view_frames Result Recorded at time: 609.331 world Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (609.331 sec old) Most recent transform: 0.000 (609.331 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base_link table Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 50.207 Hz Most recent transform: 0.000 (609.331 sec old) Most recent transform: 609.324 (0.007 sec old) Buffer length: 0.000 sec Buffer length: 4.820 sec link_1 base Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 609.324 (0.007 sec old) Buffer length: 4.820 sec link_2 Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 609.324 (0.007 sec old) Buffer length: 4.820 sec link_3 Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 609.324 (0.007 sec old) Buffer length: 4.820 sec link_4 Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 609.324 (0.007 sec old) Buffer length: 4.820 sec link_5 Broadcaster: /robot_state_publisher Average rate: 50.207 Hz Most recent transform: 609.324 (0.007 sec old) Buffer length: 4.820 sec link_6 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (609.331 sec old) Buffer length: 0.000 sec flange Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (609.331 sec old) Buffer length: 0.000 sec tool0 Broadcaster: /robot_state_publisher Broadcaster: /arm_camera_to_flange Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (609.331 sec old) | Most recent transform: 0.000 (609.331 sec old) Most recent transform: 0.000 (609.331 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec camera_color_optical_frame camera_bottom_screw_frame eff_frame Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (609.331 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec laser_origin sensors_assembly quelltech_sensor_optical_frame camera_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (609.331 sec old) Buffer length: 0.000 sec camera_depth_frame Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (609.331 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec camera_color_frame camera_depth_optical_frame camera_left_ir_frame camera_right_ir_frame Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (609.331 sec old) Most recent transform: 0.000 (609.331 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_right_ir_optical_frame camera_left_ir_optical_frame