

CS 300: Advanced Computer Graphics I

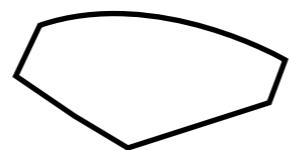
Pushpak Karnick

Lecture 23

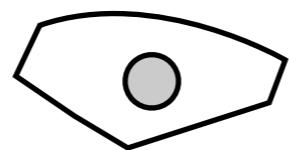
Global Illumination & Ambient Occlusion

Introduction to Global Illumination

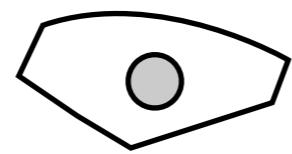
Illumination in Computer Graphics



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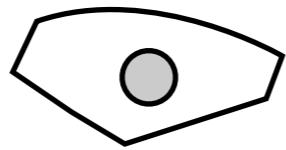
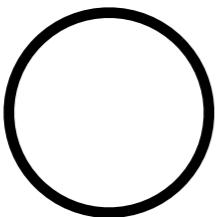


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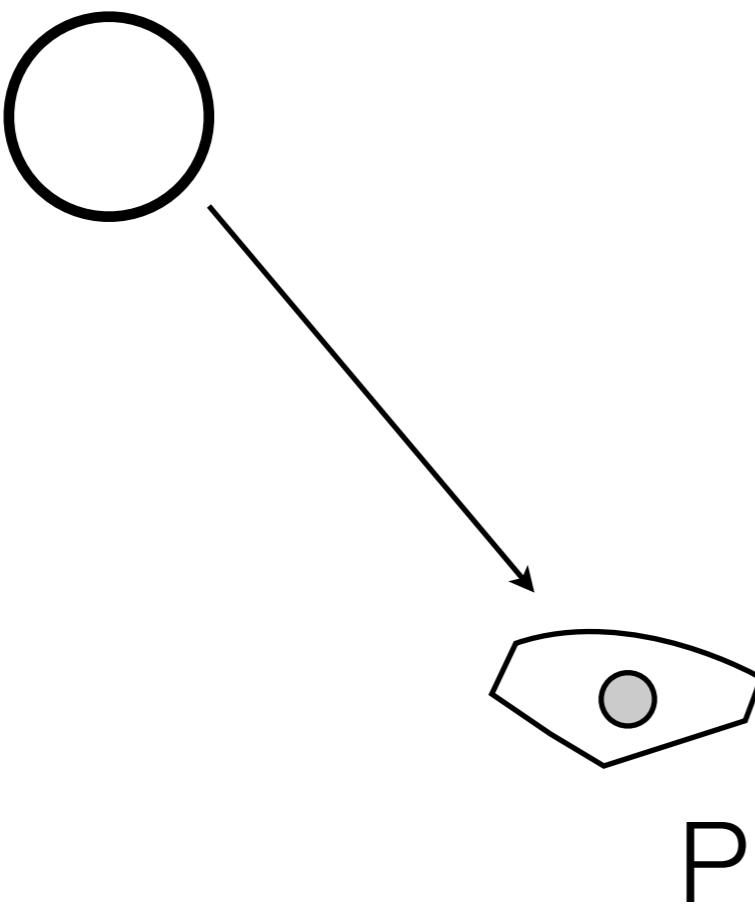
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Illumination in Computer Graphics

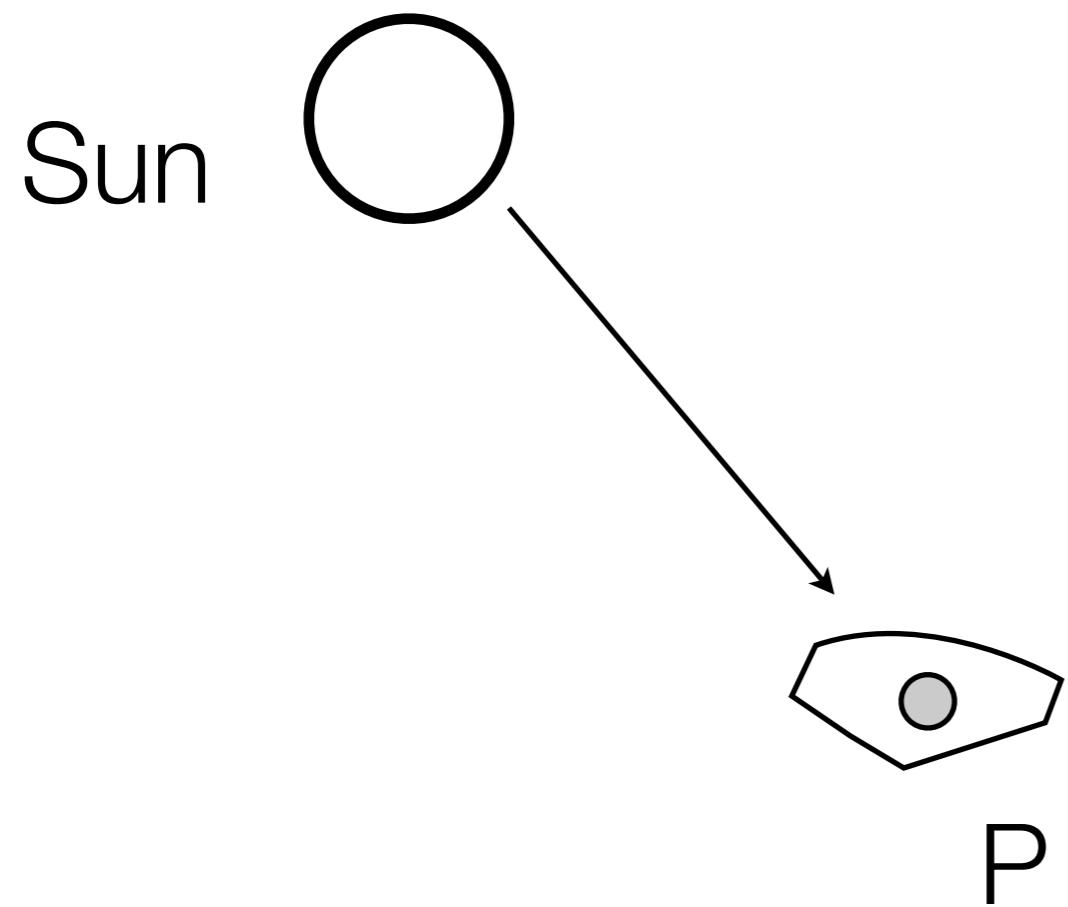


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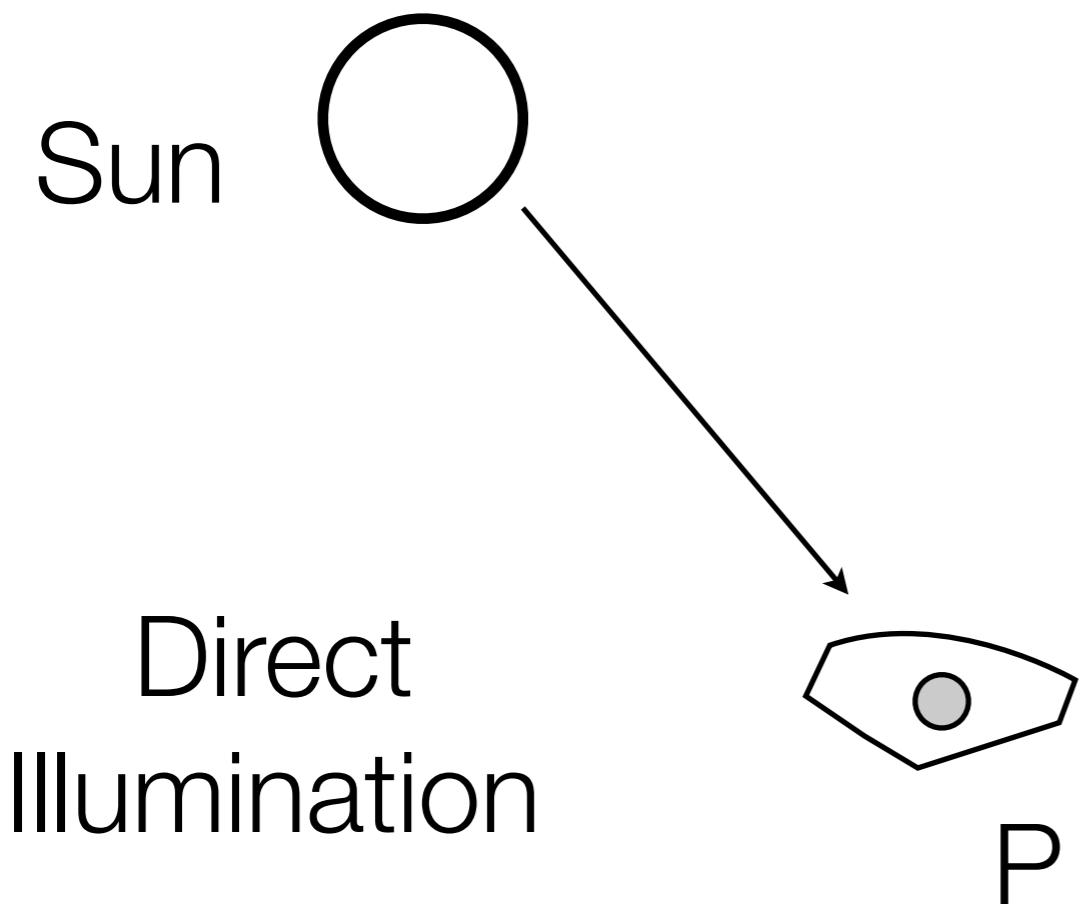
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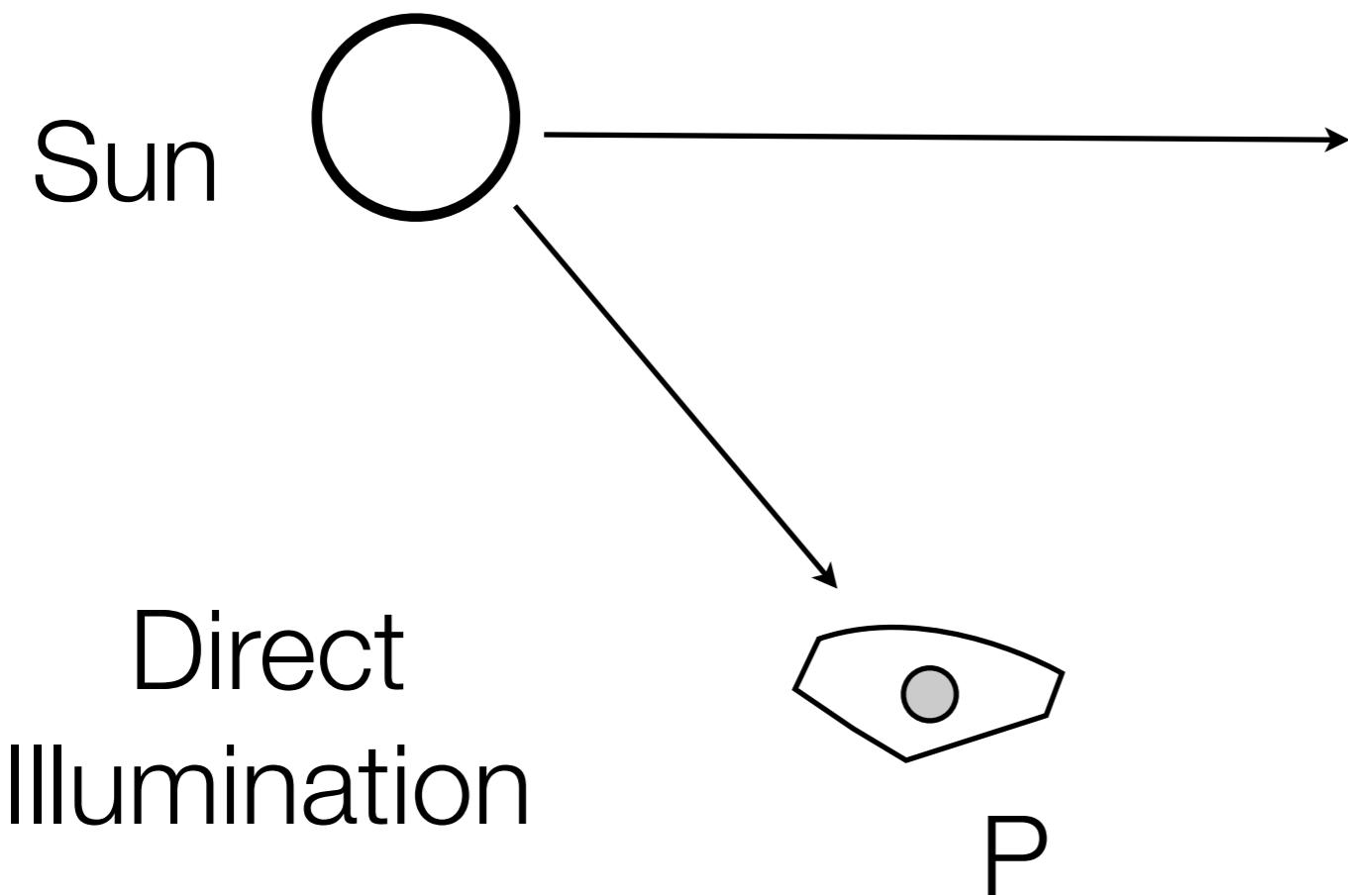
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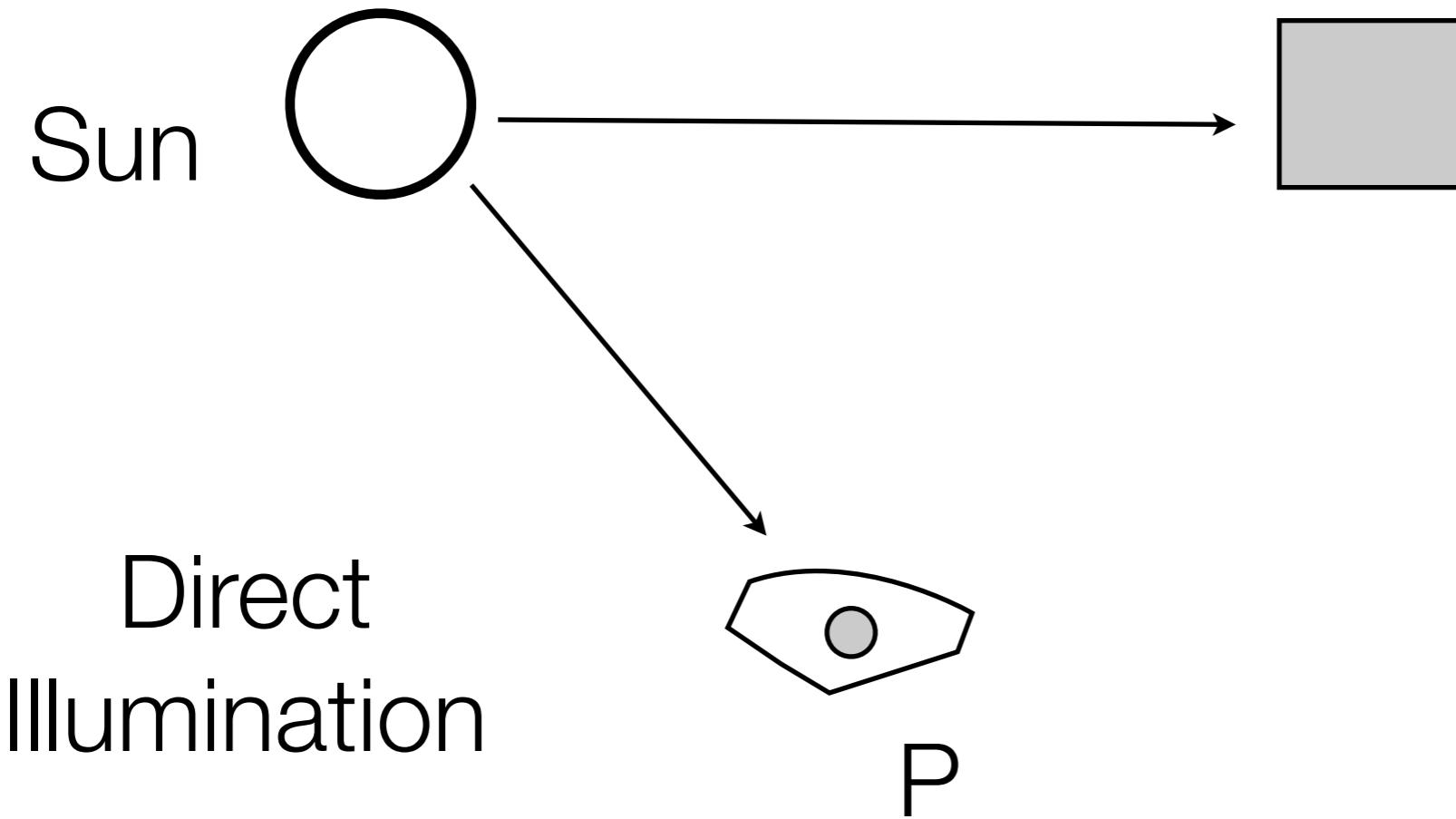
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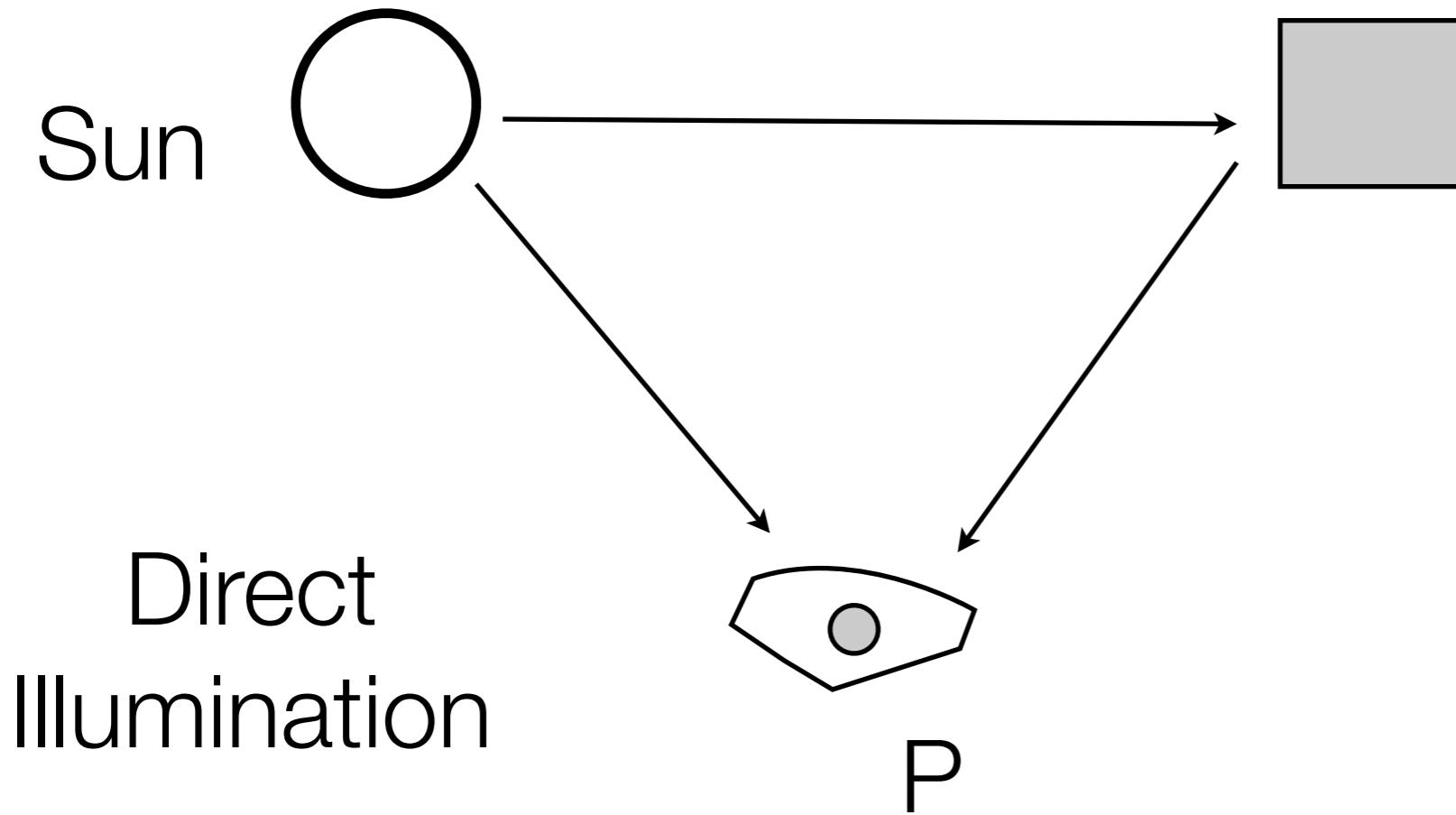
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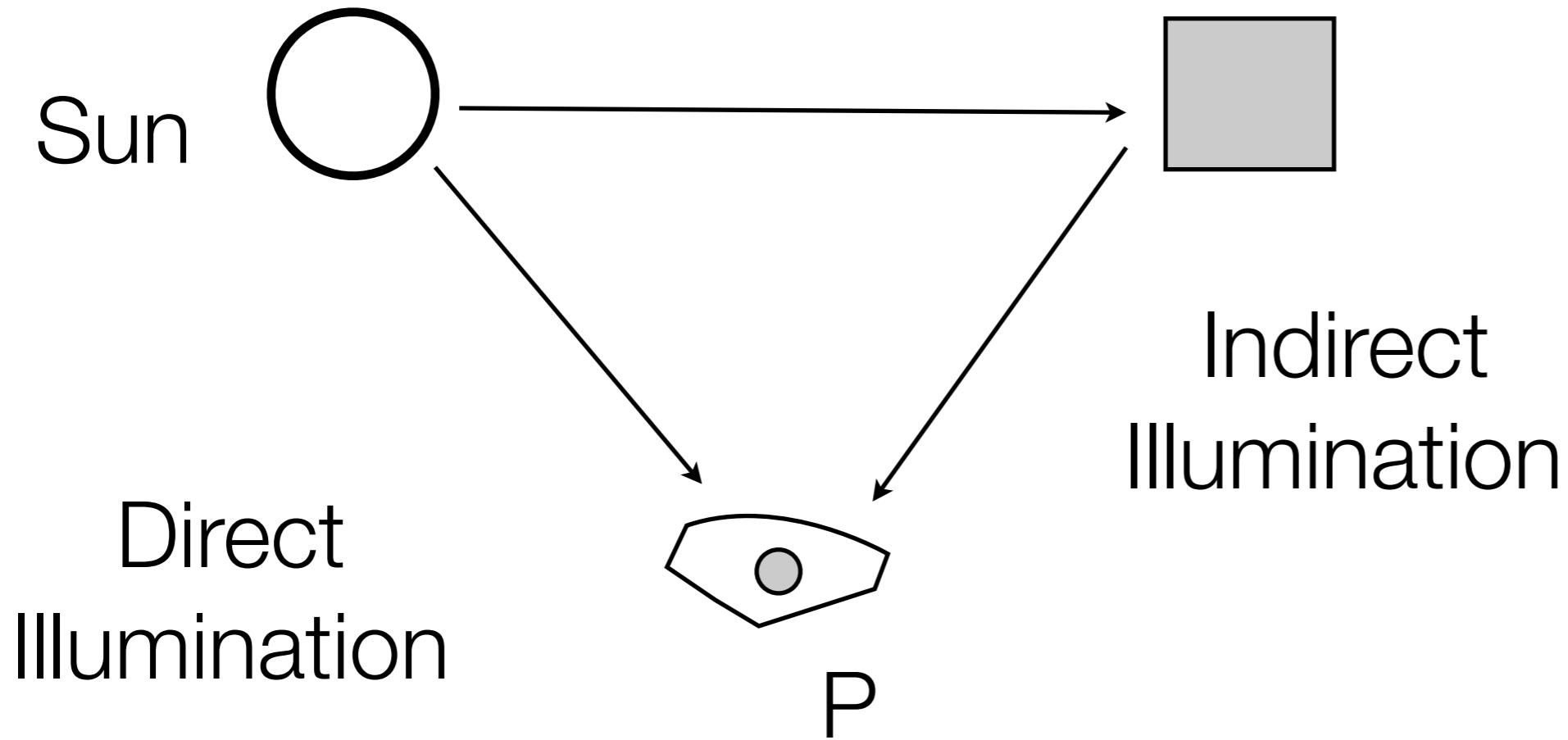
Illumination in Computer Graphics



