

## 1 Maschine Learning

Algorithm learns class of tasks, measured by loss function, from experience.

**supervised learning** learn  $h : \Delta^* \rightarrow \Sigma^*, h = t$ ; example:  $(x, y) \in \Delta^* \times \Sigma^*, t(x) = y$ .

**unsupervised learning** learn  $h : \Delta^* \rightarrow \Sigma^*, \ker(h) = \ker(t)$ ; example:  $x \in \Delta^*$ .

**reinforcement learning** learn strategy based on feedback from environment.

## 2 Supervised Learning

- model function  $t : \mathcal{M} \rightarrow \mathcal{R}$

-  $\text{supp}(t) = \{m \in \mathcal{M} \mid t(m) \neq 0\}$

-  $\bar{m} \in \text{supp}(t) \Leftrightarrow t(\bar{m}) = 1$

**Hypothesis** of A: potential result of A

**Hypothesis space**  $\mathcal{H}_A$  of A: set of all hypotheses

**h fits D** if  $h(x_i) = y_i$  for all  $(x_i, y_i) \in D$

**Version space**  $\mathcal{V}_A(D)$  of A: all hypotheses that fit D

**Inductive bias** of A: set of assumptions that A uses to predict outputs of unseen data

### 2.1 Conjunctive Clause

$\theta = (\theta_1, \dots, \theta_k), \theta_i \in M_i \cup \{\star, \perp\}$

-  $\theta_\perp = (\perp, \dots, \perp)$  most specific

-  $\theta_\star = (\star, \dots, \star)$  most general

-  $\text{supp}(h_{\theta_\perp}) = \emptyset, \text{supp}(h_{\theta_\star}) = \mathcal{M}$

-  $h_{\theta_\perp} = h_{(\theta_1, \dots, \perp, \dots, \theta_k) = \dots}$

induced hypothesis  $h_\theta(m_1, \dots, m_k) = 1$  if  $\forall i : \theta_i \in \{m_i, \star\}$  else 0

$h \preceq h'$  if  $\text{supp}(h) \subseteq \text{supp}(h')$ .  $h$  is more specific (less general) than  $h'$

**Find-S Algorithm** finds most specific conjunctive clause that fits D

1. Start with  $\theta_\perp = (\perp, \dots, \perp)$
2. iterate over POSITIVE examples
3. min-generalize  $\theta$  to fit example
4.  $\perp \rightarrow a, a \rightarrow \star$

- maximal general hypothesis:

1. start at  $\theta_\star = (\star, \dots, \star)$
2. exclude every negative example
3.  $(\star, \dots) \rightarrow \{(b, \dots), (c, \dots) \dots\}$

- If  $V_A(D) \neq \emptyset$ , Find-S finds  $h \in V_A(D)$

**disjunctive normal form**  $\Theta = \{\theta_1, \dots, \theta_m\}$

'finite set of conjunctive clauses'

induced hypothesis  $h_\Theta(\bar{m}) = 1$  if  $\exists \theta \in \Theta : h_\theta(\bar{m}) = 1$  else 0

-  $\text{supp}(\Theta) = \bigcup_{\theta \in \Theta} \text{supp}(h_\theta)$

- can represent all boolean functions

### Boundary sets of version space

maximally general hypotheses  $V_A^\top(D) = \{h \in V_A(D) \mid \nexists h' \in V_A(D) : h \prec h'\}$

maximally specific hypotheses  $V_A^\perp(D) = \{h \in V_A(D) \mid \nexists h' \in V_A(D) : h' \preceq h\}$

-  $h \in V_A^\top$  maximal, weil:  $\forall x \in M \setminus \text{supp}(h) : \text{supp}(h) \cup \{x\} \notin \text{supp}(V_A(D))$

Theorem:  $V_A(D) = \{h \in H_A \mid \exists h_\top \in V_A^\top(D), \exists h_\perp \in V_A^\perp(D) : h_\perp \preceq h \preceq h_\top\}$

-  $\rightarrow V_A(D)$  det. by  $V_A^\top(D)$  and  $V_A^\perp(D)$

- only 1 lower bound (in  $V_A^\perp(D)$ ), potentially multiple upper bounds (in  $V_A^\top(D)$ )

**Candidate Elimination Algorithm**

Output: DNF for  $V_A^\top(D)$  and  $V_A^\perp(D)$

1.  $S_\perp = \{\theta_\perp\}, S_\top = \{\theta_\star\}$

2. for  $1 \leq i \leq n : y_i = 1$  (pos. xmpls)

1. keep only fitting  $h$  from  $S_\top$
2.  $\forall \theta \in S_\perp : h_\theta(x_i) = 0$ 
  - remove  $\theta$ , add all min generalizations  $\theta'$  of  $\theta$  that fit  $x_i$  to  $S_\perp$

3. keep only most specific  $h$  in  $S_\perp$

3. for  $1 \leq i \leq n : y_i = 0$  (neg. xmpls)

1. keep only fitting  $h$  from  $S_\perp$

2.  $\forall \theta \in S_\top : h_\theta(x_i) = 1$

- remove  $\theta$ , add all min specializations  $\theta'$  of  $\theta$  that fit  $x_i$  to  $S_\top$ , for which a more specific  $\theta_\perp \in S_\perp$  exists!

