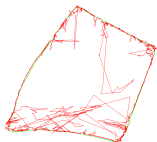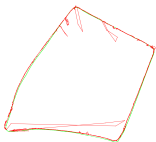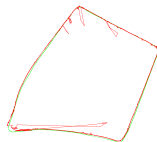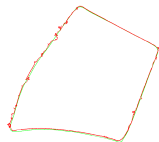# Result on Oxford RobotCar dataset
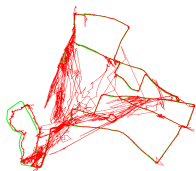

1 km

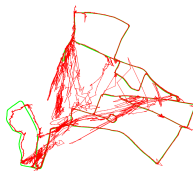PoseNet [1]　　MapNet [2]　　MapNet+PGO [2]　　Our method

10 km

MapNet [2]　　MapNet+PGO [2]　　Our method

[1] A. Kendall, M. Grimes, and R. Cipolla, "Posenet: A convolutional network for real-time 6-dof camera relocalization," in CVPR, 2015.

[2] S. Brahmbhatt, J. Gu, K. Kim, J. Hays, and J. Kautz, "Geometry-aware learning of maps for camera localization," in CVPR, 2018.