta(q_1, \epsilon, z_0) &= (q_2, z_0)\end{aligned}$$

\* GNF always starts with terminal

To accept the string

Final state  $\rightarrow$  empty stack  
(don't show  $z_0$  explicitly in the last transition function)

$$(q_2, z_0)$$

$$\downarrow$$

$$(q_2, \epsilon)$$

$$\delta(q_0, baacaab, z_0) \vdash (q_0, aacaab \ bz_0)$$

$$\vdash (q_0, aCaab \ abz_0)$$

$$\vdash (q_0, Caab \ aabz_0)$$

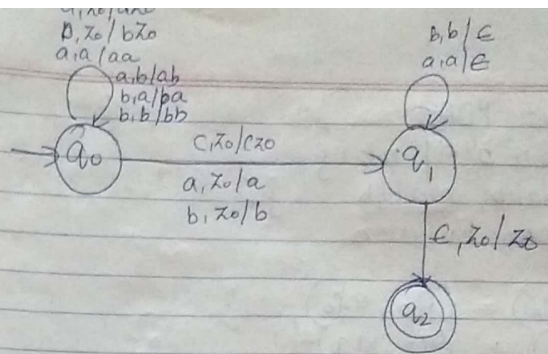
$$\vdash (q_1, aab \ aabz_0)$$

$$\vdash (q_1, ab \ abz_0)$$

$$\vdash (q_1, b \ , \ bz_0)$$

$$\vdash (q_1, \epsilon \ , \ z_0)$$

$$\vdash (q_2, z_0)$$



$$\delta(q_0, aabCab, z_0) \vdash (q_0, abCab \ a z_0)$$

$$\vdash (q_0, bCab \ baa z_0)$$

$$\vdash (q_0, Cab \ baa z_0)$$

$$\vdash (q_1, ab \ baa z_0)$$

~~$$\vdash (q_1, b \ baa z_0)$$~~

~~$$\vdash (q_1, \epsilon \ a z_0)$$~~

Rejected.

Q) Construct PDA

$$L = \{a^n b^n \mid n \geq 1\}$$

$$L = \{ab, aabb, aaabbb, \dots\}$$

sol Transition Function

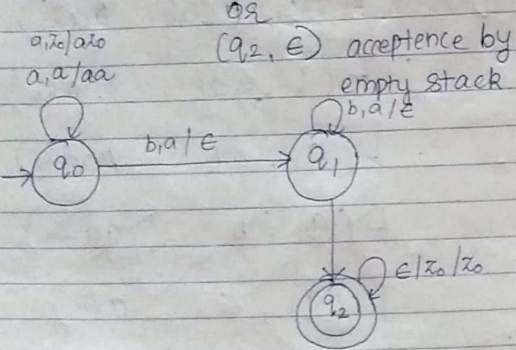
$$\delta(q_0, a, z_0) = (q_0, a z_0)$$

$$\delta(q_0, a, a) = (q_0, aa)$$

$$\delta(q_0, b, a) = (q_1, \epsilon)$$

$$\delta(q_1, b, a) = (q_1, \epsilon)$$

$$\delta(q_1, \epsilon, z_0) = (q_2, z_0)$$



Acceptance

$$\delta(q_0, aaabbb, z_0) \vdash (q_0, aaabbb, a z_0)$$

$$\vdash (q_0, abbb, aa z_0)$$

$$\vdash (q_0, bbb, aaa z_0)$$

$$\vdash (q_1, bb, aa z_0)$$

$$\vdash (q_1, b, a z_0)$$

$$\vdash (q_1, \epsilon, z_0)$$

$$\vdash (q_2, z_0) \Rightarrow \text{Acceptance.}$$

Rejection

$$\delta(q_0, aabbb, z_0) \vdash (q_0, abbb, a z_0)$$

$$\vdash (q_0, bbb, aa z_0)$$

$$\vdash (q_1, bb, a z_0)$$

$$\vdash (q_1, b, z_0)$$

$$\Downarrow$$

Rejected.

