

# Computation

## 1 Programs

### 1.1 Logical Instructions

Define  $\mathcal{L}$ ; an ordered set of operations  $s_i$

$$\mathcal{L} := \{s_1, s_2, \dots, s_N\}$$

### 1.2 Memory

Define Memory  $\mathcal{M}$ ; a set of elements, magnitudes, or sets  $b_i$

$$\mathcal{M} := \{b_1, b_2, \dots, b_M\}$$

### 1.3 Program

Define Program; a set of logical instructions and memory

$$P := \{s_1, s_2, \dots, s_N, b_1, b_2, \dots, b_M\}$$

#### 1.3.1 State Notation

Define State Notation; separating the final operation  $s_N$  and the first memory element  $b_1$

$$\begin{aligned} P &:= \{s_1, s_2, \dots, s_N, b_1, b_2, \dots, b_M\} \\ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M\} \end{aligned}$$

### 1.4 Boolean Programs

Define a boolean program; boolean programs can represent functions with inputs  $x_i$ , input set  $C$ , and boolean output  $y_o$

$$\begin{aligned} X &= \{x_1, \dots, x_n, C\}; \quad C = \{u_1, u_2, \dots, u_c\} \\ P &= P[X] := \{s_1, s_2, \dots, s_N \mid b_1, b_2, \dots, b_M, y_o\} = \\ &\quad P[X] \rightarrow y_o \in \{\mathbb{T}, \mathbb{F}\} \end{aligned}$$

### 1.5 Void Programs

Define a void program; a program with inputs  $x_i$ , input set C, and no output

$$X = \{x_1, \dots, x_n, C\}$$
$$P = P[X] := \{s_1, s_2, \dots, s_N \mid b_1, b_2, \dots, b_M\}$$

### 1.6 Numerical Programs

Define a numerical program; a program with inputs  $x_i$ , input set C, and real, rational output  $y_o$

$$X = \{x_1, \dots, x_n, C\}$$
$$P = P[X] := \{s_1, s_2, \dots, s_N \mid b_1, b_2, \dots, b_M, y_o\} =$$
$$P[X] \rightarrow y_o \in \mathbb{Q} \quad y_o \geq 0$$

### 1.7 System Programs

Define a system program; a program with inputs  $x_i$ , input set C, and real, output set  $Y_o$

$$X = \{x_1, \dots, x_n, C\}$$
$$P = P[X] := \{s_1, s_2, \dots, s_N \mid b_1, b_2, \dots, b_M, Y_o\} =$$
$$P[X] \rightarrow Y_o = \{y_1, y_2, \dots, y_K\}$$

### 1.8 Mathematical Programs

Define a mathematical program; a program with inputs  $x_i$ , input set C and numerical output  $y_o$

$$X = \{x_1, \dots, x_n, C\}$$
$$P = P[X] := \{s_1, s_2, \dots, s_N \mid b_1, b_2, \dots, b_M, y_o\} =$$
$$P[X] \rightarrow y_o \in \mathbb{Q}$$

## 2 Problem Definition

Also denoted as a "Question"

$$X_i = \{x_1, \dots, x_n\}$$
$$Q := f[X_i] = Y_o \subseteq \Omega \quad \forall X_i$$

### 2.1 Set of Questions

Define  $\mathbb{Q}$ ; the set of questions

$$\mathbb{Q} := \{Q_1, Q_2, \dots\} :$$
$$Q_i = f[X_j] = Y_o \subseteq \Omega \quad \forall X_j, i$$

### 2.2 Decision Questions / Decision Problems

#### 2.2.1 Definition

Define decision problem; a function with inputs  $x_i$  and boolean output "answer"  $a_o$

$$X_i = \{x_1, \dots, x_n\}$$
$$D := f[X_i] = a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

### 2.3 Numerical Questions / Numerical Problems

#### 2.3.1 Definition

Define numerical problem; a function with inputs  $x_i$  and numerical output  $y_o$

$$X_i = \{x_1, \dots, x_n\}$$
$$Q := f[X_i] = y_o \in \mathbb{R} \quad \forall X_i$$

### 2.4 System Questions / System Problems

#### 2.4.1 Definition

Define system problem; a function with inputs  $x_i$  and outputs  $y_j$

$$X_i = \{x_1, \dots, x_n\}$$
$$Q := f[X_i] = Y_o = \{y_1, \dots, y_m\} \quad \forall X_i$$

### 3 General Solutions

#### 3.1 Definition

Program P is a general solution  $s^+$  to decision problem D if

1. P outputs answer  $a_o$  for all inputs  $X_i \ \forall i$   
and
2.  $s^+[X_i]$  is a subset of  $s^+[\hat{X}_i]$

$$\begin{aligned}
 X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_n, x_{n+1}, C\} \\
 D &:= f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i \\
 s^+ &= s^+[X_i] := P : \\
 (P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
 P[X_i] &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} \\
 s^+ = P[X_i] &= \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \quad \forall X_i
 \end{aligned}$$

##### 3.1.1 Property of No-op ;

No-op ; can be added to any solution  $S_i$  without modifying the output  $y_o$  or memory  $b_i$

$$\begin{aligned}
 & ; := \emptyset \\
 s^+ &= \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
 \hat{s}^+ &= \{s_1, s_2, \dots, ;, \dots, s_{O_T[n]+1}, \hat{b}_1, \hat{b}_2, \dots, \hat{b}_{O_S[n]}, \hat{y}_o\} \\
 \hat{y}_o &= y_o \quad \forall k
 \end{aligned}$$

#### 3.2 Definition of $S^+$

Define  $S^+$ ; the set of solutions to decision problem D

$$\begin{aligned}
 X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_n, x_{n+1}, C\} \\
 D &:= f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i \\
 s_j^+ &= s_j^+[X_i] := P : \\
 (P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
 S^+ &:= \{s_j^+, \dots\} \quad \forall j
 \end{aligned}$$

### 3.3 Definition of Solvable

Define solvable

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_n, x_{n+1}, C\} \\
D &:= f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i \\
solvable &:= solvable[D] \rightarrow b_o \in \{\mathbb{T}, \mathbb{F}\} = \\
\exists P : (P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i)
\end{aligned}$$

## 4 The set of all Decision Problems $\mathbb{D}$

### 4.1 Definition

Define the set of decision problems  $\mathbb{D}$

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\} \\
D_j &:= f_j[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i \\
\mathbb{D} &:= \{D_j, \dots\} \quad \forall j
\end{aligned}$$

