1 Instruction

1.1 Definiton of Instruction

Define instruction s

$$instruction \ s :=$$

$$(s \equiv function) \oplus (s \equiv operation)$$

2 Instruction Set

2.1 Definiton of Instruction Set

Define \mathcal{I} ; an ordered set of computational instructions s_i

$$\mathcal{I} := \{s_1, s_2, ..., s_N\}$$

2.2 Abstraction Notation

Define \mathcal{I} ; an ordered set of computational instructions s_i

"Instruction Set":=
$$\mathcal{I}$$
:

$$(\mathcal{I} \equiv \mathrm{Set}) \wedge (s_i \equiv \mathrm{instruction} \ \forall s_i \in \mathcal{I})$$

3 Memory

3.1 Definiton of Memory

$$memory \ m :=$$

$$m \in \Omega$$

3.2 Definition of Memory Set

Define Memory \mathcal{M} ; an ordered set of objects m_i

$$\mathcal{M} := \{m_1, m_2, ..., m_M\}$$

3.3 Abstraction Notation

Define Memory \mathcal{M} ; an ordered set of either bools numbers or objects m_i

"Memory Set" :=
$$\mathcal{M}$$
:

$$(\mathcal{M} \equiv Set) \wedge (m_i \equiv object \ \forall m_i \in \mathcal{M})$$

4 Program

4.1 Definition of a Program

Define program \mathcal{P} ; a tensor of instructions and memory

$$\mathcal{P} := \{\{s_1, s_2, ..., s_N\}, \{m_1, m_2, ..., m_M\}\}$$

$$= \langle \mathcal{I}, \mathcal{M} \rangle$$

4.2 Abstraction Notation

Define a method \mathcal{P} ; a tensor of instructions and memory

$$\label{eq:Method} \begin{split} \text{"Method"} &:= \mathcal{P}: \\ (\mathcal{P} \equiv \mathrm{Tensor}) \, \wedge \, (\mathcal{P} \supseteq \mathcal{I}) \, \wedge \, (\mathcal{P} \supseteq \mathcal{M}) \end{split}$$

4.3 State Variable Notation

It is convention to use | to separate instructions and memory

$$\mathcal{P} := \{ \{s_1, s_2, ..., s_N\}, \{m_1, m_2, ..., m_M\} \}$$

$$= \{s_1, s_2, ..., s_N | m_1, m_2, ..., m_M \}$$

$$= \{ \mathcal{I} \mid \mathcal{M} \}$$

5 Boolean Methods

5.1 Definition of Boolean Methods

Define a boolean method; a method with inputs x_i and boolean output y

$$\begin{split} X_n &= \{x_1,...,x_n\} \ : \ x_i \in \Omega \ \, \forall x_i \in X_n \\ P_{boolean}[X_n] &:= \{s_1,s_2,...,s_N \mid y,b_2,...,b_M\} \to y \ : \ y \in \{\mathbb{T},\mathbb{F}\} \ \, \forall X_n \in \mathbb{D}_P \end{split}$$

5.2 Abstraction Notation

$$\label{eq:Boolean} \mbox{"Boolean Method"} := P_{boolean}[X_n] :$$

$$(P_{boolean}[X_n] \equiv \mbox{method}) \wedge (\exists \mathbb{D}_P : X_n \in \mathbb{D}_P \Leftrightarrow P_{boolean}[X_n] \to y \equiv bool)$$

5.3 Boolean Method Output

The output of a boolean method y is read as "the result"

$$P_{boolean}[X_n] \to y$$

"Boolean Method $P_{boolean}$ with input(s) X_n outputs result y"

6 True or False Questions

6.1 Definition of True or False Question

Define a True or False Question; a bounded boolean expression given input(s) X_n

 Given

$$X_n = \{x_1, x_2, ..., x_n\}$$

$$Q^{T/F} := Q[X_n] : Q[X_n] \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_n \in \mathbb{D}_Q$$

A True or False Question is sometimes read as a "decision question"

6.2 Abstraction Notation

Given

$$X_n = \{x_1, x_2, ..., x_n\}$$

"True or False Question":= $Q^{T/F}[X_n]$:

$$\exists \mathbb{D}_Q : (X_n \in \mathbb{D}_Q \Leftrightarrow Q^{T/F}[X_n] \equiv bool)$$

7 Approach to a True or False Question

?? Does ($\mathbb{D}_S == \mathbb{D}_Q$) or merely contained/bounded???

7.1 Definition of an Approach to a True or False Question

Given input(s) X_n and True or False Question $Q^{T/F}$; Define an approach to True or False Question $Q^{T/F}$; a boolean method bounded by the domain of $Q^{T/F}$

Given

$$X_n = \{x_1, x_2, ..., x_n\}$$
$$Q^{T/F}[X_n]$$

$$\begin{split} S_Q[X_n] := P_Q[X_n] &= \{s_1, s_2, ..., s_N \mid y, b_2, ..., b_M\} : \\ (P_Q[X_n] \to y) \wedge (y \in \{\mathbb{T}, \mathbb{F}\}) \quad \forall X_n \in \mathbb{D}_Q \end{split}$$

7.2 Abstraction Notation

Given

$$X_n = \{x_1, x_2, ..., x_n\}$$
$$Q^{T/F}[X_n]$$

"Approach to True or False Question Q":= $S_Q[X_n]$: $(S_Q[X_n] \equiv \equiv \text{boolean method}) \land (\mathbb{D}_S == \mathbb{D}_Q)$

Solution to a True or False Question

7.3 Definition of Solution to a True or False Question

Given input(s) X_n and True or False Question $Q^{T/F}$; Define a solution of True or False Question $Q^{T/F}$; an approach to $Q^{T/F}$ asserting output y is the answer for all input(s) in the domain of Q

Given

$$X_n = \{x_1, x_2, ..., x_n\}$$
$$Q = Q^{T/F}[X_n]$$

$$S_Q^+[X_n] := P_Q[X_n] = \{s_1, s_2, ..., s_N \mid y, b_2, ..., b_M\} :$$

 $(P_Q[X_n] \to y) \land (y == a) \quad \forall X_n \in \mathbb{D}_Q$

7.4 Abstraction Notation

Given

$$X_n = \{x_1, x_2, ..., x_n\}$$
$$Q = Q^{T/F}[X_n]$$

"Solution to True or False Question Q":= $S_Q^+[X_n]$: $(S_Q^+[X_n] \equiv \equiv \text{approach to a True or False Question Q}) \land (S_Q^+[X_n].output == |Q^{T/F}[X_n]|)$

Incomplete Solution to a True or False Question

- 7.5 Definition of Incomplete Solution to a True or False Question
- 7.6 Abstraction Notation

8 Complexity of a Method

8.1 Definition of a Method's Complexity

Given

$$\mathcal{P} = \{s_1, s_2, ..., s_N \mid y, b_2, ..., b_M\}$$

$$\mathbf{O}_{\mathcal{P}} := < |\{s_1, s_2, ..., s_N\}|, |\{y, b_2, ..., b_M\}| >$$

= $< |\mathcal{I}|, |\mathcal{M}| > = < N, M >$

8.2 Abstraction Notation

"Method" :=
$$\mathcal{P}$$
:

$$(\mathcal{P} \equiv \mathrm{Tensor}) \wedge (\mathcal{P} \supseteq \mathcal{I}) \wedge (\mathcal{P} \supseteq \mathcal{M})$$

1. By definition

$$\mathcal{P} \equiv \mathrm{tensor}$$

2. By inheritence of Tensor

$$\mathcal{P} \cong \text{size}$$

≘is read as "has the attribute of"

3. Therefore size of \mathcal{P} is defined

$$\therefore |\mathcal{P}| := <|S_1|, |S_2|, \dots >$$

4. By definition

$$(\mathcal{P} \supseteq \mathcal{I}) \wedge (\mathcal{P} \supseteq \mathcal{M})$$

5. Let

$$|\mathcal{P}| = \mathbf{O}_P = \text{"Complexity of Method } \mathcal{P}$$
"

6. By 3, 4, and 5

"Complexity of Method \mathcal{P} " = $\mathbf{O}_P := <|\mathcal{I}|, |\mathcal{M}| >$

7. By definition of \mathcal{I}, \mathcal{M}

$$\mathcal{I} \equiv \operatorname{Set} \wedge \mathcal{M} \equiv \operatorname{Set}$$

8. By inheritance of Sets

$$\mathcal{I} \ extstyle \ ext{count} \ \wedge \ \mathcal{M} \ extstyle \ ext{count}$$

9. Therefore count of $\mathcal I$ and $\mathcal M$ is defined; by definition of $\mathcal I$ and $\mathcal M$

$$\therefore |\mathcal{I}| = |\{s_1, s_2, ..., s_N\}| := N; |\mathcal{M}| = \{y, b_2, ..., b_M\} := M$$

10. By 6 and 9

"Complexity of Method
$$\mathcal{P}$$
" = $\mathbf{O}_P := \langle |\mathcal{I}|, |\mathcal{M}| \rangle = \langle N, M \rangle$

9 Total Complexity of a Method

10 Simple Computational Complexity

The remainder of this document assumes simple computational complexity of dimension 2

10.1 Definition

Define simple computational complexity of dimension 2

$$\mathbf{O}[n] := \langle O_T[n], O_S[n] \rangle$$

10.2 Total Complexity

Define Total Complexity of solution s^+

$$O[n] := |s^{+}[X_n]| = |\{\mathcal{L}, \mathcal{M}, y_o\}|$$

= $|\mathcal{L}| + |\mathcal{M}| + |y_o| = N + M + 1$

10.3 Time Complexity

Restate definition of Time Complexity $O_T[n]$ of solution s^+

$$s^{+} = \{\mathcal{L}, \mathcal{M}, y_{o}\}$$
$$O_{T}[n] := |\mathcal{L}| = N$$

