

EECS351 Discussion 8 Problems, 11/10/16

Nate Sawicki

Select problems by Mai Le and Kevin Moon

1 System Diagrams

Consider the following Transfer Function:

$$H(z) = 8 + \frac{-7+8z^{-1}}{1-.75z^{-1}+.125z^{-2}}$$

Note:

- (a) Find the LCCDE (difference equation) $y[n]$ in terms of shifted $y[n]$ and shifted $x[n]$.
- (b) Draw the system diagram for the difference equation you found in part (a)

2 Properties of ROC

Consider a signal $x[n]$, which has the following z-transform:

$$X(z) = \frac{2z(z-\frac{1}{12})}{(z-\frac{1}{2})(z+\frac{1}{3})}$$

- (a) Determine the partial fraction expansion of $X(z)$
- (b) Sketch the ROC for $X(z)$. Based on your sketch, does the DTFT for $x[n]$ exist? Is $x[n]$ right sided, left sided or neither? Is $x[n]$ causal?
- (c) Find $x[n]$ using the inverse z-transform. Based on your answer for $x[n]$: Is $x[n]$ right sided, left sided or neither? Is $x[n]$ causal?

3 Z-transform

Determine the inverse z-transform for the following:

$$X(z) = \log(1 + \alpha z^{-1})$$

$$\text{HINT: } nx[n] \longleftrightarrow -z \frac{dX(z)}{dz}$$

4 2D Basis

Recall in 1D, the standard (canonical) basis for \mathbb{R}^2 :

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

In 2D, the standard basis for $\mathbb{R}^{2 \times 2}$:

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Similarly to \mathbb{R}^2 , we can show the standard basis is valid by showing:

$$\alpha_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \alpha_2 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + \alpha_3 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + \alpha_4 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Implies $\alpha_1 = \alpha_2 = \alpha_3 = \alpha_4 = 0$

We could also show that a linear combination of basis matrices form the standard basis.

5 2D Basis Question

(a) Show

$$\begin{bmatrix} -1 & -2 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ -3 & -3 \end{bmatrix}, \begin{bmatrix} -1 & -1 \\ -1 & -2 \end{bmatrix}$$

is not a valid basis for $\mathbb{R}^{2 \times 2}$

2D Basis Question continued

(b) Consider the following four matrices:

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Show the canonical (standard) basis can be formed as a linear combination of the above matrices.

(c) Consider the following matrix:

$$\begin{bmatrix} 1296 & 4899 \\ 3516 & 0135 \end{bmatrix}$$

Can this matrix be expressed as a linear combination of the matrices from part (b)?