CSC 384
Introduction to Artificial Intelligence

CSP 1

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Learning Goals

By the end of this lecture, you should be able to

- Formulate a CSP as a Search Problem.
- Define a constraint using a table or using an expression.
- Explain the relative advantages and disadvantages of multiple CSP formulations.
- Trace the execution of the Backtracking Search algorithm.
- Choose a variable by using the Minimum-Remaining-Value heuristic or the Degree heuristic.
- Choose a value for a variable using the Least-Constraining-Value heuristic.

Outline

1. CSP Examples
2. Formulating a CSP
3. Backtracking Search
4. Heuristics

CSP EXAMPLES

Example: Scheduling

Want to schedule a time and a space for each final exam so that

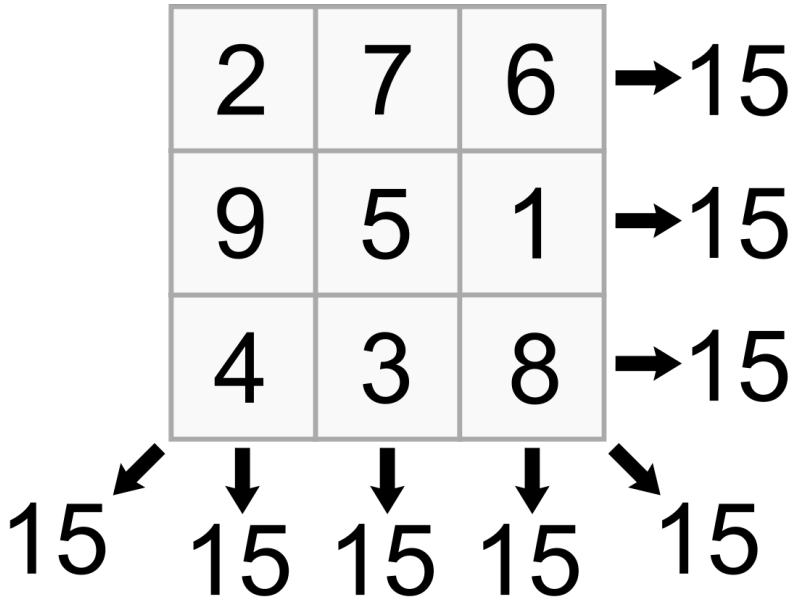
- No student is scheduled to take more than one final exam at the same time.
- The space allocated must be available at the time set.
- The space must be large enough to accommodate all the students taking the exam.

Example: Sudoku

	2							
			6					3
	7	4		8				
					3			2
	8			4			1	
6			5					
				1		7	8	
5					9			
							4	

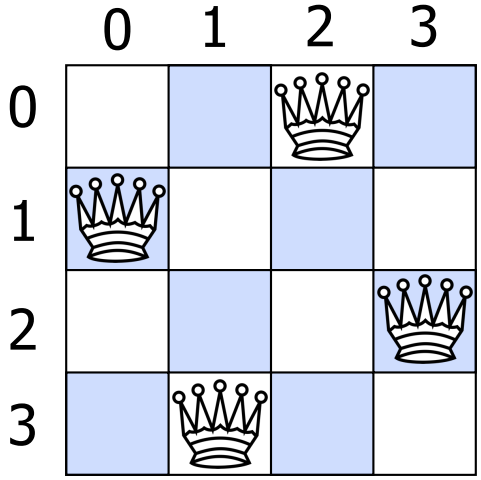
1	2	6	4	3	7	9	5	8
8	9	5	6	2	1	4	7	3
3	7	4	9	8	5	1	2	6
4	5	7	1	9	3	8	6	2
9	8	3	2	4	6	5	1	7
6	1	2	5	7	8	3	9	4
2	6	9	3	1	4	7	8	5
5	4	8	7	6	9	2	3	1
7	3	1	8	5	2	6	4	9

Example: Magic Square



FORMULATING A CSP

4-Queens Problem



4-Queens as a Search Problem

- State:
- Initial State:
- Successor Function:
- Goal States:
- (Optionally) Cost Function:
- (Optionally) Heuristic Function:

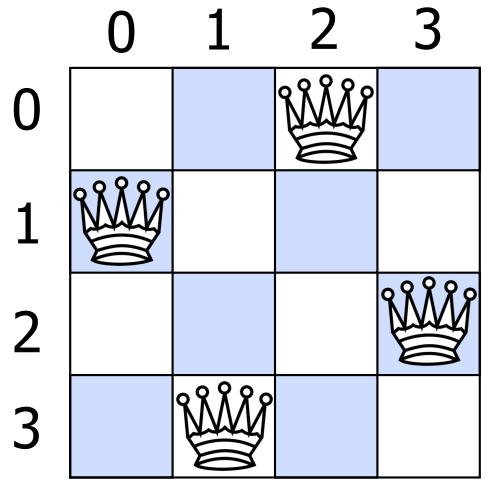
Defining a State of a CSP

Each state contains

- A set of variables.
- A domain of possible values for each variable.
- A set of constraints specifying the allowable value combinations.