## 5 Instruction and Memory Notation

Define  $\mathcal{L}$  a set of logical operations

Define  $\mathcal{M}$  a set of memory elements, magnitudes, and sets

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \\
P[X_i] \rightarrow y_o &= \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
\mathcal{L} &:= \{s_1, s_2, \dots, s_{O_T[n]}\} \\
\mathcal{M} &:= \{b_1, b_2, \dots, b_{O_S[n]}\} \\
P[X_i] &= \{\mathcal{L}, \mathcal{M}, y_o\}
\end{aligned}$$

## 6 Complexity

### 6.1 Time Complexity of a Decision Problem $O_T[n]$

Define Time Complexity  $O_T[n]$  of solution  $s^+$  to Decision Problem  $D$  as the total number of logical operations

$$X_i = \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\}$$

$$D := f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

$$s^+[X_i] := P :$$

$$(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) \quad \cap \quad (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i)$$

$$\begin{aligned} s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\ &= \{\mathcal{L}, \mathcal{M}, y_o\} \end{aligned}$$

$$O_T[n] := |\mathcal{L}| = N$$

## 6.2 Space Complexity $O_S[n]$

Define Space Complexity  $O_S[n]$  of solution  $s^+$  to Decision Problem  $D$  as the total number of memory elements

$$X_i = \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\}$$

$$D := f[X_i] \rightarrow a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

$$s^+[X_i] := P :$$

$$(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) \quad \cap \quad (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i)$$

$$\begin{aligned} s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\ &= \{\mathcal{L}, \mathcal{M}, y_o\} \end{aligned}$$

$$O_S[n] := |\mathcal{M}| + |y_o|^* = M + 1$$

\*It is convention to reserve one memory element for output  $y_o$ .  
Void programs do not require the  $y_o$  memory element for output

## 7 Definition of Complexity

Define Complexity  $O[n]$  as a vector of dimension  $V$

$$\mathbf{O}[n] := \langle O_T[n], O_S[n], O_3[n], O_4[n], \dots, O_V[n] \rangle$$

## 8 Simple Computational Complexity

The remainder of this document assumes simple computational complexity of dimension 2

### 8.1 Definition

Define simple computational complexity of dimension 2

$$\mathbf{O}[n] := \langle O_T[n], O_S[n] \rangle$$

### 8.2 Total Complexity

Define Total Complexity of solution  $s^+$

$$\begin{aligned} O[n] &:= |s^+[X_n]| = |\{\mathcal{L}, \mathcal{M}, y_o\}| \\ &= |\mathcal{L}| + |\mathcal{M}| + |y_o| = N + M + 1 \end{aligned}$$

### 8.3 Time Complexity

Restate definition of Time Complexity  $O_T[n]$  of solution  $s^+$

$$\begin{aligned} s^+ &= \{\mathcal{L}, \mathcal{M}, y_o\} \\ O_T[n] &:= |\mathcal{L}| = N \end{aligned}$$

### 8.4 Space Complexity

Restate definition of Time Complexity  $O_S[n]$  of solution  $s^+$

$$\begin{aligned} s^+ &= \{\mathcal{L}, \mathcal{M}, y_o\} \\ O_S[n] &:= |\mathcal{M}| + |y_o| = M + 1 \end{aligned}$$

### 8.5 Total Complexity as a Function of Time and Space Complexity

$$\begin{aligned} O[n] &:= |s^+[X_n]| = |\{\mathcal{L}, \mathcal{M}, y_o\}| \\ &= |\mathcal{L}| + |\mathcal{M}| + |y_o| \\ &= O_T[n] + O_S[n] \end{aligned}$$

## 8.6 $O_S[n] > 0^*$

Assuming Program is not void

### 8.6.1 Proof

Assume  $O_S[n] = 0$

$$O_S[n] := |\mathcal{M}| + |y_o|$$

$$O_S[n] = 0 \Rightarrow \mathcal{M} = y_o = \emptyset$$

$$y_o = \emptyset; \ y_o \in \{\mathbb{T}, \mathbb{F}\} \text{ by definition of } s^+$$

$\therefore O_S[n] = 0$  contradicts the definition of solution  $s^+$  of a decision problem

$$O_S[n] \geq 0 \text{ by definition of magnitude}$$

$$\therefore O_S[n] > 0$$

## 8.7 $O_T[n] > 0^*$

Assuming Program is not void

### 8.7.1 Proof

Assume  $O_T[n] = 0$

$$O_T[n] := |\mathcal{L}|$$

$$O_T[n] = 0 \Rightarrow y_o \notin \{\mathbb{T}, \mathbb{F}\}$$

$$y_o \notin \{\mathbb{T}, \mathbb{F}\}; \ y_o \in \{\mathbb{T}, \mathbb{F}\} \text{ by definition of } s^+$$

$\therefore O_T[n] = 0$  contradicts the definition of solution  $s^+$  of a decision problem

$$O_T[n] \geq 0 \text{ by definition of magnitude}$$

$$\therefore O_T[n] > 0$$

## 8.8 $O[n] > 0^*$

Assuming Program is not void



### 8.8.1 Proof

$$O[n] := O_T[n] + O_S[n]$$

$$O_T[n] > 0; \quad O_S[n] > 0$$

$$\therefore O[n] > 0$$

### 8.9 $O[n] > O_T[n]^*$

Assuming Program is not void

#### 8.9.1 Proof

$$O[n] := O_T[n] + O_S[n]$$

$$O_S[n] > 0$$

$$\therefore O[n] > O_T[n]$$

### 8.10 $O[n] > O_S[n]^*$

Assuming Program is not void

#### 8.10.1 Proof

$$O[n] := O_T[n] + O_S[n]$$

$$O_T[n] > 0$$

$$\therefore O[n] > O_S[n]$$

### 8.11 $O[n+1] \geq O[n]$

#### 8.11.1 Proof

$$X_i = \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\}$$

$$O[n] = |s^+[X_i]|$$

$$O[n+1] = \hat{O}[n] = |s^+[\hat{X}_i]|$$

For general solutions  $s^+$

$$\begin{aligned}
s^+[\hat{X}_i] &\supseteq s^+[X_i] \\
\Rightarrow |s^+[\hat{X}_i]| &\geq |s^+[X_i]| \\
\therefore \hat{O}[n] = O[n+1] &\geq O[n]
\end{aligned}$$

## Computational Operators

### 9 No-op ;

#### 9.1 Define No-op ;

Define void program No-op ;

$$;[\emptyset] := \{s; = \emptyset\} = \{\mathcal{L}\}$$

#### 9.2 Time Complexity of No-op

$$O_T[n] := |\mathcal{L}| = 1$$

#### 9.3 Space Complexity of No-op

$$O_S[n] := |\mathcal{M}| = 0$$

#### 9.4 Total Complexity of No-op

$$O[n] = O_T[n] + O_S[n] = 0$$

#### 9.5 Property of No-op ;

Prove No-op can be added to any Program  $P$  without modifying the output  $y_o$  or memory  $b_i$

$$P = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} = \{\mathcal{L}, \mathcal{M}, y_o\}$$

