Lecture VIII

- Vector norms and the associated matrix norms
- Some max and minimax principles
- Location of eigenvalues

Vector Norms

Any regular vector-norm satisfies:

|x| denotes the (generic) norm of vector x.

- |x| > 0, if $x \ne 0$; |x| = 0, if x = 0.
- $|\lambda x| = |\lambda| \cdot |x|$, for any scalar λ .
- $|x+y| \le |x| + |y|$, "triangle inequality"
- |x| depends continuously on x.
- $\exists \alpha, \ \beta > 0 \text{ such that}$ $\alpha \max_{k} |x_{k}| \le |x| \le \beta \max_{k} |x_{k}|, \ \forall \text{ vector } x.$

Comment

It is of interest to note that the last 2 properties in the definition of norm follow from the first 3 properties.

Examples of Norm

(1) The Euclidean norm of x is:

$$|x| = \left(\sum_{k=1}^{n} |x_k|^2\right)^{\frac{1}{2}} \doteq ||x|| \text{ (or sometimes, } |x|_2\text{)}.$$

(2) Riemannian metric:

$$|x| = \langle Px, x \rangle^{\frac{1}{2}} = \left(\sum_{j} \sum_{k} p_{jk} x_{k} \overline{x}_{j}\right)^{\frac{1}{2}}$$

where *P* is positive definite.

Examples of Norm

(3) The "Manhattan", or l_1 norm of x is:

$$\left|x\right|_{1} = \sum_{k=1}^{n} \left|x_{k}\right|.$$

- (4) The " l_{∞} " norm: $|x|_{\infty} = \max_{1 \le i \le n} |x_i|$.
- (5) The " l_p " norm: $|x|_p = \left(\sum_{i=1}^n |x_i|^p\right)^{1/p}$

Can you verify that these are indeed norms??

All norms over any finite-dimensional space are equivalent.

Some useful inequalities:

$$\begin{vmatrix} x _{1} \le \sqrt{n} & |x|_{2} \end{vmatrix}, \quad |x|_{1} \le n & |x|_{\infty} \end{vmatrix},$$
 $|x|_{2} \le |x|_{1}, \quad |x|_{2} \le \sqrt{n} & |x|_{\infty} \end{vmatrix},$
 $|x|_{\infty} \le |x|_{1}, \quad |x|_{\infty} \le |x|_{2}.$

The Related Matrix Norm

For any given regular vector-norm |x|, we can define the related matrix-norm as

$$|A| = \max_{x \neq 0} \frac{|Ax|}{|x|}, A: n \times m \text{ matrix.}$$

Remark: It reduces to the vector norm when m = 1.

Example of matrix-norm

From the Euclidean vector-norm, define the related *spectral* matrix-norm:

$$||A||_2 = \max_{x \neq 0} \frac{|Ax|_2}{|x|_2}$$

$$= \max_{x \neq 0} \sqrt{\frac{\langle Ax, Ax \rangle}{\langle x, x \rangle}} = \max_{x \neq 0} \sqrt{\frac{\langle A^*Ax, x \rangle}{\langle x, x \rangle}}$$

$$=\sqrt{\lambda_{\max}(A^*A)}$$
, using Rayleigh's principle below.

For example,

$$A = \begin{pmatrix} 0 & -2 \\ 1 & 0 \end{pmatrix} \Rightarrow A^*A = \begin{pmatrix} 1 & 0 \\ 0 & 4 \end{pmatrix}$$
$$\Rightarrow ||A|| = \sqrt{4} = 2.$$

Other Matrix Norms

• Frobenius norm (or, Euclidean norm, l_2 -norm, Schur norm, Hilbert-Schmidt norm):

$$|A|_F := |A|_2 = \left(\sum_{i,j=1}^n |a_{ij}|^2\right)^{1/2}.$$

• l_1 -norm: $|A|_1 = \sum_{i,j=1}^n |a_{ij}|$.

