

# Computation

## 1 Programs

### 1.1 Logical Instructions

Define  $\mathcal{L}$ ; an ordered set of logical operations  $s_i$

$$\mathcal{L} := \{s_1, s_2, \dots, s_N\}$$

### 1.2 Memory

Define Memory  $\mathcal{M}$ ; a set of elements, magnitudes, or sets  $b_i$

$$\mathcal{M} := \{b_1, b_2, \dots, b_M\}$$

### 1.3 State |

Define state; the memory utilized to perform program P

$$P := \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M\} = \\ \{s_1, s_2, \dots, s_N, b_1, b_2, \dots, b_M\}$$

### 1.4 Boolean Programs

Define a boolean program; boolean programs can represent functions with inputs  $x_i$ , input set C, and boolean output  $y_o$

$$X = \{x_1, \dots, x_n, C\}; \quad C = \{u_1, u_2, \dots, u_c\} \\ P = P[X] := \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \\ P[X] \rightarrow y_o \in \{\mathbb{T}, \mathbb{F}\}$$

### 1.5 Void Programs

Define a void program; a program with inputs  $x_i$ , input set C, and no output

$$X = \{x_1, \dots, x_n, C\} \\ P = P[X] := \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M\}$$

## 1.6 Numerical Programs

Define a numerical program; a program with inputs  $x_i$ , input set C, and real, rational output  $y_o$

$$\begin{aligned} X &= \{x_1, \dots, x_n, C\} \\ P = P[X] &:= \{s_1, s_2, \dots, s_N \mid b_1, b_2, \dots, b_M, y_o\} = \\ P[X] &\rightarrow y_o \in \mathbb{Q} \quad y_o \geq 0 \end{aligned}$$

## 1.7 System Programs

Define a system program; a program with inputs  $x_i$ , input set C, and real, output set  $Y_o$

$$\begin{aligned} X &= \{x_1, \dots, x_n, C\} \\ P = P[X] &:= \{s_1, s_2, \dots, s_N \mid b_1, b_2, \dots, b_M, Y_o\} = \\ P[X] &\rightarrow Y_o = \{y_1, y_2, \dots, y_K\} \end{aligned}$$

## 1.8 Mathematical Programs

Define a mathematical program; a program with inputs  $x_i$ , input set C and numerical output  $y_o$

$$\begin{aligned} X &= \{x_1, \dots, x_n, C\} \\ P = P[X] &:= \{s_1, s_2, \dots, s_N \mid b_1, b_2, \dots, b_M, y_o\} = \\ P[X] &\rightarrow y_o \in \mathbb{Q} \end{aligned}$$

## 2 No-op ;

### 2.1 Definition

$$; := \emptyset$$

### 2.2 Property of No-op

No-op can be inserted into any set with equality

$$S = \{s_1, s_2, \dots, s_N\}$$

$$S_; = insert[S, ;, i]$$

$$S_; = S_1 \quad \forall i$$

$$|S_;| = |S| \quad \forall i$$

### 2.3 Proof

by definition of magnitude of null = 0 with Set And

### 3 Decision Problems

#### 3.1 Definition

Define decision problem; a function with inputs  $x_i$  and boolean output "answer"  $a_o$

$$X_i = \{x_1, \dots, x_n, C\}$$

$$D := f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

### 4 General Solutions

#### 4.1 Definition

Program P is a general solution  $s^+$  to decision problem D if

1. P outputs answer  $a_o$  for all inputs  $X_i \quad \forall i$   
and
2.  $s^+[X_i]$  is a subset of  $s^+[\hat{X}_i]$

$$X_i = \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_n, x_{n+1}, C\}$$

$$D := f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

$$s^+ = s^+[X_i] := P :$$

$$(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) \cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i)$$

$$P[X_i] = \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\}$$

$$s^+ = P[X_i] = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \quad \forall X_i$$

##### 4.1.1 Property of No-op ;

No-op ; can be added to any solution  $S_i$  without modifying the output  $y_o$

$$s^+ = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\}$$

$$\hat{s}^+ \rightarrow \hat{y}_o = insert[s^+, ;, k]$$

$$\hat{y}_o = y_o \quad \forall k$$

#### 4.2 Definition of $S^+$

Define  $S^+$ ; the set of solutions to decision problem D

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_n, x_{n+1}, C\} \\
D &:= f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i \\
s_j^+ &= s_j^+[X_i] := P : \\
(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
S^+ &:= \{s_j^+, \dots\} \quad \forall j
\end{aligned}$$

### 4.3 Definition of Solvable

Define solvable

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_n, x_{n+1}, C\} \\
D &:= f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i \\
solvable &:= solvable[D] \rightarrow b_o \in \{\mathbb{T}, \mathbb{F}\} = \\
\exists P : (P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i)
\end{aligned}$$

## 5 The set of all Decision Problems $\mathbb{D}$

### 5.1 Definition

Define the set of decision problems  $\mathbb{D}$

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\} \\
D_j &:= f_j[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i \\
\mathbb{D} &:= \{D_j, \dots\} \quad \forall j
\end{aligned}$$

## 6 Instruction and Memory Notation

Define  $\mathcal{L}$  a set of logical operations

Define  $\mathcal{M}$  a set of memory elements, magnitudes, and sets

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \\
P[X_i] \rightarrow y_o &= \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
\mathcal{L} &:= \{s_1, s_2, \dots, s_{O_T[n]}\} \\
\mathcal{M} &:= \{b_1, b_2, \dots, b_{O_S[n]}\} \\
P[X_i] &= \{\mathcal{L}, \mathcal{M}, y_o\}
\end{aligned}$$

## 7 Complexity

### 7.1 Time Complexity of a Decision Problem $O_T[n]$

Define Time Complexity  $O_T[n]$  of solution  $s^+$  to Decision Problem  $D$  as the total number of logical operations

$$X_i = \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\}$$

$$D := f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

$$s^+[X_i] := P :$$

$$(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) \quad \cap \quad (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i)$$

$$\begin{aligned} s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\ &= \{\mathcal{L}, \mathcal{M}, y_o\} \end{aligned}$$

$$O_T[n] := |\mathcal{L}| = N$$

### 7.2 Space Complexity $O_S[n]$

Define Space Complexity  $O_S[n]$  of solution  $s^+$  to Decision Problem  $D$  as the total number of memory elements

$$X_i = \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\}$$

$$D := f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

$$s^+[X_i] := P :$$

$$(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) \quad \cap \quad (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i)$$

$$\begin{aligned} s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\ &= \{\mathcal{L}, \mathcal{M}, y_o\} \end{aligned}$$

$$O_S[n] := |\mathcal{M}| + |y_o|^* = M + 1$$

\*It is convention to reserve one memory element for output  $y_o$ .  
Void programs do not require the  $y_o$  memory element for output