Q)  $L = \{a^n b^{2n} \mid n \geq 1\}$  For each  $a$ , push two  $a$ 's

$L = \{abb, aabbbb, \dots\}$  on to the stack

Transition Function

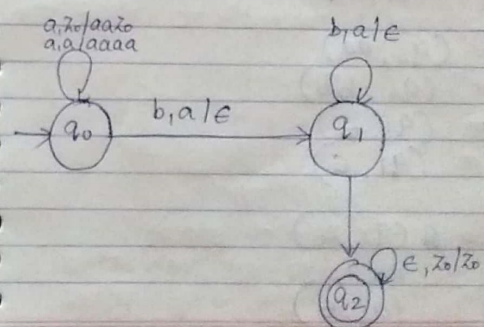
$$\delta(q_0, a, z_0) = (q_0, aa z_0)$$

$$\delta(q_0, a, a) = (q_0, aaa)$$

$$\delta(q_0, b, a) = (q_1, \epsilon)$$

$$\delta(q_1, b, a) = (q_1, \epsilon)$$

$$\delta(q_1, \epsilon, z_0) = (q_2, z_0)$$





$$\delta(q_0, aabbbb, z_0) \vdash (q_0, abbbb, aa z_0)$$

$$\vdash (q_0, bbbb, aaaa z_0)$$

$$\vdash (q_1, bbb, aaaa z_0)$$

$$\vdash (q_1, bb, aaaa z_0)$$

$$\vdash (q_1, b, aaaa z_0)$$

$$\vdash (q_1, \epsilon, aaaa z_0)$$

$$\vdash (q_2, z_0)$$

Accepted.

Q) Draw PDA for acceptance by final state  
 $d = \{w \mid w \in (a,b)^n, n_a(w) = n_b(w)\}$

$$d = \{ab, ba, baab, abab, \dots\}$$

$$\delta(q_0, a, z_0) = (q_0, a z_0)$$

$$\delta(q_0, b, z_0) = (q_0, b z_0)$$

$$\delta(q_0, a, a) = (q_0, aa)$$

$$\delta(q_0, b, b) = (q_0, bb)$$

$$\delta(q_0, a, b) = (q_1, \epsilon)$$

$$\delta(q_0, b, a) = (q_1, \epsilon)$$

$$\delta(q_1, \epsilon, z_0) = (q_2, z_0)$$

$$\text{or } (q_2, \epsilon)$$

$$\delta(q_0, baab, z_0) \vdash (q_0, aab, bz_0)$$

$$\vdash (q_1, ab, z_0)$$

$$\vdash (q_1, b, az_0)$$

$$\vdash (q_1, \epsilon, z_0)$$

$$\vdash (q_2, z_0)$$

Accepted.

$$d_1 = \{w \mid w \in (a,b)^n, n_a(w) > n_b(w)\}$$

$$d_2 = \{w \mid w \in (a,b)^n, n_b(w) > n_a(w)\}$$

$$d_1 = \{aab, aaab, aaabb, \dots\}$$

Construct PDA for the given lang.  
 $L = \{ a^n b^m c^n \mid n, m \geq 1 \}$

$L = \{ abc, \dots \}$

$\delta(q_0, a, z_0) = \delta(q_0, a, z_0)$  } push  
 $\delta(q_0, b, a) = (q_0, aa)$   
 $\delta(q_0, b, a) = (q_1, a)$  } no  
 $\delta(q_1, b, a) = (q_1, a)$  } change  
 $\delta(q_1, c, a) = (q_1, \epsilon)$  } pop.  
 $\delta(q_1, \epsilon, z_0) = (q_2, \epsilon)$  }

(For each a pop c)

$L = \{ a^n b^m c^m d^n \mid n, m \geq 1 \}$

a - push  
 b - push  
 c - pop  
 d - pop

\* CFG to PDA

Convert the given grammar to GNF form

~~CFG~~ CNF  
 $A \rightarrow BC \{ NT \}$   
 or  
 $A \rightarrow a \{ T \}$

GNF  
 $A \rightarrow a d$   
 $\downarrow$   
 NT\*  
 (should start with terminal later can have any number of NT)

② Let  $q_0$  be the start state without consuming any input symbol push the start symbol on to the top of stack & change state from  $q_0$  to  $q_1$ .

Introduce the transition function for each and every production in given grammar.