Let

$$P; = \{s_1, s_2, \dots, s_j, s;, s_{j+1}, \dots, s_{O_T[n]}, \hat{b}_1, \hat{b}_2, \dots, \hat{b}_{O_S[n]}, \hat{y}_o\}$$

Suppose

$$\hat{y}_o \neq y_o$$

## 10 Inductive Functions

### 10.1 Inductive Function $f_{n+1}$

$$\begin{aligned} O[n] &= O_T[n] + O_S[n] \\ O[n+1] &= O_T[n+1] + O_S[n+1] \\ f_{n+1}[n] &:= O[n+1] - O[n] \end{aligned}$$

### 10.2 Inductive Space and Time Formulas

$$\begin{aligned} f_{n+1}^T[n] &:= O_T[n+1] - O_T[n] \\ O_T[n+1] &= O_T[n] + f_{n+1}^T[n] \\ f_{n+1}^S[n] &:= O_S[n+1] - O_S[n] \\ O_S[n+1] &= O_S[n] + f_{n+1}^S[n] \end{aligned}$$

### 10.3 Inductive Function Expressions

Relate  $f_{n+1}[n]$  to equivalence functions

$$\begin{aligned} O[n] &= O_T[n] + O_S[n] \\ O[n+1] &= O_T[n+1] + O_S[n+1] = O[n] + f_{n+1}[n] \\ O_T[n] &= O[n] - O_S[n] \\ O_S[n] &= O[n] - O_T[n] \end{aligned}$$

$$\begin{aligned} f_{n+1}[n] &= O[n+1] - O[n] \\ f_{n+1}[n] &= O_T[n+1] + O_S[n+1] - O[n] \\ f_{n+1}[n] &= O_T[n+1] - O_T[n] + O_S[n+1] - O_S[n] \\ f_{n+1}[n] &= O[n+1] - O_T[n] - O_S[n] \\ f_{n+1}[n] &= f_{n+1}^T[n] + f_{n+1}^S[n] \end{aligned}$$

### 10.4 Zero Order Space Inductive Function

$$\text{Let } O_S[n] \sim n^0$$

$$f_{n+1}[n] = O_T[n+1] - O_T[n] + O_S[n+1] - O_S[n] = O_T[n+1] - O_T[n]$$

## 11 Polynomial Complexity

### 11.1 Definition

Decision problem  $D$  with solution  $s^+$  has polynomial total complexity  $O[n]$  if

$$\begin{aligned} & \exists K, C, \lambda_1 \dots \lambda_K : \\ & O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \end{aligned}$$

### 11.2 Polynomial Problems

Define  $\mathbb{P}$ , the set of Decision Problems that can be solved with Polynomial Complexity

$$\begin{aligned} & \mathbb{P} := \{D_1, D_2, \dots\} : \\ & \exists K, C, \lambda_1 \dots \lambda_K : \\ & O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n, D_i \in \mathbb{P} \end{aligned}$$

### 11.3 Polynomial Order of Complexity

Solution  $s^+$  with total complexity  $O[n]$  is said to be of order  $n^K$

$$\begin{aligned} & O[n] \sim n^K \\ & O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \end{aligned}$$

### 11.4 Property of Polynomial Complexity 1

Solutions with polynomial complexity have convergent complexity

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1$$

#### 11.4.1 Proof

$$\begin{aligned} & O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \\ & O[n+1] = (\lambda_K (n+1))^K + (\lambda_{K-1} (n+1))^{K-1} \dots + \lambda_1 (n+1) + C \\ & = (\lambda_K n)^K + (\tilde{\lambda}_{K-1} n)^{K-1} \dots + \tilde{\lambda}_1 n + \tilde{C} \\ & \lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \\ & = \lim_{n \rightarrow \infty} \frac{(\lambda_K n)^K + (\tilde{\lambda}_{K-1} n)^{K-1} \dots + \tilde{\lambda}_1 n + \tilde{C}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} \end{aligned}$$

$$\begin{aligned}
&= \lim_{n \rightarrow \infty} \frac{(\lambda_K n)^K}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} + \frac{(\tilde{\lambda}_{K-1} n)^{K-1}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} + \dots + \\
&\quad \frac{\tilde{\lambda}_1 n}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} + \frac{\tilde{C}}{(\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C} \\
&= 1 = \lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]}
\end{aligned}$$

## 11.5 Property of Polynomial Complexity 2

$$\begin{aligned}
&\exists K, \hat{C}, \hat{\lambda}_1, \dots, \hat{\lambda}_{K-1} : \\
O[n+1] - O[n] &= f_{n+1}[n] = (\hat{\lambda}_{K-1} n)^{K-1} \dots + \hat{\lambda}_1 n + \hat{C} \quad \forall n
\end{aligned}$$

### 11.5.1 Proof

$$\begin{aligned}
O[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \\
O[n+1] &= (\lambda_K (n+1))^K + (\lambda_{K-1} (n+1))^{K-1} \dots + \lambda_1 (n+1) + C \\
&= (\lambda_K n)^K + (\tilde{\lambda}_{K-1} n)^{K-1} \dots + \tilde{\lambda}_1 n + \tilde{C} \\
O[n+1] - O[n] &= ((\tilde{\lambda}_{K-1} - \lambda_{K-1}) n)^{K-1} \dots + (\tilde{\lambda}_1 - \lambda_1) n + (\tilde{C} - C) \\
O[n+1] - O[n] &= (\hat{\lambda}_{K-1} n)^{K-1} \dots + \hat{\lambda}_1 n + \hat{C}
\end{aligned}$$

## 11.6 Property of Polynomial Complexity 3

$$\lim_{n \rightarrow \infty} \frac{f_{n+1}[n]}{O[n]} = 0$$

### 11.6.1 Proof

$$\begin{aligned}
\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} &= 1 \\
\lim_{n \rightarrow \infty} \frac{O[n] + f_{n+1}[n]}{O[n]} &= 1 \\
\lim_{n \rightarrow \infty} \frac{O[n]}{O[n]} + \frac{f_{n+1}[n]}{O[n]} &= 1 \\
\lim_{n \rightarrow \infty} 1 + \frac{f_{n+1}[n]}{O[n]} &= 1 \\
\lim_{n \rightarrow \infty} \frac{f_{n+1}[n]}{O[n]} &= 0
\end{aligned}$$