Illumination in Computer Graphics



Illumination in Computer Graphics



“Global” Illumination

- What is “global”?
 - The light arrives at a point from all sources
 - The light-surface interaction is “global” in nature
- **Goal:** Make the renderings as photo-realistic as possible
- **Issues:**
 - How to track light as it travels through the scene?
 - What about objects that are not self-illuminated?

Side-effects of Global Illumination

- Object-light interaction is more natural
- No special case processing for shadow generation
 - Shadows are regions where there is “not enough” incident illumination available
- Vigorous research problem in its own right



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Models of Global Illumination

Mathematical Model

- Model proposed by Kajiya (1986)
 - “... to provide a unified context for viewing rendering algorithms as more or less accurate approximations to the solutions for a single equation.”
- Completely general mathematical statement
- Not tied down to any particular assumption about the light transport behavior

Kajiya's Equation

$$I(x, x') = g(x, x')[\xi(x, x') + \int \rho(x, x', x'') I(x', x'') dx'']$$

Kajiya's Equation

$$I(x, x') = g(x, x')[\xi(x, x') + \int \rho(x, x', x'') I(x', x'') dx'']$$

$I(x, x')$: transport intensity or the intensity of light passing from point x' to point x

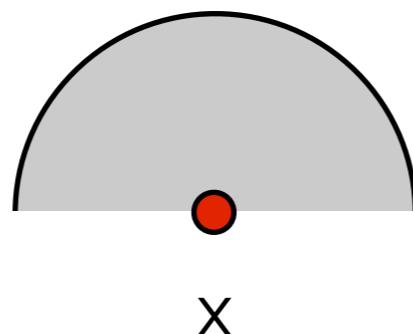
$g(x, x')$: visibility function between x and x' . If x and x' cannot ‘see’ each other, then this value is zero, else g varies as the square of the distance between them.

$\xi(x, x')$: the transfer emittance from x' to x related to any self-emitted light by x' towards x

$\rho(x, x', x'')$: is the scattering term wrt. direction x' and x'' . It is the intensity of the energy scattered towards x from the point on surface x' arriving from point x'' . Also known as the “unoccluded three-point transport reflectance.”

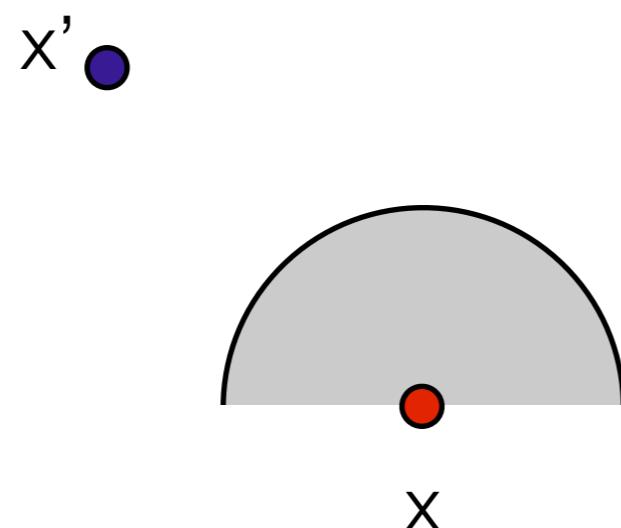
Integral Term in Kajiya's Equation

- Integral is defined over all points on all surfaces in the scene
- Equivalently - all points surrounding point x
 - If we consider only front-faces of polygons, the region simplifies to an hemisphere around x



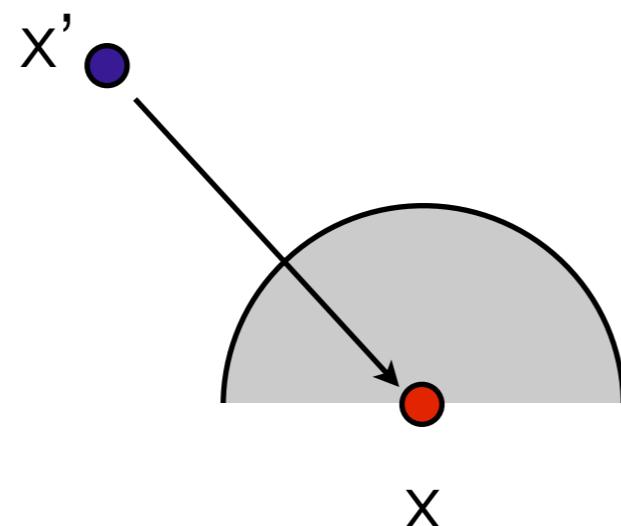
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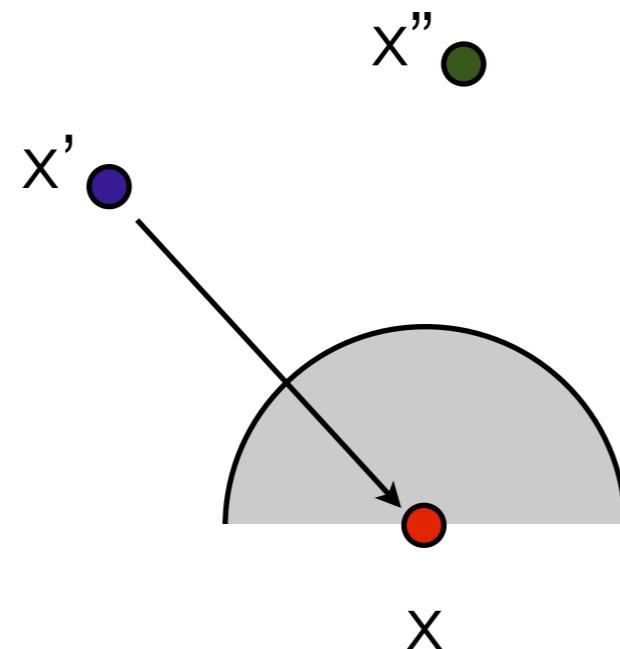
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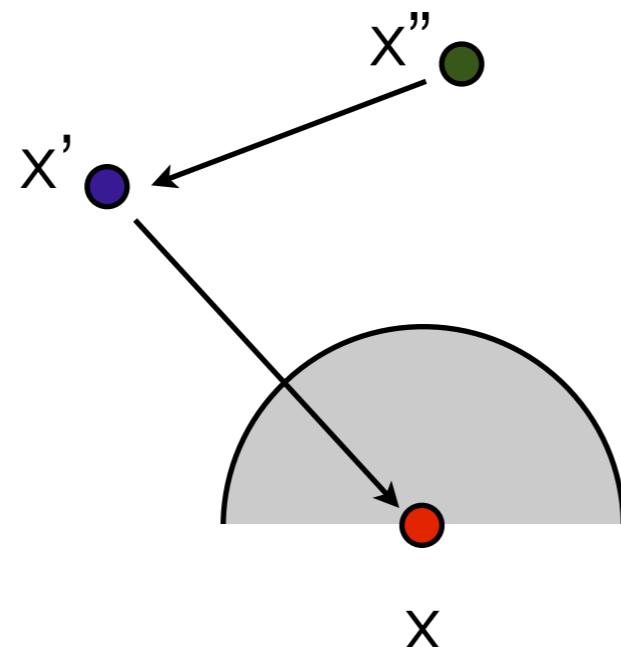
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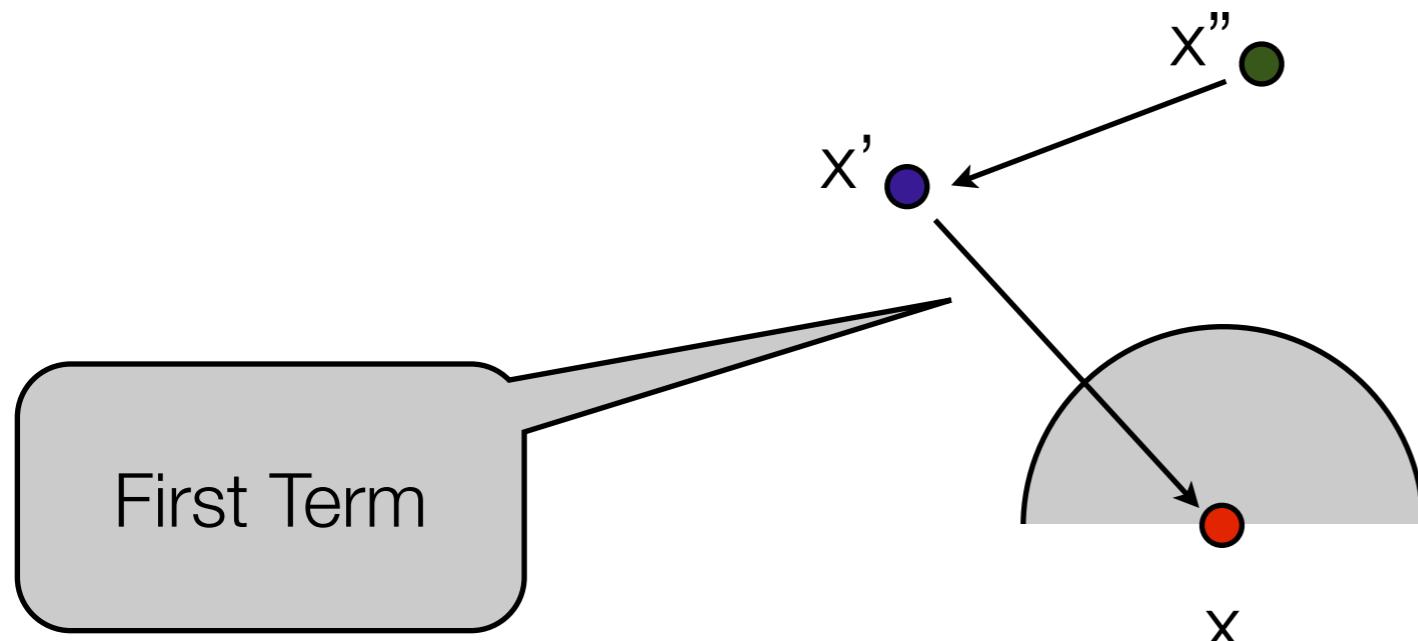
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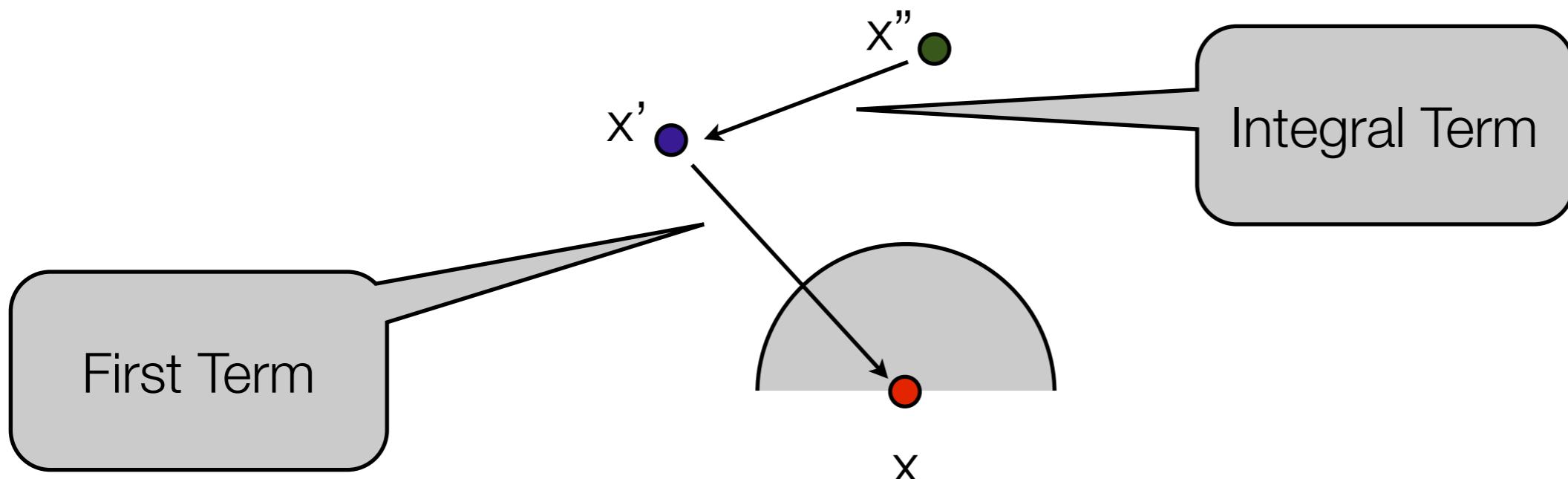
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 - View-dependent representation - can help in reducing the complexity of the solution