10.4 Space Complexity

Restate definition of Time Complexity $O_S[n]$ of solution s^+

$$s^{+} = \{\mathcal{L}, \mathcal{M}, y_{o}\}$$
$$O_{S}[n] := |\mathcal{M}| + |y_{o}| = M + 1$$

10.5 Total Complexity as a Function of Time and Space Complexity

$$O[n] := |s^{+}[X_n]| = |\{\mathcal{L}, \mathcal{M}, y_o\}|$$
$$= |\mathcal{L}| + |\mathcal{M}| + |y_o|$$
$$= O_T[n] + O_S[n]$$

10.6 $O_S[n] > 0^*$

Assuming Program is not void

10.6.1 Proof

Assume $O_S[n] = 0$

$$O_S[n] := |\mathcal{M}| + |y_o|$$

$$O_S[n] = 0 \Rightarrow \mathcal{M} = y_o = \emptyset$$

$$y_o = \emptyset; \ y_o \in \{\mathbb{T}, \mathbb{F}\} \text{ by definition of } s^+$$

 $O_S[n] = 0$ contradicts the definition of solution s^+ of a decision problem $O_S[n] \ge 0$ by definition of magnitude

$$\therefore O_S[n] > 0$$

10.7
$$O_T[n] > 0^*$$

Assuming Program is not void

10.7.1 Proof

Assume $O_T[n] = 0$

$$\begin{split} O_T[n] := |\mathcal{L}| \\ O_T[n] = 0 \Rightarrow y_o \notin \{\mathbb{T}, \mathbb{F}\} \\ y_o \notin \{\mathbb{T}, \mathbb{F}\}; \ y_o \in \{\mathbb{T}, \mathbb{F}\} \text{ by definition of } s^+ \end{split}$$

 $\therefore O_T[n] = 0$ contradicts the definition of solution s^+ of a decision problem

$$O_T[n] \geqslant 0$$
 by definition of magnitude
 $\therefore O_T[n] > 0$

10.8
$$O[n] > 0^*$$

Assuming Program is not void

10.8.1 **Proof**

$$O[n] := O_T[n] + O_S[n]$$

$$O_T[n] > 0; O_S[n] > 0$$

$$\therefore O[n] > 0$$

10.9 $O[n] > O_T[n] *$

Assuming Program is not void

10.9.1 **Proof**

$$O[n] := O_T[n] + O_S[n]$$
$$O_S[n] > 0$$
$$\therefore O[n] > O_T[n]$$

10.10 $O[n] > O_S[n]^*$

Assuming Program is not void

10.10.1 Proof

$$O[n] := O_T[n] + O_S[n]$$

$$O_T[n] > 0$$

$$\therefore O[n] > O_S[n]$$

10.11
$$O[n+1] \geqslant O[n]$$

10.11.1 Proof

$$X_i = \{x_1, ..., x_n, C\}; \quad \hat{X}_i = \{x_1, ..., x_{n+1}, C\}$$

$$O[n] = |s^+[X_i]|$$

$$O[n+1] = \hat{O}[n] = |s^+[\hat{X}_i]|$$

For general solutions s^+

$$s^{+}[\hat{X}_{i}] \supseteq s^{+}[X_{i}]$$

$$\Rightarrow |s^{+}[\hat{X}_{i}]| \geqslant |s^{+}[X_{i}]|$$

$$\therefore \hat{O}[n] = O[n+1] \geqslant O[n]$$

11 Definition of Problem

Define Problem (also denoted as Question); a function with input(s) X_n and "answer" Y

$$X_n = \{x_1, ..., x_n\}$$

11.1 Set of Questions

Define \mathbb{Q} ; the set of questions

$$\mathbb{Q} := \{Q_1, Q_2, \dots\} :$$

$$Q_i = f[X_j] = Y_o \subseteq \Omega \ \forall X_j, i$$

11.2 Decision Questions / Decision Problems

11.2.1 Definition

Define decision problem; a function with inputs x_i and boolean output "answer" a_o

$$X_i = \{x_1, ..., x_n\}$$
$$D := f[X_i] = a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

11.3 Numerical Questions / Numerical Problems

11.3.1 Definition

Define numerical problem; a function with inputs x_i and numerical output y_o

$$X_i = \{x_1, ..., x_n\}$$
$$Q := f[X_i] = y_o \in \mathbb{R} \quad \forall X_i$$

11.4 System Questions / System Problems

11.4.1 Definition

Define system problem; a function with inputs x_i and outputs y_j

$$X_i = \{x_1, ..., x_n\}$$

 $Q := f[X_i] = Y_o = \{y_1, ..., y_m\} \quad \forall X_i$

12 Solutions

12.1 Definition

Program P is a solution s^+ to decision problem D if

- 1. P outputs answer a_o for all inputs $X_i \ \forall i$ and
- 2. $s^+[X_i]$ is a subset of $s^+[\hat{X}_i]$

$$X_{i} = \{x_{1}, ..., x_{n}, C\}; \quad \hat{X}_{i} = \{x_{1}, ..., x_{n}, x_{n+1}, C\}$$

$$D := f[X_{i}] \rightarrow a_{o} \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_{i}$$

$$s^{+} = s^{+}[X_{i}] := P :$$

$$(P[X_{i}] \rightarrow y_{o} == a_{o} \quad \forall X_{i}) \quad \cap \quad (P[\hat{X}_{i}] \supseteq P[X_{i}] \quad \forall X_{i}, \hat{X}_{i})$$

$$P[X_{i}] = \{s_{1}, s_{2}, ..., s_{N} | b_{1}, b_{2}, ..., b_{M}, y_{o}\}$$

$$s^{+} = P[X_{i}] = \{s_{1}, s_{2}, ..., s_{O_{T}[n]}, b_{1}, b_{2}, ..., b_{O_{S}[n]}, y_{o}\} \quad \forall X_{i}$$

12.1.1 Property of No-op;

No-op; can be added to any solution S_i without modifying the output y_o or memory b_i

$$\begin{split} & ; := \varnothing \\ s^+ = \{s_1, s_2, ..., s_{O_T[n]}, b_1, b_2, ..., b_{O_S[n]}, y_o\} \\ \hat{s}^+ = \{s_1, s_2, ..., \ ; \ , ..., s_{O_T[n]+1}, \hat{b}_1, \hat{b}_2, ..., \hat{b}_{O_S[n]}, \hat{y}_o\} \\ & \hat{y}_o = y_o \ \, \forall k \end{split}$$

12.2 Definition of S^+

Define S^+ ; the set of solutions to decision problem D

$$X_{i} = \{x_{1}, ..., x_{n}, C\}; \quad \hat{X}_{i} = \{x_{1}, ..., x_{n}, x_{n+1}, C\}$$

$$D := f[X_{i}] \rightarrow a_{o} \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_{i}$$

$$s_{j}^{+} = s_{j}^{+}[X_{i}] := P :$$

$$(P[X_{i}] \rightarrow y_{o} == a_{o} \quad \forall X_{i}) \quad \cap \quad (P[\hat{X}_{i}] \supseteq P[X_{i}] \quad \forall X_{i}, \hat{X}_{i})$$

$$S^{+} := \{s_{j}^{+}, ...\} \quad \forall j$$

12.3 Definition of Solvable

Define solvable

$$X_{i} = \{x_{1}, ..., x_{n}, C\}; \quad \hat{X}_{i} = \{x_{1}, ..., x_{n}, x_{n+1}, C\}$$

$$D := f[X_{i}] \rightarrow a_{o} \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_{i}$$

$$solvable = solvable[D] = b_{o} \in \{\mathbb{T}, \mathbb{F}\} :=$$

$$\exists P : (P[X_{i}] \rightarrow y_{o} == a_{o} \quad \forall X_{i}) \quad \cap \quad (P[\hat{X}_{i}] \supseteq P[X_{i}] \quad \forall X_{i}, \hat{X}_{i})$$

13 The set of all Decision Problems \mathbb{D}

13.1 Definition

Define the set of decision problems \mathbb{D}

$$X_i = \{x_1, ..., x_n, C\}$$

$$D_j := f_j[X_i] \to a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

$$\mathbb{D} := \{D_j, ...\} \quad \forall j$$

14 Complexity

14.1 Time Complexity of a Decision Problem $O_T[n]$

Define Time Complexity $O_T[n]$ of solution s^+ to Decision Problem D as the total number of logical operations

$$X_{i} = \{x_{1}, ..., x_{n}, C\}; \quad \hat{X}_{i} = \{x_{1}, ..., x_{n+1}, C\}$$

$$D := f[X_{i}] \rightarrow a_{o} \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_{i}$$

$$s^{+}[X_{i}] := P :$$

$$(P[X_{i}] \rightarrow y_{o} == a_{o} \quad \forall X_{i}) \quad \cap \quad (P[\hat{X}_{i}] \supseteq P[X_{i}] \quad \forall X_{i}, \hat{X}_{i})$$

$$s^{+} = \{s_{1}, s_{2}, ..., s_{N} | b_{1}, b_{2}, ..., b_{M}, y_{o}\} = \{s_{1}, s_{2}, ..., s_{O_{T}[n]}, b_{1}, b_{2}, ..., b_{O_{S}[n]}, y_{o}\}$$

$$= \{\mathcal{L}, \mathcal{M}, y_{o}\}$$

$$O_{T}[n] := |\mathcal{L}| = N$$

14.2 Space Complexity $O_S[n]$

Define Space Complexity $O_S[n]$ of solution s^+ to Decision Problem D as the total number of memory elements

$$X_{i} = \{x_{1}, ..., x_{n}, C\}; \quad \hat{X}_{i} = \{x_{1}, ..., x_{n+1}, C\}$$

$$D := f[X_{i}] \rightarrow a_{o} \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_{i}$$

$$s^{+}[X_{i}] := P :$$

$$(P[X_{i}] \rightarrow y_{o} == a_{o} \quad \forall X_{i}) \quad \cap \quad (P[\hat{X}_{i}] \supseteq P[X_{i}] \quad \forall X_{i}, \hat{X}_{i})$$

$$s^{+} = \{s_{1}, s_{2}, ..., s_{N} | b_{1}, b_{2}, ..., b_{M}, y_{o}\} = \{s_{1}, s_{2}, ..., s_{O_{T}[n]}, b_{1}, b_{2}, ..., b_{O_{S}[n]}, y_{o}\}$$

$$= \{\mathcal{L}, \mathcal{M}, y_{o}\}$$

$$O_{S}[n] := |\mathcal{M}| + |y_{o}|^{*} = M + 1$$

*It is convention to reserve one memory element for output y_o . Void programs do not require the y_o memory element for output