Change the state from  $q_1$  to  $q_f$  where  $q_1$  is an accepting state

① GNF

②  $(q_0, \epsilon, z_0) = (q_1, S z_0)$

③  $A \rightarrow ad$

$\delta(q_1, a, A) = (q_1, \alpha)$

④ Convert the given grammar to its equivalent PDA

$S \rightarrow aABB$

$A \rightarrow aBB$

$B \rightarrow bAA$

$C \rightarrow a$

$\delta(q_0, \epsilon, z_0) = (q_1, S z_0)$

$S \rightarrow aABB$

$A \rightarrow aBB$

$\delta(q_1, a, S) = (q_1, ABB)$

$\delta(q_1, a, A) = (q_1, BB)$

$\delta(q_1, b, B) = (q_1, AA)$

$\delta(q_1, a, C) = (q_1, \epsilon)$

$\delta(q_1, \epsilon, z_0) = (q_f, z_0)$



$$S \rightarrow aSa / aa$$

$$S \rightarrow bSb / bb$$

$$S \rightarrow aSA / aA$$

$$S \rightarrow bSB / bB$$

$$\delta(q_0, \epsilon, z_0) = (q_1, Sz_0)$$

$$\frac{S}{A} \rightarrow \frac{aSA}{aA}$$

$$\delta(q_1, a, S) = (q_1, SA)$$

$$\delta(q_1, a, S) = (q_1, A)$$

$$\delta(q_1, b, S) = (q_1, SB)$$

$$\delta(q_1, b, S) = (q_1, B)$$

$$\delta(q_1, \epsilon, z_0) = (q_f, z_0)$$

Q) Grammar for

$$\alpha = \{a^n b^n \mid n \geq 1\}$$

$$S \rightarrow aSb / ab$$

↓

Not in GNF.

Converting.

$$S \rightarrow aSB / aB$$

$$B \rightarrow b$$

$$\delta(q_0, \epsilon, z_0) = (q_1, Sz_0)$$

$$\delta(q_1, a, S) = (q_1, SB)$$

$$\delta(q_1, a, S) = (q_1, B)$$

$$\delta(q_1, b, B) = (q_1, \epsilon)$$

$$\delta(q_1, \epsilon, z_0) = (q_f, z_0)$$

Deterministic / Non-deterministic PDA

Q)  $\alpha = \{n_a(w) = n_b(w) \mid w \in (a+b)^*\}$

$$S \rightarrow aSb / bSa$$

$$S \rightarrow \epsilon$$

$$S \rightarrow SS$$

convert to GNF.

$$\frac{S}{B} \rightarrow \frac{aSb}{bSa}$$

Q)  $S \rightarrow aSb / bSa \rightarrow$  not in GNF.

$$S \rightarrow aA \rightarrow \text{GNF}$$

$$S \rightarrow bB \rightarrow \text{GNF}$$

convert

$$S \rightarrow aSB / bSA$$

$$B \rightarrow b$$

$$A \rightarrow a$$

$$S \rightarrow aA$$

$$S \rightarrow bB$$

$$\delta(q_0, \epsilon, z_0) = (q_1, Sz_0)$$

$$\delta(q_1, a, S) = (q_1, SB)$$

$$\delta(q_1, b, S) = (q_1, SA)$$

$$\delta(q_1, a, S) = (q_1, A)$$

$$\delta(q_1, b, B) = (q_1, \epsilon)$$

$$\delta(q_1, \epsilon, z_0) = (q_f, z_0)$$



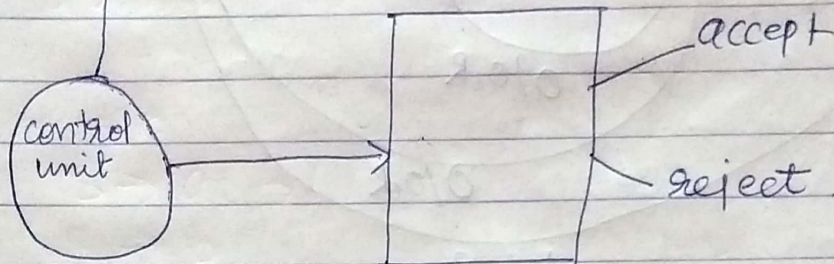
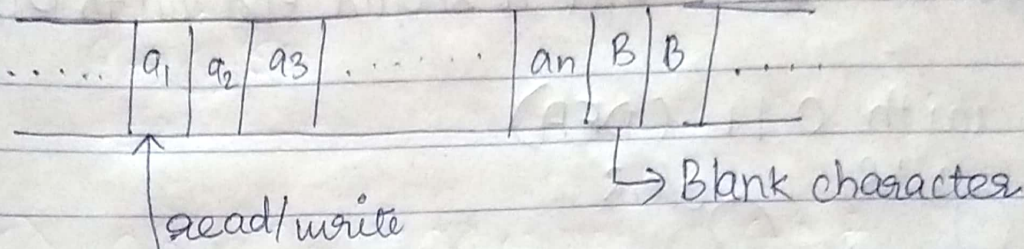
# TURING MACHINE

def, working model, problems - DFA  
short notes

↳ Transducers

↳ multitape ~~mt~~ machines.