A State for 4-Queens Problem

- Variables:



- Domains:

- Constraints:

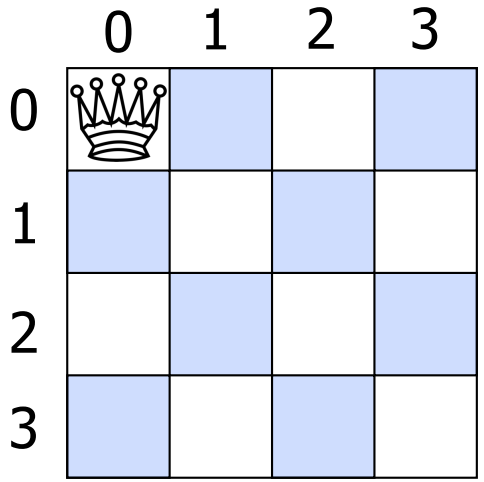
4-Queens as a Search Problem

- State: see the previous slide.
- Initial state:
- Goal states:
- Successor function:

Question: Which ones are the successors?

Which of the following is/are successor(s) of $0NNN$?

A. 00NN
B. 01NN
C. 02NN
D. 03NN



Defining a Constraint in Two Ways

- List all allowable value combinations with a table.

x	y
0	3
1	2
2	1
…	…

- Write a logical expression (a compact version).

$$x + y = 3$$

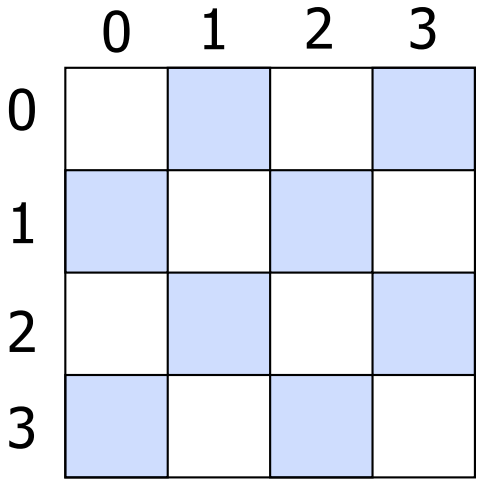
Defining a Constraint with a Table

How can we define the constraint below?

"queens x_1 and x_3 are not in the same row or diagonal."

(1) Define this constraint in a table.

x_1	x_3

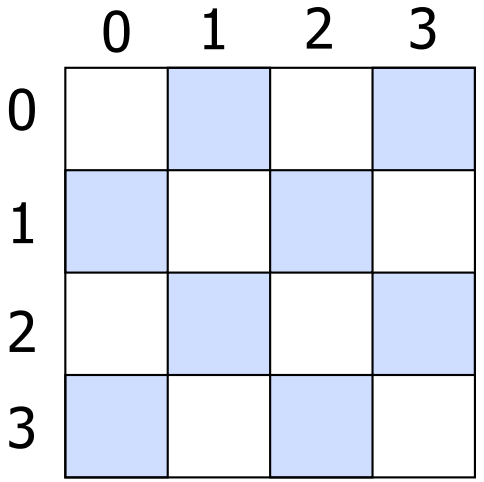


Defining a Constraint with an Expression

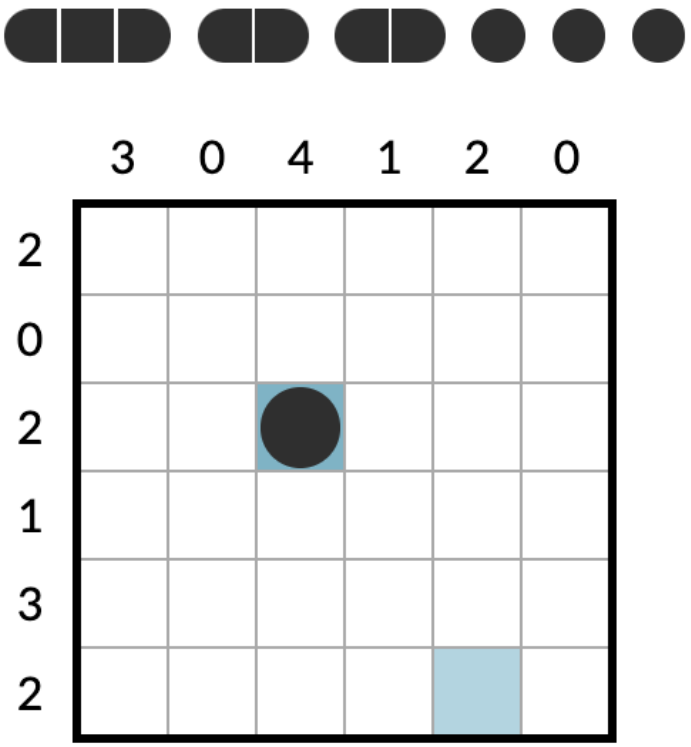
How can we define the constraint below?

