

# Hardware Assignment -3

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## PART-1

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### 1 Memory Generation and Architecture

There are 4 types of memory used :-

#### 1.1 ROM1

This is a ROM type memory .This ROM stores the values of the filter. This ROM has following 3 ports:-

- a: in std\_logic\_vector(3 downto 0 as it stores 9 values of the kernel );
- spo: out std\_logic\_vector(7 downto 0 for the image stored);
- clk: in std\_logic

#### 1.2 ROM2

This ROM stores the values of input image. This ROM has 3 ports:-

- a : Input address of the pixel ( 11 downto 0 in case of an image of 4096 pixels)
- clk : std logic\_vector type (input clock)
- spo : This is the output pixel of the given input address (7 downto 0) (std logic\_vector type)

### 1.3 RAM

This is a RAM memory type. This RAM stores the values of pixels after applying 3x3 filter. It has 5 ports:-

- a : Input address of the pixel ( 11 downto 0 in case of an image of 4096 pixels)
- clk : std logic\_vector type (input clock)
- d : This is the input pixel to be stored by RAM (15 downto 0 in this case)(std logic\_vector type)
- we : ( when we is 1,it represents write mode, else it represents read mode) (std\_logic type)
- spo : This is the output pixel obtained in read mode(15 downto 0)(std logic\_vector type)

### 1.4 RAM2

This is also a RAM memory ; This RAM stores the values of pixels after Normalisation. It has 5 ports:-

- a : Input address of the pixel ( 11 downto 0 in case of an image of 4096 pixels)
- clk : std logic\_vector type (input clock)
- d : This is the input pixel to be stored by RAM (11 downto 0 in this case)(std logic\_vector type)
- we : ( when we is 1,it represents write mode, else it represents read mode) (std logic type)
- spo : This is the output pixel obtained in read mode(15 downto 0)(std logic\_vector type)

## 2 Signals Used

We have used the following signals for the filtering,image processing and noramlization:-

- clk\_slow :-used in clock divider part;it oscillates between 0 and 1.

- registers reg00,reg02,reg01,reg10,reg11,reg12,reg20,reg21,reg22; these registers store input values of kernel
- kernel\_itr;used for iterating over kernel
- kernel\_comp:used as a helper to continue kernel traversal cycle.
- ker\_rom\_add: std\_logic\_vector(3 downto 0);is a vector that access the index at which we are present for the kernel.
- data\_rom\_ker: std\_logic\_vector(7 downto 0); accessing output data of kernel during register assignment.
- FSM\_state: a flag which controls the process operation.

All of the above signals are used in kernel to ROM storage. Now are the signals for the image processing part:-

- pix00,pix01,pix02,pix10,pix11,pix12,pix20,pix21,pix22 :used for accessing the pixels for multiplication.
- i,j: used as iterators for ROM to RAM conversion.
- grad\_cycle:this signal run the cycle for image processing.
- rom\_add: std\_logic\_vector(11 downto 0) :this vector extracts the image address (which was stored in ROM2).
- ram\_add: std\_logic\_vector(11 downto 0) : this vector access the RAM1 data,which includes the pixels after applying operations.
- data\_rom: std\_logic\_vector(7 downto 0) :a vector used for accessing the output data from the ROM2,after operation.
- sum: integer :used as a helper for mathematical calculations.
- wr\_enable:a signal for enabling or disabling writing.
- temp\_max\_val:maximum value for initial pixels.
- temp\_min\_val: minimum value for initial pixels.
- final\_min\_val: minimum value for final pixels.
- data\_in: std\_logic\_vector(15 downto 0): a signal for giving input from RAM1 .

- `final_max_val`: maximum value for final pixels.

now are the signals for normalization part:-

- `itr_nrml,jtr_nrml`: iterators for iterating over RAM1 for image normalization.
- `nrm_comp`: a vector for accessing the index at which we are present.
- `nrm_ram_add`: `std_logic_vector(11 downto 0)`: similar to kernel processes.
- `nrm_output_pixel` : `std_logic_vector(15 downto 0)`: for accessing the output pixel after operation.
- `nrm_data_in`: `std_logic_vector(15 downto 0)`: to access output data from the RAM2.
- `nrm_wr_enable`: same as a flag for writing.
- `nrm_sum`: helper integer.

### 3 Logic and Algorithms

#### 3.1 For the ROM storage of kernel

The process starts with the rising edge of `clk_slow`, and runs for the whole time while `kernel_comp < 27`. There are 27 cycles because on each kernel value, which processes that value in 3 cycles:

- First one is for assigning of `ker_rom_add` the 4-bit value of the address.
- Second, we wait for one cycle.
- Third, we assign the corresponding Register value from the kernel data. These registers are the one's which will store the kernel filter value in whole processes from now.

for implementation of above algorithm, we have used case statements, which are as follows:-

- Cases 0, 3, 6, 9, 12, 15, 18, 21, and 24: `ker_rom_add` is set to the value of `kernel_itr` (converted to a 4-bit vector). `kernel_comp` is incremented by 1. This step marks assignment of `ker_rom_add` for accessing kernel addresses. Also note that this process runs simultaneously with the FSM writing in the implementation.