•
$$l_{\infty}$$
-norm: $|A|_{\infty} = \sum_{j=1}^{n} |a^{j}|_{\infty}$, where $A = [a^{1} \ a^{2} \ \cdots \ a^{n}]$.

Fundamental Theorem

For any matrix norm $\| \bullet \|$, then

$$\rho(A) \le ||A||$$
, with A a square matrix

where $\rho(A)$ is the spectral radius of A, i.e.

$$\rho(A) = \max\{|\lambda| : \lambda \text{ is an eigenvalue of } A\}.$$

Remark: Provided an upper-bound for all eigenvalues of any given matrix.

Indeed, we have

$$|\lambda||x| = |\lambda x| = |Ax| \le ||A|| \bullet |x|$$

where x is an associated eigenvector.

So,
$$\rho(A) \leq ||A||$$
.

Example

Verify this theorem on the following matrices:

$$1) A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix};$$

$$2) A = \begin{pmatrix} 0 & j \\ -j & 0 \end{pmatrix}.$$

You may consider the l_2 -norm only.

Question

What are the tightest bounds in

$$c_1 \|x\|^2 \le \langle Hx, x \rangle \le c_2 \|x\|^2$$

where H is an $n \times n$ Hermitian matrix.

Simplified Question

Given a Hermitian matrix H, what is the maximum of $\overline{u}^T H u := \langle H u, u \rangle, \quad ||u|| = 1$

The Rayleigh Principle

Consider a Hermitian matrix H. Then,

$$\max_{\|u\|=1} \langle Hu, u \rangle = \lambda_1$$

where λ_1 is the largest eigenvalue of H. Morever, the equality is attained with u being a λ_1 -associated eigenvector.

Corollary

If H is Hermitian and λ_1 is its largest eigenvalue, then

$$\lambda_1 = \max_{x \neq 0} \frac{\langle Hx, x \rangle}{\langle x, x \rangle},$$

where $\frac{\langle Hx, x \rangle}{\langle x, x \rangle}$ is called Rayleigh quotient.

Comment

As a direct consequence, we obtain a useful inequality:

$$|x^T H x| \leq \lambda_{\max}(H) |x|^2, \quad \forall x$$

for H positive definite.

An Example

Consider the matrix
$$H = \begin{pmatrix} 4 & 3i \\ -3i & 2 \end{pmatrix}$$
.

- Is it Hermitian?
- Compute its eigenvalues.
- Verify the Rayleigh's Principle.

Answer

- Yes, it is Hermitian, and therefore, its eigenvalues must be real.
- $\bullet \ \lambda_{1,2} = 3 \pm \sqrt{10}.$

•
$$\frac{\langle Hx, x \rangle}{\langle x, x \rangle} = \frac{4|x_1|^2 + 3i\overline{x}_1 x_2 - 3i\overline{x}_2 x_1 + 2|x_2|^2}{|x_1|^2 + |x_2|^2}$$

 $\leq 3 + \sqrt{10}$ (using CFT. Do you know why/how?) where the equality is attained when $\begin{bmatrix} x_1 & x_2 \end{bmatrix}^T = x$

is an eigenvector associated with $3 + \sqrt{10}$.

Comment

The Rayleigh principle cannot be applied to non-Hermitian matrix. Here is a simple counter-example:

$$A = \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix}, \quad b \neq 0.$$

Proof of the Rayleigh Principle

As shown previously with canonical diagonal form, a Hermitian matrix H only has real eigenvalues $\lambda_1 \ge \cdots \ge \lambda_n$ and has mutually orthogonal eigenvectors

$$\left\|\left\{u^i\right\}_{i=1}^n$$
, with $\left\|u^i\right\| = \sqrt{\left\langle u^i, u^i\right\rangle} = 1$.

Notice that
$$\lambda_i = \langle Hu^i, u^i \rangle$$
, $\forall 1 \leq i \leq n$.