## 8 Definition of Complexity

Define Complexity  $O[n]$  as a vector of dimension Y

$$\mathbf{O}[n] := \langle O_T[n], O_S[n], O_3[n], O_4[n] \dots, O_V[n] \rangle$$

## 9 Total Complexity

$$O[n] := O_T[n] + O_S[n] + \sum_{i=3}^V O_i[n]$$

## 10 Simple Computational Complexity

The remainder of this document assumes simple computational complexity of dimension 2

### 10.1 Definition

Define simple computational complexity of dimension 2

$$\mathbf{O}[n] := \langle O_T[n], O_S[n] \rangle$$

### 10.2 Time Complexity

Restate definition of Time Complexity  $O_T[n]$  of solution  $s^+$

$$s^+ = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$O_T[n] := |\mathcal{L}| = N$$

### 10.3 Space Complexity

Restate definition of Time Complexity  $O_S[n]$  of solution  $s^+$

$$s^+ = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$O_S[n] := |\mathcal{M}| + |y_o| = M + 1$$

### 10.4 Total Complexity

$$\begin{aligned} O[n] &:= O_T[n] + O_S[n] \\ &= |\mathcal{L}| + |\mathcal{M}| + |y_o| = N + M + 1 \end{aligned}$$

### 10.5 $O_S[n] > 0$

#### 10.5.1 Proof

Assume  $O_S[n] = 0$

$$O_S[n] := |\mathcal{M}| + |y_o|$$

$$O_S[n] = 0 \Rightarrow \mathcal{M} = y_o = \emptyset$$

$$y_o = \emptyset; \ y_o \in \{\mathbb{T}, \mathbb{F}\} \text{ by definition of } s^+$$

$\therefore O_S[n] = 0$  contradicts the definition of solution  $s^+$  of a decision problem



$O_S[n] \geq 0$  by definition of magnitude

$$\therefore O_S[n] > 0$$

**10.6**  $O_T[n] > 0$

**10.6.1 Proof**

Assume  $O_T[n] = 0$

$$O_T[n] := |\mathcal{L}|$$

$$O_T[n] = 0 \Rightarrow y_o \notin \{\mathbb{T}, \mathbb{F}\}$$

$$y_o \notin \{\mathbb{T}, \mathbb{F}\}; \quad y_o \in \{\mathbb{T}, \mathbb{F}\} \text{ by definition of } s^+$$

$\therefore O_T[n] = 0$  contradicts the definition of solution  $s^+$  of a decision problem

$O_T[n] \geq 0$  by definition of magnitude

$$\therefore O_T[n] > 0$$

**10.7**  $O[n] > 0$

**10.7.1 Proof**

$$O[n] := O_T[n] + O_S[n]$$

$$O_T[n] > 0; \quad O_S[n] > 0$$

$$\therefore O[n] > 0$$

**10.8**  $O[n] > O_T[n]$

**10.8.1 Proof**

$$O[n] := O_T[n] + O_S[n]$$

$$O_S[n] > 0$$

$$\therefore O[n] > O_T[n]$$

**10.9**  $O[n] > O_S[n]$

**10.9.1 Proof**

$$O[n] := O_T[n] + O_S[n]$$

$$O_T[n] > 0$$

$$\therefore O[n] > O_S[n]$$

$$\mathbf{10.10} \quad O[n+1] \geq O[n]$$

**10.10.1 Proof**

$$X_i = \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\}$$

$$O[n] = |s^+[X_i]|$$

$$O[n+1] = \hat{O}[n] = |s^+[\hat{X}_i]|$$

For general solutions  $s^+$

$$s^+[\hat{X}_i] \supseteq s^+[X_i]$$

$$\Rightarrow |s^+[\hat{X}_i]| \geq |s^+[X_i]|$$

$$\therefore \hat{O}[n] = O[n+1] \geq O[n]$$

## 11 Polynomial Complexity

### 11.1 Definition

Decision problem  $D$  with solution  $s^+$  has polynomial total complexity  $O[n]$  if

$$\begin{aligned} & \exists K, C, \lambda_1 \dots \lambda_K : \\ & O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \end{aligned}$$

### 11.2 Polynomial Problems

Define  $\mathbb{P}$ , the set of Decision Problems that can be solved with Polynomial Complexity

$$\begin{aligned} & \mathbb{P} := \{D_1, D_2, \dots\} : \\ & \exists K, C, \lambda_1 \dots \lambda_K : \\ & O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n, D_i \in \mathbb{P} \end{aligned}$$

### 11.3 Polynomial Order of Complexity

Solution  $s^+$  with total complexity  $O[n]$  is said to be of order  $n^K$

$$\begin{aligned} & O[n] \sim n^K \\ & O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \end{aligned}$$

### 11.4 Property of Polynomial Complexity 1

Solutions with polynomial complexity have convergent complexity

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1$$

#### 11.4.1 Proof

$$\begin{aligned} & O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \\ & O[n+1] = (\lambda_K (n+1))^K + (\lambda_{K-1} (n+1))^{K-1} \dots + \lambda_1 (n+1) + C \\ & = (\lambda_K n)^K + (\tilde{\lambda}_{K-1} n)^{K-1} \dots + \tilde{\lambda}_1 n + \tilde{C} \\ & \lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \\ & = \lim_{n \rightarrow \infty} \frac{(\lambda_K n)^K + (\tilde{\lambda}_{K-1} n)^{K-1} \dots + \tilde{\lambda}_1 n + \tilde{C}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} \end{aligned}$$

$$\begin{aligned}
&= \lim_{n \rightarrow \infty} \frac{(\lambda_K n)^K}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} + \frac{(\tilde{\lambda}_{K-1} n)^{K-1}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} + \dots + \\
&\quad \frac{\tilde{\lambda}_1 n}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} + \frac{\tilde{C}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} \\
&= 1 = \lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]}
\end{aligned}$$

## 11.5 Property of Polynomial Complexity 2

$$\begin{aligned}
&\exists K, \hat{C}, \hat{\lambda}_1, \dots, \hat{\lambda}_{K-1} : \\
O[n+1] - O[n] &= f_{n+1}[n] = (\hat{\lambda}_{K-1} n)^{K-1} \dots + \hat{\lambda}_1 n + \hat{C} \quad \forall n
\end{aligned}$$