- Cases 2, 5, 8, 11, 14, 17, 20, 23: `kernel_itr` is incremented by 1, and a variable `regXY` is assigned the value of `data_rom_ker` converted to an integer. This step marks the register assignment.
- Case 25 (the "others" case): `kernel_itr` is incremented by 1, and `reg22` is assigned the value of `data_rom_ker` converted to an integer. `kernel_comp` is also incremented by 1. This marks the end of whole cycle for the process.

Thus, this signifies the markings of the registers in the process, which are assigned the corresponding RAM to be used in further processing.

### 3.2 Image processing (MAC)

This Process is the MAC unit which calculates the value of output pixel after applying 3x3 filter.

- In every 4 cycles, we calculate the value of each `pixXY`. In first cycle we assign corresponding value to the ram address. Then we wait for next cycle and in third cycle value assigned to corresponding `pixXY`. Then we wait for next cycle.
- This is repeated again and again for each of the `pixXY` register. So in 36 cycles, all of our 9 `pixXY` registers are assigned their corresponding values.
- In 38th cycle we calculate the value of sum, i.e., the value calculated by multiplying these `pixXY` with corresponding `regXY` and then adding all these 9 terms.
- In 39th cycle the `final_max_val` and `final_min_val` is updated.
- In the 40th cycle the value of iterators `i` and `j` is being updated.
- Also in the corner and edges cases the corresponding `pixXY` values are assigned zero which goes out of bounds.

### 3.3 The FSM process

This process controls the synchronisation between the `process2`, `process3` and `process3`:

- This process decides that in which state the program is currently working and accordingly allows only one process at a time to execute.

- As soon as the conditions(values of flag signals) changes, it starts another process and halts previous one.
- Initially only process1 activates because both of the if statements in FSM are false.
- Then as `kernel_comp >=27` then process1 halts and process2 is triggered by this FSM.
- When value of `i` equals 64 then process 3 is also triggered by this FSM. Also, note that in process3 we have assigned the value to the `ram_add` using this process(it means at the starting of first cycle of process3 this FSM assigns a value to `ram add` which is further used in later 11 cycles of process 3).
- This also controls the `write_enable` signal of the RAMs.

### 3.4 For the Normalization of Image

This process starts with the rising edge of `clk_slow`;(Note that this process runs only for the part when `i=64`;which indicates the the whole image is extracted to RAM and is available for operation) This process has 12 cycles ;which are as follows:-

- in the first cycle,the value is assigned to `r_add` by the FSM process which is running in parallel with the current process.
- We wait for 1 cycle for output pixel and proper image processing .
- Then in the third cycle , `nrm_sum` is assigned the value of `output_pixel` .

We have implemented our idea by using case statements as follows:-

- case 0,1,3,4,8 are the cases where we just wait and increase our `nrm_comp` by 1;
- Case 2: `nrm_comp` is incremented by 1, and `nrm_sum` is assigned the value of `output_pixel` converted to an integer.
- Case 5: `nrm_sum` is updated by multiplying it by 255, and `nrm_comp` is incremented by 1.This ensures that `nrm_sum` gets its correct value.

- Case 6: `nrm_sum` is updated by dividing it by the difference between `final_max_val` and `final_min_val`, and `nrm_comp` is incremented by 1. This completes our normalisation formula.
- Case 7: `nrm_ram_add` set to  $(64*i+j)$  in an unsigned vector of 16 bits, and `nrm_comp` is incremented by 1.
- Case 9: `nrm_data_in` is set to the value of `nrm_sum` converted to a 16-bit vector, which is the output data we need to calculate, and `nrm_comp` is incremented by 1.
- Case 10: Checks if `jtr_nrml` is equal to 63. If true, it resets `jtr_nrml` to 0 and increments `itr_nrml` by 1; Thus sending the cycle to initials of the image pixels stored in RAM1. Otherwise, it increments `jtr_nrml`; Thus continuing the Loop. `nrm_comp` is incremented by 1.
- Others case: If `itr_nrml` is equal to 64, it resets both `itr_nrml` and `jtr_nrml` to 0. `nrm_comp` is set to 0. This is the formal end of our loop.

