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# Chapter 1

## Errata

## 5.1 Correction to text before Eqn.5.1.48 (radial distribution function)

Fengyu Xi brought it to our attention that there is a sign problem in some steps in Equation (5.1.48). However, the resulting equation itself was correct. Below, we correct and expand the derivation of (5.1.48).

The incorrect sentence was the following: “As the argument of the  $\delta$ -function is  $\mathbf{r} - \mathbf{r}_j$ , we can replace  $\hat{\mathbf{r}} \cdot \nabla_{\mathbf{r}}$  by  $-\hat{\mathbf{r}}_j \cdot \nabla_{\mathbf{r}_j}$  and perform a partial integration.” This sentence was wrong because, in Equation (5.1.49),  $\hat{\mathbf{r}}$  is only replaced by  $\hat{\mathbf{r}}_j$  *after* the partial integration:

$$\begin{aligned}
 \left( \frac{\partial g(\mathbf{r})}{\partial \mathbf{r}} \right) &= \frac{1}{\rho} \frac{\int d\hat{\mathbf{r}} \int d\mathbf{r}^{N-1} e^{-\beta U(\mathbf{r}^N)} \sum_{j \neq i} \hat{\mathbf{r}} \cdot \nabla_{\mathbf{r}} \delta(\mathbf{r} - \mathbf{r}_j)}{\int d\mathbf{r}^{N-1} e^{-\beta U(\mathbf{r}^N)}} \\
 &= \frac{-1}{\rho} \frac{\int d\hat{\mathbf{r}} \int d\mathbf{r}^{N-1} e^{-\beta U(\mathbf{r}^N)} \sum_{j \neq i} \hat{\mathbf{r}} \cdot \nabla_{\mathbf{r}_j} \delta(\mathbf{r} - \mathbf{r}_j)}{\int d\mathbf{r}^{N-1} e^{-\beta U(\mathbf{r}^N)}} \\
 &= \frac{-\beta}{\rho} \frac{\int d\hat{\mathbf{r}} \int d\mathbf{r}^{N-1} e^{-\beta U(\mathbf{r}^N)} \sum_{j \neq i} \delta(\mathbf{r} - \mathbf{r}_j) \hat{\mathbf{r}} \cdot \nabla_{\mathbf{r}_j} U(\mathbf{r}^N)}{\int d\mathbf{r}^{N-1} e^{-\beta U(\mathbf{r}^N)}} \\
 &= \frac{\beta}{\rho} \int d\hat{\mathbf{r}} \left\langle \sum_{j \neq i} \delta(\mathbf{r} - \mathbf{r}_j) \hat{\mathbf{r}}_j \cdot \mathbf{F}_j(\mathbf{r}^N) \right\rangle_{N-1}
 \end{aligned} \tag{5.1.49}$$

where  $\hat{\mathbf{r}}_j \cdot \mathbf{F}_j \equiv F_j^{(r)}$  denotes the force on particle  $j$  in the radial direction. **NOTE:** In step 2, we replaced differentiation of the delta function with respect to  $\mathbf{r}$  by differentiation with respect to  $-\mathbf{r}_j$ . Step 3: partial integration. Here it is important to note that  $\mathbf{r}$  does not depend on  $\mathbf{r}_j$ . Only in step 3 we then use the fact that the delta function imposes  $\mathbf{r} = \mathbf{r}_j$ .

## 5.2 Maxwell-Stefan expression for diffusion coefficient

Thejas Hulikal Chakrapani pointed out there is a typographical error in Chapter 5, Illustration 3 (Diffusion coefficients), which is repeated twice. First of all, Eqn. (5.2.18) should read

$$J(c) \equiv -\frac{L(c)}{k_B T} \nabla \mu = -\frac{c D^c(c)}{k_B T} \nabla \mu.$$

rather than

$$J(c) \equiv -\frac{L(c)}{k_B T} \nabla \mu = -\frac{D^c(c)}{k_B T c} \nabla \mu.$$

The error also affects the next equation, which should read:

$$D^t = D^c \frac{c}{k_B T} \frac{\partial \mu}{\partial \ln c} \frac{\partial \ln c}{\partial c} = \Gamma D^c,$$

But the following equation for  $\Gamma$ , the thermodynamic coefficient, is correct

$$\Gamma = \frac{1}{k_B T} \frac{\partial \mu}{\partial \ln c} = \frac{\partial \ln f}{\partial \ln c},$$

where we have replaced the chemical potential by the logarithm of the fugacity.

## 7.1 Stochastic global energy rescaling

Michael Allen pointed out that there are errors in the equations describing the corrected “Heyes” thermostat on page 257. Below, we highlight the corrections in red:

... the equilibrium distribution of the total kinetic energy  $E_k$  at inverse temperature  $\beta$  is:

$$P(E_k) = \mathcal{C} E_k^{\mathbf{d(N-1)/2-1}} \exp(-\beta E_k) ,$$

where  $\mathcal{C}$  is an (unimportant) normalization constant.