## 11.7 Total Polynomial Complexity Implies Time bounded Polynomial Complexity

$$D \in \mathbb{P} \implies O_T[n] < (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C$$

### 11.7.1 Proof

$$\begin{aligned}
O[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \\
O[n] &:= O_T[n] + O_S[n]; \quad O_S[n] > 0 \\
\therefore O_T[n] &< (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n
\end{aligned}$$

## 11.8 Total Polynomial Complexity Implies Space bounded Polynomial Complexity

$$D \in \mathbb{P} \implies O_S[n] < (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C$$

### 11.8.1 Proof

$$\begin{aligned}
O[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \\
O[n] &:= O_T[n] + O_S[n]; \quad O_T[n] > 0 \\
\therefore O_S[n] &< (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n
\end{aligned}$$

## 11.9 Polynomial Complexity in Space and Time Implies Polynomial Total Complexity

$$\begin{aligned}
(O_S[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + \lambda_0) \\
&\quad \wedge \\
(O_T[n] &= (\hat{\lambda}_M n)^M + (\hat{\lambda}_{M-1} n)^{M-1} \dots + \hat{\lambda}_1 n + \hat{\lambda}_0) \\
&\implies D \in \mathbb{P}
\end{aligned}$$

### 11.9.1 Proof

$$\begin{aligned}
O_S[n] &= \lambda_K n^K + \lambda_{K-1} n^{K-1} + \dots + \lambda_1 n + \lambda_0 \\
O_T[n] &= \hat{\lambda}_M n^M + \hat{\lambda}_{M-1} n^{M-1} + \dots + \hat{\lambda}_1 n + \hat{\lambda}_0 \\
O[n] &= O_S[n] + O_T[n] \\
*O[n] &= (\hat{\lambda}_0 + \lambda_0) + n(\lambda_1 + \hat{\lambda}_1) + \dots + n^K(\lambda_K + \hat{\lambda}_K) + \hat{\lambda}_{K+1} n^{K+1} + \dots + \hat{\lambda}_M n^M \\
\therefore O[n] &\text{ has polynomial total complexity by definition}
\end{aligned}$$

\* Assume  $K < M$ , similar proof for  $K=M$ ,  $K>M$

## 12 Non-Polynomial Complexity

### 12.1 Definition

Decision problem  $\tilde{D}$  with solution  $s^+$  has non-polynomial total complexity  $O[n]$  if

$$\nexists K, C, \lambda_1 \dots \lambda_K : \\ O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

### 12.2 Non-Polynomial Problems

Define  $\mathcal{N}$ , the set of Decision Problems that cannot be solved with Polynomial Complexity

$$\mathcal{N} := \{\tilde{D}_1, \tilde{D}_2, \dots\} : \\ \nexists K, C, \lambda_1 \dots \lambda_K : \\ O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n, s^+ \in S_i^+, \tilde{D}_i \in \mathcal{N}$$

### 12.3 $\mathbb{P}$ and $\mathcal{N}$ are disjoint

$$\mathbb{P} \cap \mathcal{N} = \emptyset$$

#### 12.3.1 Proof

Let  $D \in \mathcal{N}$

$$\nexists K, C, \lambda_1 \dots \lambda_K : \\ O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

Assume  $D \in \mathbb{P}$

$$\exists K, C, \lambda_1 \dots \lambda_K : \\ O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

Contradicts the definition of  $\mathcal{N}$

$$\therefore D \in \mathcal{N} \Rightarrow D \notin \mathbb{P}$$

Let  $D \in \mathbb{P}$



$$\begin{aligned} & \exists K, C, \lambda_1 \dots \lambda_K : \\ O[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \end{aligned}$$

Assume  $D \in \mathcal{N}$

$$\begin{aligned} & \nexists K, C, \lambda_1 \dots \lambda_K : \\ O[n] &= (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n \end{aligned}$$

Contradicts the definition of  $\mathbb{P}$

$$\therefore D \in \mathbb{P} \Rightarrow D \notin \mathcal{N}$$

$$D \in \mathcal{N} \Rightarrow D \notin \mathbb{P}; D \in \mathbb{P} \Rightarrow D \notin \mathcal{N}$$

$$\therefore \mathbb{P} \cap \mathcal{N} = \emptyset$$

## 13 Divergent Complexity

### 13.1 Definition

Decision problem  $\hat{D}$  with solution  $s^+$  has divergent total complexity  $O[n]$  if

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges}$$

### 13.2 Divergent Problems

$$\mathcal{D} := \{\hat{D}_1, \hat{D}_2, \dots\} :$$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges} \quad \forall s^+ \in S_i^+, \hat{D}_i \in \mathcal{D}$$

### 13.3 The Set of Polynomial Solutions and the Set of Divergent Solutions are disjoint

$$\mathbb{P} \cap \hat{\mathcal{D}} = \emptyset$$

### 13.4 Proof

Let  $D \in \hat{\mathcal{D}}$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges by definition}$$

Assume  $D \in \mathbb{P}$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1$$

$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1$  contradicts the definition of Divergent Problems

$$\therefore D \in \hat{\mathcal{D}} \Rightarrow D \notin \mathbb{P}$$

Let  $D \in \mathbb{P}$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1 \text{ by property of Polynomial complexity}$$

Assume  $D \in \hat{\mathcal{D}}$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges}$$

$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges contradicts a property of Polynomial complexity}$

$$\therefore D \in \mathbb{P} \Rightarrow D \notin \hat{\mathcal{D}}$$

$$\therefore \mathbb{P} \cap \hat{\mathcal{D}} = \emptyset$$

## 14 Subfunctions

### 14.1 Restate the subfunction condition of general solutions

Recall the definition of general solution  $s^+$

$$\begin{aligned} X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\ s^+ &= s^+[X_i] := P : \\ (P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \end{aligned}$$

The subfunction condition is one of two conditions for a general solution

$$P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i$$

### 14.2 Prove $O[n]$ is a non-decreasing function

Consider solution  $s^+$  with complexity  $O[n]$

$$\begin{aligned} X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\ s^+ &= s^+[X_i] := P : \\ (P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\ s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\ &= \{\mathcal{L}, \mathcal{M}, y_o\} \end{aligned}$$

$$O[n] := O_T[n] + O_S[n]$$

$$O_T[n] := |\mathcal{L}| = N$$

$$O_S[n] := |\mathcal{M}| + |y_o| = M + 1$$

$O[n+1]$  denotes the total complexity for solution  $s^+[\hat{X}_i]$

$$s^+[\hat{X}_i] = \hat{s}^+$$

Let

$$\begin{aligned}
O[n+1] &< O[n] \\
\Rightarrow \hat{N} + \hat{M} &< N + M \\
\hat{s}^+ &= \{s_1, s_2, \dots, s_{\hat{N}} | b_1, b_2, \dots, b_{\hat{M}}, y_o\} \\
&\Rightarrow \hat{s}^+ \not\supseteq s^+ \\
P[\hat{X}_i] &\not\supseteq P[X_i] \quad \forall X_i, \hat{X}_i
\end{aligned}$$