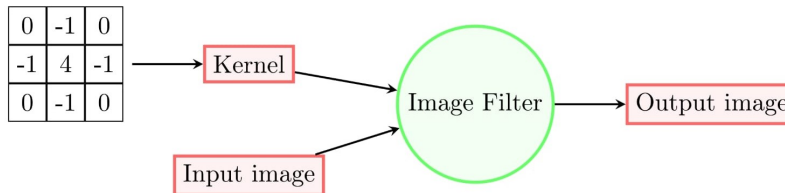
## 4 Formula and theory used for this part

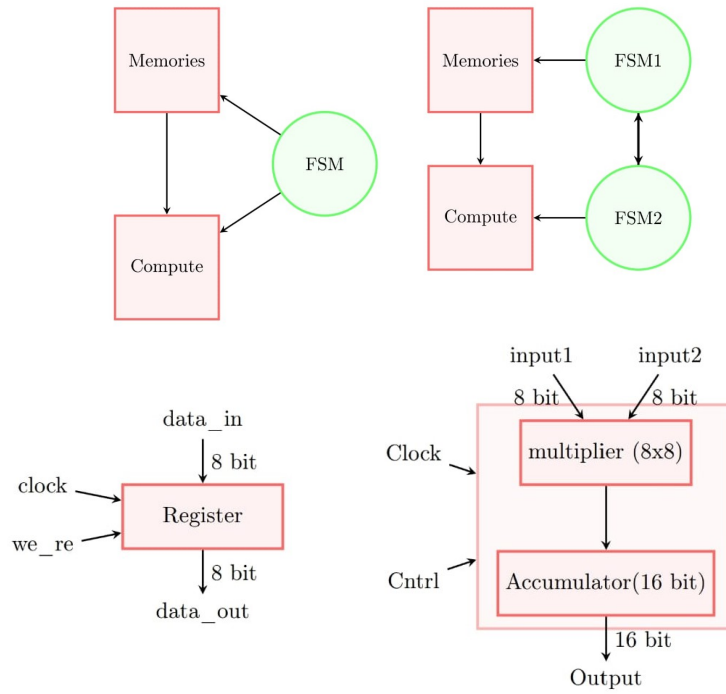
### 4.1 for the image processing part:-

The output pixel value  $O(i, j)$  at location  $(i, j)$  is computed as the sum of element-wise multiplications between kernel value and input image pixel, as shown in the equation below. The input image pixel at location  $(i, j)$  is denoted  $I(i, j)$ .

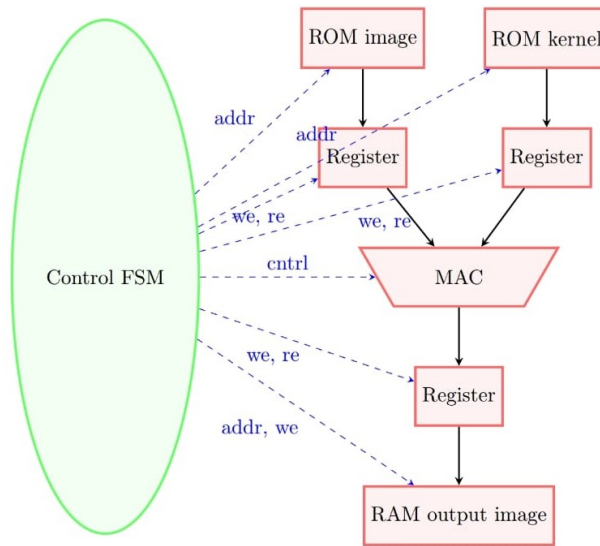
$$O(i, j) = a * I(i-1, j-1) + b * I(i-1, j) + c * I(i-1, j+1) + d * I(i, j-1) + e * I(i, j) + f * I(i, j+1) + g * I(i+1, j-1) + h * I(i+1, j) + i * I(i+1, j+1)$$

Below is the Block diagram/raw idea of assignment:-





(Block diagram for the Register unit and MAC unit )



(This diagram is shown for how FSM is controlling the path of execution)



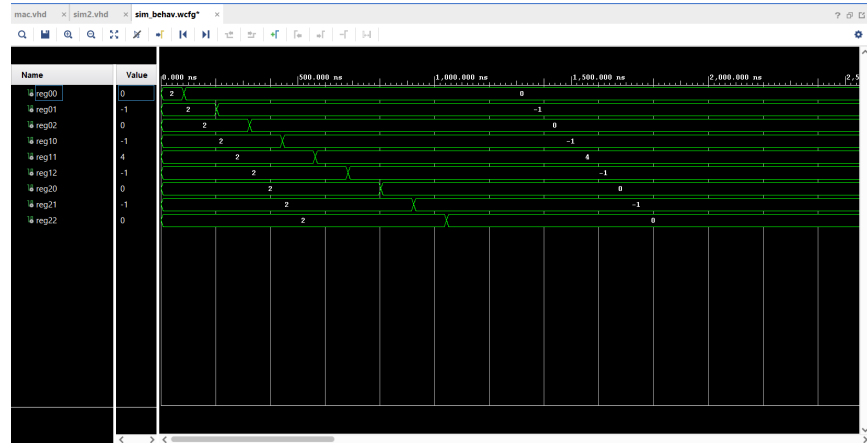
## 4.2 For the normalisation part

In linear normalization, for each pixel, we perform a scaling according to the equation 1, where old\_max and old\_min are minimum and maximum pixel values in the output image, new\_max and new\_min is the new range of pixel value in the final image:

$$\text{New\_I}(i, j) = (\text{I}(i, j) - \text{old\_min}) * (\text{new\_max} - \text{new\_min}) / (\text{old\_max} - \text{old\_min}) + \text{new\_min}$$

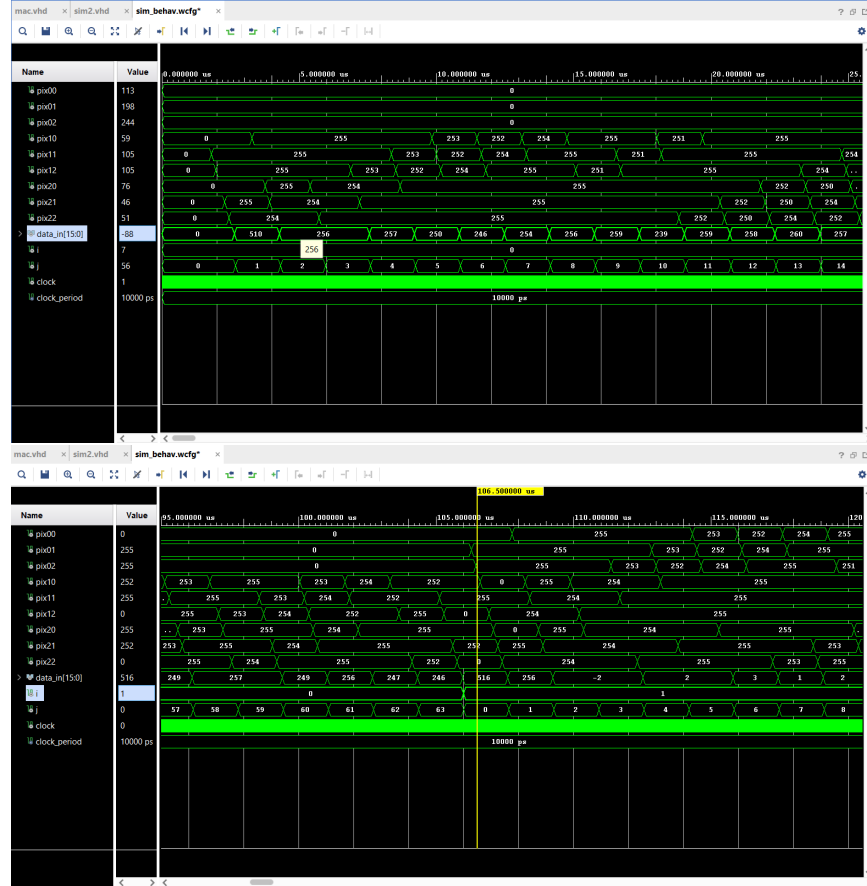
## 5 Snapshots and testcases

### 5.1 Testbench simulation for the Kernel reading part

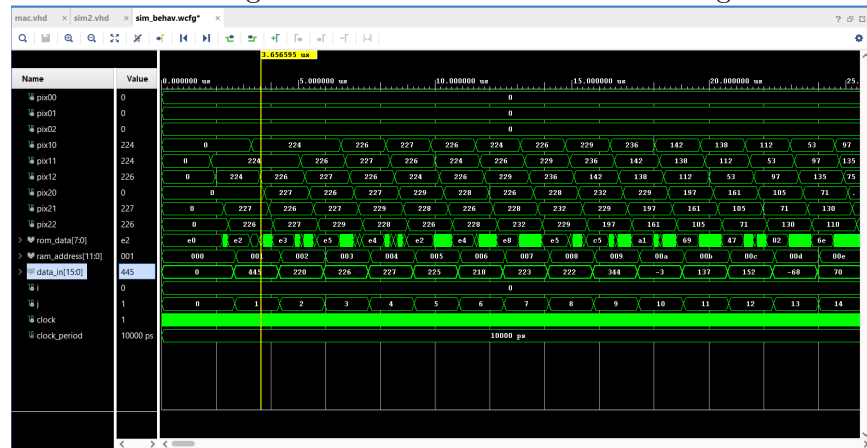


Note That the filter value is read correct here and all registers' value is initialised by 2,as in our code.