3. keep only most general  $h$  in  $S_\top$

-  $V_A^\top = \{h_\theta \mid \theta \in S_\top\}, V_A^\perp = \{h_\theta \mid \theta \in S_\perp\}$

- Concept identified if:  $S_\perp = S_\top$  and  $|S_\top| = 1$ .  $V_A(D) = \emptyset$  if  $S_\perp = \emptyset \vee S_\top = \emptyset$

**2.2 Decision Trees**

**Splitting**  $\Pi = \{M - 1, \dots, M_p\}$  is finite partition of (sub)feature Space  $\mathcal{M}'$

- induces splitting of  $\{1, \dots, n\}$  into  $I_{D'}(M_1), \dots, I_{D'}(M_p)$  (sets of indices)

- monothetic splits: based on 1 feature

- simple split: monothetic, into all realizations  $M = \{\bar{m} \in M \mid m_1 = a(b, \dots)\}$

- binary split: monothetic, into 2 sets  $M = \{\bar{m} \in M \mid m_1 \in A\} \cup \{\bar{m} \in M \mid m_1 \notin A\}$

- induced hypothesis  $h_T(\bar{m}) = T(v)$ , where  $v$  is unique leaf s.t.  $\bar{m} \in M_v$

- simple decision trees can represent all hypotheses

**Decision Tree Quality Measures**

• Number of leaves

• Height (max number of constraints to check)

• External path length (sum of all path lengths from root to leaf)

- Weighted external path length (sum of all path lengths from root to leaf, weighted by number of examples classified in that leaf)

Theorem: Given D and bound b, its NP hard to decide existence of decision tree T s.t.  $h_T$  fits D and T has ext. p.l.  $\leq b$

- Majority Class  $\text{Maj}_D(M')$  maj.  $r \in R$

- Number of Misclassifications:  $\text{Err}_D(M', r)$  in feature subspace  $M'$  with majority class  $r$

-  $\text{Err}_D(T)$ : sum up all  $\text{Err}_D(M_v, T(v))$

**Pure Node** v if  $\text{Err}_D(M_v, T(v)) = 0$

- class distribution  $p_D^{M'}(r)$ :  $p(r)$  in  $M'$

- **Impurity Function**  $\iota : [0, 1]^R \rightarrow \mathbb{R}$  if

- $\iota(p)$  is minimal  $\forall p : p(r) = 1$
- $\iota$  symmetric in classes
- $\iota$  is maximal for uniform distr.

gets probability distribution as input

1.  $\bar{\iota}(p) = 1 - \max_{r \in R} p(r)$

2. Entropy  $H(p) = - \sum_{r \in R} p(r) \log_2 p(r)$

3. Gini Impurity  $G(p) = 1 - \sum_{r \in R} p(r)^2$

- Impurity of  $M'$  is  $\iota_D(M') = \iota(p_D^{M'})$

**Impurity Reduction** of splitting

$\Pi = \{M'_1, \dots, M'_p\}$  of  $M'$  is:

$\iota_D(\Pi) = \iota_D(M') - \sum_{i=1}^p \frac{|I_D(M'_i)|}{|I_D(M')|} \iota_D(M'_i)$

**Tree Construction** for  $M' \subseteq M$

1. if no elements in  $M'$ : new leave  $v$ :  $T(v) = \text{Maj}_D(M)$

2. if  $\iota(M') \leq \epsilon$ : new leaf  $v$ :  $T(v) = \text{Maj}_D(M')$

3. else: select split  $\Pi$  of  $M'$  with maximal impurity reduction

- strict imp. fct.: concave at every point

-  $\iota_D(\Pi) \geq 0 \forall \Pi$  and strict imp. fct.  $\iota$

**ID3** simple D.T., monothetic simple splits, impurity function: entropy.

inductive bias: local optimization (greedy)

**CART** D.T., binary splits, impurity function: Gini impurity

- true loss of  $h \in H_A$ : misclassifications:  $l^*(h) = \sum_{\bar{m} \in M} (1 - \delta_{h(\bar{m}), t(\bar{m})})$

-  $h$  **overfits** D if  $\exists h' \in H_A :$

$l(h, D) < l(h', D)$  and  $l^*(h) > l^*(h')$

when: training data: noisy, small, biased

- Training Data: optimize loss here

- Validation: optimize hyperparameters

- Test Data: final estimation (true loss)

-  $h$  **overfits**  $(D, D_V)$  if  $\exists h' \in H_A :$

$l(h, D) < l(h', D)$  and  $l^*(h) > l^*(h')$

true loss of  $h$  estimated by  $l(h, D_V)$

Countermeasures to overfitting:

- increase data quality/quantity
- early stopping (no more splits) thrhld large  $\rightarrow$  omits useful splits thrhld small  $\rightarrow$  Large Tree
- regularization (penalize model complexity in training process)

**Pruning**: turn inner node  $v$  into leave with label  $\text{Maj}(M_v)$

**D.T. pruning Algorithm**

1. given fully trained D.T.

2. prune every inner node as long as pruning doesn't increase validation loss:

$l(h'_T, D_V) \leq l(h_T, D_V)$

### loss functions (and derivatives)

- $l(h, D) = \sum_{i=1}^n (1 - \delta_{y_i, h(x_i)})$
- $\delta_{ij} = 1$  if  $i = j$ , 0 otherwise.
- asd