$\therefore O[n+1] < O[n]$  contradicts the definition of solution  $s^+$

$$O[n+1] \geq O[n]$$

### 14.3 Definition of Subfunction

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\
s^+ &= s^+[X_i] := P : \\
(P[X_i] \rightarrow y_o = a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
&= \{\mathcal{L}, \mathcal{M}, y_o\}
\end{aligned}$$

$$\begin{aligned}
Sub[X_i] &:= S = \{s_j, \dots | b_k, \dots, y_o\} : \\
s_j, b_k &\in s^+ \quad \forall s_j, b_k \in S
\end{aligned}$$

#### 14.3.1 $s^+[X_i]$ is a subfunction of $s^+[\hat{X}_i]$

$$\begin{aligned}
s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
\hat{s}^+ &= \{s_1, s_2, \dots, s_N, \dots, s_{\hat{N}} | b_1, b_2, \dots, b_M, \dots, b_{\hat{M}}, y_o\}; \quad \hat{N} + \hat{M} \geq N + M
\end{aligned}$$

By definition of solution

$$\begin{aligned}
\hat{s}^+ &= P[\hat{X}_i] \supseteq P[X_i] = s^+ \quad \forall X_i, \hat{X}_i \\
&\Rightarrow s_j, b_k \in \hat{s}^+ \quad \forall s_j, b_k \in s^+
\end{aligned}$$

### 14.4 Subfunction Decomposition of Solutions

FIX Double check conditions!!! Solutions  $s^+$  can be written as the union of subfunctions  $Sub_k[X_i]$

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\
s^+ &= s^+[X_i] := P : \\
(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
&= \{\mathcal{L}, \mathcal{M}, y_o\} \\
s^+ &= Sub_1[X_i] \cup Sub_2[X_i] \cup \dots \cup Sub_z[X_i] \\
&= \{\mathcal{L}_1 | \mathcal{M}_1, y_o\} \cup \{\mathcal{L}_2 | \mathcal{M}_2, y_o\} \cup \dots \cup \{\mathcal{L}_z | \mathcal{M}_z, y_o\} : \\
&\quad \mathcal{L}_j \cap \mathcal{L}_k = \emptyset \quad \forall j, k \neq j \\
s^+ &= \{s_1^1, \dots, s_{N_1}^1 | b_1^1, \dots, y_o\} \cup \{s_1^2, \dots, s_{N_2}^2 | b_1^2, \dots, y_o\} \cup \dots \cup \{s_1^z, \dots, s_{N_z}^z | b_1^z, \dots, y_o\} : \\
&\quad \sum_{l=1}^z N_l = N = O_T[n]
\end{aligned}$$

## 15 Subfunction Complexity

### 15.1 Disjoint Subfunction Operations

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$$

### 15.2 Shared Subfunction Memory

$$|\mathcal{M}_i \cap \mathcal{M}_j| \geq 0 \quad \forall i, j \neq i$$

#### 15.2.1 Time Complexity of Subfunctions

Subfunction time complexity is additive

$$\begin{aligned}
s^+ &= \{\mathcal{L}, \mathcal{M}, y_o\} \\
Sub_i[X] &:= S_i = \{s_j, \dots | b_k, \dots, y_o\} : \\
s_j, b_k &\in s^+ \quad \forall s_j, b_k \in S_i \\
s^+ &= \{\mathcal{L}_1 | \mathcal{M}_1, y_o\} \cup \{\mathcal{L}_2 | \mathcal{M}_2, y_o\} \cup \dots \cup \{\mathcal{L}_z | \mathcal{M}_z, y_o\} : \\
&\quad \mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i \\
\mathcal{L} &= \cup_{i=1}^z \mathcal{L}_i
\end{aligned}$$

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$$

$$\begin{aligned} O_T[n] &= |\mathcal{L}| = N \\ O_T[n] &= |\cup_{i=1}^z \mathcal{L}_i| = \sum_{i=1}^z |\mathcal{L}_i|^* = |\mathcal{L}_1| + |\mathcal{L}_2| + \dots + |\mathcal{L}_z| \\ &= O_{T_1}[n] + O_{T_2}[n] + \dots + O_{T_z}[n] = N_1 + N_2 + \dots + N_z \end{aligned}$$

\*Due to the disjoint condition of subfunction operations  $\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$

### 15.2.2 Space Complexity of Subfunctions

Subfunctions can access the full memory  $\mathcal{M}$  with no added space complexity

$$s^+ = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$Sub_i[X] := S_i = \{s_j, \dots | b_k, \dots, y_o\} :$$

$$s_j, b_k \in s^+ \quad \forall s_j, b_k \in S_i$$

$$s^+ = \{\mathcal{L}_1 | \mathcal{M}_1, y_o\} \cup \{\mathcal{L}_2 | \mathcal{M}_2, y_o\} \cup \dots \cup \{\mathcal{L}_z | \mathcal{M}_z, y_o\} :$$

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$$

$$s^+ = \{\mathcal{L}_1 | \mathcal{M}, y_o\} \cup \{\mathcal{L}_2 | \mathcal{M}, y_o\} \cup \dots \cup \{\mathcal{L}_z | \mathcal{M}, y_o\} :$$

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$$

$$\mathcal{M} = \cup_{i=1}^z \mathcal{M}_i = \cup_{i=1}^z \mathcal{M}$$

$$O_S[n] = |\mathcal{M}| = M$$

$$O_S[n] = |\cup_{i=1}^z \mathcal{M}_i| = M$$

### 15.2.3 Shared State Notation

$$s^+ = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$Sub_i[X] := S_i = \{s_j, \dots | b_k, \dots, y_o\} :$$

$$s_j, b_k \in s^+ \quad \forall s_j, b_k \in S_i$$

$$s^+ = \{\mathcal{L}_1 | \mathcal{M}, y_o\} \cup \{\mathcal{L}_2 | \mathcal{M}, y_o\} \cup \dots \cup \{\mathcal{L}_z | \mathcal{M}, y_o\} :$$

$$\mathcal{L}_i \cap \mathcal{L}_j = \emptyset \quad \forall i, j \neq i$$

## 16 Polynomial Solution Subfunction Properties

### 16.1 Restate Definition of Subfunction

$$X_n = \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\}$$

$$s^+ = s^+[X_n] := P :$$

$$(P[X_n] \rightarrow y_o == a_o \quad \forall X_i) \quad \cap \quad (P[\hat{X}_n] \supseteq P[X_n] \quad \forall X_n, \hat{X}_n)$$