Proof (cont'd)

Since $\{u^i\}_{i=1}^n$ are mutually orthogonal, then,

every unit vector u can be written as

$$u = c_1 u^1 + \cdots + c_n u^n,$$

$$u = c_1 u^1 + \dots + c_n u^n,$$
with $|c_1|^2 + \dots + |c_n|^2 = 1.$

On the other hand, $Hu = \sum c_i \lambda_i u^i$, implying

$$|\langle Hu, u \rangle = \sum \lambda_i |c_i|^2 \le \lambda_1$$
, as wished.

On Other Eigenvalues

Consider Hermitian *H* having real eigenvalues

$$\lambda_1 \ge \cdots \ge \lambda_n$$
. Let $\{u^k\}_{k=1}^{i-1}$ be mutually

orthogonal unit eigenvectors associated

with
$$\{\lambda_k\}_{k=1}^{i-1}$$
. Then,

$$\lambda_{i} = \max_{\substack{\|u\|=1\\ \langle u, u^{k} \rangle = 0\\ 1 \leq k \leq i-1}} \langle Hu, u \rangle$$

Benefit of quadratic forms

Courant's MinMax Theorem

To independently evaluate each eigenvalue:

Theorem: Let $\lambda_1 \ge \cdots \ge \lambda_n$ be the eigenvalues

of a Hermitian matrix $H \in \mathbb{C}^{n \times n}$.

Then, for $1 \le i < n$,

$$\lambda_{i+1} = \min_{\substack{v^1, \dots, v^i \ \|u\|=1 \\ \langle u, v^k \rangle = 0 \\ k=1, \dots, i}} \max_{\substack{\langle u, v^k \rangle = 0 \\ k=1, \dots, i}} \langle Hu, u \rangle.$$

An Example

Consider the quadratic form

$$\langle Hu,u\rangle = 3u_1^2 + 2u_2^2 + u_3^2 \implies H = diag(3, 2, 1).$$

Thus,
$$\lambda_1 = 3$$
, $\lambda_2 = 2$, $\lambda_3 = 1$, and

its associated eigenvectors are:

$$u^{1} = e^{1} = col(1, 0, 0), u^{2} = e^{2} = col(0, 1, 0),$$

 $u^{3} = e^{3} = col(0, 0, 1).$

An Example (cont'd)

By Rayleigh's principle,

$$\lambda_2 = \max_{\substack{\|u\|=1\\ \langle u,e^1 \rangle = 0}} \left(3u_1^2 + 2u_2^2 + u_3^2 \right)$$

$$= \max_{u_2^2 + u_3^2 = 1} (2u_2^2 + u_3^2) = 2$$
, as expected.

By Courant's principle,

$$\lambda_{2} = \min_{v^{1}} \max_{\substack{\|u\|=1 \\ \langle u, v^{1} \rangle = 0}} \left(3u_{1}^{2} + 2u_{2}^{2} + u_{3}^{2} \right) := \min_{v^{1}} \phi(v^{1}).$$

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An Example (cont'd)

Clearly, $\phi(0) = \lambda_1 = 3$ (Rayleigh's principle). When $v^1 \neq 0$, to compute λ_2 is equivalent to solving two (constrained) nonlinear

optimization problems.

Here, we apply a graphical proof to yield:

$$\lambda_2 = 2 = \phi(e^1) = \min \phi(v^1),$$

because $3u_1^2$ is the dominating term.

A Useful Test

For any $n \times n$ Hermitian matrix $H = (h_{ij})$, it is positive definite if and only if all its leading principal minors are positive:

$$h_{11} > 0$$
, $\det \begin{pmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{pmatrix} > 0$, ...,

$$\det\begin{pmatrix} h_{11} & \dots & h_{1n} \\ \vdots & \ddots & \vdots \\ h_{n1} & \dots & h_{nn} \end{pmatrix} > 0.$$

Recursive Proof

 \Rightarrow : If *H* is positive definite, then all its eigenvalues are positive. Then, det H > 0.

Let H_k denote the submatrix of H formed of the first k rows and columns of H.

Then, H_k must be positive definite, because

$$\langle H_k x^k, x^k \rangle = \langle Hx, x \rangle$$
, with $x = (x^k, 0)$.