"queens x_1 and x_3 are not in the same row or diagonal."

(2) Define this constraint using a logical expression.



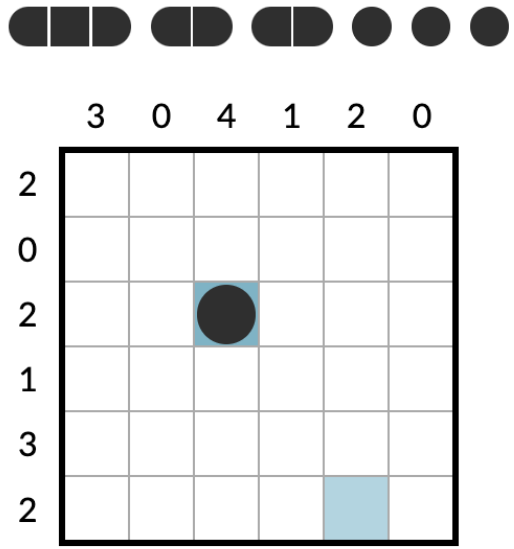
Battleship Solitaire



Play here: https://lukerissacher.com/battleships

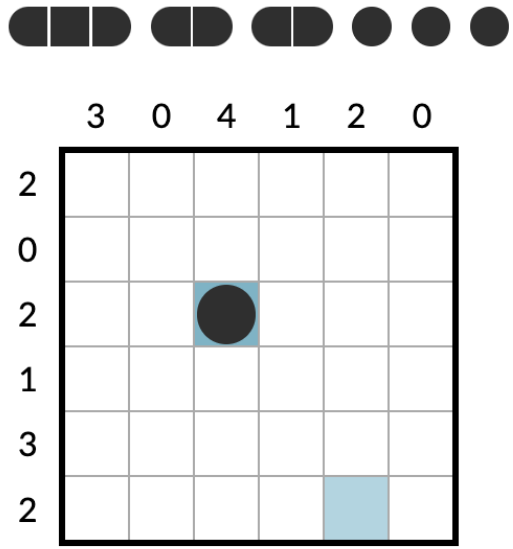
A State for Battleship Solitaire (Cell Based)

- Variables: each cell (x, y). $0 \leq x, y \leq dim$.
- Domains:
- Constraints:



A State for Battleship Solitaire (Ship Based)

- Variables: each ship's top-left corner location (x, y) and orientation (h or v).
  $0 \leq x, y \leq dim$.



- Domains:

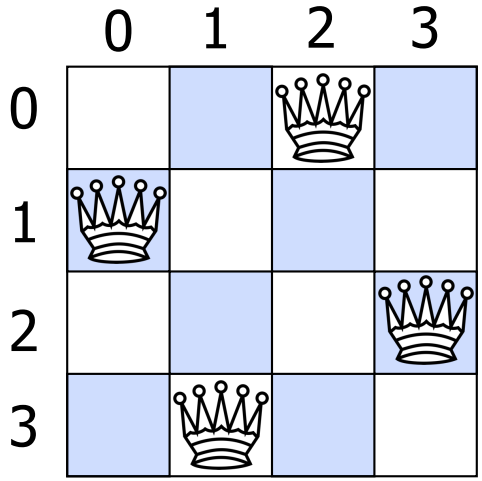
- Constraints:

BACKTRACKING SEARCH

How are solving the two puzzles different?