$$\begin{aligned} s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\ &= \{\mathcal{L}, \mathcal{M}, y_o\} \end{aligned}$$

$$Sub[X_n] := S = \{s_j, \dots | b_k, \dots, y_o\} :$$

$$s_j, b_k \in s^+ \quad \forall s_j, b_k \in S$$

### 16.2 Property of Polynomial Solution Subfunctions

Let

$$D \in \mathbb{P}$$

$$X_n = \{x_1, \dots, x_n, C\}; \quad \hat{X}_n = \{x_1, \dots, x_{n+1}, C\}$$

$$s^+ = s^+[X_n] := P :$$

$$(P[X_i] \rightarrow y_o == a_o \quad \forall X_n) \quad \cap \quad (P[\hat{X}_n] \supseteq P[X_n] \quad \forall X_n, \hat{X}_n)$$

$$\exists K, C, \lambda_1 \dots \lambda_K \quad :$$

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

$$s^+ = Sub_1[X_n] \cup Sub_2[X_n] \cup \dots \cup Sub_z[X_n]$$

$$\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = 1$$

$$= \lim_{n \rightarrow \infty} \frac{O_T^1[n+1] + O_T^2[n+1] + \dots + O_T^z[n+1] + O_S[n+1]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]}$$

$$\lim_{n \rightarrow \infty} \frac{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n] + f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \dots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} =$$



$$\begin{aligned}
&= \lim_{n \rightarrow \infty} 1 + \frac{f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \dots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} = 1 \\
&\Rightarrow \lim_{n \rightarrow \infty} \frac{f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \dots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} = 0^* \\
&\Rightarrow \lim_{n \rightarrow \infty} \frac{f_{T_{n+1}}^i[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} = 0 \quad \forall i \\
&\lim_{n \rightarrow \infty} \frac{f_{n+1}^i[n]}{O[n]} = 0 \quad \forall i
\end{aligned}$$

\*  $O[n]$  is a positive, non-decreasing function

### 16.3 Theorem of Polynomial Subfunctions

The Theorem of Polynomial Subfunctions states a solution has polynomial complexity if and only if all of its subfunctions have polynomial complexity

$$|s^+[X_n]| = O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

$$s^+ = Sub_1[X_n] \cup Sub_2[X_n] \cup \dots \cup Sub_z[X_n]$$

$$O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

$$\Longleftrightarrow$$

$$|Sub_i[X_n]| = O_i[n] = (\hat{\lambda}_M n)^M + (\hat{\lambda}_{M-1} n)^{M-1} + \dots + \hat{\lambda}_1 n + C \quad \forall i, n$$

#### 16.3.1 Forward Direction

Solution  $s^+$  having polynomial complexity implies all of its subfunctions  $Sub_i$  have polynomial complexity

Let

$$|s^+[X_n]| = O[n] = (\lambda_K n)^K + (\lambda_{K-1} n)^{K-1} \dots + \lambda_1 n + C \quad \forall n$$

$$O[n] = \sum_{i=1}^z O_i[n] = O_1[n] + O_2[n] + \dots + O_z[n]$$

Since  $O[n], O_i[n]$  is positive, non-decreasing

$$O_i[n] = (\hat{\lambda}_{M_i} n)^{M_i} + (\hat{\lambda}_{M_i-1} n)^{M_i-1} \dots + \hat{\lambda}_1 n + C \quad M_i \leq K \quad \forall i, n$$

$\Rightarrow Sub_i$  has polynomial complexity by definition of polynomial complexity

### 16.3.2 Backward Direction

Every subfunction  $Sub_i$  having polynomial complexity implies solution  $s^+$  has polynomial complexity

Let

$$O_i[n] = (\hat{\lambda}_{M_i} n)^{M_i} + (\hat{\lambda}_{M_i-1} n)^{M_i-1} + \dots + \hat{\lambda}_{1_i} n + \hat{\lambda}_{0_i} \quad \forall i, n$$

$$O_{max}[n]^* := \tilde{O}[n] \in \{O_1[n], O_2[n], \dots, O_z[n]\} :$$

$$\lim_{n \rightarrow \infty} \frac{\tilde{O}[n]}{\sum_{i=1}^z O_i[n]} = c \neq 0$$

$$O_{max}[n] = (\hat{\lambda}_{M_{max}} n)^{M_{max}} + (\hat{\lambda}_{M_{max}-1} n)^{M_{max}-1} + \dots + \hat{\lambda}_{1_{max}} n + \hat{\lambda}_{0_{max}} \quad \forall i, n$$

$$O[n] = \sum_{i=1}^z O_i[n] = O_1[n] + O_2[n] + \dots + O_z[n]$$

$$= (\tilde{\lambda}_L n)^L + (\tilde{\lambda}_{L-1} n)^{L-1} + \dots + \tilde{\lambda}_1 n + C \quad L = M_{max} \quad \forall n$$

$\Rightarrow s^+$  has polynomial complexity by definition of polynomial complexity

\*  $O_{max}$  is not necessarily unique, but necessarily exists. See appendix for proof

## 17 Divergent Solution Subfunction Properties

### 17.1 Restate Definition of Subfunction

$$\begin{aligned}
X_i &= \{x_1, \dots, x_n, C\}; \quad \hat{X}_i = \{x_1, \dots, x_{n+1}, C\} \\
s^+ &= s^+[X_i] := P : \\
(P[X_i] \rightarrow y_o == a_o \quad \forall X_i) &\cap (P[\hat{X}_i] \supseteq P[X_i] \quad \forall X_i, \hat{X}_i) \\
s^+ &= \{s_1, s_2, \dots, s_N | b_1, b_2, \dots, b_M, y_o\} = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} \\
&= \{\mathcal{L}, \mathcal{M}, y_o\} \\
Sub[X_i] &:= S = \{s_j, \dots | b_k, \dots, y_o\} : \\
s_j, b_k &\in s^+ \quad \forall s_j, b_k \in S
\end{aligned}$$

### 17.2 Property of Divergent Subfunctions

Let

$$D \in \hat{\mathcal{D}}$$

$$\begin{aligned}
X_n &= \{x_1, \dots, x_n\}; \quad \hat{X}_n = \{x_1, \dots, x_{n+1}\} \\
s^+ &= s^+[X_n] := P : \\
(P[X_i] \rightarrow y_o == a_o \quad \forall X_n) &\cap (P[\hat{X}_n] \supseteq P[X_n] \quad \forall \hat{X}_n : \hat{X}_n \supset X_n)
\end{aligned}$$