15 Definition of Complexity

Define Complexity O[n] as a vector of dimension V

$$\mathbf{O}[n] := \langle O_T[n], O_S[n], O_3[n], O_4[n], ..., O_V[n] \rangle$$

16 Complexity of Canonical Instructions

$$c := a \leftarrow l[X_n]$$

17 Complexity of Computational Operations

17.1 +

Express the bounds of complexity for Computational Operation +

18 Inductive Functions

18.1 Inductive Function f_{n+1}

$$O[n] = O_T[n] + O_S[n]$$

$$O[n+1] = O_T[n+1] + O_S[n+1]$$

$$f_{n+1}[n] := O[n+1] - O[n]$$

18.2 Inductive Space and Time Formulas

$$f_{n+1}^{T}[n] := O_{T}[n+1] - O_{T}[n]$$

$$O_{T}[n+1] = O_{T}[n] + f_{n+1}^{T}[n]$$

$$f_{n+1}^{S}[n] := O_{S}[n+1] - O_{S}[n]$$

$$O_{S}[n+1] = O_{S}[n] + f_{n+1}^{S}[n]$$

18.3 Inductive Function Expressions

Relate $f_{n+1}[n]$ to equivalence functions

$$O[n] = O_T[n] + O_S[n]$$

$$O[n+1] = O_T[n+1] + O_S[n+1] = O[n] + f_{n+1}[n]$$

$$O_T[n] = O[n] - O_S[n]$$

$$O_S[n] = O[n] - O_T[n]$$

$$f_{n+1}[n] = O[n+1] - O[n]$$

$$f_{n+1}[n] = O_T[n+1] + O_S[n+1] - O[n]$$

$$f_{n+1}[n] = O_T[n+1] - O_T[n] + O_S[n+1] - O_S[n]$$

$$f_{n+1}[n] = O[n+1] - O_T[n] - O_S[n]$$

$$f_{n+1}[n] = f_{n+1}^T[n] + f_{n+1}^S[n]$$

18.4 Zero Order Space Inductive Function

Let
$$O_S[n] \sim n^0$$

 $f_{n+1}[n] = O_T[n+1] - O_T[n] + O_S[n+1] - O_S[n] = O_T[n+1] - O_T[n]$

19 Polynomial Complexity

19.1 Definition

Decision problem D with solution s^+ has polynomial total complexity O[n] if

$$\exists K, C, \lambda_1 ... \lambda_K :$$

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} ... + \lambda_1 n + C \quad \forall n$$

19.2 Polynomial Problems

Define \mathbb{P} , the set of Decision Problems that can be solved with Polynomial Complexity

$$\mathbb{P}:=\{D_1,D_2,\ldots\}:$$

$$\exists K,C,\lambda_1...\lambda_K:$$

$$O[n]=(\lambda_K n)^K+(\lambda_{K-1} n)^{K-1}...+\lambda_1 n+C \quad \forall n,D_i\in\mathbb{P}$$

19.3 Polynomial Order of Complexity

Solution s^+ with total complexity O[n] is said to be of order n^K

$$O[n] \sim n^K$$

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

19.4 Property of Polynomial Complexity 1

Solutions with polynomial complexity have convergent complexity

$$\lim_{n\to\infty} \frac{O[n+1]}{O[n]} = 1$$

19.4.1 Proof

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C$$

$$O[n+1] = (\lambda_K (n+1))^K + (\lambda_{K-1} (n+1))^{K-1} \dots + \lambda_1 (n+1) + C$$

$$= (\lambda_K n)^K + (\tilde{\lambda}_{K-1} n)^{K-1} \dots + \tilde{\lambda_1} n + \tilde{C}$$

$$\lim_{n \to \infty} \frac{O[n+1]}{O[n]}$$

$$= \lim_{n \to \infty} \frac{(\lambda_K n)^K + (\tilde{\lambda}_{K-1} n)^{K-1} \dots + \tilde{\lambda_1} n + \tilde{C}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + \tilde{C}}$$

$$\begin{split} = \lim_{n \to \infty} & \frac{(\lambda_K n)^K}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} + \frac{(\tilde{\lambda}_{K-1} n)^{K-1}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} + \dots + \\ & \frac{\tilde{\lambda}_1 n}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} + \frac{\tilde{C}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} \\ & = 1 = \lim_{n \to \infty} \frac{O[n+1]}{O[n]} \end{split}$$

19.5 Property of Polynomial Complexity 2

$$\exists K, \hat{C}, \hat{\lambda}_1, ..., \hat{\lambda}_{K-1}:$$

$$O[n+1] - O[n] = f_{n+1}[n] = (\hat{\lambda}_{K-1}n)^{K-1}... + \hat{\lambda}_1 n + \hat{C} \quad \forall n$$

19.5.1 Proof

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C$$

$$O[n+1] = (\lambda_K (n+1))^K + (\lambda_{K-1} (n+1))^{K-1} \dots + \lambda_1 (n+1) + C$$

$$= (\lambda_K n)^K + (\tilde{\lambda}_{K-1} n)^{K-1} \dots + \tilde{\lambda}_1 n + \tilde{C}$$

$$O[n+1] - O[n] = ((\tilde{\lambda}_{K-1} - \lambda_{K-1}) n)^{K-1} \dots + (\tilde{\lambda}_1 - \lambda_1) n + (\tilde{C} - C)$$

$$O[n+1] - O[n] = (\hat{\lambda}_{K-1} n)^{K-1} \dots + \hat{\lambda}_1 n + \hat{C}$$

19.6 Property of Polynomial Complexity 3

$$limit_{n\to\infty} \frac{f_{n+1}[n]}{O[n]} = 0$$

19.6.1 Proof

$$limit_{n\to\infty} \frac{O[n+1]}{O[n]} = 1$$

$$limit_{n\to\infty} \frac{O[n] + f_{n+1}[n]}{O[n]} = 1$$

$$limit_{n\to\infty} \frac{O[n]}{O[n]} + \frac{f_{n+1}[n]}{O[n]} = 1$$

$$limit_{n\to\infty} 1 + \frac{f_{n+1}[n]}{O[n]} = 1$$

$$limit_{n\to\infty} \frac{f_{n+1}[n]}{O[n]} = 0$$

19.7 Total Polynomial Complexity Implies Time bounded Polynomial Complexity

$$D \in \mathbb{P} \Longrightarrow O_T[n] < (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C$$

19.7.1 Proof

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \ \forall n$$

$$O[n] := O_T[n] + O_S[n]; \ O_S[n] > 0$$

$$\therefore O_T[n] < (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \ \forall n$$

19.8 Total Polynomial Complexity Implies Space bounded Polynomial Complexity

$$D \in \mathbb{P} \Longrightarrow O_S[n] < (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C$$

19.8.1 Proof

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} ... + \lambda_1 n + C \ \forall n$$

$$O[n] := O_T[n] + O_S[n]; \ O_T[n] > 0$$

$$\therefore O_S[n] < (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} ... + \lambda_1 n + C \ \forall n$$

19.9 Polynomial Complexity in Space and Time Implies Polynomial Total Complexity

$$(O_S[n] == (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + \lambda_0)$$

$$\wedge$$

$$(O_T[n] == (\hat{\lambda}_M n)^M + (\hat{\lambda}_{M-1} n)^{M-1} \dots + \hat{\lambda}_1 n + \hat{\lambda}_0)$$

$$\Rightarrow D \in \mathbb{P}$$

19.9.1 Proof

$$O_S[n] = \lambda_K n^K + \lambda_{K-1} n^{K-1} + \dots + \lambda_1 n + \lambda_0$$

$$O_T[n] = \hat{\lambda}_M n^M + \hat{\lambda}_{M-1} n^{M-1} + \dots + \hat{\lambda}_1 n + \hat{\lambda}_0$$

$$O[n] = O_S[n] + O_T[n]$$

$$^*O[n] = (\hat{\lambda}_0 + \lambda_0) + n(\lambda_1 + \hat{\lambda}_1) + \dots + n^K (\lambda_K + \hat{\lambda}_K) + \hat{\lambda}_{K+1} n^{K+1} + \dots + \hat{\lambda}_M n^M$$

$$\therefore O[n] \text{ has polynomial total complexity by definition}$$

* Assume K < M, similar proof for K=M, K>M

20 Non-Polynomial Complexity

20.1 Definition

Decision problem \tilde{D} with solution s^+ has non-polynomial total complexity O[n] if

20.2 Non-Polynomial Problems

Define \mathcal{N} , the set of Decision Problems that cannot be solved with Polynomial Complexity

20.3 \mathbb{P} and \mathcal{N} are disjoint

$$\mathbb{P} \cap \mathcal{N} = \emptyset$$

20.3.1 Proof

Let $D \in \mathcal{N}$

$$\sharp K, C, \lambda_1 ... \lambda_K :$$

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} ... + \lambda_1 n + C \quad \forall n$$