### 11.5.1 Proof

$$\begin{aligned}
O[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \\
O[n+1] &= (\lambda_K (n+1))^K + (\lambda_{K-1} (n+1))^{K-1} \dots + \lambda_1 (n+1) + C \\
&= (\lambda_K n)^K + (\tilde{\lambda}_{K-1} n)^{K-1} \dots + \tilde{\lambda}_1 n + \tilde{C} \\
O[n+1] - O[n] &= ((\tilde{\lambda}_{K-1} - \lambda_{K-1}) n)^{K-1} \dots + (\tilde{\lambda}_1 - \lambda_1) n + (\tilde{C} - C) \\
O[n+1] - O[n] &= (\hat{\lambda}_{K-1} n)^{K-1} \dots + \hat{\lambda}_1 n + \hat{C}
\end{aligned}$$

## 11.6 Total Polynomial Complexity Implies Time bounded Polynomial Complexity

$$D \in \mathbb{P} \implies O_T[n] < (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C$$

### 11.6.1 Proof

$$\begin{aligned}
O[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \\
O[n] &:= O_T[n] + O_S[n]; \quad O_S[n] > 0 \\
\therefore O_T[n] &< (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n
\end{aligned}$$

## 11.7 Total Polynomial Complexity Implies Space bounded Polynomial Complexity

$$D \in \mathbb{P} \implies O_S[n] < (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C$$

### 11.7.1 Proof

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

$$O[n] := O_T[n] + O_S[n]; \quad O_T[n] > 0$$

$$\therefore O_S[n] < (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

## 12 Non-Polynomial Complexity

### 12.1 Definition

Decision problem  $\tilde{D}$  with solution  $s^+$  has non-polynomial total complexity  $O[n]$  if

$$\nexists K, C, \lambda_1 \dots \lambda_K : \\ O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

### 12.2 Non-Polynomial Problems

Define  $\mathcal{N}$ , the set of Decision Problems that cannot be solved with Polynomial Complexity

$$\mathcal{N} := \{\tilde{D}_1, \tilde{D}_2, \dots\} : \\ \nexists K, C, \lambda_1 \dots \lambda_K : \\ O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n, s^+ \in S_i^+, \tilde{D}_i \in \mathcal{N}$$

### 12.3 $\mathbb{P}$ and $\mathcal{N}$ are disjoint

$$\mathbb{P} \cap \mathcal{N} = \emptyset$$

#### 12.3.1 Proof

Let  $D \in \mathcal{N}$

$$\nexists K, C, \lambda_1 \dots \lambda_K : \\ O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

Assume  $D \in \mathbb{P}$

$$\exists K, C, \lambda_1 \dots \lambda_K : \\ O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

Contradicts the definition of  $\mathcal{N}$

$$\therefore D \in \mathcal{N} \Rightarrow D \notin \mathbb{P}$$

Let  $D \in \mathbb{P}$

$$\begin{aligned} & \exists K, C, \lambda_1 \dots \lambda_K : \\ O[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \end{aligned}$$

Assume  $D \in \mathcal{N}$

$$\begin{aligned} & \nexists K, C, \lambda_1 \dots \lambda_K : \\ O[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \end{aligned}$$

Contradicts the definition of  $\mathbb{P}$

$$\therefore D \in \mathbb{P} \Rightarrow D \notin \mathcal{N}$$

$$D \in \mathcal{N} \Rightarrow D \notin \mathbb{P}; D \in \mathbb{P} \Rightarrow D \notin \mathcal{N}$$

$$\therefore \mathbb{P} \cap \mathcal{N} = \emptyset$$

## 13 Divergent Complexity

### 13.1 Definition

Decision problem  $\hat{D}$  with solution  $s^+$  has divergent total complexity  $O[n]$  if

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges } \forall n$$

### 13.2 Divergent Problems

$$\mathcal{D} := \{\hat{D}_1, \hat{D}_2, \dots\} :$$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges } \forall s^+ \in S_i^+, \hat{D}_i \in \mathcal{D}$$

### 13.3 The Set of Polynomial Solutions and the Set of Divergent Solutions are disjoint

$$\mathbb{P} \cap \hat{D} = \emptyset$$

### 13.4 Proof

Let  $D \in \hat{D}$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges by definition}$$

Assume  $D \in \mathbb{P}$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1$$

$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1$  contradicts the definition of Divergent Problems

$$\therefore D \in \hat{\mathcal{D}} \Rightarrow D \notin \mathbb{P}$$

Let  $D \in \mathbb{P}$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1 \text{ by property of Polynomial complexity}$$

Assume  $D \in \hat{\mathcal{D}}$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges}$$

$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges}$  contradicts a property of Polynomial complexity

$$\therefore D \in \mathbb{P} \Rightarrow D \notin \hat{\mathcal{D}}$$

$$\therefore \mathbb{P} \cap \hat{\mathcal{D}} = \emptyset$$



## 14 Inductive Functions

### 14.1 Inductive Function $f_{n+1}$

$$\begin{aligned} O[n] &:= O_T[n] + O_S[n] \\ O[n+1] &= O_T[n+1] + O_S[n+1] \\ f_{n+1}[n] &:= O[n+1] - O[n] \end{aligned}$$

### 14.2 Inductive Space and Time Formulas

$$\begin{aligned} f_{n+1}^T[n] &:= O_T[n+1] - O_T[n] \\ O_T[n+1] &= O_T[n] + f_{n+1}^T[n] \\ f_{n+1}^S[n] &:= O_S[n+1] - O_S[n] \\ O_S[n+1] &= O_S[n] + f_{n+1}^S[n] \end{aligned}$$

### 14.3 Inductive Function Expressions

Relate  $f_{n+1}[n]$  to equivalence functions

$$\begin{aligned} D &\in \mathbb{P} \\ O[n] &:= O_T[n] + O_S[n] \\ O[n+1] &= O_T[n+1] + O_S[n+1] = O[n] + f_{n+1}[n] \\ O_T[n] &= O[n] - O_S[n] \\ O_S[n] &= O[n] - O_T[n] \\ f_{n+1} &= O[n+1] - O[n] \\ f_{n+1} &= O_T[n+1] + O_S[n+1] - O[n] \\ f_{n+1} &= O_T[n+1] - O_T[n] + O_S[n+1] - O_S[n] \\ f_{n+1} &= O[n+1] - O_T[n] - O_S[n] \\ f_{n+1}[n] &= f_{n+1}^T[n] + f_{n+1}^S[n] \end{aligned}$$

### 14.4 Zero Order Inductive Function

$$\begin{aligned} \text{Let } O_S[n] &\sim n^0 \\ f_{n+1} &= O_T[n+1] - O_T[n] + O_S[n+1] - O_S[n] = O_T[n+1] - O_T[n] \end{aligned}$$