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- The equation is dependent on the location of point x in the scene
 - In fact, point x is every point in the scene !
 - View-dependent representation - can help in reducing the complexity of the solution
- Recursive equation
 - Find $I(x',x'')$ to calculate $I(x,x')$
 - Leads to an elegant **path tracing** algorithm for light transport

Implementing Kajiya's Equation

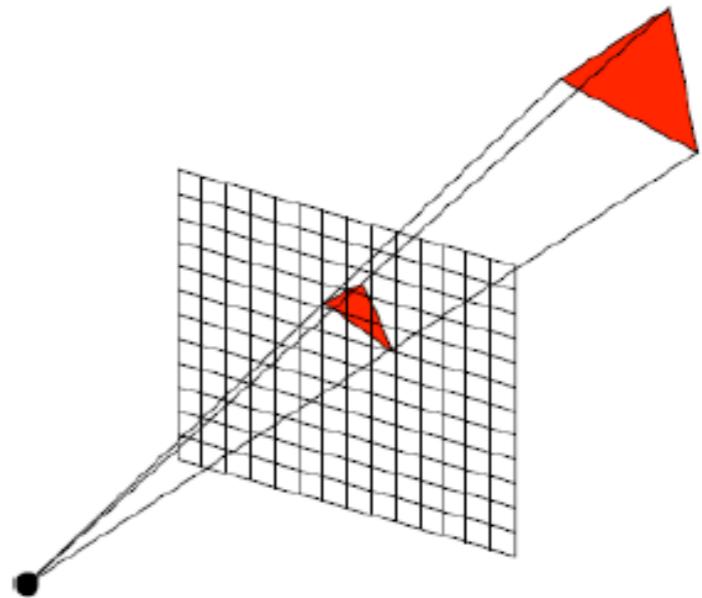
- **Rendering** : visualizing 3D data on 2D screen
- Two main approaches
 - Projective Methods
 - Path Tracing Methods

Projective Vs Ray Tracing

Projective methods:

Object-order rendering, i.e.

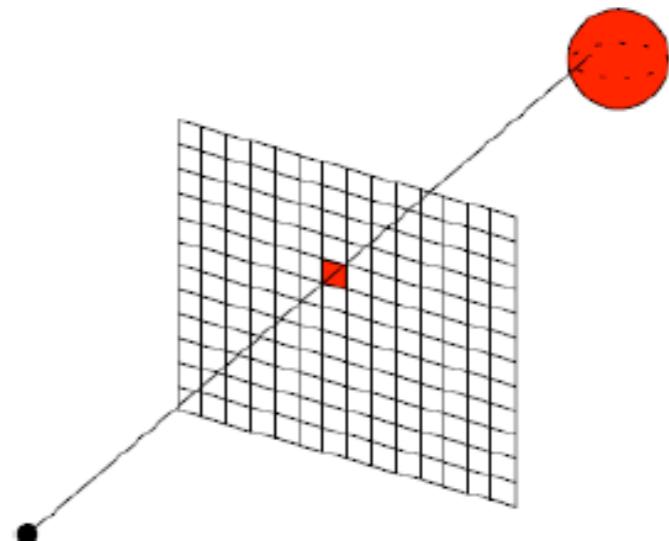
- For each object ...
- ... find and update all pixels that it influences



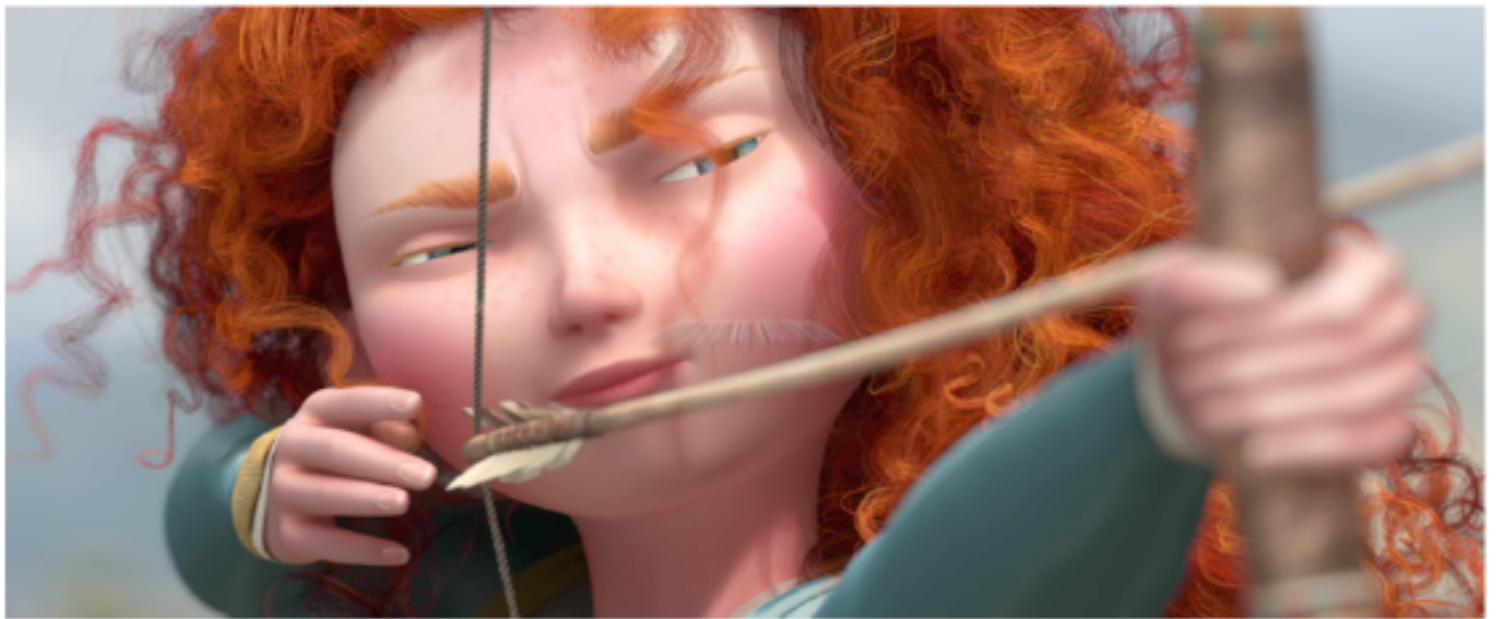
Ray tracing:

Image-order rendering, i.e.

- For each pixel ...
- ... find all objects that influence it and update it accordingly



Examples : Ray Traced Rendering



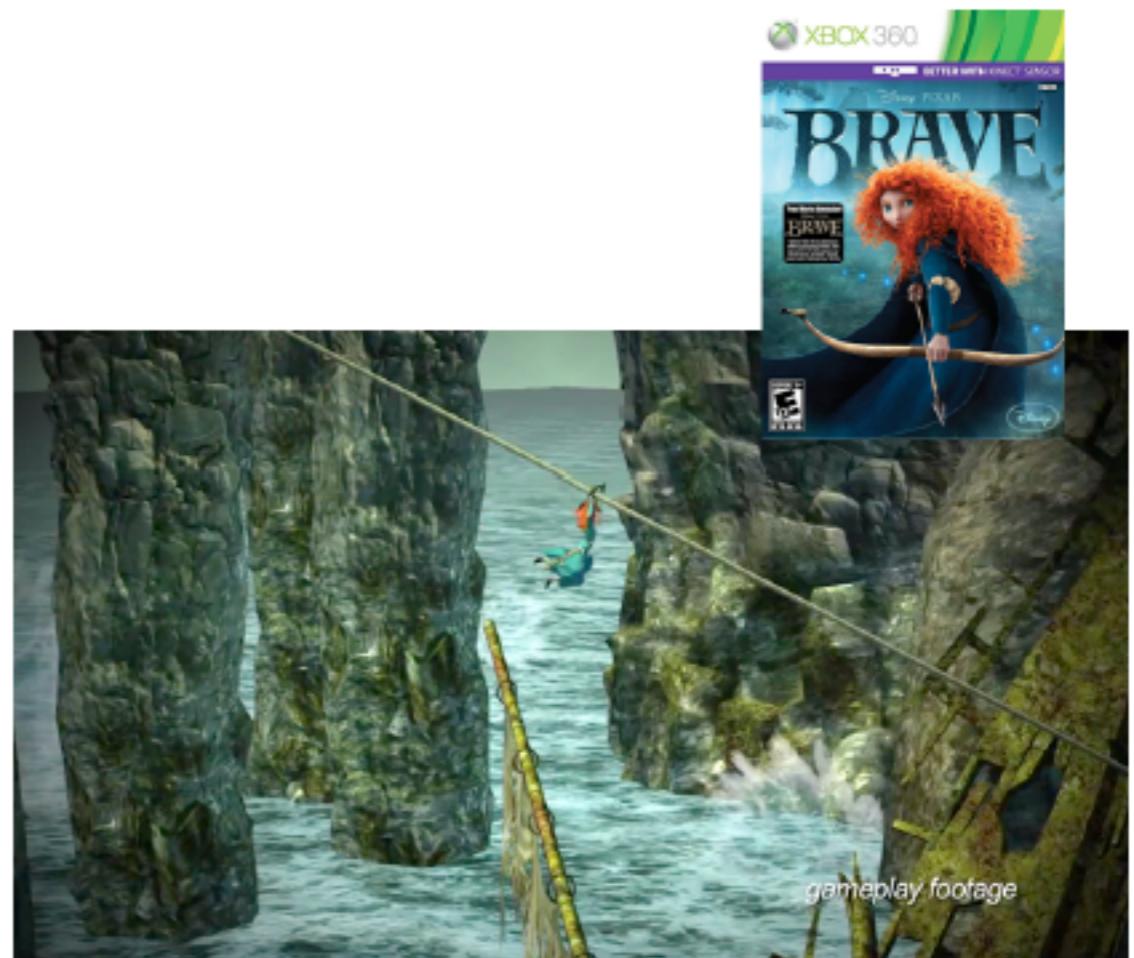
Images courtesy Wolfgang Hürst, Utrecht University

Example : (Real-time) Projected Rendering



Images courtesy Wolfgang Hürst, Utrecht University

Examples : Comparison



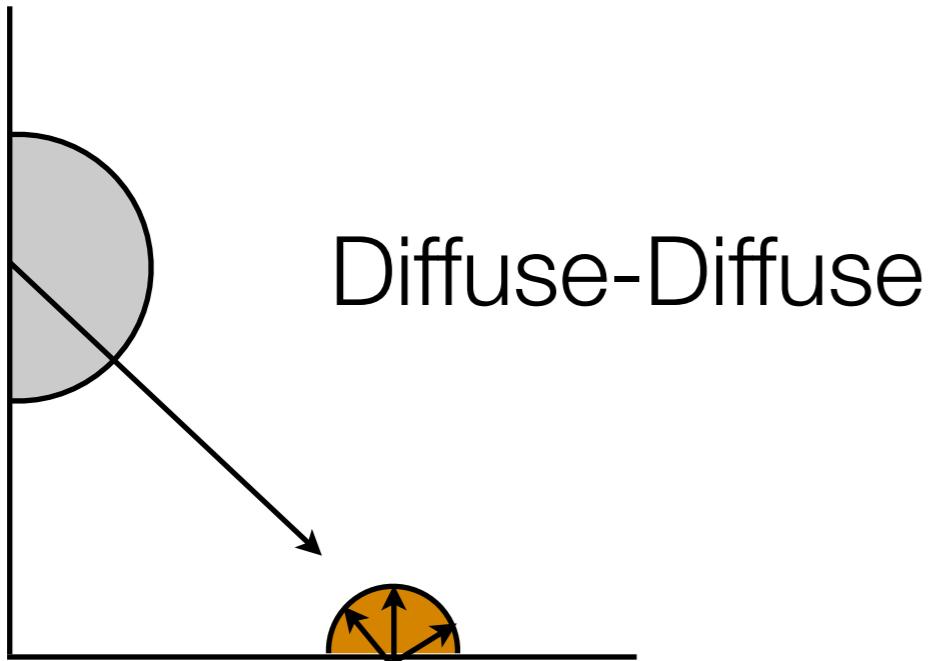
Images courtesy Wolfgang Hürst, Utrecht University

Surface-Light Transport Model

- Categorized based on the surface to surface interactions
- Non-mathematical organization, enables easy comparison between the various algorithms
- One surface (or point) is considered the “source” and another is the “sensor”
- What types of light transport occurs between the source and the sensor
 - Diffuse light - isotropic - same in all directions
 - Specular light - anisotropic - directional behavior