Sliding Puzzle

4-Queens



Solving a CSP as a Search Problem

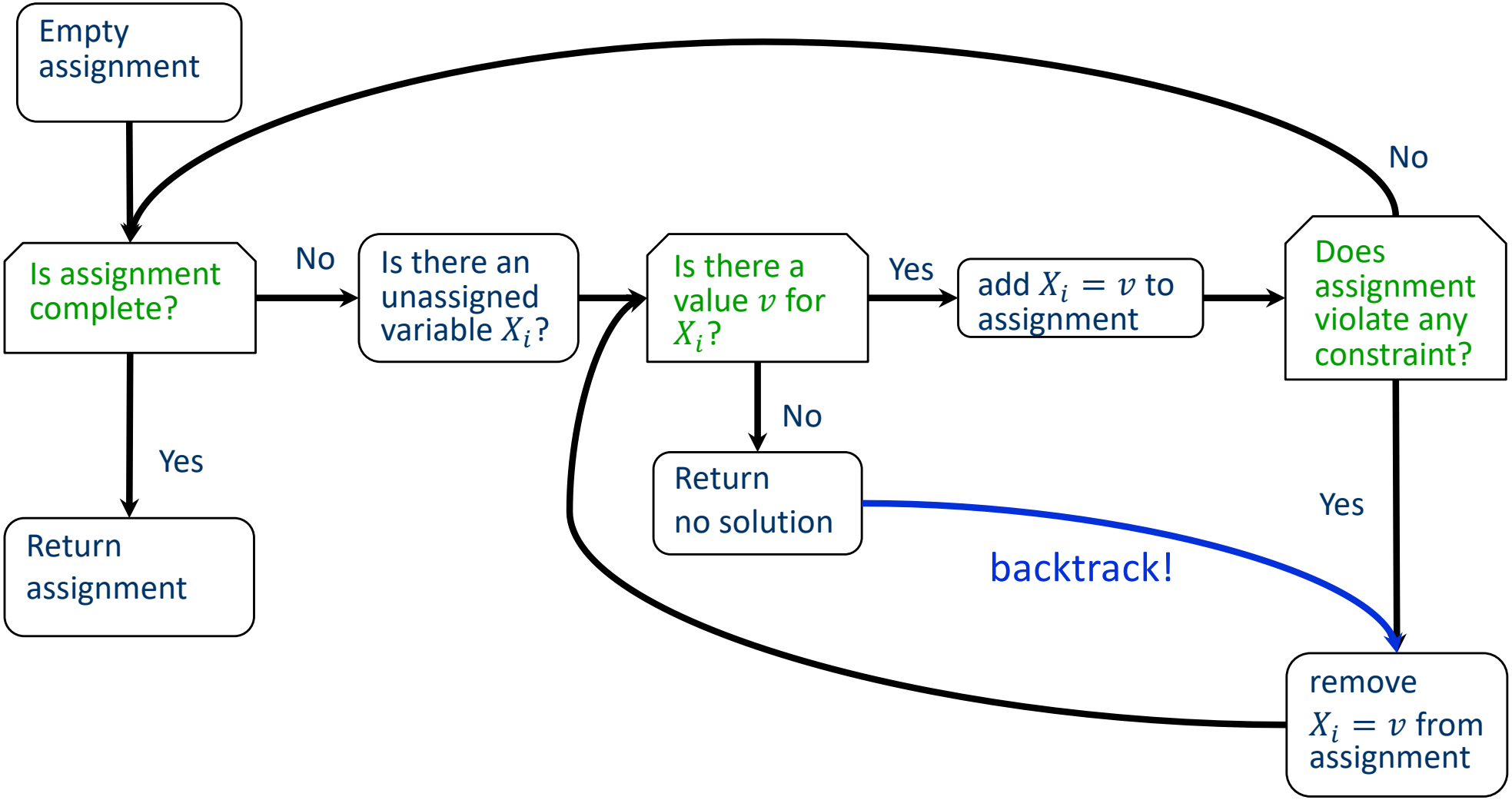
Do not care about finding a path to the goal.

Can use a specialized version of **depth-first search**.

Key ideas of **backtracking search**:

1. Start with the empty assignment.
2. Search through the partial assignments.
3. At each step, assign a value to an unassigned variable.
4. If a partial assignment violates a constraint, backtrack.

Backtracking Search (Flowchart)



Backtracking Search (Pseudocode)

```
1. function BACKTRACKING-SEARCH(csp)
2.     return BACKTRACK({}, CSP)
3.
4. function BACKTRACK(assignment, csp)
5.     if assignment is complete then return assignment
6.     var <- SELECT-UNASSIGNED-VARIABLE(csp)
7.     for each value in ORDER-DOMAIN-VALUES(var, assignment, csp) do
8.         add {var = value} to assignment
9.         if assignment does not violate any constraint then
10.            result <- BACKTRACK(assignment, csp)
11.            if result ≠ no solution then
12.                return result
13.        remove {var = value} from assignment
14.    return no solution
```

Solving 4-Queens using Backtracking Search

HEURISTICS

Heuristics for Variable and Value Ordering

- How do we choose the next **variable** to consider?
  - Minimum-remaining-values heuristic
    - Most powerful
    - “fail-first” heuristic.
  - Degree heuristic
    - Helpful for choosing the first variable.
    - A useful tie-breaker.
- How do we choose the next **value** to consider?
  - Least-constraining-value heuristic
    - “fail-last” heuristic.