## 5.2 Test cases' test simulation during image processing

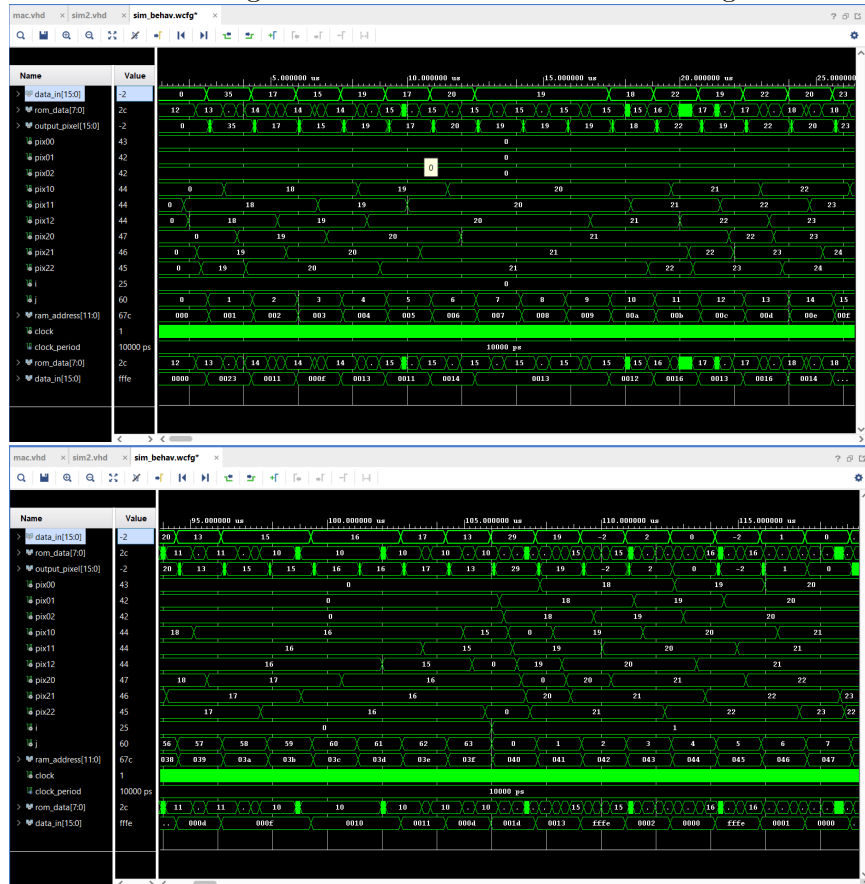


Two images of 'coin' test case while simulating .



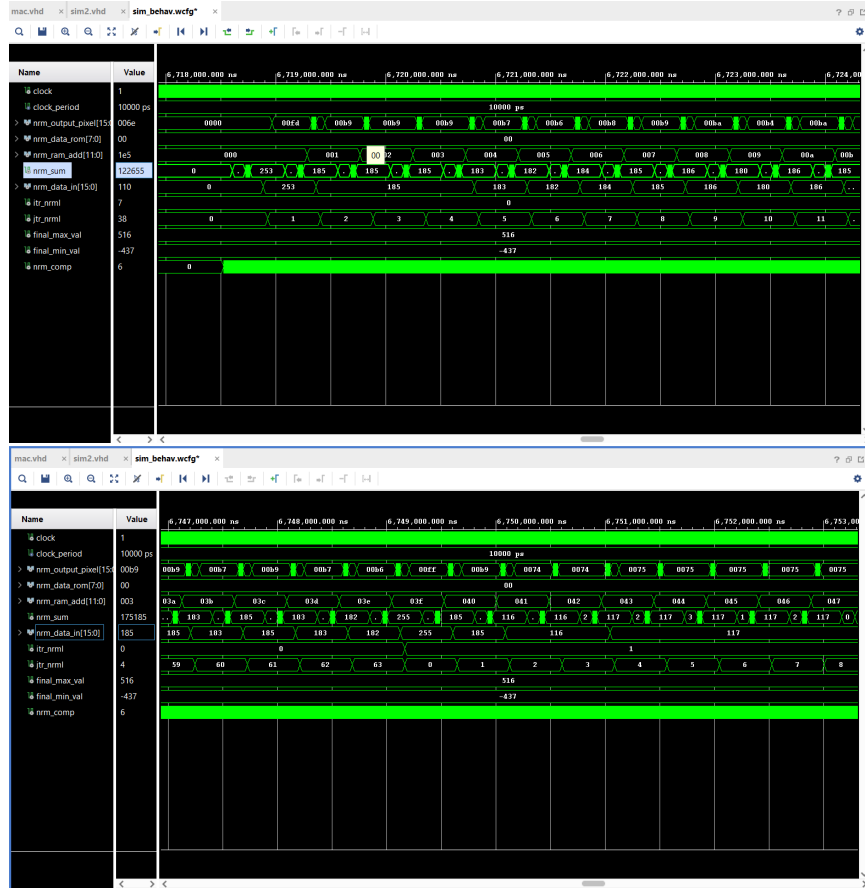


Two images of 'face' Test case while simulating.