**In the original text, we wrote  $d(N-1)$  instead of  $d(N-1)/2-1$  in the exponent of the kinetic energy.** The correct results can be derived as follows: first, because momentum-scaling thermostats only work correctly if the total momentum is zero (and therefore remains zero upon rescaling), the number of independent momenta is equal to  $d(N-1) \equiv f$ , where  $f$  denotes the number of independent degrees of freedom.

Now consider the Boltzmann distribution of these momenta. We write the kinetic energy  $E_k$  as  $E_k = \sum_{i=1}^N p_i^2 / (2m_i)$ . For the sake of convenience, we assume that all masses are the same. However, if this is not the case, it is important to remember that, if the masses of the particles are different, conserving (zero) momentum is not equivalent to conserving zero *average* particle velocity (as opposed to zero center-of-mass velocity), and conversely. With equal masses, the hyper-surface of constant kinetic energy is a (hyper)sphere in momentum-space with radius  $p_t \equiv \sqrt{\sum p_i^2}$ , such that  $E_k \sim p_t^2 / 2m$ . Then

$$P_B(\mathbf{p}^f) d\mathbf{p}^f \sim P_B(\mathbf{p}^f) p_t^{f-1} dp_t \sim P_B(E_k) E_k^{(f-1)/2-1/2} dE_k$$

Therefore,  $P(E_k)$ , the kinetic energy distribution (again, ignoring the constant normalization factor) is

$$P(E_k) = P_B(E_k) E_k^{f/2-1}$$

Inserting  $f = d(N-1)$ , we arrive at the desired result.

The missing factor 1/2 in the uncorrected expression comes back in the acceptance rule, which should be corrected to:

$$\text{acc}(E_k \rightarrow E'_k) = \min \left( 1, z^{\mathbf{d(N-1)}} e^{-\beta E_k (z^2-1)} \right) .$$

## 11.3 The width of a Gaussian charge cloud

Benjamin Rotenberg pointed out that Section 11.2 contains a typo:

The width of the Gaussian distribution (middle of page 376) is of course not  $\sqrt{2/\alpha}$  as written, but  $\sqrt{1/(2\alpha)}$





## Chapter 2

# Additions

### 2.1 Statistical errors in numerical quadrature

#### What is the issue ?

In Chapters 8 and 9, and in Appendix N, we refer to the use of Gauss-Legendre quadrature to approximate the definite integrals that are used in thermodynamic integration.

The quadrature results in possible systematic errors, which tend to be quite small if enough quadrature points are used and if the integration variables are chosen judiciously, and statistical errors due to the fact that the quantity that we integrate is obtained by sampling and is, therefore, subject to fluctuations.

Knowing the variance in the sampled integrands allows us to estimate the statistical error in the estimate of the integral. The quadrature used need not be Gauss-Legendre.

#### Error estimates

Consider an integral

$$I = \int_a^b dx f(x) \quad (2.1.1)$$

We represent the integral by a Gauss-Legendre (GL) quadrature  $I'$ <sup>1</sup>

$$I' = (b - a) \sum_i w_i f(x_i) \quad (2.1.2)$$

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<sup>1</sup>We mention Gauss-Legendre here, but the arguments below apply just as well to other quadratures

where  $x_i \equiv a + \lambda_i(b - a)$  and  $0 < \lambda_i < 1$  is the scaled coordinate of the  $i$ -th GL point.  $w_i$  is the weight of the  $i$ -th point in the GL quadrature. We assume that the  $w_i$  are normalized, such that  $\sum_{i=1}^n w_i = 1$ , where  $n$  is the number of GL points.

If we obtain  $f(x_i)$  by sampling, it will be subject to statistical error:

$$\sigma_i^2 = \langle f_i^2 \rangle - \langle f_i \rangle^2 \quad (2.1.3)$$

The error in  $I'$ ,  $\sigma^2(I')$  depends on the variance of the individual  $i$  data points. Then

$$\sigma_i^2(I') = (b - a)^2 \left[ \langle (\sum_i w_i f(x_i))^2 \rangle - \langle \sum_i w_i f(x_i) \rangle^2 \right] \quad (2.1.4)$$

as the fluctuations in the estimates of different data points are uncorrelated and as the average fluctuation in any data point vanishes, we can write:

$$\sigma_i^2(I') = (b - a)^2 \sum_i w_i^2 \langle \sigma_i^2 \rangle \quad (2.1.5)$$

Hence, you just do one simulation to compute  $\langle f(x_i) \rangle$  and  $\langle f^2(x_i) \rangle$ . We then get  $\sigma_i^2 = \langle f_i^2 \rangle - \langle f_i \rangle^2$ , and this immediately yields the estimated error in the GL quadrature...