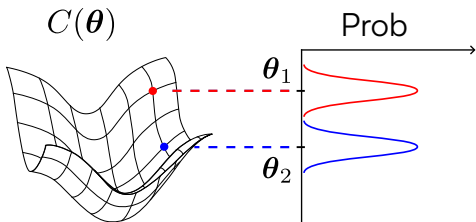
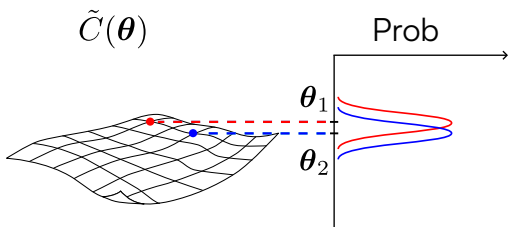


(a) Noiseless cost landscape



(b) Noisy cost landscape



(c) Error-mitigated cost landscape

