

# EECS351 Discussion 8 Problems, 11/10/16

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## 1 System Diagrams

Consider the following Transfer Function:

$$H(z) = 8 + \frac{-7+8z^{-1}}{1-.75z^{-1}+.125z^{-2}}$$

Note:

- (a) Find the LCCDE (difference equation)  $y[n]$  in terms of shifted  $y[n]$  and shifted  $x[n]$ .
- (b) Draw the system diagram for the difference equation you found in part (a)

## 2 Properties of ROC

Consider a signal  $x[n]$ , which has the following z-transform:

$$X(z) = \frac{2z(z-\frac{1}{12})}{(z-\frac{1}{2})(z+\frac{1}{3})}$$

$$|z| > 1/2$$

- (a) Determine the partial fraction expansion of  $X(z)$
- (b) Sketch the ROC for  $X(z)$ . Based on your sketch, does the DTFT for  $x[n]$  exist? Is  $x[n]$  right sided, left sided or neither? Is  $x[n]$  causal?
- (c) Find  $x[n]$  using the inverse z-transform. Based on your answer for  $x[n]$ : Is  $x[n]$  right sided, left sided or neither? Is  $x[n]$  causal?

## 3 Z-transform

Determine the inverse z-transform for the following:

$$X(z) = \log(1 + \alpha z^{-1})$$

$$|z| > |\alpha|$$

$$\text{HINT: } nx[n] \longleftrightarrow -z \frac{dX(z)}{dz}$$

## 4 2D Basis

Recall in 1D, the standard (canonical) basis for  $\mathbb{R}^2$  :

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

In 2D, the standard basis for  $\mathbb{R}^{2 \times 2}$  :

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Similarly to  $\mathbb{R}^2$ , we can show the standard basis is valid by showing:

$$\alpha_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \alpha_2 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + \alpha_3 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + \alpha_4 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Implies  $\alpha_1 = \alpha_2 = \alpha_3 = \alpha_4 = 0$

We could also show that a linear combination of basis matrices form the standard basis.

## 5 2D Basis Question

(a) Show

$$\begin{bmatrix} -1 & -2 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ -3 & -3 \end{bmatrix}, \begin{bmatrix} -1 & -1 \\ -1 & -2 \end{bmatrix}$$

is not a valid basis for  $\mathbb{R}^{2 \times 2}$

## 2D Basis Question continued

(b) Consider the following four matrices:

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Show the canonical (standard) basis can be formed as a linear combination of the above matrices.

(c) Consider the following matrix:

$$\begin{bmatrix} 1296 & 4899 \\ 3516 & 0135 \end{bmatrix}$$

Can this matrix be expressed as a linear combination of the matrices from part (b)?