## 14.5 Property of Polynomial Complexity

$$\lim_{n \rightarrow \infty} \frac{f_{n+1}[n]}{O[n]} = 0$$

### 14.5.1 Proof

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1$$

$$\lim_{n \rightarrow \infty} \frac{O[n] + f_{n+1}[n]}{O[n]} = 1$$

$$\lim_{n \rightarrow \infty} \frac{O[n]}{O[n]} + \frac{f_{n+1}[n]}{O[n]} = 1$$

$$\lim_{n \rightarrow \infty} 1 + \frac{f_{n+1}[n]}{O[n]} = 1$$

$$\lim_{n \rightarrow \infty} \frac{f_{n+1}[n]}{O[n]} = 0$$

## 15 Subfunctions

### 15.1 Restate the subfunction condition of general solutions

Recall the definition of general solution  $s^+$

$$\begin{aligned} X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\ s^+ &= s^+[X_i] := P : \\ (P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \end{aligned}$$

The subfunction condition is one of two conditions for a general solution

$$P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i$$

### 15.2 Prove $O[n]$ is a non-decreasing function

Consider solution  $s^+$  with complexity  $O[n]$

$$\begin{aligned} X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\ s^+ &= s^+[X_i] := P : \\ (P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\ s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\ &= \{\mathcal{L}, \mathcal{M}, y_o\} \end{aligned}$$

$$O[n] := O_T[n] + O_S[n]$$

$$O_T[n] := |\mathcal{L}| = N$$

$$O_S[n] := |\mathcal{M}| + |y_o| = M + 1$$

$O[n+1]$  denotes the total complexity for solution  $s^+[\hat{X}_i]$

$$s^+[\hat{X}_i] = \hat{s}^+$$

Let

$$\begin{aligned}
O[n+1] &< O[n] \\
\Rightarrow \hat{N} + \hat{M} &< N + M \\
\hat{s}^+ &= \{s_1, s_2, \dots, s_{\hat{N}} | b_1, b_2, \dots, b_{\hat{M}}, y_o\} \\
&\Rightarrow \hat{s}^+ \not\supseteq s^+ \\
P[\hat{X}_i] &\not\supseteq P[X_i] \quad \forall X_i, \hat{X}_i
\end{aligned}$$

$\therefore O[n+1] < O[n]$  contradicts the definition of solution  $s^+$

$$O[n+1] \geq O[n]$$

### 15.3 Definition of Subfunction

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\
s^+ &= s^+[X_i] := P : \\
(P[X_i] \rightarrow y_o = a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
&= \{\mathcal{L}, \mathcal{M}, y_o\}
\end{aligned}$$

$$\begin{aligned}
Sub[X_i] &:= S = \{s_j, \dots | b_k, \dots, y_o\} : \\
s_j, b_k &\in s^+ \quad \forall s_j, b_k \in S
\end{aligned}$$

#### 15.3.1 $s^+[X_i]$ is a subfunction of $s^+[\hat{X}_i]$

$$\begin{aligned}
s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
\hat{s}^+ &= \{s_1, s_2, \dots, s_N, \dots, s_{\hat{N}} | b_1, b_2, \dots, b_M, \dots, b_{\hat{M}}, y_o\}; \quad \hat{N} + \hat{M} \geq N + M
\end{aligned}$$

By definition of solution

$$\begin{aligned}
\hat{s}^+ &= P[\hat{X}_i] \supseteq P[X_i] = s^+ \quad \forall X_i, \hat{X}_i \\
&\Rightarrow s_j, b_k \in \hat{s}^+ \quad \forall s_j, b_k \in s^+
\end{aligned}$$

### 15.4 Subfunction Decomposition of Solutions

FIX Double check conditions!!! Solutions  $s^+$  can be written as the union of subfunctions  $Sub_k[X_i]$

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\
s^+ &= s^+[X_i] := P : \\
(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
&= \{\mathcal{L}, \mathcal{M}, y_o\} \\
s^+ &= Sub_1[X_i] \cup Sub_2[X_i] \cup \dots \cup Sub_z[X_i] \\
&= \{\mathcal{L}_1 | \mathcal{M}_1, y_o\} \cup \{\mathcal{L}_2 | \mathcal{M}_2, y_o\} \cup \dots \cup \{\mathcal{L}_z | \mathcal{M}_z, y_o\} : \\
&\quad \mathcal{L}_j \cap \mathcal{L}_k = \emptyset \quad \forall j, k \neq j \\
s^+ &= \{s_1^1, \dots, s_{N_1}^1 | b_1^1, \dots, y_o\} \cup \{s_1^2, \dots, s_{N_2}^2 | b_1^2, \dots, y_o\} \cup \dots \cup \{s_1^z, \dots, s_{N_z}^z | b_1^z, \dots, y_o\} : \\
&\quad \sum_{l=1}^z N_l = N = O_T[n]
\end{aligned}$$

## 16 Subfunction Complexity

### 16.1 Disjoint Subfunction Operations

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$$

### 16.2 Shared Subfunction Memory

$$|\mathcal{M}_i \cap \mathcal{M}_j| \geq 0 \quad \forall i, j \neq i$$

#### 16.2.1 Time Complexity of Subfunctions

Subfunction time complexity is additive

$$s^+ = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$\begin{aligned}
Sub_i[X] &:= S_i = \{s_j, \dots | b_k, \dots, y_o\} : \\
s_j, b_k &\in s^+ \quad \forall s_j, b_k \in S_i
\end{aligned}$$

$$\begin{aligned}
s^+ &= \{\mathcal{L}_1 | \mathcal{M}_1, y_o\} \cup \{\mathcal{L}_2 | \mathcal{M}_2, y_o\} \cup \dots \cup \{\mathcal{L}_z | \mathcal{M}_z, y_o\} : \\
\mathcal{L}_i \cap \mathcal{L}_j &= \emptyset \quad \forall i, j \neq i
\end{aligned}$$

$$\mathcal{L} = \cup_{i=1}^z \mathcal{L}_i$$

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$$

$$\begin{aligned} O_T[n] &= |\mathcal{L}| = N \\ O_T[n] &= |\cup_{i=1}^z \mathcal{L}_i| = \sum_{i=1}^z |\mathcal{L}_i|^* = |\mathcal{L}_1| + |\mathcal{L}_2| + \dots + |\mathcal{L}_z| \\ &= O_{T_1}[n] + O_{T_2}[n] + \dots + O_{T_z}[n] = N_1 + N_2 + \dots + N_z \end{aligned}$$

\*Due to the disjoint condition of subfunction operations  $\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$

### 16.2.2 Space Complexity of Subfunctions

Subfunctions can access the full memory  $\mathcal{M}$  with no added space complexity

$$s^+ = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$Sub_i[X] := S_i = \{s_j, \dots | b_k, \dots, y_o\} :$$

$$s_j, b_k \in s^+ \quad \forall s_j, b_k \in S_i$$

$$s^+ = \{\mathcal{L}_1 | \mathcal{M}_1, y_o\} \cup \{\mathcal{L}_2 | \mathcal{M}_2, y_o\} \cup \dots \cup \{\mathcal{L}_z | \mathcal{M}_z, y_o\} :$$