That is: $\det H_k > 0$, as wished.

Recursive Proof

 \Leftarrow : Now, det $H_k > 0$, $\forall k$. In order to prove the positive definiteness of H, we need the following "Inclusion Principle".

The Inclusion Principle

From a Hermitian matrix $A = (a_{ij})_{n \times n}$, form an $(n-1) \times (n-1)$ matrix B by deleting the last row and column of A. Then, the eigenvalues $\alpha_1 \ge \cdots \ge \alpha_n$ of A, and $\beta_1 \ge \cdots \ge \beta_{n-1}$ of B satisfy:

$$\alpha_1 \ge \beta_1 \ge \alpha_2 \ge \cdots \ge \alpha_{n-1} \ge \beta_{n-1} \ge \alpha_n$$
.

Proof: using Courant's MinMax theorem.

Recursive Proof (cont'd)

 \Leftarrow : Now, det $H_k > 0$, $\forall k$. Then, $H_1 = (h_{11})$

is positive definite. By induction, assume that H_k , k < n, is positive definite. We then need to prove that H_{k+1} is positive definite.

Let $\alpha_1 \ge \cdots \ge \alpha_{k+1}$ be the eigenvalues of H_{k+1} , and $\beta_1 \ge \cdots \ge \beta_k$ be the eigenvalues of H_k .

It follows from the inclusion principle that

$$\alpha_1 \ge \beta_1 \ge \cdots \ge \beta_k \ge \alpha_{k+1}$$

Recursive Proof (cont'd)

$$\iff \alpha_1 \ge \beta_1 \ge \dots \ge \beta_k \ge \alpha_{k+1} \text{ implies}$$

$$\alpha_1 > 0, \dots, \alpha_k > 0.$$

It remains to prove $\alpha_{k+1} > 0$ to conclude the positive definiteness of H_{k+1} .

Using
$$\alpha_1 \cdots \alpha_k \bullet \alpha_{k+1} = \det H_{k+1} > 0$$
, we have $\alpha_{k+1} > 0$.

Question

How to provide a fine characterization for the location of the eigenvalues of a matrix?

Comment

The location of eigenvalues of an LTI system determines the stability nature of the system. See **Lecture XII**.

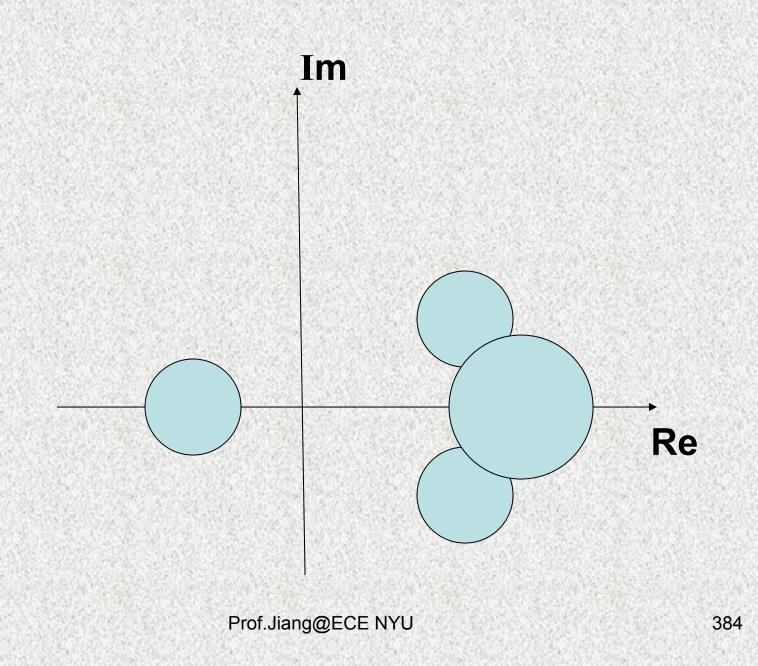
Gersgorin Disc Theorem

1) All eigenvalues of $A = [a_{ij}]_{n \times n}$ are located in the union

of
$$n$$
 discs $\bigcup_{i=1}^n \left\{ z \in \mathbb{C} : \left| z - a_{ii} \right| \le \sum_{j=1, j \ne i}^n \left| a_{ij} \right| \right\} \triangleq G(A)$.