By Definition of Divergent Problem

$$\begin{aligned}
&\nexists c : \lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} = c \\
&= \lim_{n \rightarrow \infty} \frac{O_T^1[n+1] + O_T^2[n+1] + \dots + O_T^z[n+1] + O_S[n+1]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} \\
&= \lim_{n \rightarrow \infty} \frac{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n] + f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \dots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} \\
&= \lim_{n \rightarrow \infty} 1 + \frac{f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \dots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} \neq c \\
&\Rightarrow \lim_{n \rightarrow \infty} \frac{f_{T_{n+1}}^1[n] + f_{T_{n+1}}^2[n+1] + \dots + f_{T_{n+1}}^z[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} \neq c^*
\end{aligned}$$

Prove

$$\exists i : \lim_{n \rightarrow \infty} \frac{f_{T_{n+1}}^i[n] + f_{S_{n+1}}[n]}{O_T^1[n] + O_T^2[n] + \dots + O_T^z[n] + O_S[n]} \text{ diverges}$$

\*  $O[n]$  is a positive, non-decreasing function

### 17.3 Theorem of Divergent Subfunctions

The Theorem of Divergent Subfunctions states a solution is divergent if and only if at least one of its subfunctions are divergent.

$$\begin{aligned} \lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} \text{ diverges} \\ \iff \\ \exists i : \lim_{n \rightarrow \infty} \frac{O_i[n+1]}{O[n]} \text{ diverges} \end{aligned}$$

#### 17.3.1 Forward Direction

See 18.2

#### 17.3.2 Backward Direction

## 18 Solution Spaces

### 18.1 Definition of Solution Space

$$\mathbb{S} = \{c_1^+, c_2^+, \dots, c_{C[n]}^+\}$$

$$s^+[X_n] = \vee_{c_i^+ \in \mathbb{S}} c_i^+$$

### 18.2 Existence, Uniqueness, etc.

### 18.3 Worst Case

## 19 Fundamental Theorem of Computation

The Fundamental Theorem of Computation relates the complexity of optimal solution to the number of candidate solutions in the Solution Space.

$$\mathbb{S} = \{c_1^+, c_2^+, \dots, c_{C[n]}^+\}$$

$$s^+[X_n] = \vee_{c_i^+ \in \mathbb{S}} c_i^+$$

$O_{opt}[n]$  has the same order as  $C[n]$

### 19.1 Proof by Induction

### 19.2 Proof by Contradiction

## **20   Combination Notation**

### **20.1   Set Definition**

### **20.2   Numerical Definition**

### **20.3   Properties**

#### **20.3.1   Binary Property of Combination**

#### **20.3.2   Subfunction Property of Combination**

## 21 Sum to N Problem with 2 integers

### 21.1 State formal definition of Sum to N : $x_i + x_j == N$

$$X_n = \{x_1, \dots, x_n\}$$

$$D := f[X_i, N] = a_o \in \{\mathbb{T}, \mathbb{F}\} \quad \forall X_i$$

$$s^+[X_n] = P[X_n] :$$

$$(P[X_i] = y_o == a_o \quad \forall X_i) \quad \cap \quad (P[X_{n+1}] \supseteq P[X_n] \quad \forall X_{n+1})$$

$$s^+ = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$D = f[X_i] = \exists x_j, x_k \in X_n \quad j \neq k :$$

$$x_j + x_k == N$$

### 21.2 Express a formal solution : $O_S[n] \sim n^0$

$$s^+ = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$s_1 = y_o \leftarrow \mathbb{F};$$

$$\forall i < n \quad , \quad n \geq j > i$$

$$s_2, s_3, s_8, s_9, \dots, s_{3ij-4}, s_{3ij-3}, \dots, s_{3n(n-1)-4}, s_{3n(n-1)-3} = b_1 \leftarrow x_i + x_j$$

$$s_4, s_5, s_{10}, s_{11}, \dots, s_{3ij-2}, s_{3ij-1}, \dots, s_{3n(n-1)-2}, s_{3n(n-1)-1} = b_1 \leftarrow b_1 == N$$

$$s_6, s_7, s_{12}, s_{13}, \dots, s_{3ij}, s_{3ij+1}, \dots, s_{3n(n-1)}, s_{3n(n-1)+1} = y_o \leftarrow y_o \vee b_1$$

$$s^+ = \{y_o \leftarrow \mathbb{F}, y_o \leftarrow y_o \vee (x_i + x_j == N) \quad \forall i, j > i \mid b_1, y_o\}$$

### 21.3 Prove $s^+$ satisfies the subfunction condition of solutions:

$$P[X_{n+1}] \supseteq P[X_n] \quad \forall X_{n+1}$$

$$X_n = \{x_1, x_2, \dots, x_n\}; \quad X_{n+1} = \{x_1, x_2, \dots, x_n, x_{n+1}\}$$

$$s^+ = \{s_1, s_2, \dots, s_{O_T[n]}, b_1, b_2, \dots, b_{O_S[n]}, y_o\} = \{\mathcal{L}, \mathcal{M}, y_o\}$$

$$s_{n+1}^+ = s^+ \cup \hat{s}^+$$

$$s_1 = y_o \leftarrow \mathbb{F};$$

$$\forall i < n \quad , \quad n \geq j > i$$



$$\begin{aligned}
s_2, s_3, s_8, s_9, \dots, s_{3ij-4}, s_{3ij-3}, \dots, s_{3n(n-1)-4}, s_{3n(n-1)-3} &= b_1 \leftarrow x_i + x_j \\
s_4, s_5, s_{10}, s_{11}, \dots, s_{3ij-2}, s_{3ij-1}, \dots, s_{3n(n-1)-2}, s_{3n(n-1)-1} &= b_1 \leftarrow b_1 == N \\
s_6, s_7, s_{12}, s_{13}, \dots, s_{3ij}, s_{3ij+1}, \dots, s_{3n(n-1)}, s_{3n(n-1)+1} &= y_o \leftarrow y_o \vee b_1
\end{aligned}$$

$$\begin{aligned}
\forall k &< n + 1 \\
s... &= b_1 \leftarrow x_k + x_{n+1} \\
s... &= b_1 \leftarrow b_1 == N \\
s... &= y_o \leftarrow y_o \vee b_1
\end{aligned}$$

$$\begin{aligned}
s^+ &= \{y_o \leftarrow \mathbb{F}, y_o \leftarrow y_o \vee (x_i + x_j == N) \mid \forall i, j > i \mid b_1, y_o\} \\
\hat{s}^+ &= \{y_o \leftarrow y_o \vee (x_k + x_{n+1} == N) \mid \forall k < n + 1 \mid b_1, y_o\} \\
s_{n+1}^+ &= \{y_o \leftarrow \mathbb{F}, y_o \leftarrow y_o \vee (x_i + x_j == N) \mid \forall i, j > i \mid b_1, y_o\} \cup \\
&\quad \{y_o \leftarrow y_o \vee (x_k + x_{n+1} == N) \mid \forall k < n + 1 \mid b_1, y_o\} \\
s_{n+1}^+ &= s^+ \cup \hat{s}^+ = P[X_{n+1}] \supseteq P[X_n] = s^+
\end{aligned}$$