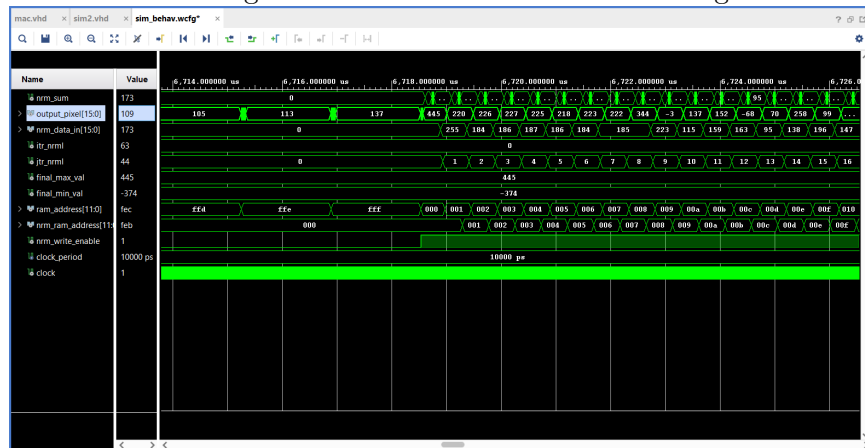


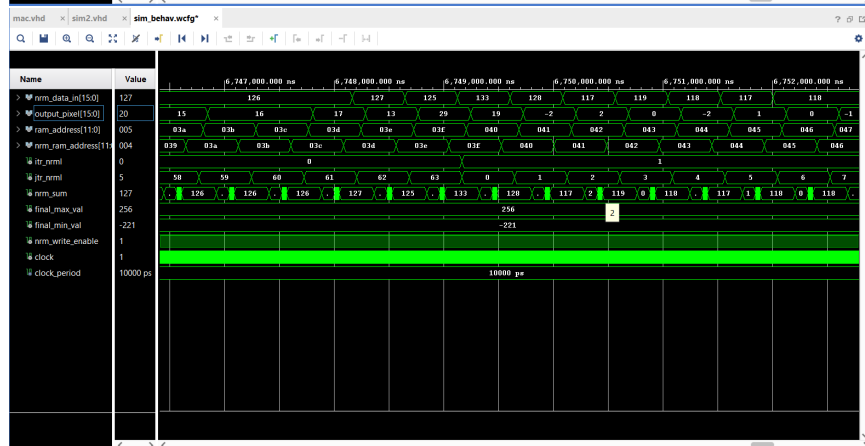
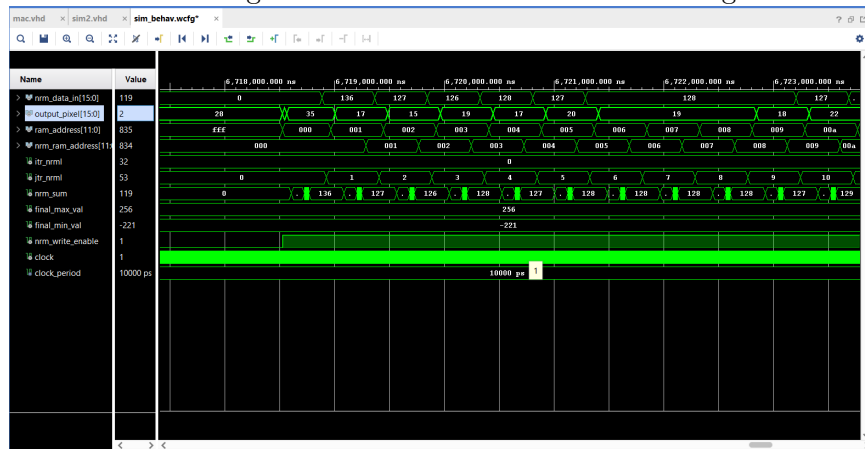
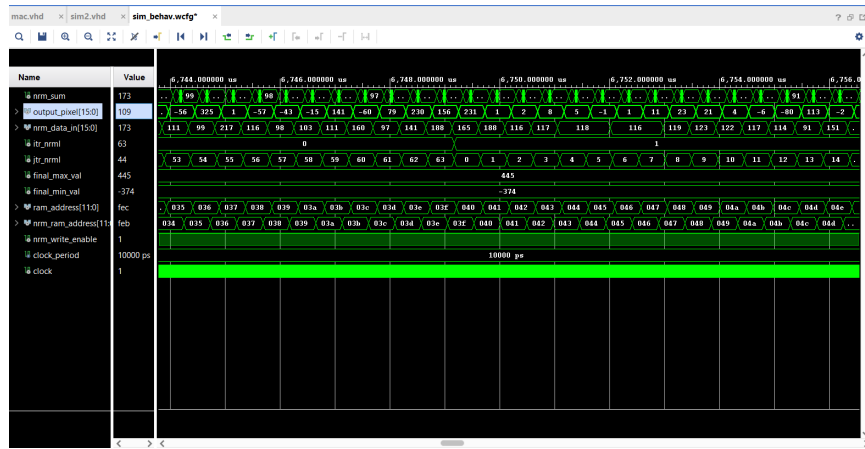
Two images of 'Light.house' test case while simulating.