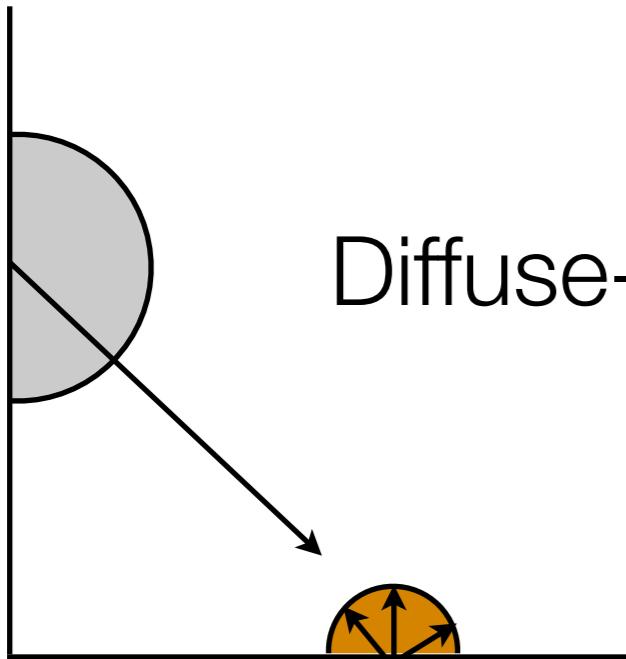
Light Transport Mechanisms

Light Transport Mechanisms

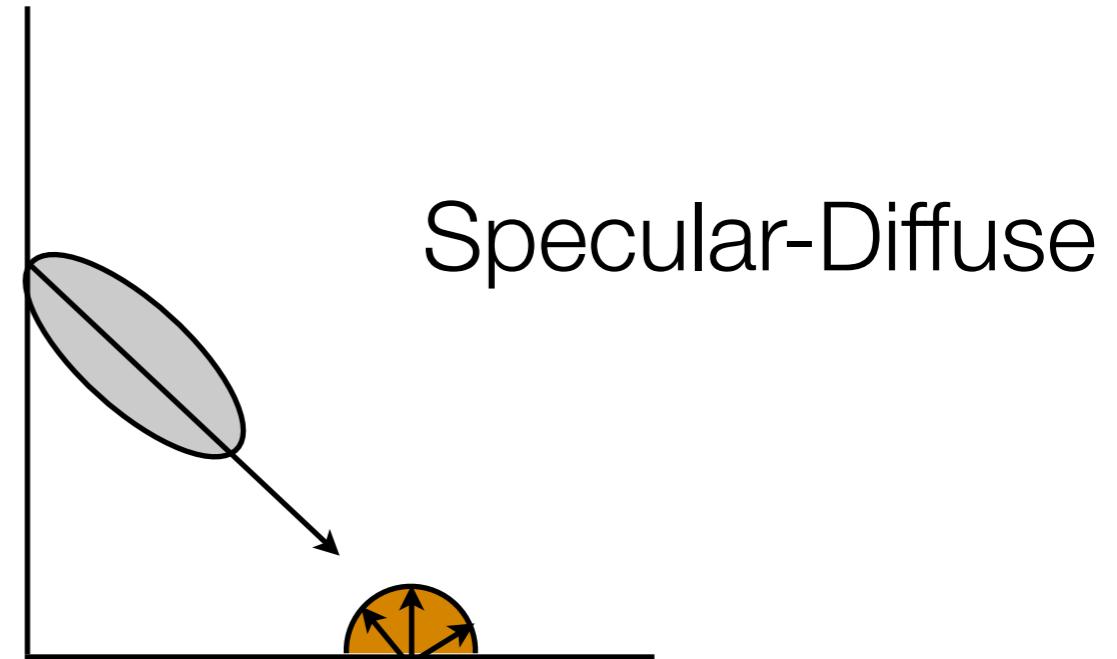


Diffuse-Diffuse

Light Transport Mechanisms

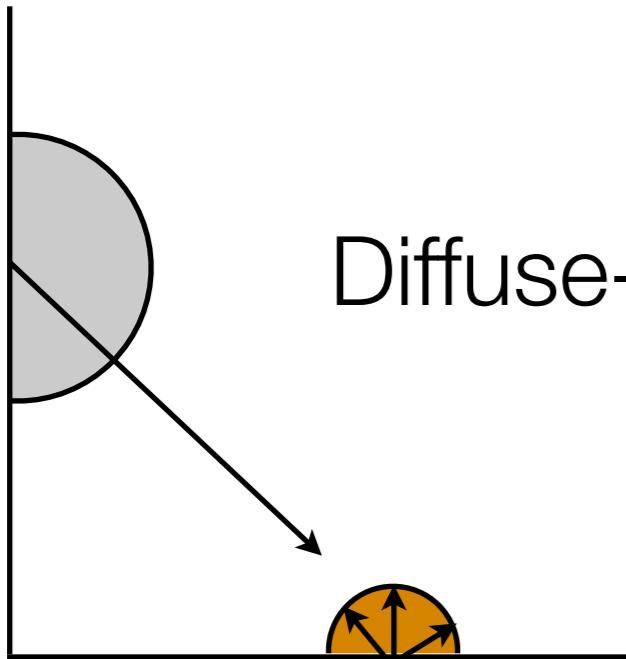


Diffuse-Diffuse

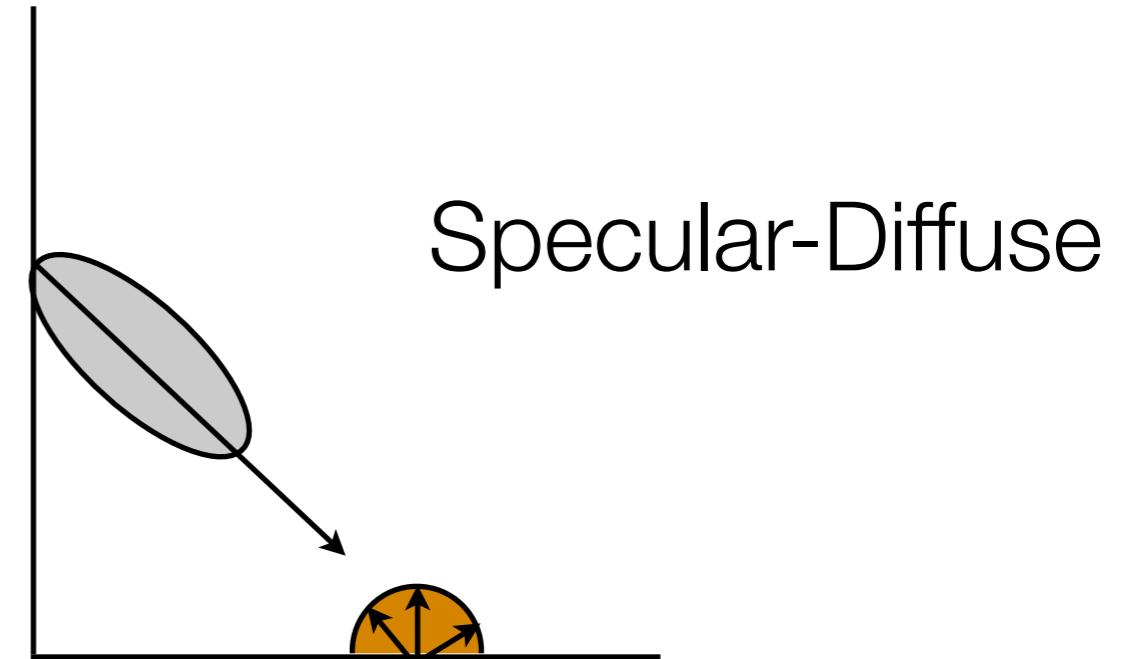


Specular-Diffuse

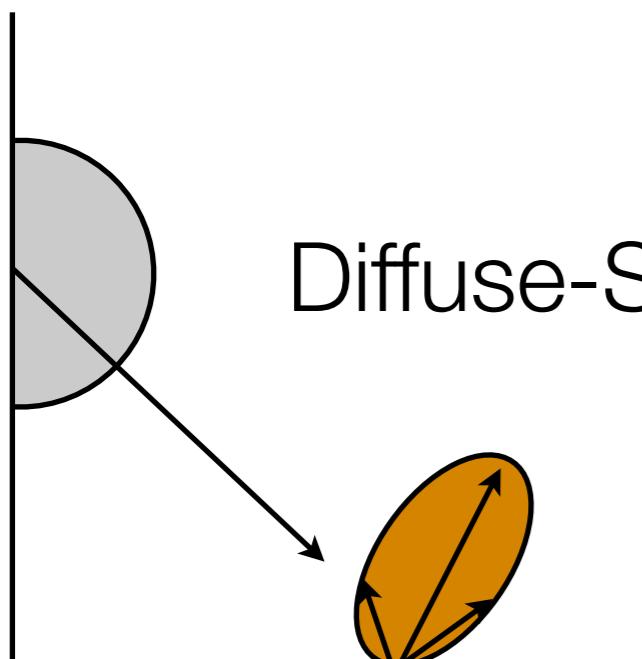
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Diffuse-Diffuse

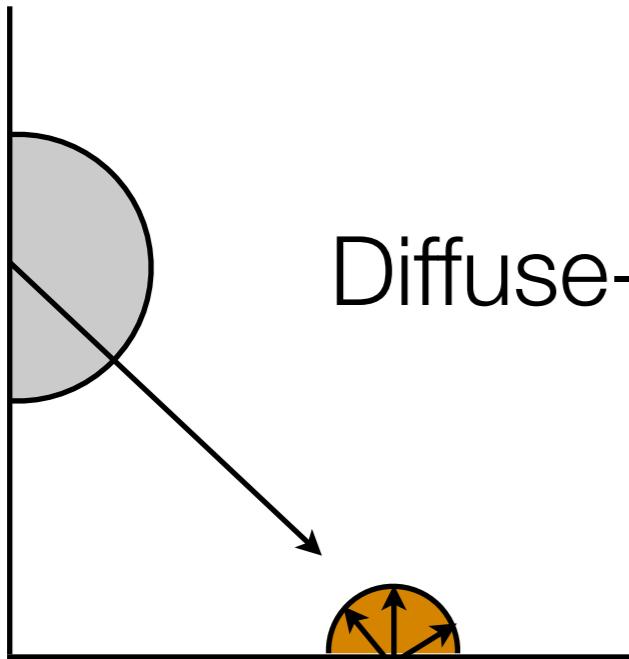


Specular-Diffuse

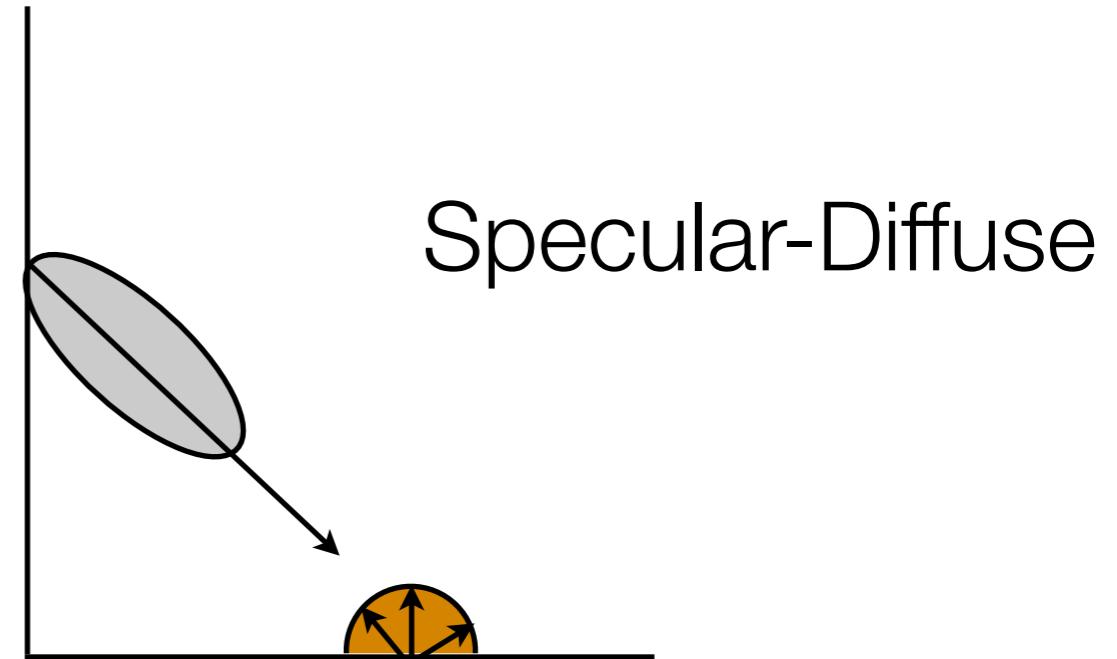


Diffuse-Specular

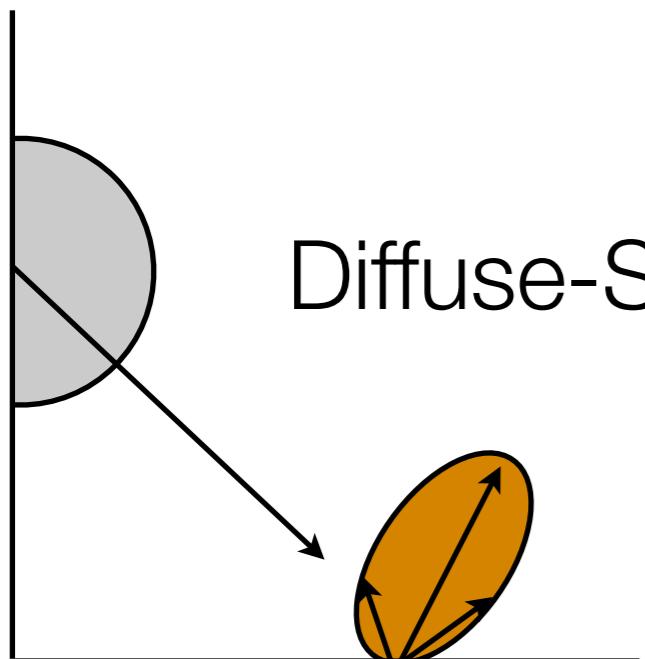
Light Transport Mechanisms



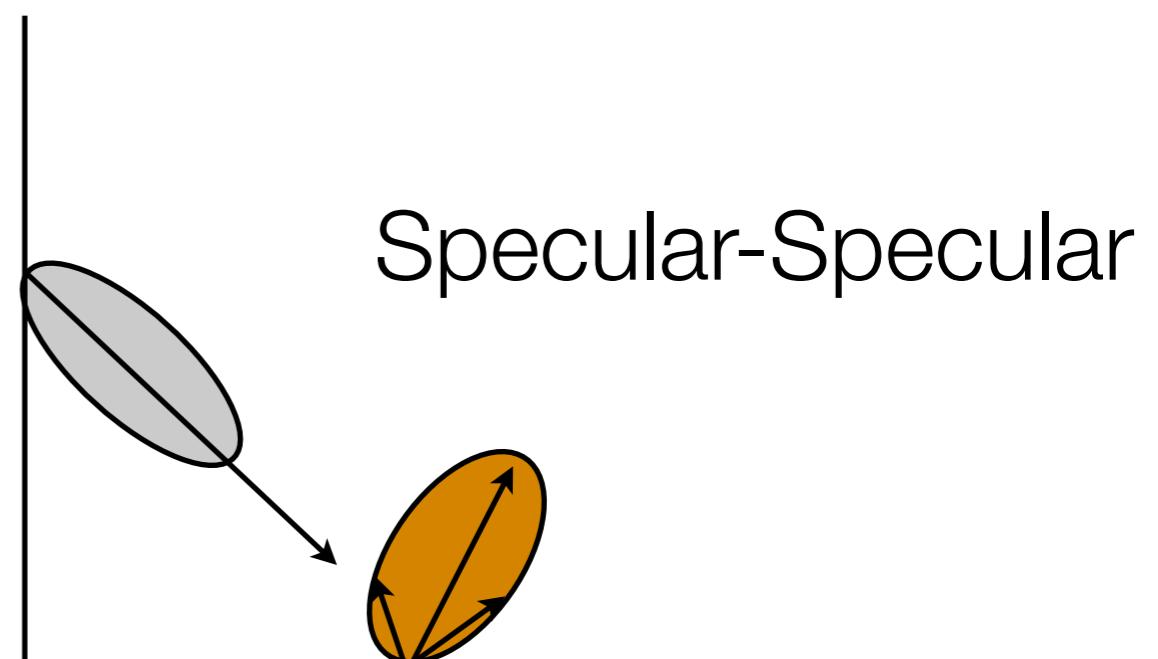
Diffuse-Diffuse



Specular-Diffuse



Diffuse-Specular



Specular-Specular

Methods to Solve Light Transport Models

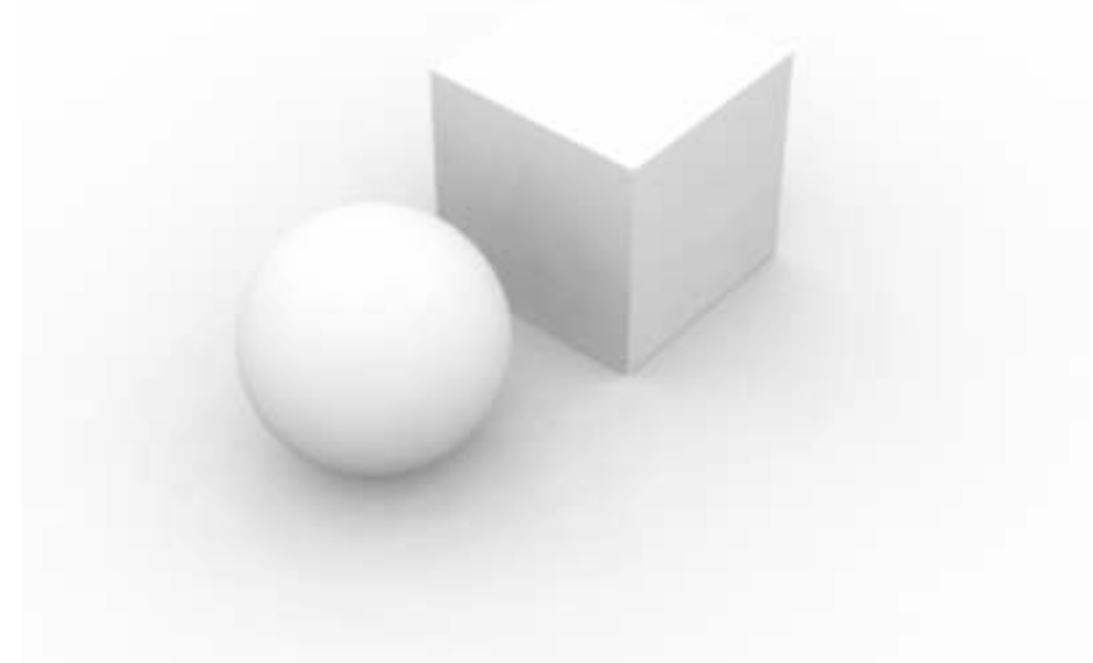
- Diffuse - Diffuse
 - Only diffuse surfaces exist in the scene (Matte finish)
 - Radiosity methods used to “solve” for the equation
- Specular - Specular, Specular - Diffuse
 - Shiny surfaces with reflective properties
 - Ray-tracing methods