Assume $D \in \mathbb{P}$

$$\exists K, C, \lambda_1 ... \lambda_K :$$

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} ... + \lambda_1 n + C \quad \forall n$$
Contradicts the definition of \mathcal{N}

$$\therefore D \in \mathcal{N} \Rightarrow D \notin \mathbb{P}$$

Let $D \in \mathbb{P}$

$$\exists K, C, \lambda_1 ... \lambda_K :$$

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} ... + \lambda_1 n + C \quad \forall n$$

Assume $D \in \mathcal{N}$

$$\sharp K, C, \lambda_1 ... \lambda_K :$$

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} ... + \lambda_1 n + C \quad \forall n$$
 Contradicts the definition of $\mathbb P$

$$\therefore D \in \mathbb{P} \Rightarrow D \notin \mathcal{N}$$

$$D \in \mathcal{N} \Rightarrow D \notin \mathbb{P}; D \in \mathbb{P} \Rightarrow D \notin \mathcal{N}$$
$$\therefore \mathbb{P} \cap \mathcal{N} = \emptyset$$

21 Discrete Derivative; Z Transform

21.1 Discrete Derivative

Define derivative for discrete function f[n]

$$\Delta_n^1 f[n] := f[n+1] - f[n]$$

We will use the above definition for the remainder of this document

21.2 Zero Order Derivative

$$\Delta_n^0 f[n] = f[n]$$

21.3 Kth Discrete Derivative

Define the K^{th} derivative of discrete function f[n]

$$\Delta_n^K f[n] := \Delta_n^{K-1} f[n+1] - \Delta_n^{K-1} f[n]$$

21.4 Kth Discrete Derivative as an Alternating Sum

$$\begin{split} \Delta_n^K f[n] &:= \Delta_n^{K-1} f[n+1] - \Delta_n^{K-1} f[n] \\ &= (\Delta_n^{K-2} f[n+2] - \Delta_n^{K-2} f[n+1]) - (\Delta_n^{K-2} f[n+1] - \Delta_n^{K-2} f[n]) \\ &= (\Delta_n^{K-2} f[n+2] - 2\Delta_n^{K-2} f[n+1] - \Delta_n^{K-2} f[n]) \\ &= \sum_{i=0}^K (-1)^j \left({}_K C_j\right) \Delta_n^0 f[n+j] \\ &= \sum_{i=0}^K (-1)^j \left({}_K C_j\right) f[n+j] \end{split}$$

21.5 Z Transform

Define the Z Transform for discrete function f[n]

$$\mathcal{Z}(f[n]) := \sum_{n=0}^{\infty} f[n]z^{-n}$$

21.6 Z Transform of 0 Order Derivative

$$\Delta_n^0 f[n] := f[n]$$

$$\mathcal{Z}(\Delta_n^0 f[n]) = \mathcal{Z}(f[n])$$

21.7 Z Transform of 1^{st} Derivative

$$\Delta_n^1 f[n] := f[n+1] - f[n]$$

$$\mathcal{Z}(\Delta_n^1 f[n]) = \mathcal{Z}(f[n+1] - f[n])$$

$$= \sum_{n=0}^{\infty} (f[n+1] - f[n]) z^{-n}$$

$$= \sum_{n=0}^{\infty} (f[n+1] z^{-n} - f[n] z^{-n})$$

$$= \sum_{n=0}^{\infty} f[n+1] z^{-n} - \sum_{n=0}^{\infty} f[n] z^{-n}$$

$$= \sum_{m=0}^{\infty} f[m+1] z^{-m} - \sum_{n=0}^{\infty} f[n] z^{-n}$$

Let

$$\hat{m} = m + 1; \quad m = \hat{m} - 1$$

$$= \sum_{m=0}^{\infty} f[\hat{m}] z^{-(\hat{m}-1)} - \mathcal{Z}(f[n])$$

$$= z^{1} \sum_{\hat{m}=1}^{\infty} f[\hat{m}] z^{-\hat{m}} - \mathcal{Z}(f[n])$$

$$\begin{split} &= z^1 \sum_{\hat{m}=1}^{\infty} f[\hat{m}] z^{-\hat{m}} + f[0] - f[0] - \mathcal{Z}(f[n]) \\ &= z^1 \sum_{\hat{m}=0}^{\infty} f[\hat{m}] z^{-\hat{m}} - f[0] - \mathcal{Z}(f[n]) \\ &= z^1 \mathcal{Z}(f[n]) - f[0] - \mathcal{Z}(f[n]) \\ &\mathcal{Z}(\Delta_n^1 f[n]) = \mathcal{Z}(f[n]) (z^1 - 1) - f[0] \end{split}$$

21.8 Z Transform of K^{th} Derivative

$$\begin{split} \mathcal{Z}(f[n]) &:= \sum_{n=0}^{\infty} f[n] z^{-n} \\ \mathcal{Z}(\Delta_n^K f[n]) &= \sum_{n=0}^{\infty} \Delta_n^K f[n] z^{-n} \\ &= \sum_{n=0}^{\infty} \sum_{i=0}^{K} (-1)^j \; (_K C_j) \; f[n+j] z^{-n} \\ &= \sum_{n=0}^{\infty} (f[n+K] - (_K C_1) f[n+K-1] + (_K C_2) f[n+K-2] - \ldots \pm f[n]) z^{-n} \\ &= \sum_{n=0}^{\infty} f[n+K] z^{-n} - (_K C_1) f[n+K-1] z^{-n} + (_K C_2) f[n+K-2] z^{-n} - \ldots \pm f[n] z^{-n} \\ &= z^K \mathcal{Z}(f[n]) + \sum_{i=0}^{K-1} f[i] - (_K C_1) z^{K-1} \mathcal{Z}(f[n]) - \sum_{j=0}^{K-2} f[j] + (_K C_2) z^{K-2} \mathcal{Z}(f[n]) + \sum_{k=0}^{K-3} f[k] - \ldots \pm \mathcal{Z}(f[n]) \end{split}$$

When K is odd

$$\mathcal{Z}(\Delta_n^K f[n]) = (z-1)^K \mathcal{Z}(f[n]) + \sum_{i=0}^{\frac{n+1}{2}} f[2i] \quad K > 0$$

When K is even

$$\mathcal{Z}(\Delta_n^K f[n]) = (z-1)^K \mathcal{Z}(f[n]) + \sum_{j=0}^{\frac{n}{2}} f[2j+1] \quad K > 0$$

22 Divergent Complexity

22.1 Definition of Converges to

$$??$$
Can $f[n] = 0??$

$$f[n]$$
 converges to $C = convergent[f[n], C] = a_o; a_o \in \{\mathbb{T}, \mathbb{F}\} =$

$$|C - f[n+1]| < |C - f[n]| \ \forall n$$

22.1.1 Notation

C is commonly denoted by a limit

$$C = \lim_{n \to \infty} f[n]$$

22.2 Definition of General Convergence

$$f[n]$$
 is $convergent = convergent[f[n]] = a_o; a_o \in \{\mathbb{T}, \mathbb{F}\} =$

 $\exists C:$

$$convergent[f[n], C] == \mathbb{T}$$

Alternatively

$$f[n]$$
 is $convergent = convergent[f[n]] = a_o \in \{\mathbb{T}, \mathbb{F}\} = \exists C:$

$$f[n]$$
 converges to C

22.3 Definition of Divergence

$$diverges[f[n]] = \neg converges[f[n]] = d_o; d_o \in \{\mathbb{T}, \mathbb{F}\}$$

:= $\sharp C : convergent[f[n], C] == \mathbb{T}$

22.4 Alternate Definition of Divergence

$$diverges[f[n]] = \neg converges[f[n]] = d_o; \ d_o \in \{\mathbb{T}, \mathbb{F}\}$$
$$= convergent[f[n], C] == \mathbb{F} \quad \forall C$$

22.4.1 Proof of Equivalence; Alternate Definition of Divergence

22.5 ?Necessary or Sufficient? Criteria 1 For Divergence

? The derivative as a function of K ? Function f[n] diverges if the K^{th} derivative of f[n] is strictly increasing

$$diverges[f[n]] := \sharp C : convergent[f[n], C] == \mathbb{T}$$

 \leftarrow

$$\Delta_n^{K+1} f[n] > \Delta_n^K f[n] \quad \forall K$$

Alternatively

$$\Delta_n^{K+1} f[n] - \Delta_n^K f[n] > 0 \quad \forall K$$

$$\Delta_n^{K+2} > 0 \quad \forall K$$

22.5.1 Criteria 1; Proof of Necessity and Sufficiency

$$diverges[f[n]] = d_o; d_o \in \{\mathbb{T}, \mathbb{F}\}$$

$$= \sharp C : convergent[f[n], C] == \mathbb{T}$$

Let

$$f[n]:$$

$$\Delta_n^{K+2} > 0 \quad \forall K$$

22.6 ?Necessary or Sufficient? Criteria 2 For Divergence

Function f[n] diverges if the Derivative as a function of K does not Converge

22.6.1 Criteria 2; Proof of Necessity and Sufficiency

$$diverges[f[n]] = d_o; \ d_o \in \{\mathbb{T}, \mathbb{F}\}$$

$$= \nexists C : convergent[f[n], C] == \mathbb{T}$$

22.7 Verbal Expressions

$$f[n]$$
 diverges = $f[n]$ is divergent = $f[n]$ is not convergent = $f[n]$ does not converge