### 5.3 Test cases' test simulation during Image Normalization



Two images of 'coin' test case while simulating .





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End of Part1

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## Part -2

(From here onwards, We Starts the part-2,i.e. implementation through use of FSM)

Similar to the Part-1 ,we first created the kernel extraction,then image processing through the pre-defined formula ,and then normalised the image through normalization process.In part-1 ,we did this using the multiplexer or MAC unit ;but this time ,we did it using FSM. For implementation of the 3 processes using FSM,we used 2 sub-processes and with the help of counters and synchronization. The 2 processes are as follows:-

### 6 VGA Controller

#### 6.1 Initialising condition

For this process,We start it on rising clock edge;because in FSM,we change the signals only at rising edges.Then we checked the condition of the **Video\_On**(a new signal for controlling when to enable change in states).If Video\_On is not set to '1',then we reset our signal vectors for R,G,B of the VGA controller to default '0'.Else ,we proceed to next step.

#### 6.2 Reset and Assignment

After this,we checked the hcnt and vcnt to be in display ranges of and thus assign the respective R,G,B values for the nrm\_output\_pixel in 4-bit vectors. If hcnt and vcnt are not in 0 to 64 ranges,then we reset them to '0'.

Thus,our VGA controller effectively controls the resetting and memory allocation to display.

### 6.3 FSM States

We have 4 FSM states which decides what we are to perform:-

- State 0:-In this state ,we read from kernel and store its data in regXY.
- State 1:- In this state,we apply the multiplication and accumulation operation and stored it in RAM1(RAM) created.
- State 2:-In this state ,we apply the normalization operation and store its final pixels in RAM2.(Final state).
- State 3:-In this state,we start over VGA controller to display the image which has pixels stored in RAM2.

By these designs , for iterating over 4 states,we make our image ready to display and after it ,It remains to state 3 until a transition in state occur.

## 7 Transition Of States

The state transition process begins with rising edge of clock and transits only in the following conditions:-

- State 0 to State 1:-This transition occurs when Kernel comp becomes 27 which marks the completion of reading from Kernel ,and only now ,we can start the MAC operation in state 1.
- State 1 to State 2:-This transition occurs when i=64(mainly)because at this state kernel comp=27 and itr\_nrml=0.So,this transition only depends on i being 64 or not. This marks completion of MAC operation and now we can perform normalization in state2.
- State 2 to State 3:- This transition occurs when itr\_nrml=64 ,which means the completion of normalization and now we can display the output image through VGA controller (State 3).State 3 is the final state.

Thus ,this ends the marking for our Transitioning model.

Now we shall make a small note on how we managed the counters.

**-Counters:-** We used following counters/synchronizers:-

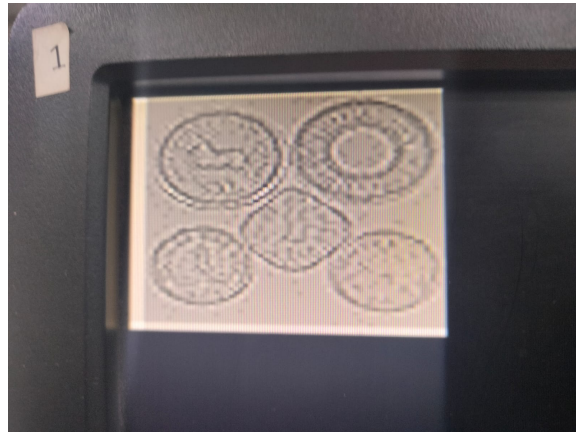
- Vsync:-Depends on Vcnt; is '1' when on rising edge,Vcnt is not in a certain range .Else,we set it to '0'.
- Vcnt:-Depends on hcnt ;is incremented by 1 when hcnt reaches a certain value and Vcnt is not the end value.
- hsync:- On rising clock edge ,when hcnt is out of a range,then it is triggered.
- hcnt :- On rising clock,increases on every edge until reaches terminal value,after which it resets to '0' again.
- Video\_On:- This signal triggers on rising edge under the condition that hcnt and vcnt both are in display range;Otherwise set to '0'.