Simplifying the Light Contribution

- Three components
 - Ambient
 - Diffuse
 - Specular
- Ambient component is assumed to be a constant value in most local illumination models
- Not observed in practice

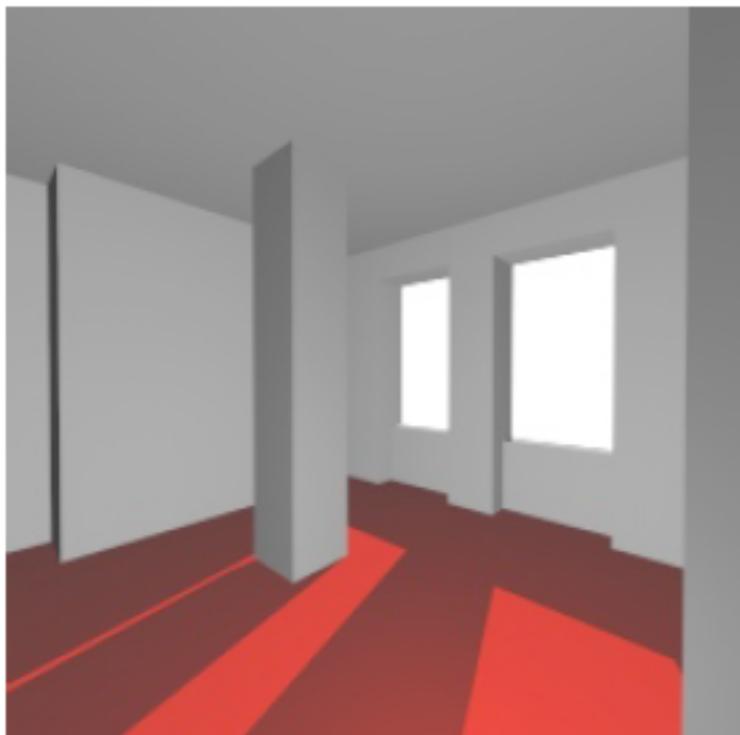
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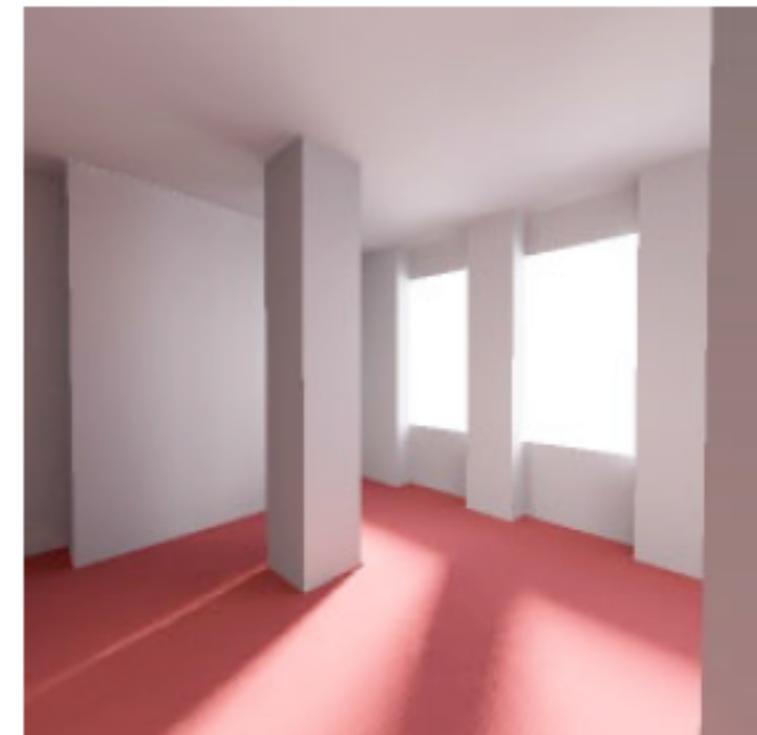


Global Vs Local Diffuse-Diffuse Interaction

Direct lighting



Global lighting



Dynamic Ambient Component

- Ambient term
 - The irradiance that reaches a point (x) as the summed contribution of the diffuse and specular emissions from all other points in the scene
 - General effect - occluded parts of the scene are darker than the exposed portions
 - Ambient occlusion (AO) computed by ray-tracing approaches
 - Very slow

Screen Space Ambient Occlusion

Motivation

- Accurate AO calculation is expensive
- Basic idea - Areas that are obscured by other objects are darker than those that are not
- Manipulation of intensity levels
- Can be approximated with screen space methods

Is SSAO necessary?



WITHOUT SSAO

WITH SSAO

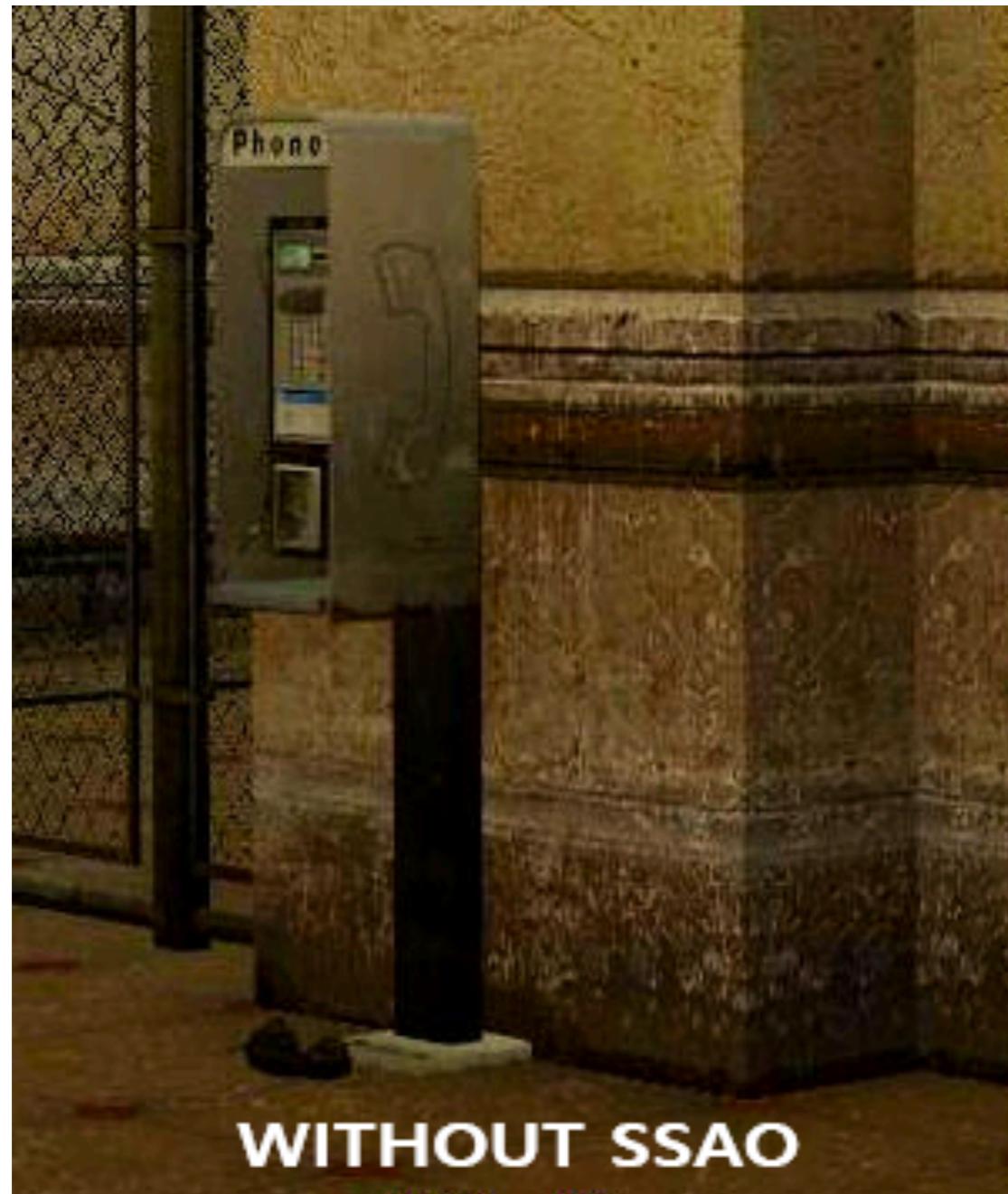
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Shadows

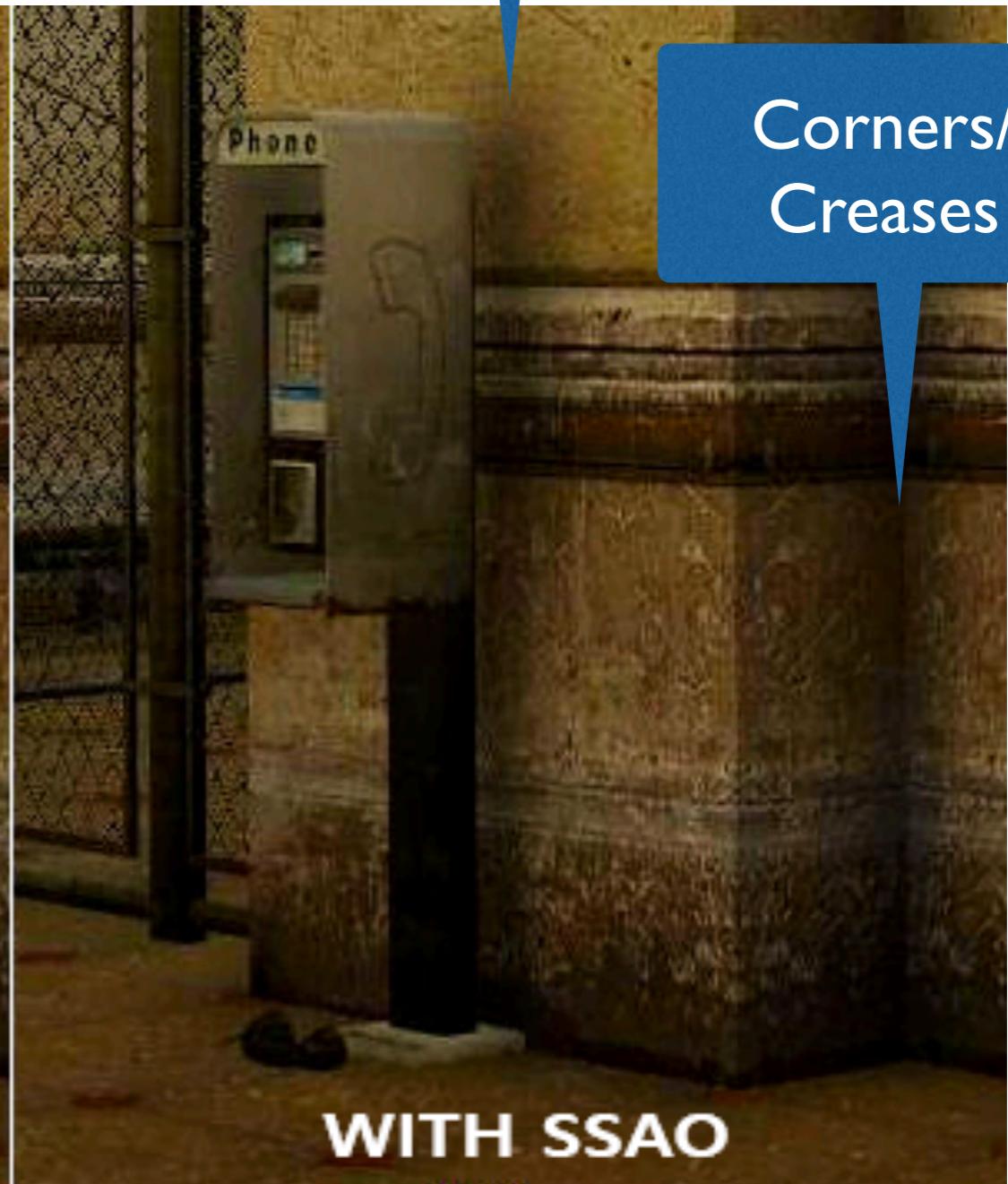


Is SSAO necessary?

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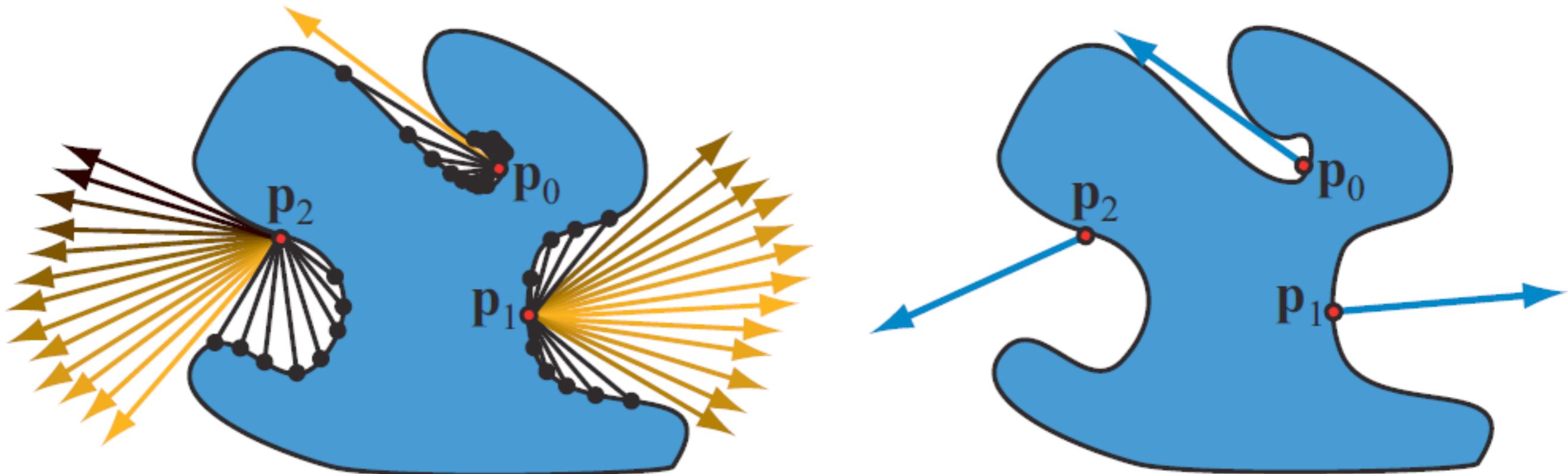
Corners/
Creases



