

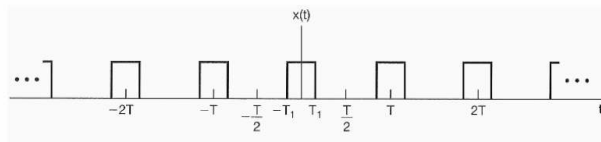
Chapter IV

Continuous Time Fourier Transform

- Representation of Aperiodic Signals: the Continuous-Time Fourier Transform
- The Fourier Transform for Periodic Signals
- Properties of the Continuous-Time Fourier Transform
- The Convolution Property
- The Multiplication Property
- Systems Characterized by Linear Constant-Coefficient Differential Equations

CT Fourier Transform of an Aperiodic Signal:

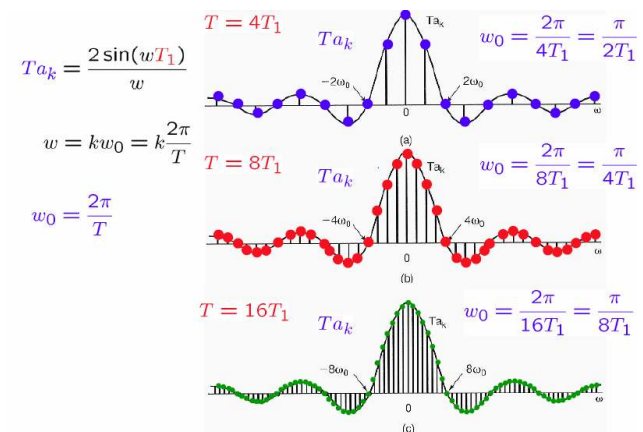
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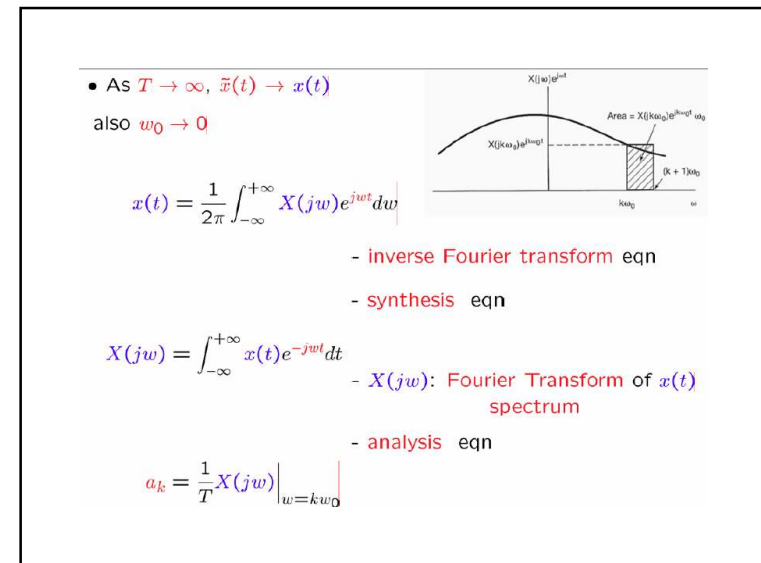
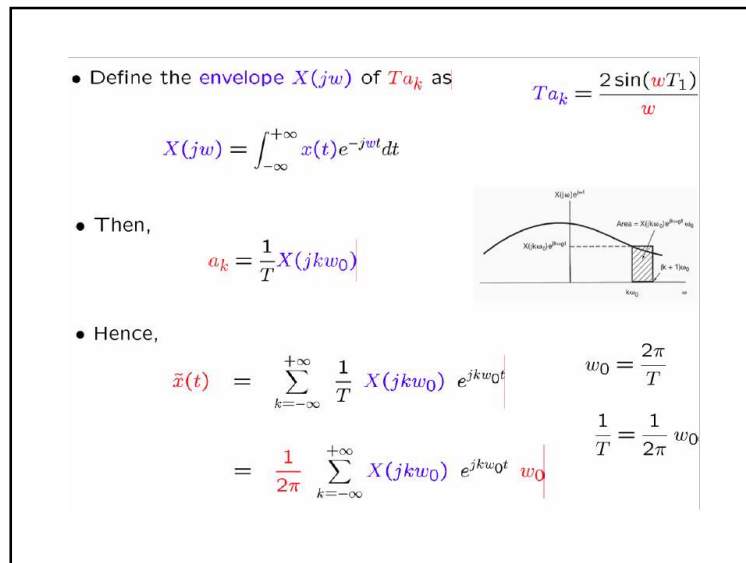
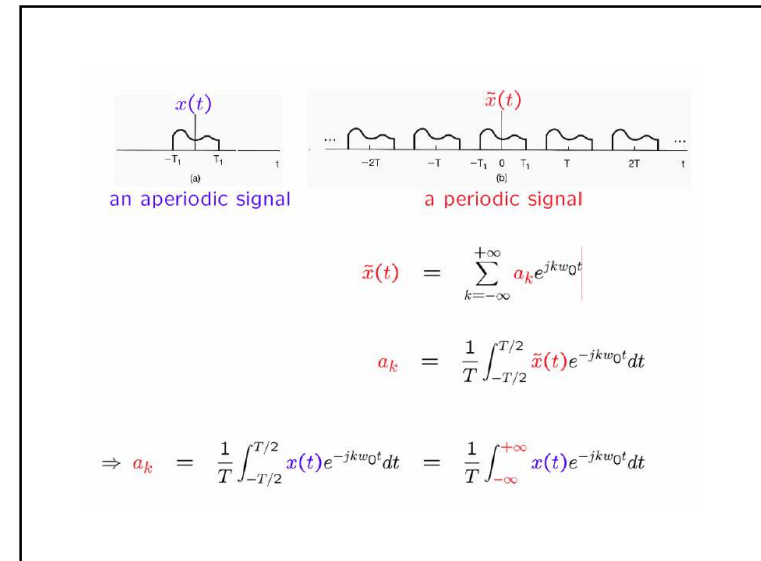
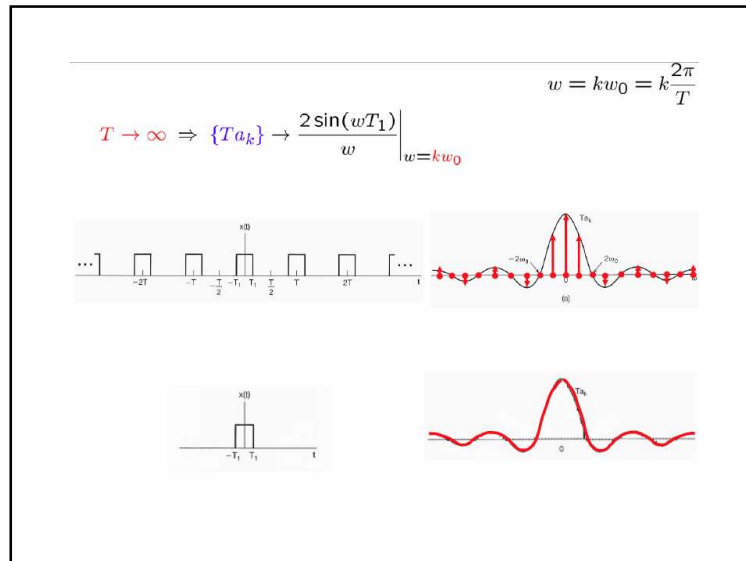