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$$

$$s^+ = \{\mathcal{L}_1 | \mathcal{M}, y_o\} \cup \{\mathcal{L}_2 | \mathcal{M}, y_o\} \cup \dots \cup \{\mathcal{L}_z | \mathcal{M}, y_o\} :$$

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$$

$$\mathcal{M} = \cup_{i=1}^z \mathcal{M}_i = \cup_{i=1}^z \mathcal{M}$$

$$O_S[n] = |\mathcal{M}| = M$$

$$O_S[n] = |\cup_{i=1}^z \mathcal{M}_i| = M$$

### 16.2.3 Shared State Notation

$$s^+ = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$Sub_i[X] := S_i = \{s_j, \dots | b_k, \dots, y_o\} :$$

$$s_j, b_k \in s^+ \quad \forall s_j, b_k \in S_i$$

$$s^+ = \{\mathcal{L}_1 | \mathcal{M}, y_o\} \cup \{\mathcal{L}_2 | \mathcal{M}, y_o\} \cup \dots \cup \{\mathcal{L}_z | \mathcal{M}, y_o\} :$$

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$$

## 17 Polynomial Solution Subfunction Properties

### 17.1 Restate Definition of Subfunction

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\
s^+ &= s^+[X_i] := P : \\
(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
&= \{\mathcal{L}, \mathcal{M}, y_o\}
\end{aligned}$$

$$\begin{aligned}
Sub[X_i] &:= S = \{s_j, \dots | b_k, \dots, y_o\} : \\
s_j, b_k &\in s^+ \quad \forall s_j, b_k \in S
\end{aligned}$$

### 17.2 Property of Polynomial Solution Subfunctions

Let

$$D \in \mathbb{P}$$

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\
s^+ &= s^+[X_i] := P : \\
(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
\exists K, C, \lambda_1 \dots \lambda_K &: \\
O[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \\
s^+ &= Sub_1[X_i] \cup Sub_2[X_i] \cup \dots \cup Sub_z[X_i] \\
\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} &= 1 \\
&= \lim_{n \rightarrow \infty} \frac{O_T^1[n+1] + O_T^2[n+1] + \dots + O_T^z[n+1] + O_S[n+1]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} \\
&= \lim_{n \rightarrow \infty} \frac{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n] + f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \dots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} \\
&= \lim_{n \rightarrow \infty} 1 + \frac{f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \dots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} = 1
\end{aligned}$$



$$\begin{aligned}
&\Rightarrow \lim_{n \rightarrow \infty} \frac{f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \dots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} = 0^* \\
&\Rightarrow \lim_{n \rightarrow \infty} \frac{f_{T_{n+1}}^i[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} = 0 \quad \forall i \\
&\lim_{n \rightarrow \infty} \frac{f_{n+1}^i[n]}{O[n]} = 0 \quad \forall i
\end{aligned}$$

\*  $O[n]$  is a positive, non-decreasing function

## 18 Sum to N Problem with 2 integers

### 18.1 State formal definition of Sum to N : $x_i + x_j == N$

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, N\} \\
D &:= f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i \\
s^+ &= P : \\
(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
s^+ &= \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} = \{\mathcal{L}, \mathcal{M}, y_o\} \\
D &= f[X_i] = \exists x_j, x_k \in X_i : x_j + x_k == N
\end{aligned}$$

### 18.2 Express a formal solution : $O_S[n] \sim n^0$

$$\begin{aligned}
s^+ &= \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} = \{\mathcal{L}, \mathcal{M}, y_o\} \\
s_1 &= y_o \leftarrow \mathbb{F}; \\
\forall i, j &> i \\
s_2, s_3, s_8, s_9, \dots, s_{3ij-4}, s_{3ij-3}, \dots, s_{3n(n-1)-4}, s_{3n(n-1)-3} &= b_1 \leftarrow x_i + x_j \\
s_4, s_5, s_{10}, s_{11}, \dots, s_{3ij-2}, s_{3ij-1}, \dots, s_{3n(n-1)-2}, s_{3n(n-1)-1} &= b_1 \leftarrow b_1 == N \\
s_6, s_7, s_{12}, s_{13}, \dots, s_{3ij}, s_{3ij+1}, \dots, s_{3n(n-1)}, s_{3n(n-1)+1} &= y_o \leftarrow y_o \vee b_1 \\
s^+ &= \{y_o \leftarrow \mathbb{F}, y_o \leftarrow y_o \vee (x_i + x_j == N) \quad \forall i, j > i \mid b_1, y_o\}
\end{aligned}$$

### 18.3 Show $s^+$ satisfies the subfunction condition of solutions:

$$P[\hat{X}_i] \supseteq P[X_i] \quad \forall \hat{X}_i, X_i$$

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, N\}; \quad \hat{X}_i = \{x_1, \dots, x_n, x_{n+1}, N\} \\
s^+ &= \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} = \{\mathcal{L}, \mathcal{M}, y_o\} \\
s_{n+1}^+ &= s^+ \cup \hat{s}^+ \\
s_1 &= y_o \leftarrow \mathbb{F}; \\
\forall i, j &> i \\
s_2, s_3, s_8, s_9, \dots, s_{3ij-4}, s_{3ij-3}, \dots, s_{3n(n-1)-4}, s_{3n(n-1)-3} &= b_1 \leftarrow x_i + x_j \\
s_4, s_5, s_{10}, s_{11}, \dots, s_{3ij-2}, s_{3ij-1}, \dots, s_{3n(n-1)-2}, s_{3n(n-1)-1} &= b_1 \leftarrow b_1 == N
\end{aligned}$$

$$s_6, s_7, s_{12}, s_{13}, \dots, s_{3ij}, s_{3ij+1}, \dots, s_{3n(n-1)}, s_{3n(n-1)+1} = y_o \leftarrow y_o \vee b_1$$

$$\forall k$$

$$s \dots = b_1 \leftarrow x_k + x_{n+1}$$

$$s \dots = b_1 \leftarrow b_1 == N$$

$$s \dots = y_o \leftarrow y_o \vee b_1$$

$$s^+ = \{y_o \leftarrow \mathbb{F}, y_o \leftarrow y_o \vee (x_i + x_j == N) \mid \forall i, j > i \mid b_1, y_o\}$$

$$\hat{s}^+ = \{y_o \leftarrow y_o \vee (x_k + x_{n+1} == N) \mid \forall k < n + 1 \mid b_1, y_o\}$$