Ambient Occlusion - Ray Cast Solution

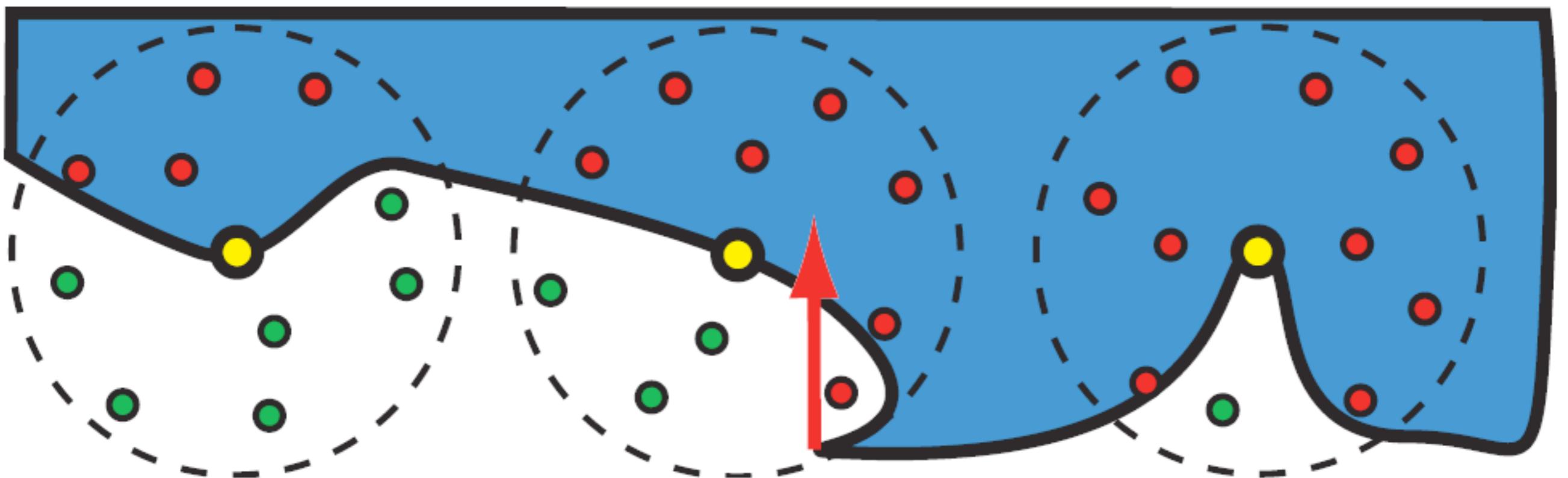
- For every point on the surface
 - Cast a set of rays in all directions surrounding the point
 - Count how many rays continue unobstructed towards the viewer
 - Can be replaced by a threshold distance
 - Use the proportion of obstructed rays as a measure of “occlusion” from surrounding surfaces

Computing Occlusion



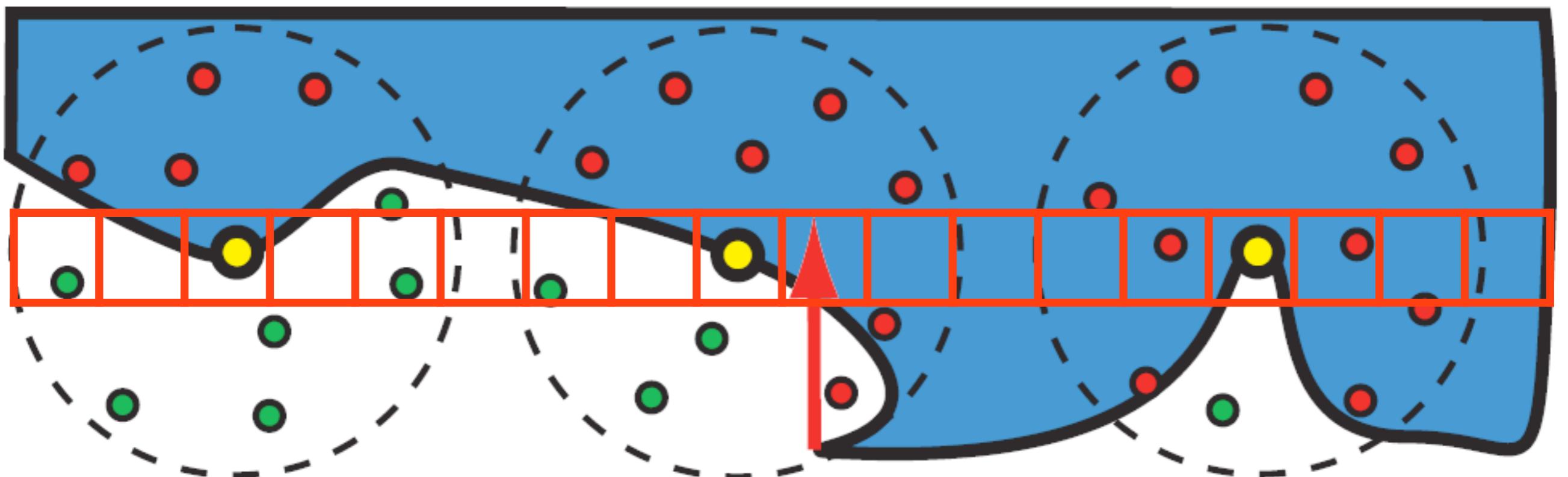
Screen Space Ambient Occlusion

Overall Idea



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 - More than 50% of the neighboring fragments are closer to the camera than the current fragment

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 - If more than 50% of the values are LESS than the current fragment depth value
 - More than 50% of the neighboring fragments are closer to the camera than the current fragment
 - The current fragment is probably in shadow region!

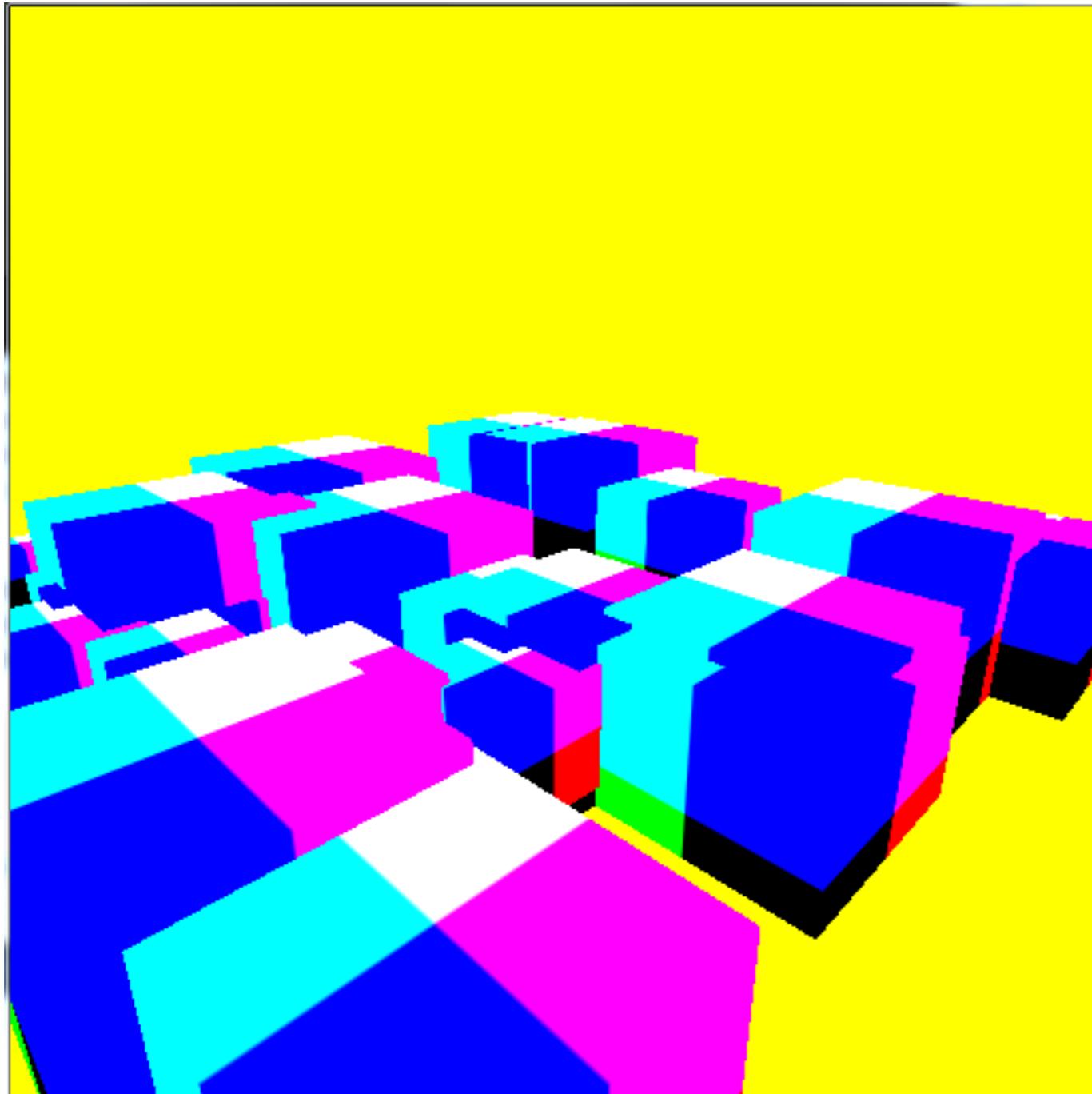
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 - More than 50% of the neighboring fragments are closer to the camera than the current fragment
 - The current fragment is probably in shadow region!
 - Compute a “blocking factor” to attenuate the light values

Algorithm

- Multi-pass implementation
- Needs render-to-texture functionality
- First pass
 - Render the 3D scene
- Subsequent passes
 - Render a fullscreen quad to process the fragments

Example Scene



3D Cubes

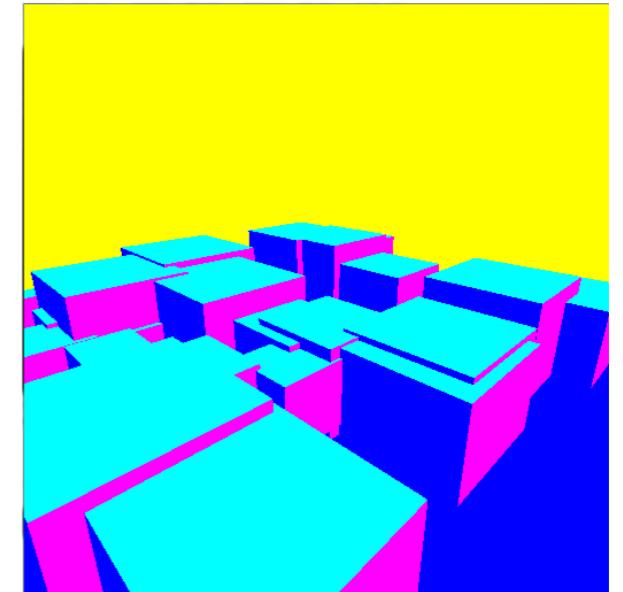
Color = local
coordinate values

Pass 1 (Fragment Shader)

- Inputs
 - Camera position
 - Eye space position
 - Eye space normals
 - Projection matrix
 - 7x7 matrix of random values

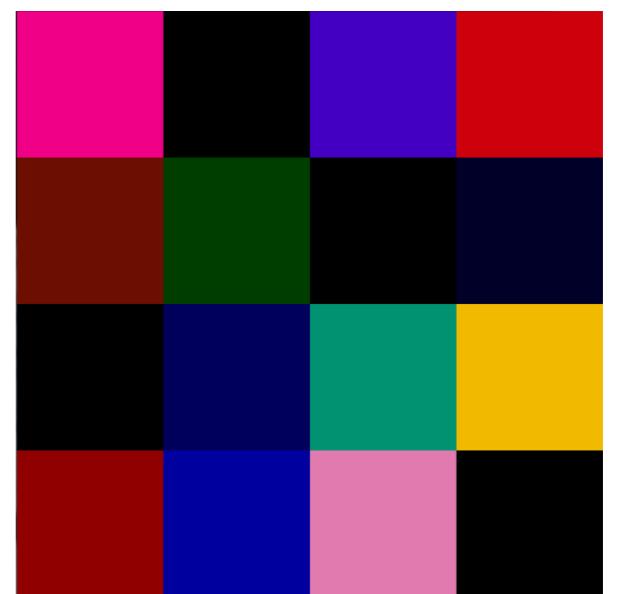
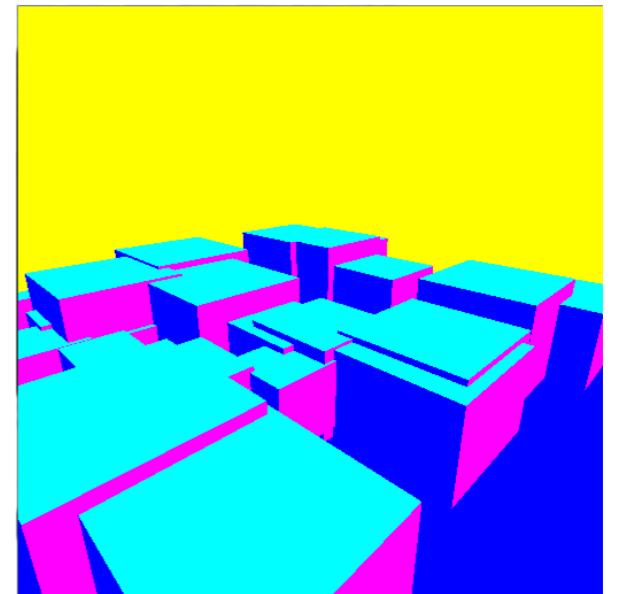
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Calculating the “Blocking Factor”

- Generate random offset vectors in a sphere, around the point under consideration
- Compare the depth values for the fragment and the neighbor at the random offset
- Calculate the blocking factor based on the depth comparison
- (In supplied code) blocking factor is calculated as a cumulative function of the z-depth difference between the point and its neighbors

