Graph Neural Networks

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Graphs are everywhere

traffic/road networks

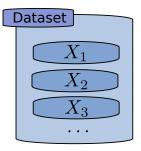
dynamic physics systems citation networks

chemical molecules visual scene understanding

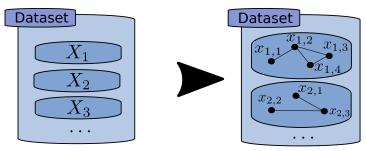
protein 3D structure

TSP, Vertex-Cover, CLIQUE, SAT...

• Often, data does not come as individual objects...

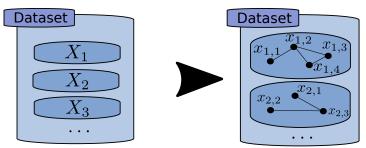


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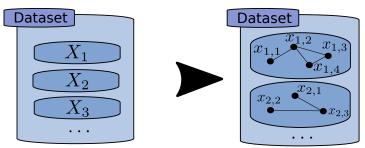
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- ... but rather in sets of objects and rules on how they interact.
- Inductive bias: constraints imposed on the set of possible pairwise interactions (represented as a graph).
- Making predictions requires 'relational reasoning' based on the graph structure.

Inductive biases can be well defined independent of the data examples:

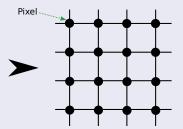
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Images





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 - Recurrent architectures for sequences.
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- But how to handle data with less well defined inductive biases? (e.g. chemical molecules, road networks, citation networks...)

Graph Neural Networks (GNNs)

Definition: Feature graph

A (directed) feature graph is a 3-tuple G = (u, V, E) with a global attribute u, nodes $V = \{v_i\}_{i=1,\dots,n}$ where v_i are the attributes of the node at index i and edges $E = \{(e_j, s_j, r_j)\}_{j=1,\dots,m}$ with edge attributes e_j , a sender node index s_j and a receiver node index r_j .

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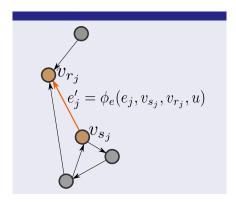
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Definition: Graph neural network

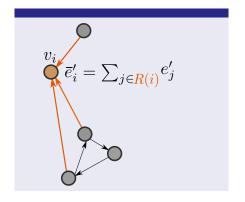
A graph neural network (GNN) is a mapping $\omega: G \mapsto G'$ that maps a feature graph G = (u, V, E) to another feature graph G' = (u', V', E') with $V' = \{v'_i\}_{i=1,\dots,n}$ and $E' = \{(e'_j, s_j, r_j)\}_{j=1,\dots,m}$.

Let ϕ_{ν} , ϕ_{e} , ϕ_{u} be learnable non-linear functions (e.g. multilayer perceptrons).

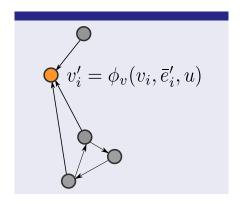
Update all edges



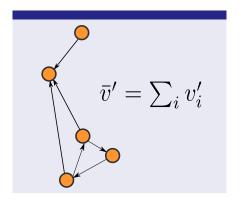
- Update all edges
- 2 Aggregate neighborhoods



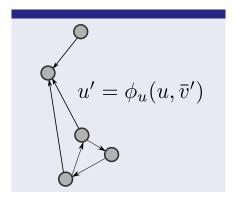
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- Update all edges
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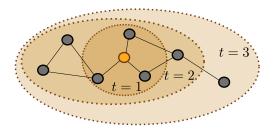


- Update all edges
- 2 Aggregate neighborhoods
- 3 Update all nodes
- 4 Aggregate nodes
- 5 Update global attribute



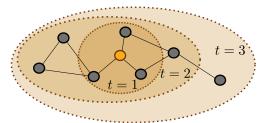
Message passing

Message passing: a composition of a GNN ω with itself for a fixed number of iterations: $\omega(\omega(\ldots\omega(G)))$



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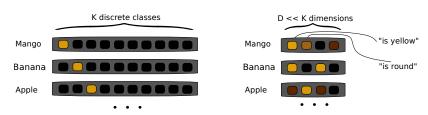
■ If the global attribute u is excluded, the output of a node v after N iterations is conditioned on all nodes with a distance of at most N to v.

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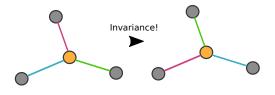


We use a *D* dimensional latent space where each neuron could represent a rather simple, independent property. Some of these properties, we can try to interpret as a human.

⇒ Empirical: A shallow model on top (e.g. a linear combination) could make accurate predictions.



A GNN is invariant to graph isomorphism, if the aggregation operations are symmetric functions (sum, average...)

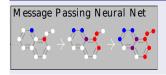


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- Therefore, we can backpropagate a loss signal in order to update θ .
- The loss may depend on u' (graph focused), V' (node focused) or E' (edge focused) or all of these.

Predict properties of chemical molecules

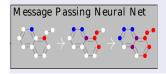


Neural Message Passing for Quantum Chemistry
– Gilmer et al.. 2017

Input

Molecule as a graph: Type of atom for each node, type of bond for each edge.

Predict properties of chemical molecules



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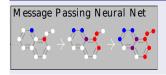
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A global property of the molecule e.g. energy

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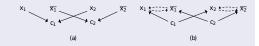
Loss

MSE on the global output u'

Solve SAT

Learning a SAT solver from single-bit supervision

– Selsam et al., 2019

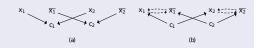


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SAT instance I encoded as an unlabeled graph G

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Loss

Binary cross entropy on the global output u'

Timesteps in a dynamic physics system



Relational inductive biases, deep learning, and graph networks

– Battaglia et al., 2018

Input

Initial state of the rope as a graph: Masses and positions as node attributes. Only add edges for adjacent masses on the rope. Possible global attribute: Gravity

Timesteps in a dynamic physics system



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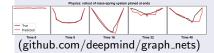
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State of the rope (i.e. updated node positions) after N timesteps.

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Loss

MSE on the node outputs v_i'

A practical example: Sorting numbers

Input

A list of pairwise distinct numbers x_1, \ldots, x_k

- WLOG $x_i \in [0,1]$
- k is variable

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A sorted list of the same numbers

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Let π be a sorting permutation of the indices, i.e. $\pi(i) = j \Leftrightarrow x_i$ is the jth smallest element

A naive approach without GNNs

We could try to solve the problem by using a simple neural network with an input vector of fixed length L:

$$(x_1, x_2, \ldots, x_k, P, P, \ldots, P)$$

where L is large enough for all reasonable inputs and P is some padding added to input lists shorter than L.

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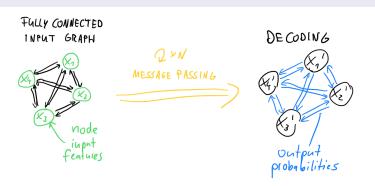
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Why **NOT** do it this way.

- maximum list length *L* is not intuitive
- overhead for k << L
- no generalization to longer lists than seen during training



- Construct a fully connected graph with numbers as nodes
- 2 Refine nodes/edge embeddings with message passing
- **3** Decode $P(\pi(j) = \pi(i) + 1 | x_1, x_2, ..., x_k)$ for all i, j = 1, ..., k



Loss and Training

For details see notebook "Sort.ipynb".