↳ programming techniques.



$T_m = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$

$Q$  → set of states  
 $\Sigma$  → i/p alphabet  
 $\Gamma$  → magnetic tape symbols  
 $\delta$  → transition function  
 $q_0$  → Start state  
 $B$  → Blank character  
 $F$  → Final state

$$\delta: (Q \times \Gamma) \rightarrow (Q \times \Gamma \times \{L, R\})$$

magnetic tape symbol

left Right (directions)

$$\delta(q_0, 0) = (q_1, x, L) \rightarrow q_0 \xrightarrow{0/x, L} q_1$$

$$\delta(q_1, 1) = (q_1, y, L) \rightarrow q_1 \xrightarrow{1/y, L} q_1$$

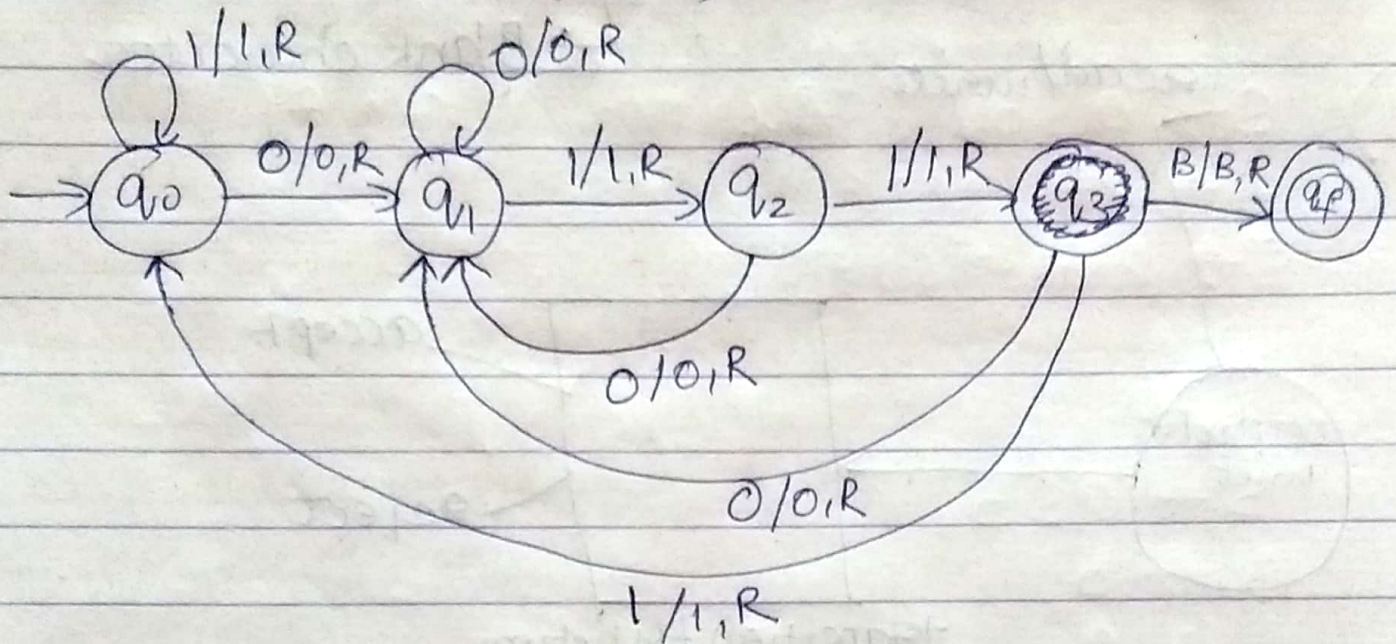
$$\delta(q_1, 0) = (q_2, x, R) \rightarrow q_1 \xrightarrow{0/x, R} q_2$$

$$\delta(q_2, x) = (q_f, B, R) \rightarrow q_2 \xrightarrow{x/B, R} q_f$$



Q) Design a Turing machine over an input symbol 0,1 such that it should end with 011.

end with 011 (DFA)



$\delta$	0	1	B
$\rightarrow q_0$	$q_1$	$q_0$	
$q_1$	$q_1$	$q_2$	
$q_2$	$q_1$	$q_3$	
$q_3$	$q_1$	$q_0$	
* $q_f$			