22.8 Definition of Divergent Function

22.8.1 Definition 1

Define Divergent Function f[n] having strictly increasing K^{th} derivative

$$f[n]$$
 is $Divergent = Divergent[f[n]] = a_o \in \{\mathbb{T}, \mathbb{F}\} :=$

$$\Delta_n^{K+1} f[n] > \Delta_n^K f[n] \quad \forall K$$

Alternatively

$$\Delta_n^{K+1} f[n] - \Delta_n^K f[n] > 0 \quad \forall K$$

$$\Delta_n^{K+2} > 0 \quad \forall K$$

22.8.2 Definition 2

22.8.3 Proof of Equivalence Definition $1 \Leftrightarrow Definition 2$

22.8.4 Sufficient Proof

$$f[n]$$
 is $Divergent \iff$

22.8.5 Necessary Proof

$$f[n]$$
 is $Divergent \iff$

Proof by contradiction of definition of limit Using the definition of increasing convergence for a discrete function*

22.9 Defintion

Decision problem \hat{D} with solution s^+ has divergent total complexity O[n] if

$$\lim_{n\to\infty} \frac{O[n+1]}{O[n]} \ diverges$$

22.10 Divergent Problems

$$\mathcal{D} := \{\hat{D}_1, \hat{D}_2, ...\} :$$

$$\lim_{n \to \infty} \frac{O[n+1]}{O[n]} \ diverges \ \forall s^+ \in S_i^+, \ \hat{D}_i \in \hat{\mathcal{D}}$$

22.11 The Set of Polynomial Solutions and the Set of Divergent Solutions are disjoint

$$\mathbb{P} \cap \hat{D} = \emptyset$$

22.12 Proof

Let $D \in \hat{\mathcal{D}}$

$$\lim_{n\to\infty} \frac{O[n+1]}{O[n]}$$
 diverges by definition

Assume $D \in \mathbb{P}$

$$\lim_{n\to\infty} \frac{O[n+1]}{O[n]} = 1$$

 $\lim_{n\to\infty} \frac{O[n+1]}{O[n]} = 1$ contradicts the definition of Divergent Problems

$$\therefore D \in \hat{\mathcal{D}} \Rightarrow D \notin \mathbb{P}$$

Let $D \in \mathbb{P}$

 $\lim_{n\to\infty} \frac{O[n+1]}{O[n]} = 1$ by property of Polynomial complexity

Assume $D \in \hat{D}$

$$\lim_{n\to\infty} \frac{O[n+1]}{O[n]}$$
 diverges

 $\lim_{n\to\infty}\frac{O[n+1]}{O[n]}$ diverges contradicts a property of Polynomial complexity

$$\therefore D \in \mathbb{P} \Rightarrow D \notin \hat{\mathcal{D}}$$

$$\therefore \mathbb{P} \cap \hat{\mathcal{D}} = \emptyset$$

23 Subprograms

23.1 Definition of Subprogram

Define a Subprogram of Program P; a subset of Program P

$$P := \{s_1, s_2, ..., s_N, b_1, b_2, ..., b_M, y_o\} = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$P_{sub} := \tilde{P} \mid \\ \tilde{P} \subseteq P$$

23.2 Identity Subprogram

23.2.1 Definition

23.2.2 Prove the Identity Subprogram is a Subprogram of P

23.3 Restate the subprogram condition of general solutions

Recall the definition of general solution s^+

$$X_{i} = \{x_{1}, ..., x_{n}, C\}; \quad \hat{X}_{i} = \{x_{1}, ..., x_{n+1}, C\}$$

$$s^{+} = s^{+}[X_{i}] := P :$$

$$(P[X_{i}] \rightarrow y_{o} == a_{o} \quad \forall X_{i}) \quad \cap \quad (P[\hat{X}_{i}] \supseteq P[X_{i}] \quad \forall X_{i}, \hat{X}_{i})$$

The subprogram condition is one of two conditions for a general solution

$$P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i$$

The term subprogram is used interchangeably with the term subfunction

23.4 Prove O[n] is a non-decreasing function

Consider solution s^+ with complexity O[n]

$$X_{i} = \{x_{1}, ..., x_{n}, C\}; \quad \hat{X}_{i} = \{x_{1}, ..., x_{n+1}, C\}$$

$$s^{+} = s^{+}[X_{i}] := P :$$

$$(P[X_{i}] \rightarrow y_{o} == a_{o} \quad \forall X_{i}) \quad \cap \quad (P[\hat{X}_{i}] \supseteq P[X_{i}] \quad \forall X_{i}, \hat{X}_{i})$$

$$s^{+} = \{s_{1}, s_{2}, ..., s_{N} | b_{1}, b_{2}, ..., b_{M}, y_{o}\} = \{s_{1}, s_{2}, ..., s_{O_{T}[n]}, b_{1}, b_{2}, ..., b_{O_{S}[n]}, y_{o}\}$$

$$= \{\mathcal{L}, \mathcal{M}, y_{o}\}$$

$$O[n] := O_T[n] + O_S[n]$$

$$O_T[n] := |\mathcal{L}| = N$$

$$O_S[n] := |\mathcal{M}| + |y_o| = M + 1$$

 $\mathrm{O}[\mathrm{n}{+}1]$ denotes the total complexity for solution $s^+[\hat{X}_i]$

$$s^+[\hat{X}_i] = \hat{s}^+$$

Let

$$O[n+1] < O[n]$$

$$\Rightarrow \hat{N} + \hat{M} < N + M$$

$$\hat{s}^+ = \{s_1, s_2, ..., s_{\hat{N}} | b_1, b_2, ..., b_{\hat{M}}, y_o\}$$

$$\Rightarrow \hat{s}^+ \not\supseteq s^+$$

$$P[\hat{X}_i] \not\supseteq P[X_i] \quad \forall X_i, \hat{X}_i$$

 $\therefore O[n+1] < O[n]$ contradicts the definition of solution s^+ $O[n+1] \geqslant O[n]$

23.5 Definition of Subfunction

$$\begin{split} X_i &= \{x_1, ..., x_n, C\}; \quad \hat{X}_i = \{x_1, ..., x_{n+1}, C\} \\ s^+ &= s^+[X_i] := P: \\ (P[X_i] \to y_o == a_o \quad \forall X_i) \quad \cap \quad (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\ s^+ &= \{s_1, s_2, ..., s_N | b_1, b_2, ..., b_M, y_o\} = \{s_1, s_2, ..., s_{O_T[n]}, b_1, b_2, ..., b_{O_S[n]}, y_o\} \\ &= \{\mathcal{L}, \mathcal{M}, y_o\} \\ \\ Sub[X_i] := S = \{s_j, ... | b_k, ..., y_o\}: \\ s_j, b_k \in s^+ \quad \forall s_j, b_k \in S \end{split}$$

23.5.1 $s^+[X_i]$ is a subfunction of $s^+[\hat{X}_i]$

$$\begin{split} s^+ &= \{s_1, s_2, ..., s_N | b_1, b_2, ..., b_M, y_o\} = \{s_1, s_2, ..., s_{O_T[n]}, b_1, b_2, ..., b_{O_S[n]}, y_o\} \\ \hat{s}^+ &= \{s_1, s_2, ..., s_N, ..., s_{\hat{N}} | b_1, b_2, ..., b_M, ..., b_{\hat{M}}, y_o\}; \quad \hat{N} + \hat{M} \geqslant N + M \end{split}$$

By definition of solution

$$\hat{s}^+ = P[\hat{X}_i] \supseteq P[X_i] = s^+ \quad \forall X_i, \hat{X}_i$$

$$\Rightarrow s_j, b_k \in \hat{s}^+ \quad \forall s_j, b_k \in s^+$$

23.6 Subfunction Decomposition of Solutions

FIX Double check conditions!!! Solutions s^+ can be written as the union of subfunctions $Sub_k[X_i]$

$$X_{i} = \{x_{1}, ..., x_{n}, C\}; \quad \hat{X}_{i} = \{x_{1}, ..., x_{n+1}, C\}$$

$$s^{+} = s^{+}[X_{i}] := P :$$

$$(P[X_{i}] \rightarrow y_{o} == a_{o} \quad \forall X_{i}) \quad \cap \quad (P[\hat{X}_{i}] \supseteq P[X_{i}] \quad \forall X_{i}, \hat{X}_{i})$$

$$s^{+} = \{s_{1}, s_{2}, ..., s_{N} | b_{1}, b_{2}, ..., b_{M}, y_{o}\} = \{s_{1}, s_{2}, ..., s_{O_{T}[n]}, b_{1}, b_{2}, ..., b_{O_{S}[n]}, y_{o}\}$$

$$= \{\mathcal{L}, \mathcal{M}, y_{o}\}$$

$$s^{+} = Sub_{1}[X_{i}] \cup Sub_{2}[X_{i}] \cup ... \cup Sub_{z}[X_{i}]$$

$$= \{\mathcal{L}_{1} | \mathcal{M}_{1}, y_{o}\} \cup \{\mathcal{L}_{2} | \mathcal{M}_{2}, y_{o}\} \cup ... \cup \{\mathcal{L}_{z} | \mathcal{M}_{z}, y_{o}\} :$$

$$\mathcal{L}_{j} \cap \mathcal{L}_{k} = \emptyset \quad \forall j, k \neq j$$

$$s^{+} = \{s_{1}^{1}, ..., s_{N_{1}}^{1} | b_{1}^{1}, ..., y_{o}\} \cup \{s_{1}^{2}, ..., s_{N_{2}}^{2} | b_{1}^{2}, ..., y_{o}\} \cup ... \cup \{s_{1}^{z}, ..., s_{N_{z}}^{z} | b_{1}^{z}, ..., y_{o}\} :$$