$$s_{n+1}^+ = \{y_o \leftarrow \mathbb{F}, y_o \leftarrow y_o \vee (x_i + x_j == N) \mid \forall i, j > i \mid b_1, y_o\} \cup$$

$$\{y_o \leftarrow y_o \vee (x_k + x_{n+1} == N) \mid \forall k < n + 1 \mid b_1, y_o\}$$

$$s_{n+1}^+ = P[\hat{X}_i] \supseteq P[X_i] = s^+$$

**18.4 Determine  $O[n]$ ,  $O_S[n]$ ,  $O_T[n]$ ,  $\hat{O}[n]$ ,  $\hat{O}_T[n]$ ,  $\hat{O}_S[n]$  for the above solution**

$$O_S[n] = |y_o| + |b_1| = 2$$

$$O_T[n] = 3n(n-1) + 1 = 3n(n-1) - 1 + O_S[n]$$

$$O[n] = 3n(n-1) + 3 = 3n^2 - 3n + 3$$

$$\hat{O}_S[n] = 0$$

$$\hat{O}_T[n] = 6n$$

$$\hat{O}[n] = \hat{O}_S[n] + \hat{O}_T[n]$$

**18.5 Verify  $O[n+1] = O[n] + \hat{O}[n]$**

$$O[n+1] = O[n] + \hat{O}[n]$$

$$3(n+1)^2 - 3(n+1) + 3 = 3n^2 - 3n + 3 + 6n$$

$$3n^2 + 6n + 3 - 3n - 3 + 3 = 3n^2 + 3n + 3$$

$$3n^2 + 3n + 3 = 3n^2 + 3n + 3$$

**18.6 Show  $s^+$  has Polynomial Complexity by the definition of Total Polynomial Complexity**

$$O[n] = 3n^2 - 3n + 3$$

**18.7 Show  $s^+$  has Polynomial Complexity by showing  $\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1$**

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} =$$

$$\lim_{n \rightarrow \infty} \frac{3n^2 + 3n + 3}{3n^2 - 3n + 3} =$$

$$\lim_{n \rightarrow \infty} \left( \frac{3n^2 - 3n + 3}{3n^2 - 3n + 3} + \frac{6n}{3n^2 - 3n + 3} \right) =$$

$$\lim_{n \rightarrow \infty} \left( 1 + \frac{6n}{3n^2 - 3n + 3} \right) = 1$$

## Traveling Salesman Problem of Dimension 2

### 19 Proof of the existence of $\mathcal{N}$

#### 19.1 The Traveling Salesman Problem of Dimension 2

English description

#### 19.2 Formal Definition

$$X_i = \{l_1, l_2, \dots, l_n, C\}$$

$$l_i = \{x_i, y_i\} \quad \forall i$$

$l_i$  denotes the 2D coordinates of location  $i$

$$C = \{d_{proposed}, p_{decimal}\}$$

$d_{proposed}$  denotes the suggested shortest distance

$p_{decimal}$  is the decimal precision

$$L[l_i, l_j] := \sqrt{(y_j - y_i)^2 + (x_j - x_i)^2}$$

Let  $L[l_i, l_j]$  denote the distance between location  $l_i$  and  $l_j$

$$\tilde{L}[l_i, l_j] := d_{trunc} : -p_{decimal} < d_{trunc} - L[l_i, l_j] < p_{decimal}$$

Let  $\tilde{L}[l_i, l_j]$  denote a truncated decimal representation of  $L[l_i, l_j]$

$$R_i := \{r_1, r_2, \dots, r_n, r_1\} : r_i \in X_i \quad \forall i; \quad r_i \neq r_j$$

Let  $R_i$  denote route  $i$

$$L_{Total}[R_i] := (\sum_{i=1}^{n-1} \tilde{L}[r_i, r_{i+1}]) + \tilde{L}[r_n, r_1]$$

Let  $L_{Total}[R_i]$  denote the sum of truncated lengths of route  $R_i$

$$D := f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

$$a_o =$$

$$(\exists R_k : L_{total}[R_k] == d_{proposed}) \cap (\nexists R_j : L_{total}[R_j] < d_{proposed})$$

## Traveling Salesman Problem of Dimension 2

### 19.3 Define subpath, subpath distance, subpath storage

$\tilde{L}[l_i, l_j]$  denotes "the distance of a subpath of length 1"

$$\begin{aligned}\tilde{L}[l_i, l_j] &:= d_{trunc} : -p_{decimal} < d_{trunc} - L[l_i, l_j] < p_{decimal} \\ &= abs(d_{trunc} - L[l_i, l_j]) < p_{decimal}\end{aligned}$$

$\tilde{R}$  denotes a subpath of length k

$$\tilde{R} = \{\tilde{r}_1, \tilde{r}_2, \dots, \tilde{r}_k\} : \tilde{r}_i \in X_i \quad \forall i, r_i \neq r_j$$

$\tilde{L}_k[\tilde{R}]$  denotes "the distance of a subpath of length k"

$$\tilde{L}_k[\tilde{R}] := \sum_{i=1}^k \tilde{L}[\tilde{r}_i, \tilde{r}_{i+1}]$$

Let  $\mathcal{M}_1$  denote the memory reserved for subpaths distances of length 1

$$\begin{aligned}\mathcal{M}_1 &= \{\hat{b}_{1;1}, \hat{b}_{1;2}, \hat{b}_{1;3}, \dots, \hat{b}_{startindex;finishindex}, \dots, \hat{b}_{n-1;n}\}^* \\ \mathcal{M} &\supseteq \mathcal{M}_1\end{aligned}$$

\* Note  $\hat{b}_{i;j} = \hat{b}_{j;i}$   
 $\sqrt{(y_j - y_i)^2 + (x_j - x_i)^2} = \sqrt{(y_i - y_j)^2 + (x_i - x_j)^2}$