GLSL Code Snippet

```
// for each sample
int count = 0;
for( int samplex = 0; samplex < 7; ++samplex )
{
    for( int sampley = 0; sampley < 7; ++ sampley )
    {
        vec2 index = vec2( samplex, sampley );
        vec4 rand_lookup = textureRect( rand_values, index );
        vec4 rotated_vector = rotationMatrix * rand_lookup;
        vec4 offset = rotated_vector * radius;
        newPos3d = pos3d + offset;

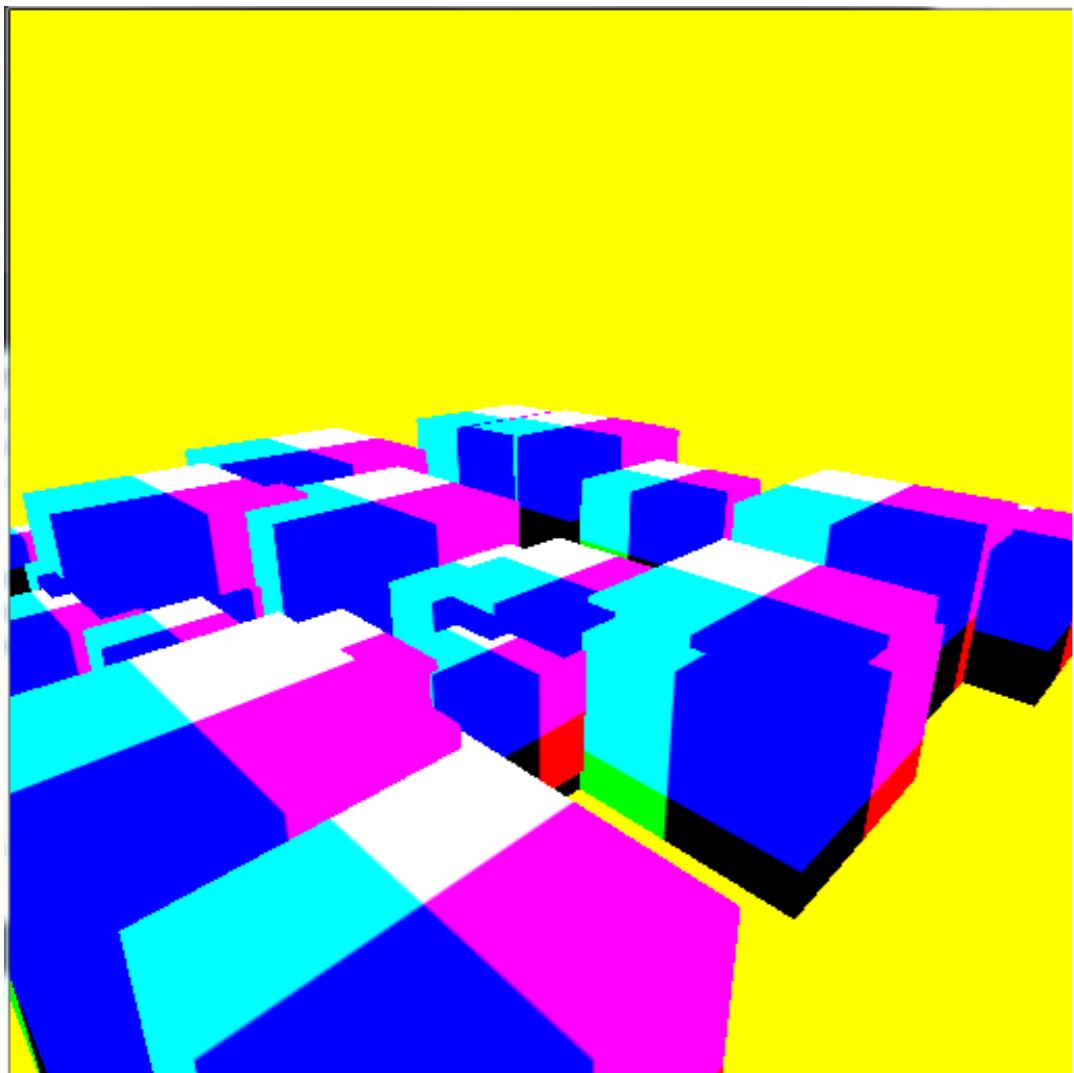
        vec4 projectedPoint = projectionMatrix * vec4(newPos3d.x, newPos3d.y, newPos3d.z, 1.0);
        vec2 screenPoint = projectedPoint.xy / projectedPoint.w;

        vec2 depth_lookup = (screenPoint.xy*0.5) + vec2(0.5, 0.5);
        vec3 neighbor_lookup = textureRect( eyeSpacePosition, depth_lookup.xy*512 ).xyz;
        neighbor_lookup.z = -1.0/neighbor_lookup.z;

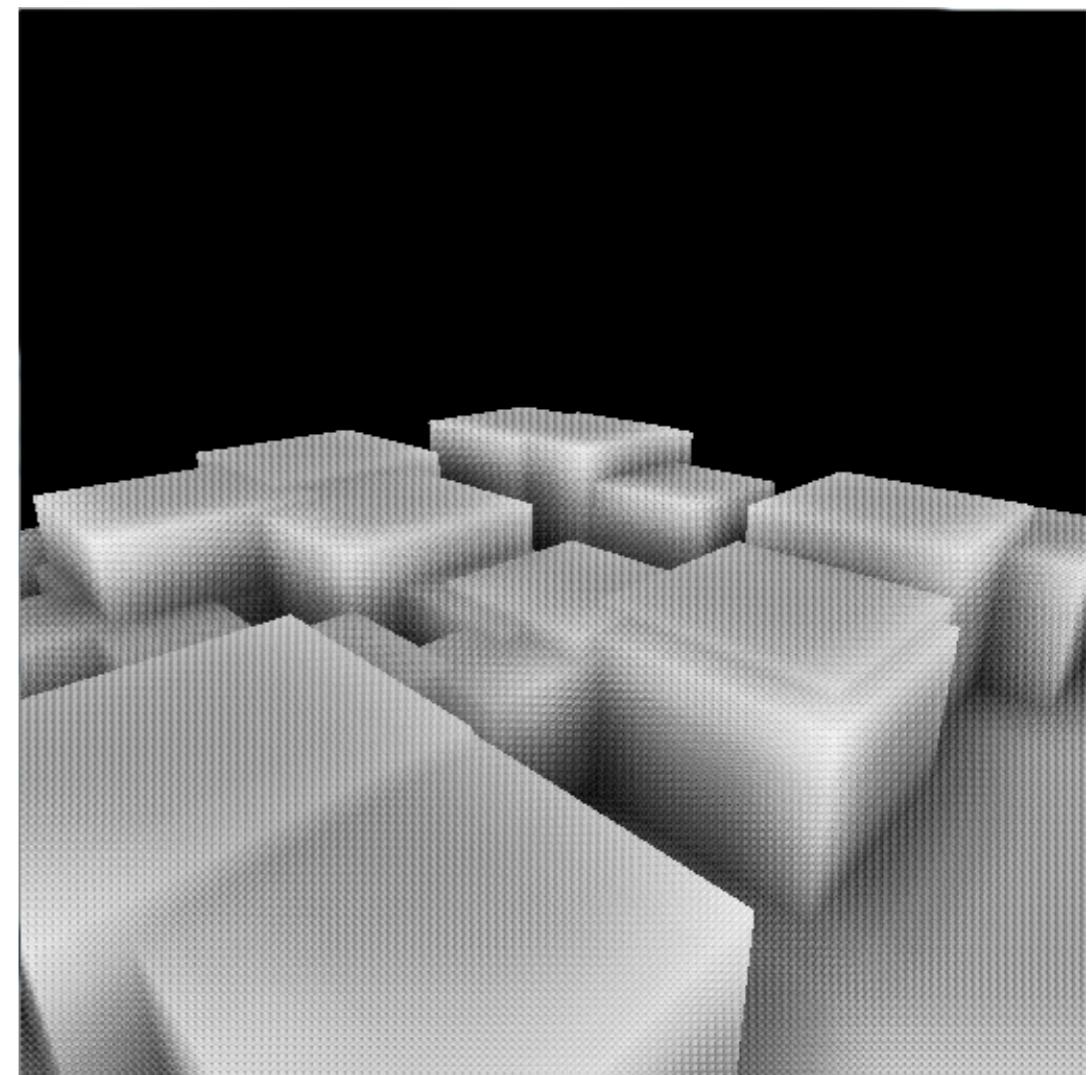
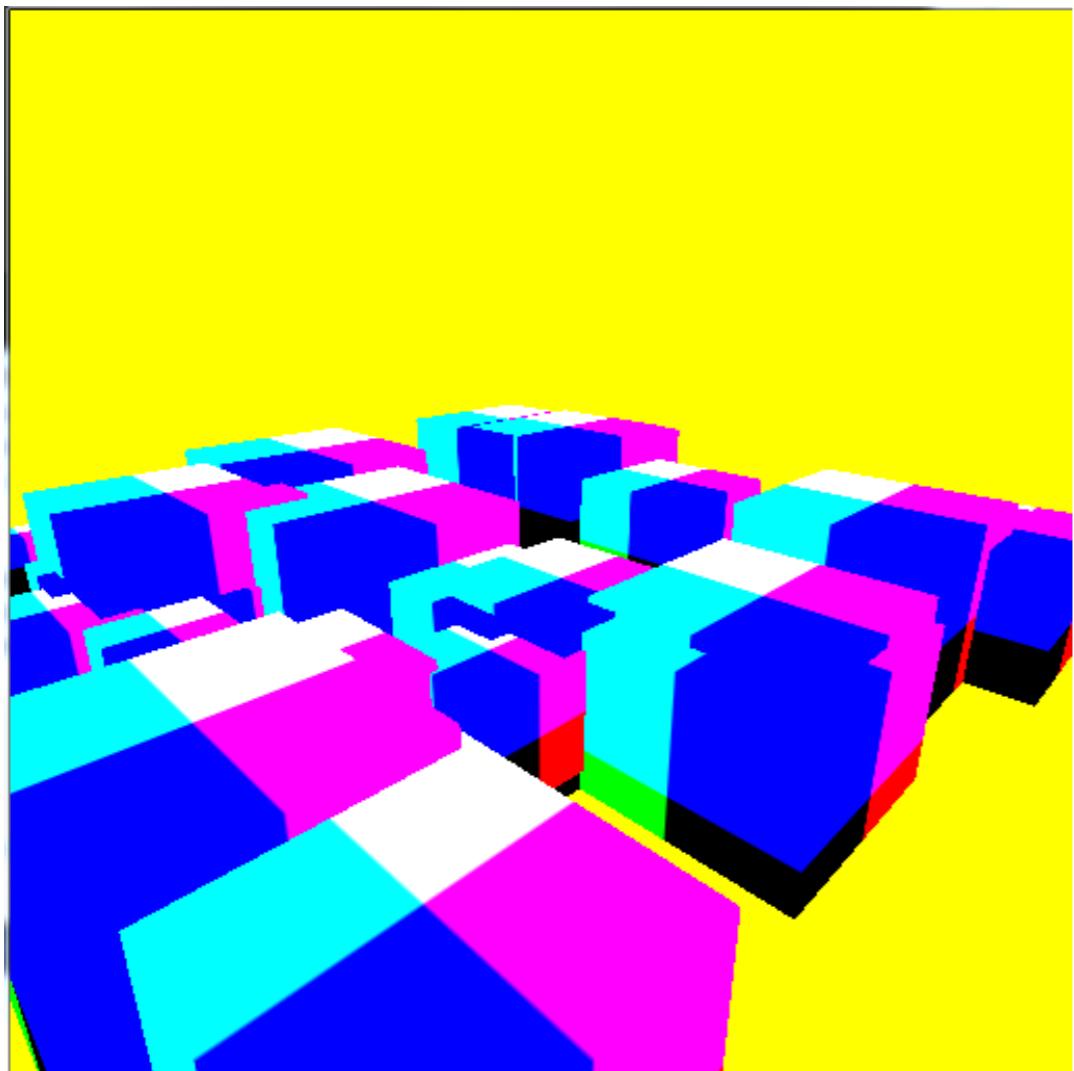
        float z_diff = 50.0 * max( 0.0, newPos3d.z - neighbor_lookup.z );
        block_factor += 1.0 / ( 1.0 + (z_diff*z_diff) );
    }
}

block_factor /= 49;
block_factor = 1.0 - block_factor;
```

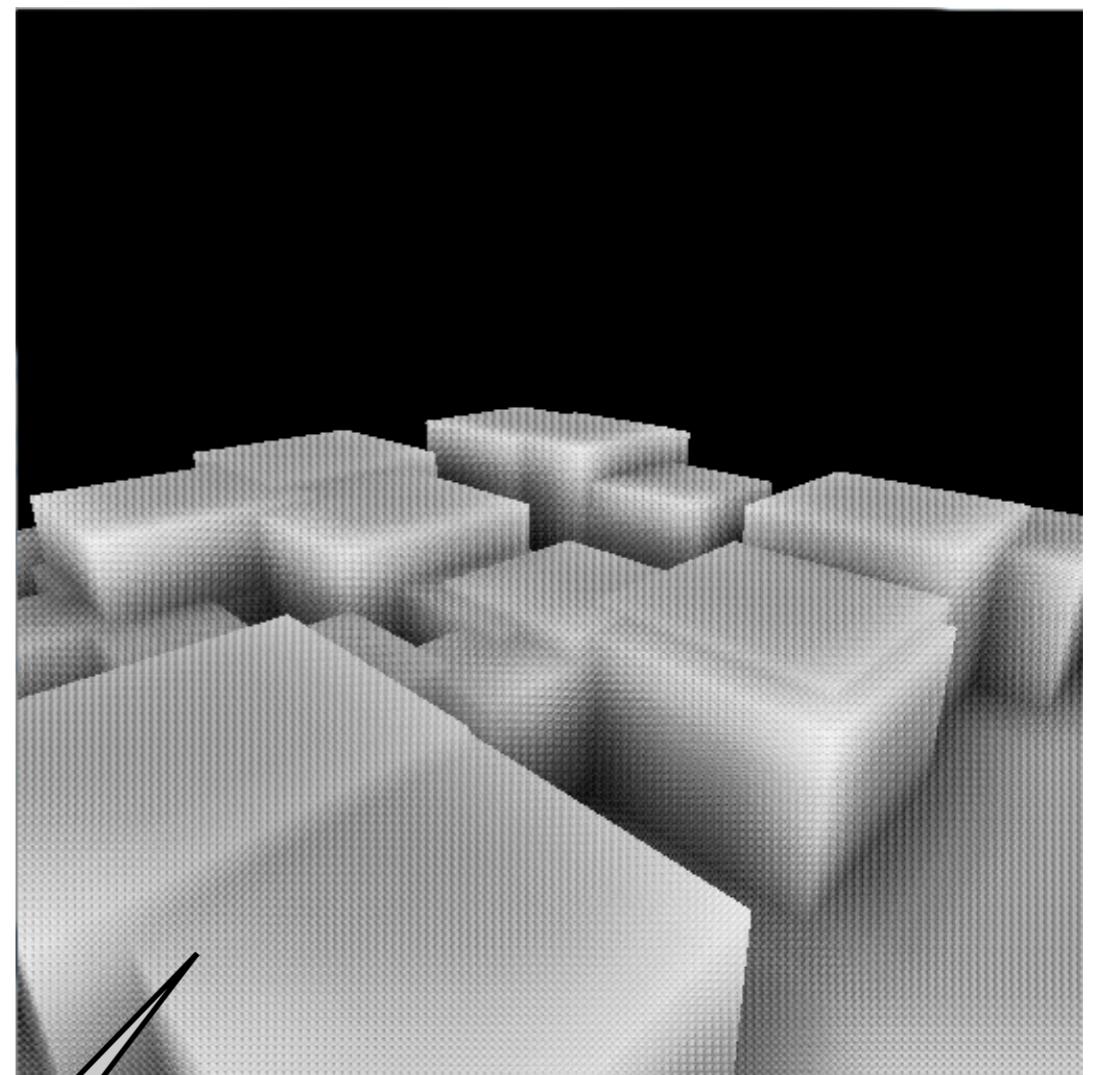
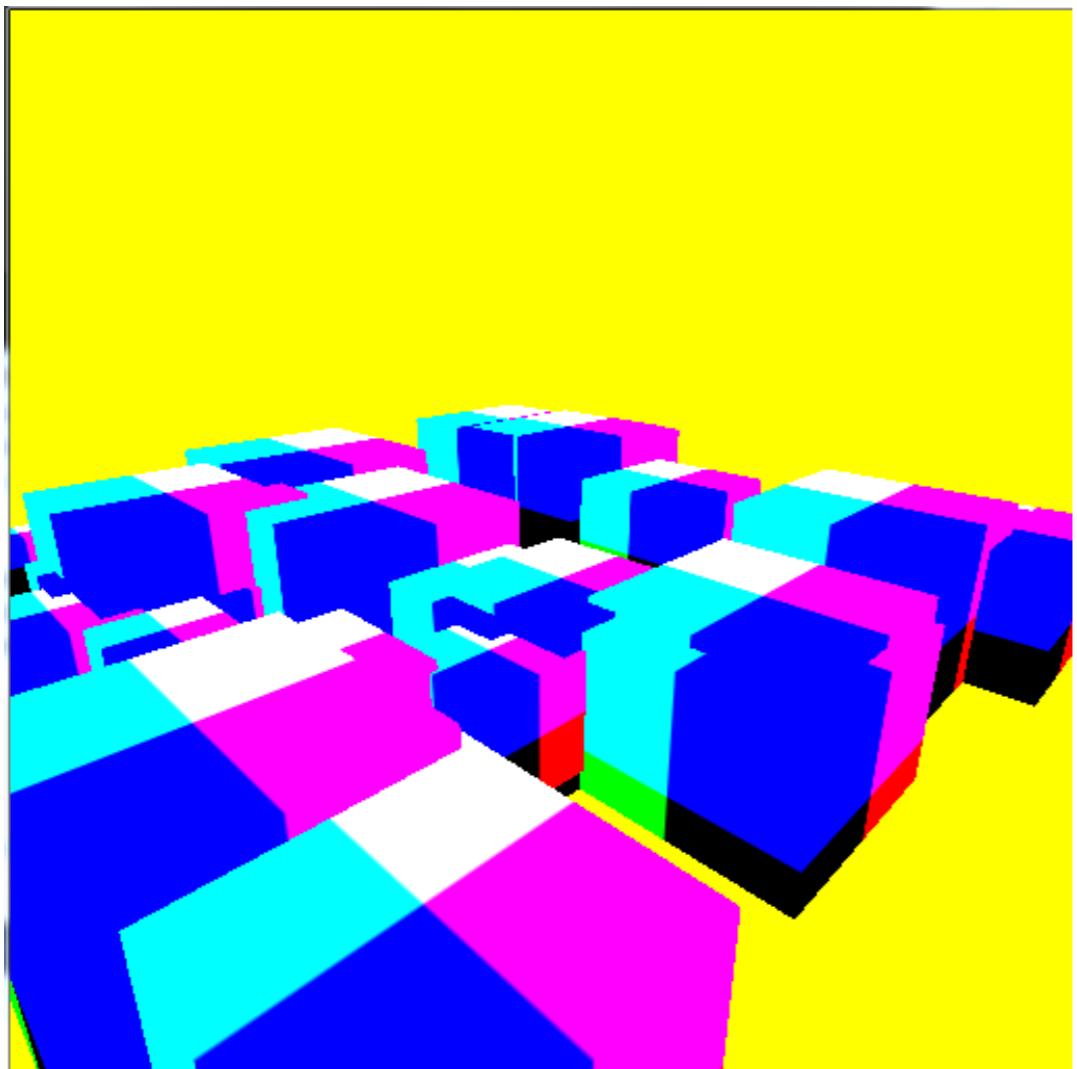
Visualizing the Blocking Factor