$$\sum_{l=1}^{z} N_{l} = N = O_{T}[n]$$

24 Subfunction Complexity

24.1 Disjoint Subfunction Operations

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \ \forall i, j \neq i$$

24.2 Shared Subfunction Memory

$$|\mathcal{M}_i \cap \mathcal{M}_i| \geqslant 0 \ \forall i, j \neq i$$

24.2.1 Time Complexity of Subfunctions

Subfunction time complexity is additive

$$s^{+} = \{\mathcal{L}, \mathcal{M}, y_{o}\}$$

$$Sub_{i}[X] := S_{i} = \{s_{j}, \dots | b_{k}, \dots, y_{o}\} :$$

$$s_{j}, b_{k} \in s^{+} \quad \forall s_{j}, b_{k} \in S_{i}$$

$$s^{+} = \{\mathcal{L}_{1} | \mathcal{M}_{1}, y_{o}\} \cup \{\mathcal{L}_{2} | \mathcal{M}_{2}, y_{o}\} \cup \dots \cup \{\mathcal{L}_{z} | \mathcal{M}_{z}, y_{o}\} :$$

$$\mathcal{L}_{i} \cap \mathcal{L}_{j} = \emptyset \quad \forall i, j \neq i$$

$$\mathcal{L} = \cup_{i=1}^{z} \mathcal{L}_{i}$$

$$\mathcal{L}_{i} \cap \mathcal{L}_{j} = \emptyset \quad \forall i, j \neq i$$

$$O_{T}[n] = |\mathcal{L}| = N$$

$$O_{T}[n] = |\mathcal{L}| = N$$

$$O_{T}[n] + |\mathcal{L}_{i}| = \sum_{i=1}^{z} |\mathcal{L}_{i}|^{*} = |\mathcal{L}_{1}| + |\mathcal{L}_{2}| + \dots + |\mathcal{L}_{z}|$$

$$= O_{T_{1}}[n] + O_{T_{2}}[n] + \dots + O_{T_{r}}[n] = N_{1} + N_{2} + \dots + N_{z}$$

*Due to the disjoint condition of subfunction operations $\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \ \forall i, j \neq i$

24.2.2 Space Complexity of Subfunctions

Subfunctions can access the full memory \mathcal{M} with no added space complexity

$$s^{+} = \{\mathcal{L}, \mathcal{M}, y_{o}\}$$

$$Sub_{i}[X] := S_{i} = \{s_{j}, \dots | b_{k}, \dots, y_{o}\} :$$

$$s_{j}, b_{k} \in s^{+} \quad \forall s_{j}, b_{k} \in S_{i}$$

$$s^{+} = \{\mathcal{L}_{1} | \mathcal{M}_{1}, y_{o}\} \cup \{\mathcal{L}_{2} | \mathcal{M}_{2}, y_{o}\} \cup \dots \cup \{\mathcal{L}_{z} | \mathcal{M}_{z}, y_{o}\} :$$

$$\mathcal{L}_{i} \cap \mathcal{L}_{j} = \emptyset \quad \forall i, j \neq i$$

$$s^{+} = \{\mathcal{L}_{1} | \mathcal{M}, y_{o}\} \cup \{\mathcal{L}_{2} | \mathcal{M}, y_{o}\} \cup \dots \cup \{\mathcal{L}_{z} | \mathcal{M}, y_{o}\} :$$

$$\mathcal{L}_{i} \cap \mathcal{L}_{j} = \emptyset \quad \forall i, j \neq i$$

$$\mathcal{M} = \bigcup_{i=1}^{z} \mathcal{M}_{i} = \bigcup_{i=1}^{z} \mathcal{M}$$
$$O_{S}[n] = |\mathcal{M}| = M$$
$$O_{S}[n] = |\bigcup_{i=1}^{z} \mathcal{M}_{i}| = M$$

24.2.3 Shared State Notation

$$s^{+} = \{\mathcal{L}, \mathcal{M}, y_{o}\}$$

$$Sub_{i}[X] := S_{i} = \{s_{j}, \dots | b_{k}, \dots, y_{o}\} :$$

$$s_{j}, b_{k} \in s^{+} \quad \forall s_{j}, b_{k} \in S_{i}$$

$$s^{+} = \{\mathcal{L}_{1} | \mathcal{M}, y_{o}\} \cup \{\mathcal{L}_{2} | \mathcal{M}, y_{o}\} \cup \dots \cup \{\mathcal{L}_{z} | \mathcal{M}, y_{o}\} :$$

$$\mathcal{L}_{i} \cap \mathcal{L}_{j} = \emptyset \quad \forall i, j \neq i$$

25 Polynomial Solution Subfunction Properties

25.1 Restate Definition of Subfunction

$$X_{n} = \{x_{1}, ..., x_{n}, C\}; \quad \hat{X}_{i} = \{x_{1}, ..., x_{n+1}, C\}$$

$$s^{+} = s^{+}[X_{n}] := P :$$

$$(P[X_{n}] \rightarrow y_{o} == a_{o} \quad \forall X_{i}) \quad \cap \quad (P[\hat{X}_{n}] \supseteq P[X_{n}] \quad \forall X_{n}, \hat{X}_{n})$$

$$s^{+} = \{s_{1}, s_{2}, ..., s_{N} | b_{1}, b_{2}, ..., b_{M}, y_{o}\} = \{s_{1}, s_{2}, ..., s_{O_{T}[n]}, b_{1}, b_{2}, ..., b_{O_{S}[n]}, y_{o}\}$$

$$= \{\mathcal{L}, \mathcal{M}, y_{o}\}$$

$$Sub[X_{n}] := S = \{s_{j}, ... | b_{k}, ..., y_{o}\} :$$

$$s_{j}, b_{k} \in s^{+} \quad \forall s_{j}, b_{k} \in S$$

25.2 Property of Polynomial Solution Subfunctions

Let

$$D \in \mathbb{P}$$

$$X_n = \{x_1, ..., x_n, C\}; \quad \hat{X}_n = \{x_1, ..., x_{n+1}, C\}$$

$$s^+ = s^+[X_n] := P:$$

$$(P[X_i] \to y_o == a_o \quad \forall X_n) \quad \cap \quad (P[\hat{X}_n] \supseteq P[X_n] \quad \forall X_n, \hat{X}_n)$$

$$\exists K, C, \lambda_1 ... \lambda_K :$$

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} ... + \lambda_1 n + C \quad \forall n$$

$$s^+ = Sub_1[X_n] \cup Sub_2[X_n] \cup ... \cup Sub_z[X_n]$$

$$\lim_{n \to \infty} \frac{O[n+1]}{O[n]} = 1$$

$$= \lim_{n \to \infty} \frac{O^1_T[n+1] + O^2_T[n+1] + ... + O^2_T[n+1] + O_S[n]}{O^1_T[n] + O^2_T[n] + ... + O^2_T[n] + O_S[n]}$$

$$\lim_{n \to \infty} \frac{O^1_T[n] + O^2_T[n] + ... + O^2_T[n] + ... + O^2_T[n] + O_S[n]}{O^1_T[n] + O^2_T[n] + ... + O^2_T[n] + O_S[n]}$$

$$\begin{split} &= limit_{n \to \infty} 1 + \frac{f_{T_{n+1}}^{1}[n] + f_{T_{n+1}}^{2}[n+1] + \ldots + f_{T_{n+1}}^{z}[n] + f_{S_{n+1}}[n]}{O_{T}^{1}[n] + O_{T}^{2}[n] + \ldots + O_{T}^{z}[n] + O_{S}[n]} = 1 \\ &\Rightarrow limit_{n \to \infty} \frac{f_{T_{n+1}}^{1}[n] + f_{T_{n+1}}^{2}[n+1] + \ldots + f_{T_{n+1}}^{z}[n] + f_{S_{n+1}}[n]}{O_{T}^{1}[n] + O_{T}^{2}[n] + \ldots + O_{T}^{z}[n] + O_{S}[n]} = 0^{*} \\ &\Rightarrow limit_{n \to \infty} \frac{f_{T_{n+1}}^{i}[n] + f_{S_{n+1}}[n]}{O_{T}^{1}[n] + O_{T}^{2}[n] + \ldots + O_{T}^{z}[n] + O_{S}[n]} = 0 \quad \forall i \\ &\qquad limit_{n \to \infty} \frac{f_{n+1}^{i}[n]}{O[n]} = 0 \quad \forall i \end{split}$$

25.3 Theorem of Polynomial Subfunctions

The Theorem of Polynomial Subfunctions states a solution has polynomial complexity if and only if all of its subfunctions have polynomial complexity

$$|s^{+}[X_{n}]| = O[n] = (\lambda_{K}n)^{K} + (\lambda_{K-1}n)^{K-1}... + \lambda_{1}n + C \quad \forall n$$

$$s^{+} = Sub_{1}[X_{n}] \cup Sub_{2}[X_{n}] \cup ... \cup Sub_{z}[X_{n}]$$

$$O[n] = (\lambda_{K}n)^{K} + (\lambda_{K-1}n)^{K-1}... + \lambda_{1}n + C \quad \forall n$$

$$\iff$$

$$|Sub_{i}[X_{n}]| = O_{i}[n] = (\hat{\lambda}_{M}n)^{M} + (\hat{\lambda}_{M-1}n)^{M-1} + ... + \hat{\lambda}_{1}n + C \quad \forall i, n$$

25.3.1 Sufficient Proof

Solution s^+ having polynomial complexity implies all of its subfunctions Sub_i have polynomial complexity

Let

$$|s^{+}[X_{n}]| = O[n] = (\lambda_{K}n)^{K} + (\lambda_{K-1}n)^{K-1}... + \lambda_{1}n + C \quad \forall n$$
$$O[n] = \sum_{i=1}^{z} O_{i}[n] = O_{1}[n] + O_{2}[n] + ... + O_{z}[n]$$

Since $O[n], O_i[n]$ is positive, non-decreasing

$$O_i[n] = (\hat{\lambda}_{M_i}n)^{M_i} + (\hat{\lambda}_{M_i-1}n)^{M_i-1}... + \hat{\lambda}_1n + C \quad M_i \leq K \quad \forall i, n$$

