## Take Home 1

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- EG/2018/3357
- GitHub:

https://github.com/UmeshanUC/Computer\_Vision\_and\_Image\_Processing\_CA1.git

```
import cv2
import numpy as np
import matplotlib.pyplot as plt

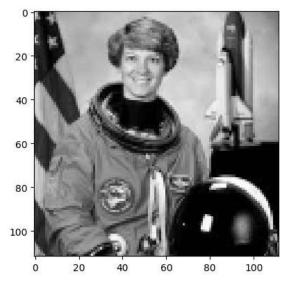
def AdjustImageIntensityLevels(imageMat, noOfLevels):
    adjustedImg = imageMat/255*(noOfLevels)
    return np.round(adjustedImg)

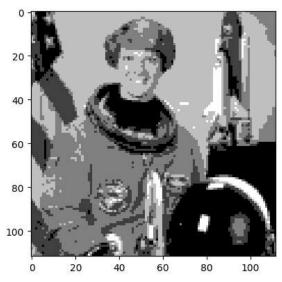
def PlotImagesInRow(img, newImage):
    fig, (ax1, ax2) = plt.subplots(1, 2, figsize=(10,5))
    ax1.imshow(img)
    ax2.imshow(newImage)
    plt.gray()
    plt.show()
```

Q1.

```
In [ ]: imgRaw = cv2.imread('assets/astronaut.jpg', 0 )
    img = cv2.resize(imgRaw,(0,0), fx=0.5, fy=0.5)

In [ ]: intensityLevels = int(input('intensityLevels as integer:'))
    newImage1 = AdjustImageIntensityLevels(img, intensityLevels)
    PlotImagesInRow(img, newImage1)
```



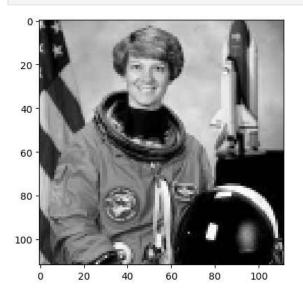


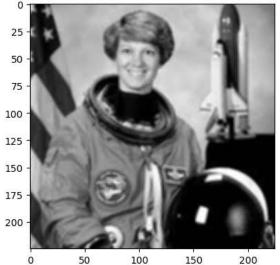
Q2.

3x3 average filter

```
In [ ]: arr1 = np.ones((3,3),np.float32)/9
   newImage2 = cv2.filter2D(imgRaw,-1,arr1)

PlotImagesInRow(img, newImage2)
```

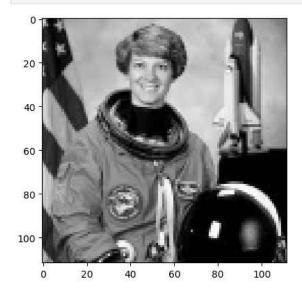


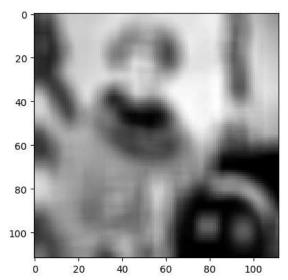


## 10x10 average filter

```
In [ ]: arr2 = np.ones((10,10),np.float32)/100
    newImage3 = cv2.filter2D(img,-1,arr2)

PlotImagesInRow(img, newImage3)
```

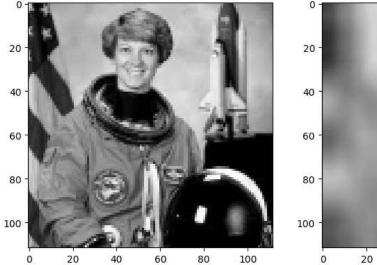


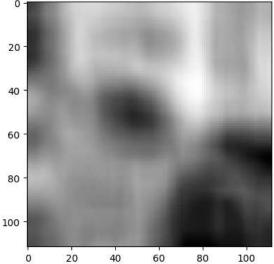


## 20x20 average filter

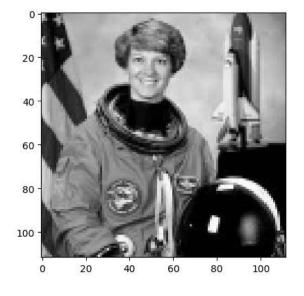
```
In [ ]: arr3 = np.ones((20,20),np.float32)/400
    newImage4 = cv2.filter2D(img,-1,arr3)

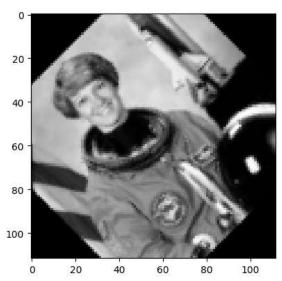
PlotImagesInRow(img, newImage4)
```

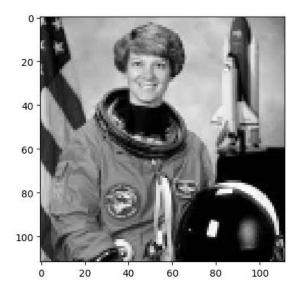


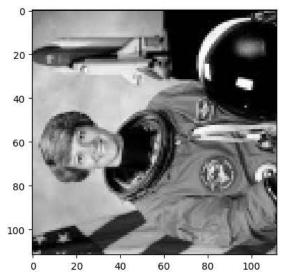


Q3.









## Q4.

```
In []: # for 3x3 block
    arr4 = np.ones((3,3),np.float32)/9
    newImage7 = cv2.filter2D(img,-1,arr4)

# for 5x5 block
    arr5 = np.ones((5,5),np.float32)/25
    newImage8 = cv2.filter2D(img,-1,arr5)

# for 7x7 block
    arr6 = np.ones((7,7),np.float32)/49
    newImage9 = cv2.filter2D(img,-1,arr6)

# Save the new images
PlotImagesInRow(img, newImage7)
PlotImagesInRow(img, newImage8)
PlotImagesInRow(img, newImage9)
```