**21.4 Determine  $O[n]$ ,  $O_S[n]$ ,  $O_T[n]$ ,  $f_{n+1}[n]$ ,  $f_{n+1}^T[n]$ ,  $f_{n+1}^S[n]$  for the above solution**

$$\begin{aligned}
O_S[n] &= |y_o| + |b_1| = 2 \\
O_T[n] &= 3n(n-1) + 1 = 3n(n-1) - 1 + O_S[n] \\
O[n] &= 3n(n-1) + 3 = 3n^2 - 3n + 3 \\
f_{n+1}^S[n] &= 0 \\
f_{n+1}^T[n] &= 6n \\
f_{n+1}[n] &= f_{n+1}^S[n] + f_{n+1}^T[n]
\end{aligned}$$

**21.5 Verify  $O[n+1] = O[n] + f_{n+1}[n]$**

$$\begin{aligned}
O[n+1] &= O[n] + \hat{O}[n] \\
3(n+1)^2 - 3(n+1) + 3 &= 3n^2 - 3n + 3 + 6n \\
3n^2 + 6n + 3 - 3n - 3 + 3 &= 3n^2 + 3n + 3
\end{aligned}$$

$$3n^2 + 3n + 3 = 3n^2 + 3n + 3$$

**21.6** Show  $s^+$  has Polynomial Complexity by the definition of Total Polynomial Complexity

$$O[n] = 3n^2 - 3n + 3$$

**21.7** Show the limit  $\lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]}$  does not Diverge

$$\begin{aligned} \lim_{n \rightarrow \infty} \frac{O[n+1]}{O[n]} &= \\ \lim_{n \rightarrow \infty} \frac{3n^2 + 3n + 3}{3n^2 - 3n + 3} &= \\ \lim_{n \rightarrow \infty} \left( \frac{3n^2 - 3n + 3}{3n^2 - 3n + 3} + \frac{6n}{3n^2 - 3n + 3} \right) &= \\ \lim_{n \rightarrow \infty} \left( 1 + \frac{6n}{3n^2 - 3n + 3} \right) &= 1 \end{aligned}$$

## 22 The Knapsack Problem

### 22.1 The Knapsack Problem

The Knapsack Problem is a famous problem in computer science which asks if objects can be stored in a knapsack. Typically the problem is designed with two constraints, weight and value. Given objects  $x_i$ , each with a respective weight  $w_i$  and value  $v_i$ , does there exist a combination of objects lighter than input weight  $W$  and more valuable than input value  $V$ ?

### 22.2 Formal Definition

$$X_n = \{x_1, x_2, \dots, x_n\} = \{\{w_1, v_1\}, \{w_2, v_2\}, \dots, \{w_n, v_n\}\}$$

$$I = \{i_1, i_2, \dots, i_n\} : i_l \in \{0, 1\} \quad \forall i_l \in I$$

$$D := f[X_n, W, V] = a_o \in \{\mathbb{T}, \mathbb{F}\} = \exists I : \\ (\sum_{j=1}^n i_j w_j < W) \wedge (\sum_{j=1}^n i_j v_j \geq V)$$

### 22.3 Solve for $C[n]$

#### 22.3.1 Expressing $I$ as a binary number

$$I = \{i_1, i_2, \dots, i_n\} : i_l \in \{0, 1\} \quad \forall i_l \in I$$

Valid combinations of  $I$

$$I_{valid} = \\ \{\{0, 0, 0, \dots, 0, 0, 1\}, \{0, 0, 0, \dots, 0, 1, 0\}, \{0, 0, 0, \dots, 0, 1, 1\}, \dots, \{1, 1, 1, \dots, 1, 1, 1\}\}$$

$$C[n] = |I_{valid}[n]| = 2^n - 1$$

#### 22.3.2 Using a sum of combinations of inputs $x_i$

$$X_n = \{x_1, x_2, \dots, x_n\} = \{\{w_1, v_1\}, \{w_2, v_2\}, \dots, \{w_n, v_n\}\}$$

Valid combinations of  $x_i$

$$\begin{aligned}
X_{valid}[n] &= \\
&\{x_1\} \cup \{x_2\} \cup \dots \cup \{x_n\} \cup \{x_1, x_2\} \cup \{x_1, x_3\} \cup \dots \cup \{x_{n-1}, x_n\} \cup \dots \cup \{x_1, x_2, \dots, x_n\} \\
&= {}_n C_1 \cup {}_n C_2 \cup \dots \cup {}_n C_n \\
C[n] &= |X_{valid}[n]| = \sum_{j=1}^n {}_n C_j
\end{aligned}$$

### 22.3.3 Verify consistency

$$\begin{aligned}
C[n] &= |X_{valid}[n]| = |I_{valid}[n]| \\
&= 2^n - 1 = \sum_{j=1}^n {}_n C_j = {}_n C_1 + {}_n C_2 + \dots + {}_n C_n \\
&= 2^n - 1 = 2^n - 1
\end{aligned}$$

**22.4 Express a solution  $s^+$  of the Knapsack Problem**

**22.5 Prove  $s^+$  satisfies the subfunction condition of solutions**

**22.6 Determine  $O[n], O_T[n], O_S[n], f_{n+1}[n]$**

**22.7 Show  $s^+ \notin \mathbb{P}$**

**22.8 Express the Solution Space  $\mathbb{S}$  for The Knapsack Problem**

**22.9 Prove a lower bound for all solutions  $s^+ \in S^+ := O_{lower}[n]$**

**22.10 Prove  $D$  has Divergent Complexity**

## Appendix

### 23 Existence of $O_{max}[n]$

#### 23.1 Proof

## Citations

- [1] *chatgpt*
- [2] *<https://stackoverflow.com/questions/3518973/floating-point-exponentiation-without-power-function>*
- [3] *<https://stackoverflow.com/questions/27086195/linear-index-upper-triangular-matrix>*
- [4] *<http://www.math.uchicago.edu/~may/VIGRE/VIGRE2011/REUPapers/Riffer-Reinert.pdf>*