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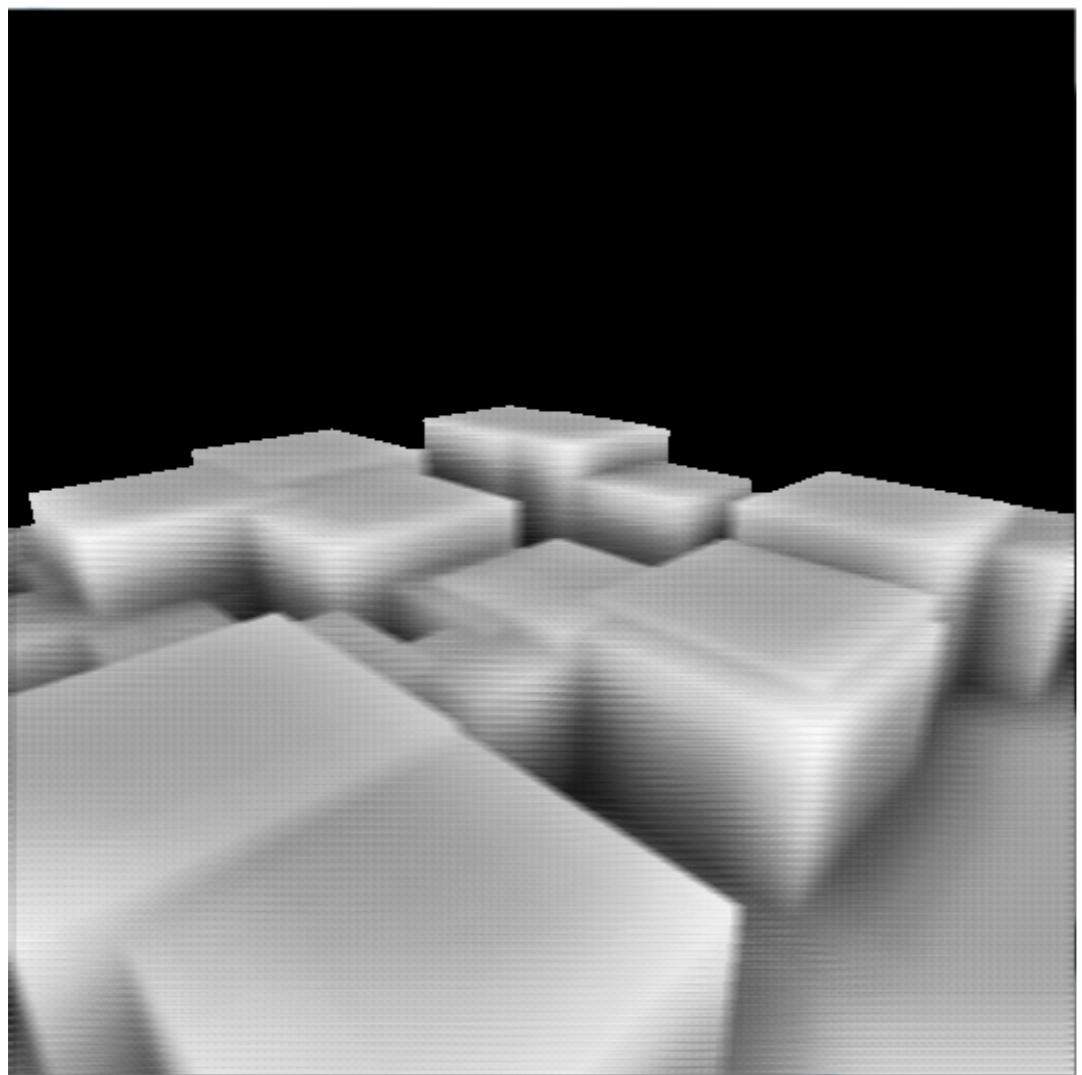
Visualizing the Blocking Factor



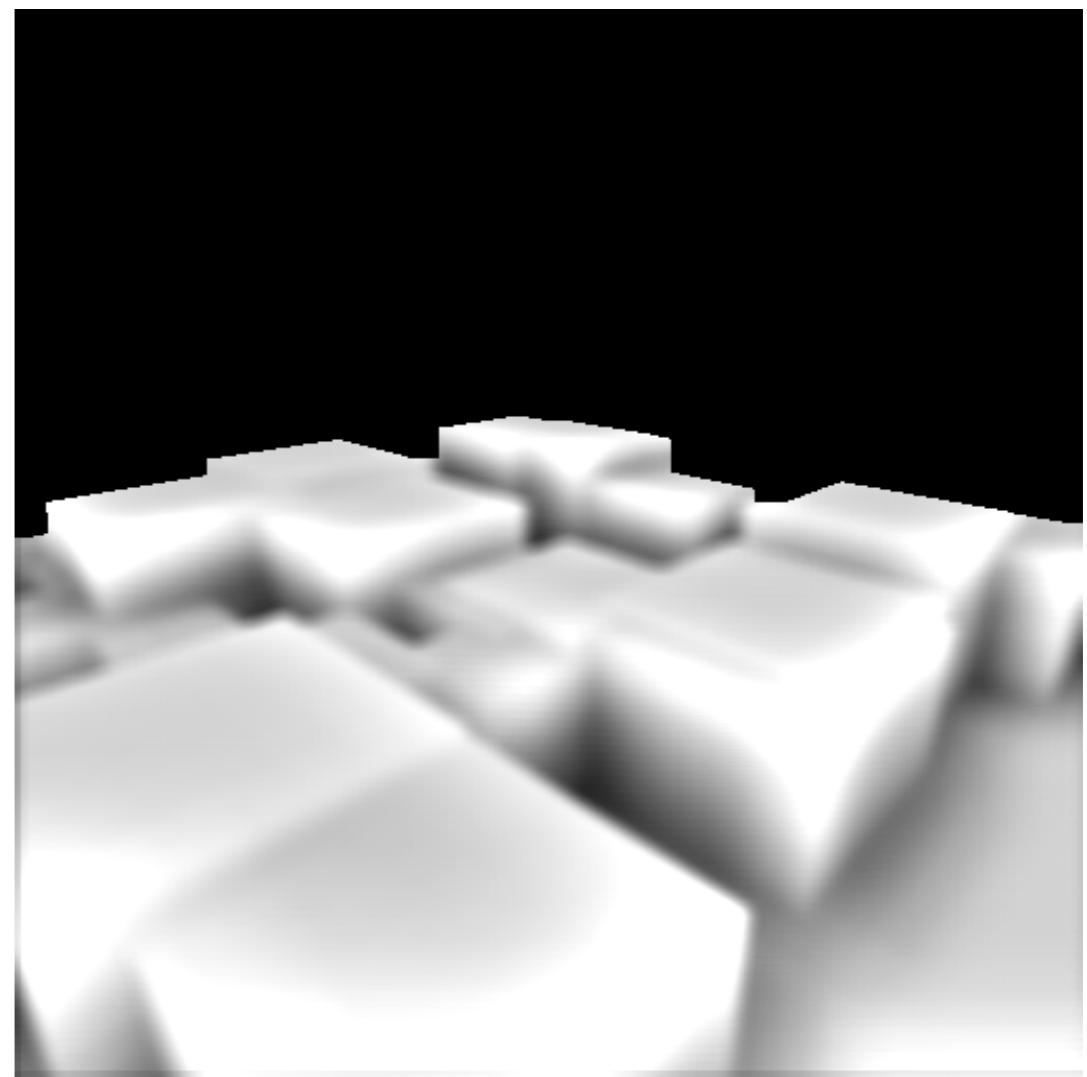
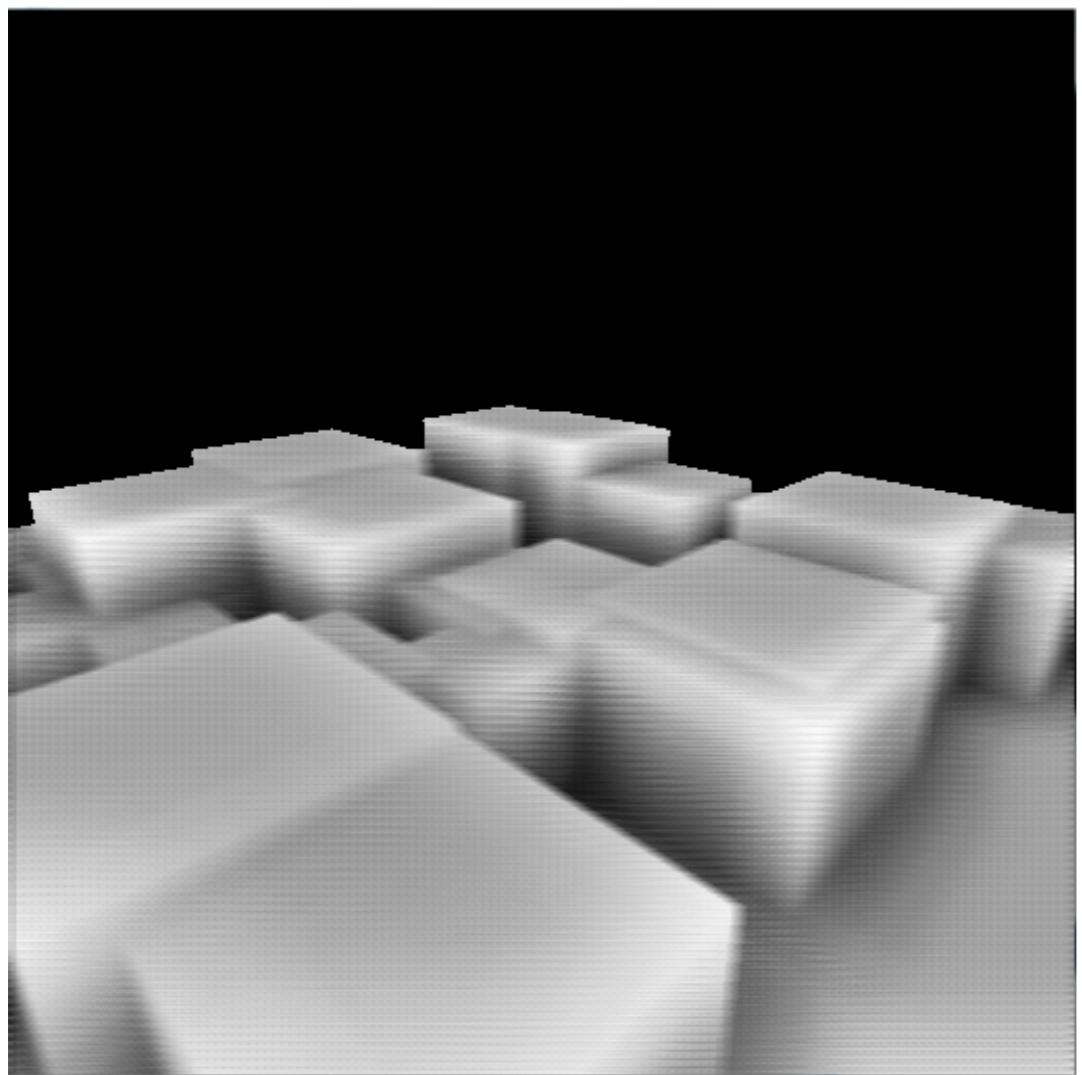
Banding artifacts

Blurring the Blocking Factor

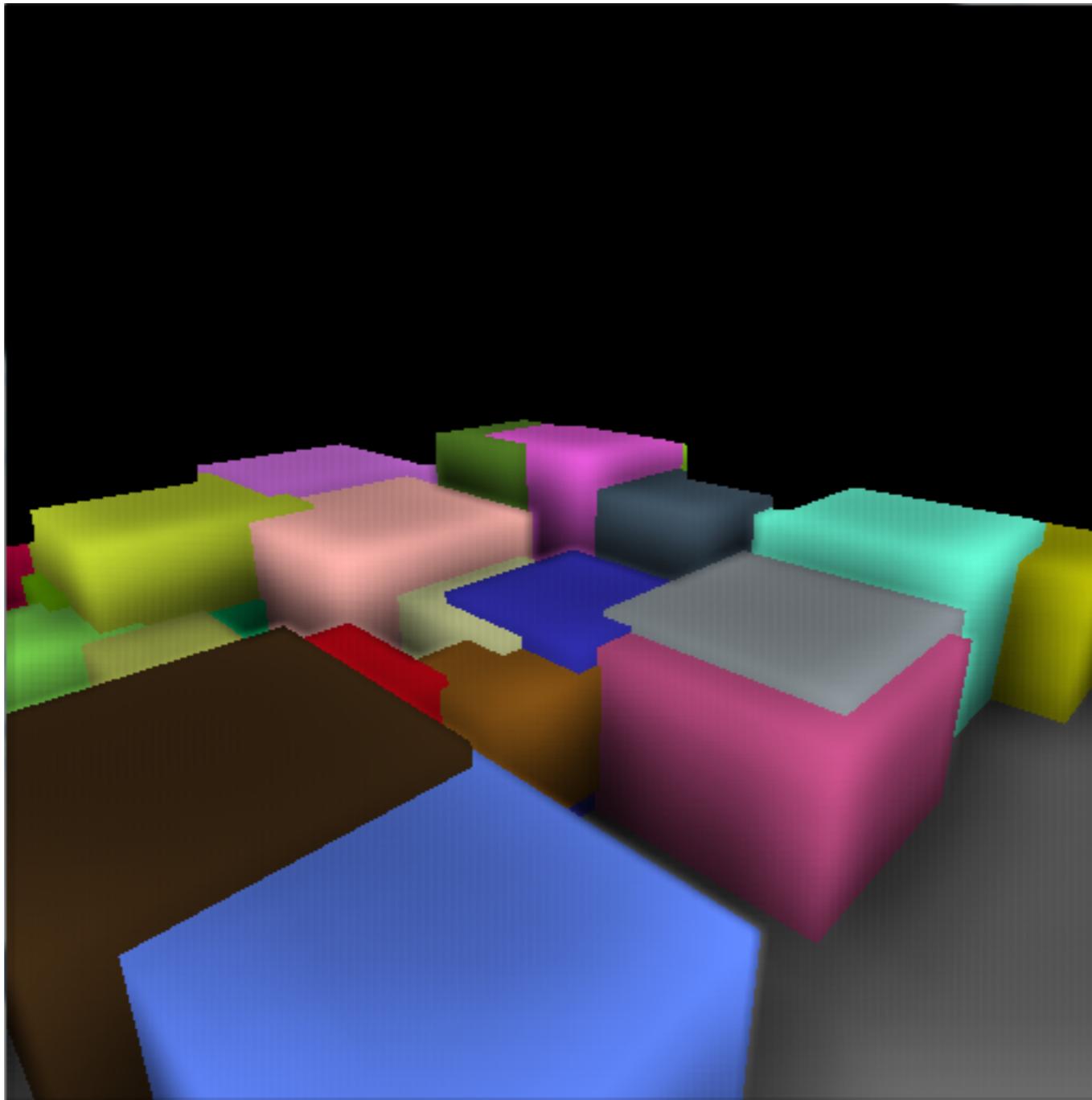
Blurring the Blocking Factor



Blurring the Blocking Factor



Combining with the Color Values



SSAO Examples



Crytek - CryEngine 2



Crytek - More Examples

Crytek - More Examples



Crytek - More Examples



“Up” - Pixar

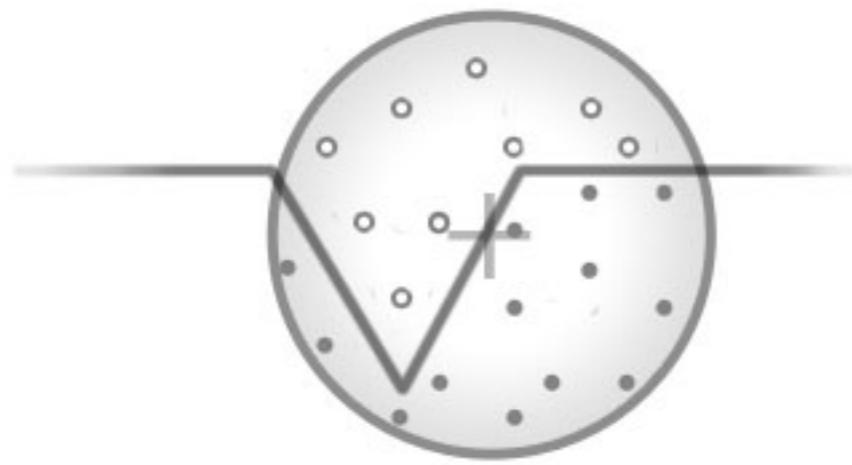


nVidia SDK Demo

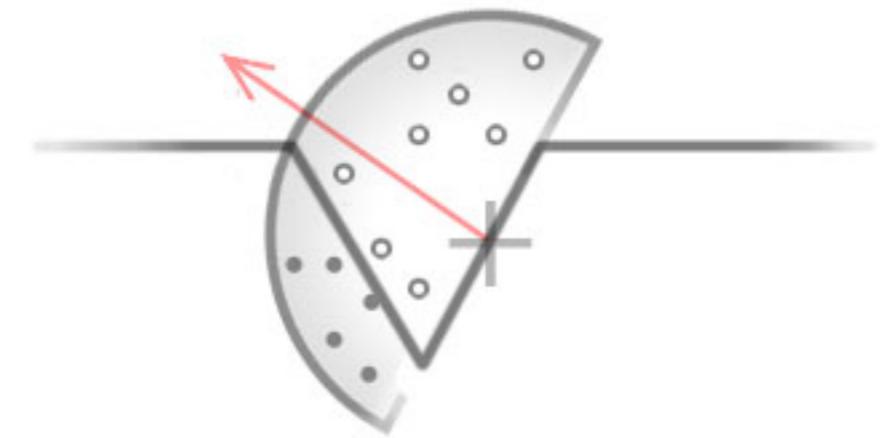


Download the Demos from developer.nvidia.com

Extensions



Crytek Method (Full Sphere)



Normal-oriented Method
(hemisphere)

<https://www.youtube.com/watch?v=-lFxjKT7MXA>

References

- SSAO Tutorials / Introduction
 - <https://learnopengl.com/#!Advanced-Lighting/SSAO>
 - <http://john-chapman-graphics.blogspot.com/2013/01/ssao-tutorial.html>
- Advanced topics (artifacts in SSAO)
 - <https://mtnphil.wordpress.com/2013/06/26/know-your-ssao-artifacts/>

Thank You.