## 8 Test cases and Simulation



Image of face under filter





coins



light house

-Now a few of our test cases:-



Initial image of bull and image of bull after filter(sharpening)



Image of bull with edge detection filter.

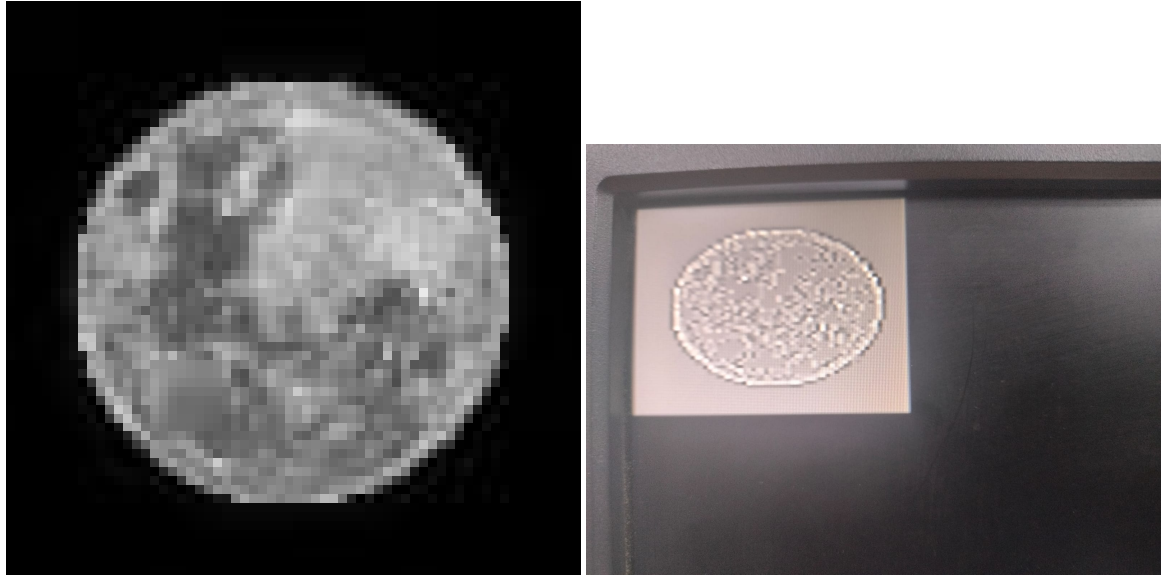
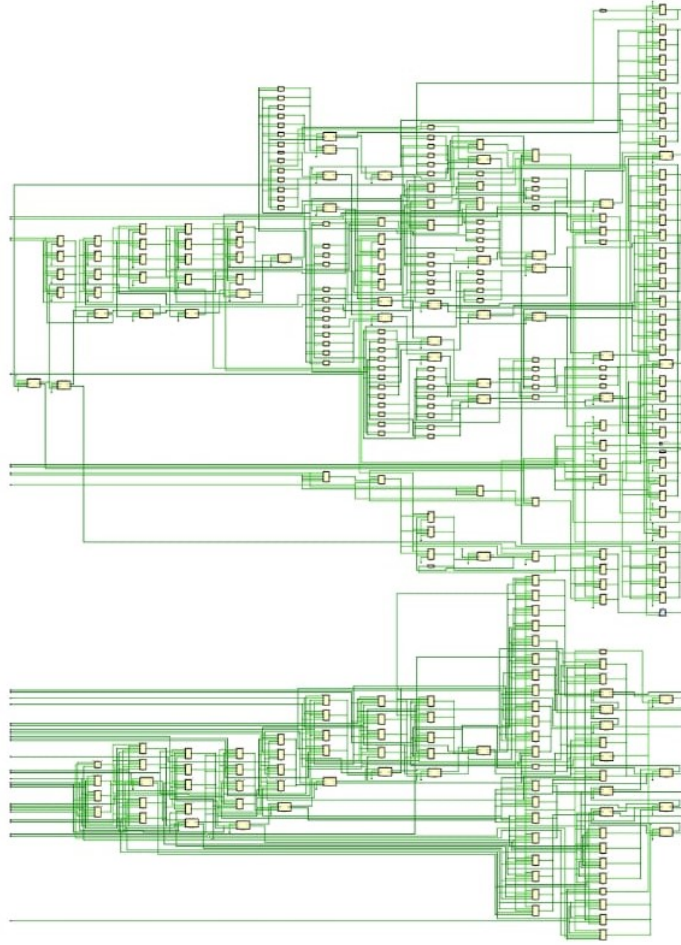


Image of moon initially and finally.

## 9 Block diagram

The block diagram for the whole FSM processing is following:-



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End Of Report