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**ASSIGNED:** Jan. 24, 2013. **READ:** Sects. 2.5 & 3.1-3.3 on z-transforms.

**DUE DATE:** Jan. 31, 2013. **TOPICS:** LTI systems and convolution.

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Please box your answers. Show your work. Turn in all Matlab plots and Matlab code.

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- [30] 1. An ideal digital *differentiator* is implemented as follows:

$$x(t) \rightarrow \boxed{\text{ANTI-ALIAS}} \rightarrow \boxed{\text{A/D}} \rightarrow x[n] \rightarrow \boxed{h[n]} \rightarrow y[n] \rightarrow \boxed{\text{D/A}} \rightarrow y(t)$$

**where:**  $y[n] = (x[n+1] - x[n-1]) - \frac{1}{2}(x[n+2] - x[n-2]) + \frac{1}{3}(x[n+3] - x[n-3]) + \dots$

[5] (a) Is the system LTI? [5] (b) Is it causal? [5] (c) Read off its impulse response  $h[n]$ .

[5] (d) Prove that this system is *not* BIBO stable. HINT:  $\sum_{n=1}^{\infty} \frac{1}{n}$  diverges.

[10] (e) Give a bounded input  $x[n]$  that produces an unbounded output  $y[n]$ . HINT:  $h[n]$ .

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- [20] 2. Compute the following convolutions *by hand*. You may check answers using `conv`.

[5] (a)  $\{3, 4, 5\} * \{6, 7, 8\}$ . [5] (b)  $\{1, 2, -3\} * u[n]$ .

[5] (c)  $\{3, 4, 5\} * (u[n] - u[n-3])$ . [5] (d)  $\{1, 2, 4\} * 2\delta[n-2]$ .

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- [20] 3. The following two input-output pairs are observed for a system known to be linear:

$$\{1, 2, 3\} \rightarrow \boxed{\text{LINEAR}} \rightarrow \{1, 4, 7, 6\} \text{ and } \delta[n] \rightarrow \boxed{\text{LINEAR}} \rightarrow \{1, 3\}.$$

[10] (a) Prove the system is *not* time-invariant. HINT: Prove this by contradiction.

[10] (b) We observe  $\{1, 2, 3\} \rightarrow \{1, 4, 7, 6\}$  for a system known to be LTI. Compute  $h[n]$ .

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- [10] 4. The AR difference equation  $y[n] - y[n-1] - y[n-2] = x[n]$  with input  $x[n] = \delta[n]$  = impulse generates the sequence of *Fibonacci numbers*. Compute the first 7 Fibonacci numbers:

[5] (a) By recursively computing  $y[0], y[1] \dots y[6]$  directly from the difference equation.

[5] (b) Using `Y=filter(B,A,X); Y(1:7)` with `B=[1]; A=[1 -1 -1]; X=[1 zeros(1,6)]`;  
Tape a printout of your Matlab output (only a couple of lines) to your submission.  
In general, `filter(B,[1],X)` gives the first `length(X)` numbers of `conv(B,X)`.

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- [20] 5. Download `p2.mat` from the web site. `>>load p2.mat` to get the sampled signal `X`.

[5] (a) Listen to `X` using `soundsc(X,24000)`. Describe it. (It's not the same as before.)

[5] (b) Plot the spectrum of `X` using the Matlab command from problem set #1.

How does it differ from the spectrum you computed in problem set #1?

[5] (c) *Filter* `X` using `Y=conv(X,H)`. Listen to `Y` and describe it.

Here `H=[0.005 0 -0.042 0 0.29 0.5 0.29 0 -0.042 0 0.005]`.

[5] (d) Plot the spectrum of `Y` using the Matlab command from problem set #1.

Explain what the convolution did to the noise that was added to `X`.

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“Chance favors the prepared mind”-Louis Pasteur.

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