### 19.4 Define the following functions

**19.4.1**  $sqrt[x, p_{decimal}] = \sqrt{x}$  [1]

**19.4.2**  $pow[x, 2, p_{decimal}] = x^2$  [2]

### 19.5 Define the following subfunctions

#### 19.5.1 loadM1Subpaths[X]

// Computes all subpaths of length 1 and stores in  $\mathcal{M}_1 = \{\hat{b}_{1;1}, \hat{b}_{1;2}, \dots, \hat{b}_{n-1;n}\}$

$$\begin{aligned}//X_i &= \{l_1, l_2, \dots, l_n, C\} \\ //l_i &= \{x_i, y_i\} \quad \forall i\end{aligned}$$

$$// \mathcal{M} = \{b_1, b_2, \dots, b_M, \hat{b}_{1;1}, \hat{b}_{1;2}, \dots, \hat{b}_{n-1;n}, y_o\} = \{b_1, b_2, \dots, b_M, \mathcal{M}_1, y_o\} = \{\mathcal{M}, \mathcal{M}_1, y_o\}$$

$$\forall i, j > i$$

$$b_3 \leftarrow y_i - y_j$$

$$b_4 \leftarrow x_i - x_j$$

$$b_3 \leftarrow b_3^2$$

$$b_4 \leftarrow b_4^2$$

$$b_3 \leftarrow b_3 + b_4$$

$$\hat{b}_{i;j} \leftarrow \sqrt{b_3}^*$$

$$*\hat{b}_{i;j} = \tilde{L}[l_i, l_j]$$

### 19.5.2 computeAllRoutes[X]

// Computes all complete routes, checks for a route ==  $d_{proposed}$ , sets  $y_o$  to false if the current route is shorter than  $d_{proposed}$

$$\forall i, j \neq i, k \neq i, j, \dots, q \neq i, j, \dots, m$$

$$b_3 \leftarrow \hat{b}_{1;j} + \hat{b}_{j;k}$$

$$b_3 \leftarrow b_3 + \hat{b}_{k;l}$$

...

$$b_3 \leftarrow b_3 + \hat{b}_{m;q}$$

$$b_3 \leftarrow b_3 + \hat{b}_{q;1}$$

$$b_4 \leftarrow b_3 == b_2$$

$$b_1 \leftarrow b_1 \vee b_4$$

$$b_4 \leftarrow b_2 \leq b_3$$

$$y_o \leftarrow y_o \wedge b_4$$

## 19.6 Express a solution using subfunctions, storing subpaths of length 1 in memory

//  $d_{proposed}$  is the shortest path

$$y_o \leftarrow \mathbb{T}$$

//  $d_{proposed}$  exists as a total path length

$$b_1 \leftarrow \mathbb{F}$$

// shortest path register

$$b_2 \leftarrow d_{proposed}$$

$loadM1Subpaths[X]$

$computeAllRoutes[X]$

**19.7 Show each subfunction satisfies the subfunction condition of solutions :**  $P[\hat{X}_i] \supseteq P[X_i] \quad \forall \hat{X}_i, X_i, \quad \hat{X}_i \supseteq X_i$

Let

$$\mathcal{M}_0 = \{b_1, b_2, b_3, b_4, y_o\}$$

$$\mathcal{M}_1 = \{\hat{b}_{1;1}, \hat{b}_{1;2}, \dots, \hat{b}_{n-1;n}\}$$

**19.7.1**  $loadM1Subpaths[X] \rightarrow \mathcal{M}_1$

Let

$$//X = \{l_1, l_2, \dots, l_n, C\}; \quad \hat{X} = \{l_1, l_2, \dots, l_n, l_{n+1}, C\}$$

$$loadM1Subpaths[X, \mathcal{M}] \rightarrow \mathcal{M}_1 = Sub_1[X, \mathcal{M}] \rightarrow \mathcal{M}_1$$

$$Sub_1[X, \mathcal{M}] = \{\mathcal{L}, \mathcal{M}\}$$

$$= \{\hat{b}_{i;j} \leftarrow \tilde{L}[l_i, l_j] \quad \forall i, j > i | b_3, b_4, \hat{b}_{1;1}, \hat{b}_{1;2}, \dots, \hat{b}_{n-1;n}\}$$

$$Sub_1[X_i, \mathcal{M}] = \{\hat{b}_{i;j} \leftarrow \tilde{L}[l_i, l_j] \quad \forall i, j > i | b_3, b_4, \mathcal{M}_1\}$$

$$Sub_1[\hat{X}, \mathcal{M}] = \{\hat{\mathcal{L}}, \hat{\mathcal{M}}\}$$

$$= \{\hat{b}_{i;j} \leftarrow \tilde{L}[l_i, l_j] \quad \forall i, j > i | b_3, b_4, \hat{b}_{1;1}, \hat{b}_{1;2}, \dots, \hat{b}_{n;n+1}\}$$

$$= \{\mathcal{L}, \hat{b}_{i;j} \leftarrow \tilde{L}[l_i, l_j] \quad \forall i, j = n+1 | \mathcal{M}, \hat{b}_{1;n+1}, \hat{b}_{2;n+1}, \dots, \hat{b}_{n;n+1}\}$$

$$Sub_1[\hat{X}, \mathcal{M}] = \{\mathcal{L}, \mathcal{L}_{n+1} | \mathcal{M}, \mathcal{M}_{n+1}\}$$

$$Sub_1[\hat{X}, \mathcal{M}] = \{\mathcal{L}, \mathcal{L}_{n+1} | \mathcal{M}, \mathcal{M}_{n+1}\} \supseteq \{\mathcal{L} | \mathcal{M}\} = Sub_1[X, \mathcal{M}]$$



### 19.7.2 *computeAllRoutes*[X]

Let

$$\begin{aligned}
& \text{computeAllRoutes}[X] = \text{Sub}_2[X] \\
& \text{Sub}_2[X] = \{\mathcal{L}, \mathcal{M}, y_o\} \\
& = \{\hat{b}_{1;i_2} + \hat{b}_{i_2;i_3} + \hat{b}_{i_3;i_4} + \dots + \hat{b}_{i_n;1} \mid \forall i_2, i_3 \neq i_2, i_4 \neq i_2, i_3 \dots i_n \neq i_2, i_3, \dots, i_{n-1} \\
& \quad | b_1, b_2, b_3, b_4, \mathcal{M}_1, y_o\} \\
& \text{Sub}_2[\hat{X}] = \{\hat{\mathcal{L}}, \hat{\mathcal{M}}, y_o\} \\
& = \{\hat{b}_{1;i_2} + \hat{b}_{i_2;i_3} + \hat{b}_{i_3;i_4} + \dots + \hat{b}_{i_{n+1};1} \mid \forall i_2, i_3 \neq i_2, i_4 \neq i_2, i_3 \dots i_{n+1} \neq i_2, i_3, \dots, i_n \\
& \quad | \mathcal{M}, \mathcal{M}_{n+1}, y_o\}
\end{aligned}$$

Let

$$\begin{aligned}
& \text{insert\_subpath}[\mathcal{L}] = \\
& \text{Sub}_2[\hat{X}] = \{\text{insert\_subpath}[\mathcal{L}, \hat{b}_{i_{n+1};j}, j] \mid \forall j \neq n+1 | \mathcal{M}, \mathcal{M}_{n+1}, y_o\}
\end{aligned}$$

**19.7.3 Show the overall solution storing subpaths of length 1 satisfies the subfunction condition of solutions :  $P[\hat{X}_i] \supseteq P[X_i] \mid \forall \hat{X}_i, X_i$**