2) If a union of k of these discs forms a connected region disjoint from the remaining n-k discs, then there are exactly k eigenvalues in this region.

Proof: See the textbook (2nd Ed., 2013, pp. 387-389.



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Essential Idea

Consider

 $A = D + \varepsilon B$, ε sufficiently small with $D = diag(a_{ii})$.

Observation:

The eigenvalues of perturbed matrix A should be "close" to those of the unperturbed matrix D.

Sketch of Proof

Take an eigenvector u associated with λ ,

and let
$$|u_m| = \max |u_j| \neq 0$$
. Using $(\lambda I - A)u = 0$,

$$(\lambda - a_{mm})u_m + \sum_{i \neq m} (-a_{mi})u_i = 0$$

$$\Rightarrow |\lambda - a_{mm}| \bullet |u_m| \le \left| \sum_{j \ne m} a_{mj} u_j \right| \le \sum_{j \ne m} |a_{mj}| \bullet |u_m|$$

$$\Rightarrow |\lambda - a_{mm}| \le \sum_{j \ne m} |a_{mj}|$$
, as wished.

Comment

Since A and A^{T} have the same eigenvalues, all eigenvalues

of
$$A = [a_{ij}]_{n \times n}$$
 are also located in the union

of
$$n$$
 discs $\bigcup_{j=1}^n \left\{ z \in \mathbb{C} : \left| z - a_{jj} \right| \le \sum_{i=1, i \ne j}^n \left| a_{ij} \right| \right\} \triangleq G(A^T).$

Clearly, all eigenvalues of any matrix A are inside

$$G(A)\bigcap G(A^T)$$
.

Example

By means of this theorem, we can give an estimate of all eigenvalues (when the exact values are not easy to obtain). For example,

$$A = \begin{pmatrix} 0 & 1 & -1 \\ 1.3 & 2 & -0.7 \\ 0.5 & 0.5i & 4i \end{pmatrix}.$$

Let
$$A = (a_{ij})_{n \times n}$$
. Show that

$$\left|\det A\right|^2 \leq \prod_{i=1}^n \left(\sum_{j=1}^n \left|a_{ij}\right|\right)^2.$$

When does the equality hold?

Assume
$$B = (b_{ij})_{n \times n}$$
 satisfies

$$|b_{ii}| > \sum_{j=1, j\neq i}^{n} |b_{ij}|$$
, for all $i = 1, \dots, n$.

Show that $\det B \neq 0$.

Consider the matrix

$$A = \begin{pmatrix} 7 & -16 & 8 \\ -16 & 7 & -8 \\ 8 & -8 & -5 \end{pmatrix}$$

- 1) Use the Geršgorin theorem to say as much as you can about the location of the eigenvalues of *A* and its spectral radius.
- 2) Then, consider $D^{-1}AD$, with $D = diag(p_1, p_2, p_3) > 0$.

Can you obtain any improvement in your location of the eigenvalues via appropriate choice of parameters p_i .

Homework 8

1. If λ_n is the least eigenvalue of a Hermitian

matrix
$$H$$
, show that $\lambda_n = \min_{x \neq 0} \frac{\langle Hx, x \rangle}{\langle x, x \rangle}$.

2. Find all possible values of μ guaranteeing the positive-definiteness of

$$H = \begin{pmatrix} 1 & 2 & 3 \\ 2 & \mu & 4 \\ 3 & 4 & 5 \end{pmatrix}.$$

Homework 8

3. Show that $|x| = \max_{k} |x_{k}|$, denoted as $|x|_{\infty}$, and $|x| = \sum_{k} |x_{k}|$, denoted as $|x|_{1}$,

are both norms.

What are their associated matrix norms?