Heuristics to Choose the Next Variable

Minimum-Remaining-Values (MRV) Heuristic

- Choose the variable with the fewest "legal" values
- a.k.a. the "most constrained variable" heuristic
- a.k.a. the "fail-first" heuristic.
  - picks a variable that is most likely to cause a failure soon.
  - prune large parts of the tree earlier.

Degree Heuristic

- Select the variable that is involved in the largest number of constraints on other unassigned variables.

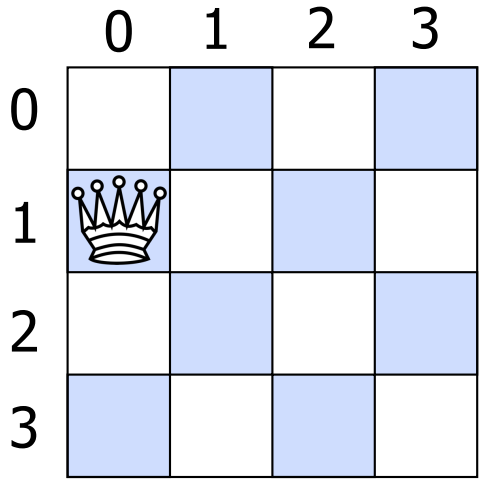
Heuristics to choose the next variable

- **MRV** heuristic is more powerful than degree heuristic.

- **Degree** heuristic is helpful for choosing the first variable.
- **Degree** heuristic is a useful tie-breaker.

Q1: Applying the MRV Heuristic

Consider the 4-queens state.



Based on the MRV heuristic,

which **variable** should we choose next?

A. x_1

B. x_2

C. x_3

Q2: Applying the Degree Heuristic

Based on the degree heuristic,

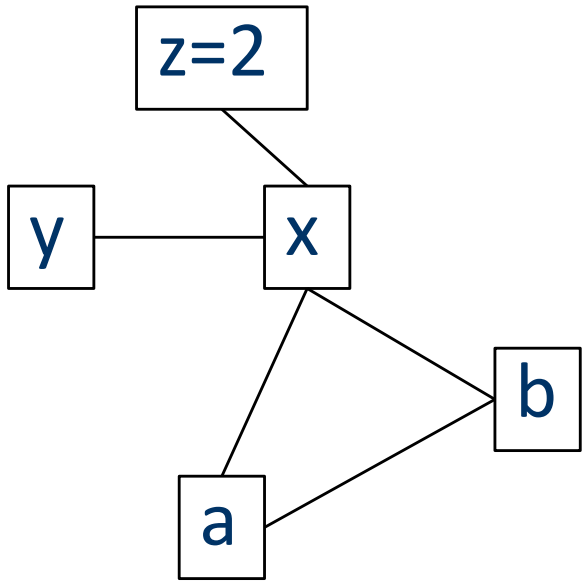
which **variable** should we choose next?

A. a

B. b

C. x

D. y



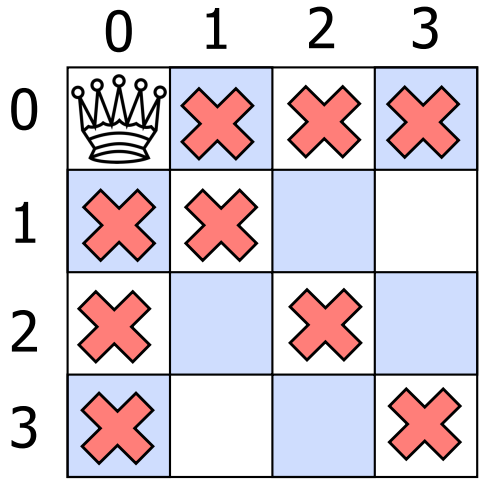
Least-Constraining-Value Heuristic

- How do we select which **value** to examine first?
- Choose the value that rules out the fewest choices for the neighboring variables.
- Leave the maximum flexibility for subsequent variable assignments.
- a.k.a. “fail-last” heuristic.
  - Only need one solution. Look for the most likely values first.

Q3: Applying the LCV Heuristic

Consider the 4-queens state.

Consider the variable x_1 next.



Based on the LCV heuristic,

which **value** should we choose next?

$A.\ \ x_1 = 2$

$B.\ \ x_1 = 3$