**19.8 Express  $O[n]$  in terms of subfunction complexities**

$$\begin{aligned}
O_{\text{sub1}}[n] &= O_{T_{\text{sub1}}}[n] + O_{S_{\text{sub1}}}[n] \\
O_{\text{sub2}}[n] &= O_{T_{\text{sub2}}}[n] + O_{S_{\text{sub2}}}[n] \\
O[n] &= O_{\text{sub1}}[n] + O_{\text{sub2}}[n] + 3
\end{aligned}$$

### 19.9 $\text{Sub}_+[X]$

Let  $\text{Sub}_+[X]$  denote a subfunction that adds all subpaths of length 1

Let  $O_+[n]$  denote the total complexity of subfunction  $\text{Sub}_+[X]$

**19.9.1 Find an expression for  $O_+[n] :=$  the number of  $\tilde{L}[l_i, l_j] + \tilde{L}[l_j, l_k]$  length 1 subpath additions**

$$O_+[n] = (\sum_{i=1}^n 1) \frac{(nP(n-1))}{2}$$

$$O_+[n] = \frac{n(n-1)!}{2}$$

$$O_+[n] = \frac{n!}{2}$$

**19.10 Prove  $Sub_+[X]$  is a subfunction of all  $s^+$  by contradiction**

suppose not all subpaths are considered  
there could exist subpath resulting in an incorrect solution  
contradicts definition of solution

**19.11 Show the solution storing subpaths of length 1 contains  $Sub_+[X]$**

//  $d_{proposed}$  is the shortest path  
 $y_o \leftarrow \mathbb{T}$

//  $d_{proposed}$  exists as a total path length  
 $b_1 \leftarrow \mathbb{F}$

// shortest path register  
 $b_2 \leftarrow d_{proposed}$

$loadM1Subpaths[X]$   
 $computeAllRoutes[X]$

**19.12 Express  $O[n]$  in terms of subfunction complexities including  $O_+[n]$  as a subfunction complexity**

$$O[n] = O_{sub1}[n] + O_{sub2}[n] + 3$$

$$O_{sub2}[n] = O_+[n] + 8\frac{n^{P(n-1)}}{2}$$

$$O_{sub2}[n] = O_+[n] + 8\frac{(n-1)!}{2}$$

$$O[n] = O_{sub1}[n] + O_+[n] + 8\frac{(n-1)!}{2} + 3$$

**19.13 Show  $\lim_{n \rightarrow \infty} \frac{O_+[n+1]}{O_+[n]}$  diverges**

$$\lim_{n \rightarrow \infty} \frac{O_+[n+1]}{O_+[n]}$$

$$\begin{aligned}
&= \lim_{n \rightarrow \infty} \frac{(n+1)!}{2} \frac{2}{n!} \\
&= \lim_{n \rightarrow \infty} n
\end{aligned}$$

There does not exist ...  
therefore  $\lim_{n \rightarrow \infty} \frac{O_+[n+1]}{O_+[n]}$  diverges

#### 19.14 Prove D is not in $\mathbb{P}$ by the definition of Polynomial Complexity

Let

$Sub_i[X]$  denote all subfunctions of a solution  $s^+$  except  $Sub_+[X]$

$$\begin{aligned}
O[n] &= O_+[n] + \sum_{i=1}^z O_{i_T}[n] \\
O[n] &= \frac{n!}{2} + \sum_{i=1}^z O_{i_T}[n]
\end{aligned}$$

Assume  $O[n]$  satisfies the condition of Polynomial total complexity for  $n = \hat{n}$   
Let  $n = K!!!$

$$\begin{aligned}
&\exists K, C, \lambda_1 \dots \lambda_K : \\
O[\hat{n}] &= (\lambda_K \hat{n})^K + (\lambda_{K-1} \hat{n})^{K-1} \dots + \lambda_1 \hat{n} + C \\
&= \frac{\hat{n}!}{2} + \sum_{i=1}^z O_{i_T}[\hat{n}]
\end{aligned}$$

Let  $n = \hat{n} + 1$

$$\begin{aligned}
O[\hat{n} + 1] &= (\lambda_K \hat{n})^K + (\lambda_{K-1} \hat{n})^{K-1} \dots + \hat{\lambda}_1 \hat{n} + \hat{C} \sim (\lambda_K \hat{n})^K \\
&\neq \frac{(\hat{n}+1)!}{2} + \sum_{i=1}^z O_{i_T}[\hat{n} + 1] \sim (\lambda_K \hat{n})^{K+1}
\end{aligned}$$

$\therefore D \in \mathbb{P}$  is a contradiction

$\therefore D \notin \mathbb{P} \Rightarrow D \in \mathcal{N}$

#### 19.15 Prove D is not in $\mathbb{P}$ by limit property of Polynomial Complexity

Let

$Sub_i[X]$  denote all subfunctions of a solution  $s^+$  except  $Sub_+[X]$

$$O[n] = O_+[n] + \sum_{i=1}^z O_{i_T}[n]$$

$$O[n] = \frac{n!}{2} + \sum_{i=1}^z O_{i_T}[n]$$

Assume  $O[n]$  satisfies the condition of Polynomial total complexity

$$\exists K, C, \lambda_1 \dots \lambda_K : \\ O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C$$

$$f_{+_{n+1}}[n] = O_+[n+1] - O_+[n] = \frac{(n+1)!}{2} - \frac{n!}{2} \\ = \frac{n!(n+1-1)}{2} = \frac{n*n!}{2}$$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1$$

$$\lim_{n \rightarrow \infty} \frac{\frac{(n+1)!}{2} + \sum_{i=1}^z O_{i_T}[n+1]}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C}$$

$$\lim_{n \rightarrow \infty} \frac{\frac{(n+1)!}{2}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} + \frac{\sum_{i=1}^z O_{i_T}[n+1]}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C}$$

$$\lim_{n \rightarrow \infty} \frac{\frac{(n+1)!}{2}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} \text{ diverges}$$

$O_{i_T}[n+1]$  is a positive, non-decreasing function

$$\therefore \lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges}$$

$\therefore D \in \mathbb{P}$  contradicts the limit property of Polynomial solutions

$$\therefore D \notin \mathbb{P} \Rightarrow D \in \mathcal{N}$$

## Citations

- [1] *chatgpt*
- [2] *<https://stackoverflow.com/questions/3518973/floating-point-exponentiation-without-power-function>*
- [3] *<https://stackoverflow.com/questions/27086195/linear-index-upper-triangular-matrix>*
- [4] *<http://www.math.uchicago.edu/~may/VIGRE/VIGRE2011/REUPapers/Riffer-Reinert.pdf>*