```
void
setup()
            Serial.begin(9600);
            pinMode(4,INPUT);
            pinMode(8,OUTPUT);
            pinMode(13,OUTPUT);
          }
          void loop()
            int p=digitalRead(4);
            Serial.println(p);
            if(p)
              digitalWrite(13,1);
              Serial.println("motion detected");
            }
            delay(1000);
            double a=analogRead(A0);
            double t=(((a/1024)*5)-0.5)*100;
            Serial.println(t);
            if(t>25)
            digitalWrite(8,1);
              Serial.println("temperature greater than 25");
            delay(1000);
            }
           }
```