 $\Rightarrow Sub_i$ has polynomial complexity by definition of polynomial complexity

^{*} O[n] is a positive, non-decreasing function

25.3.2 Necessary Proof

Every subfunction Sub_i having polynomial complexity implies solution s^+ has polynomial complexity

Let

$$\begin{split} O_{i}[n] &= (\hat{\lambda}_{M_{i}}n)^{M_{i}} + (\hat{\lambda}_{M_{i}-1}n)^{M_{i}-1} + \ldots + \hat{\lambda}_{1_{i}}n + \hat{\lambda}_{0_{i}} \quad \forall i, n \\ \\ O_{max}[n]^{*} &:= \tilde{O}[n] \in \{O_{1}[n], O_{2}[n], \ldots O_{z}[n]\} : \\ \\ \lim_{n \to \infty} \frac{\tilde{O}[n]}{\sum_{i=1}^{z} O_{i}[n]} &= c \neq 0 \\ \\ O_{max}[n] &= (\hat{\lambda}_{M_{max}}n)^{M_{max}} + (\hat{\lambda}_{M_{max}1n})^{M_{max}-1} + \ldots + \hat{\lambda}_{1_{max}}n + \hat{\lambda}_{0_{max}} \quad \forall i, n \\ \\ O[n] &= \sum_{i=1}^{z} O_{i}[n] &= O_{1}[n] + O_{2}[n] + \ldots + O_{z}[n] \\ \\ &= (\tilde{\lambda}_{L}n)^{L} + (\tilde{\lambda}_{L-1}n)^{L-1} + \ldots + \tilde{\lambda}_{1}n + C \quad L = M_{max} \quad \forall n \end{split}$$

 $\Rightarrow s^+$ has polynomial complexity by definition of polynomial complexity

^{*} O_{max} is not necessarily unique, but necessarily exists. See appendix for proof

26 Divergent Solution Subfunction Properties

26.1 Restate Definition of Subfunction

$$\begin{split} X_i &= \{x_1, ..., x_n, C\}; \quad \hat{X}_i = \{x_1, ..., x_{n+1}, C\} \\ s^+ &= s^+[X_i] := P: \\ (P[X_i] \to y_o == a_o \quad \forall X_i) \quad \cap \quad (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\ s^+ &= \{s_1, s_2, ..., s_N | b_1, b_2, ..., b_M, y_o\} = \{s_1, s_2, ..., s_{O_T[n]}, b_1, b_2, ..., b_{O_S[n]}, y_o\} \\ &= \{\mathcal{L}, \mathcal{M}, y_o\} \\ \\ Sub[X_i] := S = \{s_j, ... | b_k, ..., y_o\}: \\ s_j, b_k \in s^+ \quad \forall s_j, b_k \in S \end{split}$$

26.2 Property of Divergent Subfunctions

Let

$$D \in \hat{\mathcal{D}}$$

$$X_n = \{x_1, ..., x_n\}; \ \hat{X}_n = \{x_1, ..., x_{n+1}\}$$

$$s^+ = s^+[X_n] := P :$$

$$(P[X_i] \to y_o == a_o \ \forall X_n) \cap (P[\hat{X}_n] \supseteq P[X_n] \ \forall \hat{X}_n : \hat{X}_n \supset X_n)$$

By Definition of Divergent Problem

$$\begin{split} & \nexists c: limit_{n \to \infty} \frac{O[n+1]}{O[n]} = c \\ & = limit_{n \to \infty} \frac{O_T^1[n+1] + O_T^2[n+1] + \ldots + O_T^z[n+1] + O_S[n+1]}{O_T^1[n] + O_T^2[n] + \ldots + O_T^z[n] + O_S[n]} \\ & = \\ & limit_{n \to \infty} \frac{O_T^1[n] + O_T^2[n] + \ldots + O_T^z[n] + O_S[n] + f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \ldots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \ldots + O_T^z[n] + O_S[n]} \\ & = limit_{n \to \infty} 1 + \frac{f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \ldots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \ldots + O_T^z[n] + O_S[n]} \neq c \\ & \Rightarrow limit_{n \to \infty} \frac{f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \ldots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \ldots + O_T^z[n] + O_S[n]} \neq c^* \end{split}$$

Prove

$$\exists i: limit_{n \to \infty} \frac{f_{T_{n+1}}^{i}[n] + f_{S_{n+1}}[n]}{O_{T}^{1}[n] + O_{T}^{2}[n] + \dots + O_{T}^{z}[n] + O_{S}[n]} \ diverges$$

* O[n] is a positive, non-decreasing function

26.3 Theorem of Divergent Subfunctions

The Theorem of Divergent Subfunctions states a divergent subfunction implies divergent total complexity

$$\begin{array}{ccc} lim_{n\to\infty}\frac{O[n+1]}{O[n]} & diverges \\ & \Longleftrightarrow \\ \exists i: lim_{n\to\infty}\frac{O_i[n+1]}{O[n]} & diverges \end{array}$$

26.3.1 Sufficient Direction

See 18.2

26.3.2 Necessary Direction

27 Computational Basis

27.1 Definition of a Computational Basis of Program P

Define a Computational Basis B of Program P

$$X_n = \{x_1, x_2, ..., x_n\}$$

$$P[X_n] \to Y_o := \{s_1, s_2, ..., s_N, b_1, b_2, ..., Y_o\} \to Y_o$$

$$B :=$$

For the remainder of this document, "computational basis" is denoted as "basis" α

- 27.2 Definition of the Identity Basis of Program P
- 27.3 Prove the Identity Basis of Program P is a basis of Program P
- 27.4 Definition of Canonical Program
- 27.5 Definition of a Canonical Basis of Program P
- 27.6 Prove Canonical Basis $\mathbb B$ of Program P is a basis of Program P

27.7 Subprogram and Canonical Basis

Prove a subprogram is a canonical basis if and only if it's basis decomposition is the identity subprogram

27.8 Basis of Boolean Program P

28 Fundamental Theorem of Computation

The Fundamental Theorem of Computation states every program P has a canonical basis $\mathbb B$

28.1 Proof

29 Input Spaces

29.1 Definition of Input Space

Define the Input Space \mathbb{I} of Program P

- 29.2 Define the Cardinality Function C[n] of Input Space $\mathbb I$
- 29.3 Existence, Uniqueness, etc.
- 29.4 Worst Case
- **29.5 Prove** $|\mathbb{B}| = C[n]$

30 Theorem of Solution Complexity

The Theorem of Solution Complexity relates the complexity of solution s^+ to a basis B of solution s^+

$$X_n = \{x_1, x_2, ..., x_n\}$$

$$\mathcal{Q} := f[X_n] \to A_o \subseteq \Omega \quad \forall X_n \in D_{\mathcal{Q}}$$

$$s^+ = s^+[X_n] := P[X_n] \to Y_o :$$

$$(Y_o = A_o \quad \forall X_n \in D_{\mathcal{Q}}) \quad \cap \quad (P[X_{n+1}] \supseteq P[X_n] \quad \forall X_n \in D_{\mathcal{Q}} \quad \forall X_{n+1} \in D_{\mathcal{Q}})$$

31 Theorem of Optimal Complexity

32 Theorem of Divergent Complexity

33 Sum to N Problem with 2 integers

33.1 State formal definition of Sum to N: $x_i + x_j == N$

$$X_{n} = \{x_{1}, ..., x_{n}\}$$

$$D := f[X_{i}, N] = a_{o} \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_{i}$$

$$s^{+}[X_{n}] = P[X_{n}] :$$

$$(P[X_{i}] = y_{o} == a_{o} \quad \forall X_{i}) \quad \cap \quad (P[X_{n+1}] \supseteq P[X_{n}] \quad \forall X_{n+1})$$

$$s^{+} = \{s_{1}, s_{2}, ..., s_{O_{T}[n]}, b_{1}, b_{2}, ..., b_{O_{S}[n]}, y_{o}\} = \{\mathcal{L}, \mathcal{M}, y_{o}\}$$

$$D = f[X_{i}] = \exists x_{j}, x_{k} \in X_{n} \quad j \neq k :$$

$$x_{j} + x_{k} == N$$

33.2 Express a formal solution : $O_S[n] \sim n^0$

$$\begin{split} s^+ &= \{s_1, s_2, ..., s_{O_T[n]}, b_1, b_2, ..., b_{O_S[n]}, y_o\} = \{\mathcal{L}, \mathcal{M}, y_o\} \\ s_1 &= y_o \leftarrow \mathbb{F}; \\ \forall i < n \ , \ n \geqslant j > i \end{split}$$

$$\begin{split} s_2, s_3, s_8, s_9, \dots, s_{3ij-4}, s_{3ij-3} \dots, s_{3n(n-1)-4}, s_{3n(n-1)-3} &= b_1 \leftarrow x_i + x_j \\ s_4, s_5, s_{10}, s_{11}, \dots, s_{3ij-2}, s_{3ij-1} \dots, s_{3n(n-1)-2}, s_{3n(n-1)-1} &= b_1 \leftarrow b_1 == N \\ s_6, s_7, s_{12}, s_{13} \dots, s_{3ij}, s_{3ij+1} \dots, s_{3n(n-1)}, s_{3n(n-1)+1} &= y_o \leftarrow y_o \vee b_1 \\ s^+ &= \{y_o \leftarrow \mathbb{F}, y_o \leftarrow y_o \vee (x_i + x_j == N) \quad \forall i, j > i \mid b_1, y_o \} \end{split}$$

33.3 Prove s^+ satisfies the subfunction condition of solutions: $P[X_{n+1}] \supseteq P[X_n] \ \forall X_{n+1}$

$$X_{n} = \{x_{1}, x_{2}, ..., x_{n}\}; \quad X_{n+1} = \{x_{1}, x_{2}, ..., x_{n}, x_{n+1}\}$$

$$s^{+} = \{s_{1}, s_{2}, ..., s_{O_{T}[n]}, b_{1}, b_{2}, ..., b_{O_{S}[n]}, y_{o}\} = \{\mathcal{L}, \mathcal{M}, y_{o}\}$$

$$s^{+}_{n+1} = s^{+} \cup \hat{s}^{+}$$

$$s_{1} = y_{o} \leftarrow \mathbb{F};$$

$$\forall i < n , n \ge j > i$$

$$\begin{aligned} s_2, s_3, s_8, s_9, \dots, s_{3ij-4}, s_{3ij-3} \dots, s_{3n(n-1)-4}, s_{3n(n-1)-3} &= b_1 \leftarrow x_i + x_j \\ s_4, s_5, s_{10}, s_{11}, \dots, s_{3ij-2}, s_{3ij-1} \dots, s_{3n(n-1)-2}, s_{3n(n-1)-1} &= b_1 \leftarrow b_1 &== N \\ s_6, s_7, s_{12}, s_{13} \dots, s_{3ij}, s_{3ij+1} \dots, s_{3n(n-1)}, s_{3n(n-1)+1} &= y_o \leftarrow y_o \lor b_1 \end{aligned}$$

$$\forall k < n+1$$

$$s... = b_1 \leftarrow x_k + x_{n+1}$$

$$s... = b_1 \leftarrow b_1 == N$$

$$s... = y_o \leftarrow y_o \lor b_1$$

$$s^{+} = \{ y_{o} \leftarrow \mathbb{F}, y_{o} \leftarrow y_{o} \lor (x_{i} + x_{j} == N) \quad \forall i, j > i \mid b_{1}, y_{o} \}$$

$$\hat{s}^{+} = \{ y_{o} \leftarrow y_{o} \lor (x_{k} + x_{n+1} == N) \quad \forall k < n+1 \mid b_{1}, y_{o} \}$$

$$s_{n+1}^{+} = \{ y_{o} \leftarrow \mathbb{F}, y_{o} \leftarrow y_{o} \lor (x_{i} + x_{j} == N) \quad \forall i, j > i \mid b_{1}, y_{o} \} \quad \cup$$

$$\{ y_{o} \leftarrow y_{o} \lor (x_{k} + x_{n+1} == N) \quad \forall k < n+1 \mid b_{1}, y_{o} \}$$

$$s_{n+1}^{+} = s^{+} \cup \hat{s}^{+} = P[X_{n+1}] \supseteq P[X_{n}] = s^{+}$$

33.4 Determine $O[n], O_S[n], O_T[n], f_{n+1}[n], f_{n+1}^T[n], f_{n+1}^S[n]$ for the above solution

$$O_S[n] = |y_o| + |b_1| = 2$$

$$O_T[n] = 3n(n-1) + 1 = 3n(n-1) - 1 + O_S[n]$$

$$O[n] = 3n(n-1) + 3 = 3n^2 - 3n + 3$$

$$f_{n+1}^S[n] = 0$$

$$f_{n+1}^T[n] = 6n$$

$$f_{n+1}^S[n] = f_{n+1}^S[n] + f_{n+1}^T[n]$$

33.5 Verify
$$O[n+1] = O[n] + f_{n+1}[n]$$

$$O[n+1] = O[n] + \hat{O}[n]$$

$$3(n+1)^2 - 3(n+1) + 3 = 3n^2 - 3n + 3 + 6n$$

$$3n^2 + 6n + 3 - 3n - 3 + 3 = 3n^2 + 3n + 3$$

$$3n^2 + 3n + 3 = 3n^2 + 3n + 3$$

33.6 Show s^+ has Polynomial Complexity by the definition of Total Polynomial Complexity

$$O[n] = 3n^2 - 3n + 3$$

33.7 Show the limit $_{n\to\infty}\frac{O[n+1]}{O[n]}$ does not Diverge

$$\begin{split} limit_{n\to\infty} \frac{O[n+1]}{O[n]} &= \\ limit_{n\to\infty} \frac{3n^2 + 3n + 3}{3n^2 - 3n + 3} &= \\ limit_{n\to\infty} (\frac{3n^2 - 3n + 3}{3n^2 - 3n + 3} + \frac{6n}{3n^2 - 3n + 3}) &= \\ limit_{n\to\infty} (1 + \frac{6n}{3n^2 - 3n + 3}) &= 1 \end{split}$$

34 The Knapsack Problem

34.1 The Knapsack Problem

The Knapsack Problem is a famous problem in computer science which asks if objects can be stored in a knapsack. Typically the problem is designed with two constraints, weight and value. Given objects x_i , each with a respective weight w_i and value v_i , does there exist a combination of objects lighter than input weight W and more valuable than input value V?

34.2 Formal Definition

$$X_n = \{x_1, x_2, ..., x_n\} = \{\{w_1, v_1\}, \{w_2, v_2\}, ..., \{w_n, v_n\}\}\}$$

$$I = \{i_1, i_2, ..., i_n\} : i_l \in \{0, 1\} \ \forall i_l \in I$$

$$D := f[X_n, W, V] = a_o \in \{\mathbb{T}, \mathbb{F}\} = \exists I :$$

$$(\sum_{j=1}^n i_j w_j < W) \land (\sum_{j=1}^n i_j v_j \geqslant V)$$

34.3 Solve for C[n]

34.3.1 Expressing I as a binary number

$$I = \{i_1, i_2, ..., i_n\} : i_l \in \{0, 1\} \ \forall i_l \in I$$

Valid combinations of I

$$I_{valid} = \{\{0,0,0,...,0,0,1\},\{0,0,0,...,0,1,0\},\{0,0,0,...,0,1,1\},...,\{1,1,1,...,1,1,1\}\}\}$$

$$C[n] = |I_{valid}[n]| = 2^n - 1$$

34.3.2 Using a sum of combinations of inputs x_i

$$X_n = \{x_1, x_2, ..., x_n\} = \{\{w_1, v_1\}, \{w_2, v_2\}, ..., \{w_n, v_n\}\}$$

Valid combinations of x_i

$$X_{valid}[n] =$$

$$\{x_1\} \cup \{x_2\} \cup \dots \cup \{x_n\} \cup \{x_1, x_2\} \cup \{x_1, x_3\} \cup \dots \cup \{x_{n-1}, x_n\} \cup \dots \cup \{x_1, x_2, \dots, x_n\}$$

$$= X_n C_1 \cup X_n C_2 \cup \dots \cup X_n C_n$$

$$C[n] = |X_{valid}[n]| = \sum_{j=1}^n {n \choose j}$$

34.3.3 Verify consistency

$$C[n] = |X_{valid}[n]| = |I_{valid}[n]|$$

$$= 2^{n} - 1 = \sum_{j=1}^{n} {}_{n}C_{j} = {}_{n}C_{1} + {}_{n}C_{2} + \dots + {}_{n}C_{n}$$

$$= 2^{n} - 1 = 2^{n} - 1$$

- 34.4 Express a solution s^+ of the Knapsack Problem
- 34.5 Prove s^+ satisfies the subfunction condition of solutions
- **34.6** Determine $O[n], O_T[n], O_S[n], f_{n+1}[n]$
- 34.7 Show $s^+ \notin \mathbb{P}$
- 34.8 Express the Solution Space $\mathbb S$ for The Knapsack Problem
- **34.9** Prove a lower bound for all solutions $s^+ \in S^+ := O_{lower}[n]$
- 34.10 Prove D has Divergent Complexity

Appendix

Types of Methods

34.11 Void Methods

Define a void program; a program with inputs x_i and no output

$$X_n = \{x_1, ..., x_n\}$$

$$P = P[X] := \{s_1, s_2, ..., s_N \mid b_1, b_2, ..., b_M\}$$

34.12 Numerical Methods

Define a numerical program; a program with inputs x_i , input set C, and real, rational output y_o

$$X = \{x_1, ..., x_n, C\}$$

$$P = P[X] := \{s_1, s_2, ..., s_N \mid b_1, b_2, ..., b_M, y_o\} =$$

$$P[X] \rightarrow y_o \in \mathbb{Q} \ y_o \geqslant 0$$

34.13 System Methods

Define a system program; a program with inputs x_i , input set C, and real, output set Y_o

$$X = \{x_1, ..., x_n, C\}$$

$$P = P[X] := \{s_1, s_2, ..., s_N \mid b_1, b_2, ..., b_M, Y_o\} =$$

$$P[X] \rightarrow Y_o = \{y_1, y_2, ..., y_K\}$$

34.14 Mathematical Methods

Define a mathematical program; a program with inputs x_i , input set C and numerical output y_o

$$X = \{x_1, ..., x_n, C\}$$

$$P = P[X] := \{s_1, s_2, ..., s_N \mid b_1, b_2, ..., b_M, y_o\} =$$

$$P[X] \to y_o \in \mathbb{Q}$$

34.15 While Loop

35 Criticism of Overloaded Equivalence

In computer science, it is convention to overload equivalence =

$$a_i = a_i \quad \forall a_i \in \Omega$$

Consider standard C++ syntax

int x = 3;

int y = 4;

int z = x + y;

Int x is not inherently equal to 3. Rather, we are creating an open space "x" for a value and setting the value to 3. Similarly, z is not inherently equal to the value of x + y. Rather, we are creating an open space "z" for a value and setting the value to the sum of x and y which have already been set.

$$x \leftarrow 3$$

$$y \leftarrow 4$$

$$z \leftarrow x + y$$

36 Existence of $O_{max}[n]$

36.1 Proof

36.1.1 Alternate Definition; Left Hand Derivative

Some sources define

$$\Delta_n^1 f[n] = f[n] - f[n-1]$$

Citations

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