$$x(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & T_1 < |t| < T/2 \end{cases}$$

$$a_k = \frac{2 \sin(kw_0 T_1)}{kw_0 T} \quad \text{Fourier series coefficients}$$

$$T a_k = \frac{2 \sin(w T_1)}{w} \Big|_{w=kw_0} \quad w \text{ as a continuous variable}$$





▪ Sufficient conditions for the convergence of FT

$$x(t) \xrightarrow{\text{CTFT}} X(jw) \quad X(jw) = \int_{-\infty}^{+\infty} x(t) e^{-jw t} dt$$

$$\hat{x}(t) \xleftarrow{\text{CTIFT}} X(jw) \quad \hat{x}(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

$$e(t) = \hat{x}(t) - x(t)$$

- If $x(t)$ has finite energy

i.e., square integrable, $\int_{-\infty}^{+\infty} |x(t)|^2 dt < \infty$

$\Rightarrow X(jw)$ is finite

$$\Rightarrow \int_{-\infty}^{+\infty} |e(t)|^2 dt = 0$$

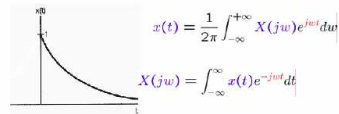
▪ Sufficient conditions for the convergence of FT

- Dirichlet conditions:

1. $x(t)$ be absolutely integrable; that is, $\int_{-\infty}^{+\infty} |x(t)| dt < \infty$
2. $x(t)$ have a finite number of maxima and minima within any finite interval
3. $x(t)$ have a finite number of discontinuities within any finite interval
Furthermore, each of these discontinuities must be finite

▪ Example 4.1:

$$x(t) = e^{-at} u(t), \quad a > 0$$



$$\Rightarrow X(jw) = \int_{-\infty}^{\infty} x(t) e^{-jw t} dt$$

$$= \int_{-\infty}^{\infty} e^{-at} u(t) e^{-jw t} dt$$

$$= \int_0^{\infty} e^{-at} e^{-jw t} dt$$

$$= \int_0^{\infty} e^{-(a+jw)t} dt$$

$$= -\frac{1}{a+jw} e^{-(a+jw)t} \Big|_0^{\infty}$$

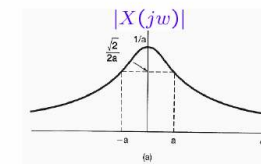
$$= 0 - \left(-\frac{1}{a+jw} e^{-(a+jw)0} \right)$$

$$= \frac{1}{a+jw}, \quad a > 0$$

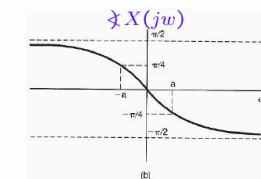
▪ Example 4.1:

$$\Rightarrow X(jw) = \frac{1}{a+jw}, \quad a > 0$$

$$\Rightarrow |X(jw)| = \frac{1}{\sqrt{a^2 + w^2}}$$



$$\Rightarrow \angle X(jw) = -\tan^{-1} \left(\frac{w}{a} \right)$$



■ Example 4.2:

$$x(t) = e^{-a|t|}, \quad a > 0$$

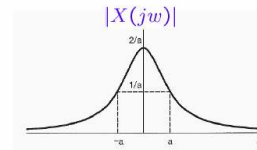
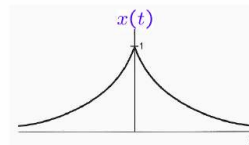
$$\Rightarrow X(jw) = \int_{-\infty}^{\infty} e^{-a|t|} e^{-jw t} dt$$

$$= \int_{-\infty}^0 e^{at} e^{-jw t} dt + \int_0^{\infty} e^{-at} e^{-jw t} dt$$

$$= \frac{1}{a - jw} + \frac{1}{a + jw}$$

$$= \frac{2a}{a^2 + w^2}$$

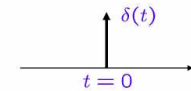
$$X(jw) = \int_{-\infty}^{\infty} x(t) e^{-jw t} dt$$



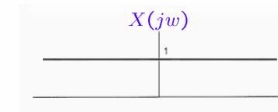
■ Example 4.3:

$$X(jw) = \int_{-\infty}^{\infty} x(t) e^{-jw t} dt$$

$$x(t) = \delta(t), \quad \text{i.e., unit impulse}$$



$$\Rightarrow X(jw) = \int_{-\infty}^{\infty} \delta(t) e^{-jw t} dt = 1$$



■ Example 4.4:

$$x(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & |t| > T_1 \end{cases}$$

$$\Rightarrow X(jw) = \int_{-\infty}^{\infty} x(t) e^{-jw t} dt = \int_{-T_1}^{T_1} e^{-jw t} dt$$

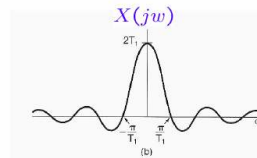
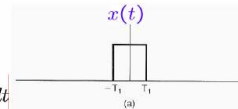
$$= \frac{1}{-jw} e^{-jw t} \Big|_{-T_1}^{T_1}$$

$$= \frac{1}{-jw} (e^{-jw T_1} - e^{jw T_1})$$

$$= \frac{1}{jw} (e^{jw T_1} - e^{-jw T_1})$$

$$= 2 \frac{\sin(w T_1)}{w}$$

$$X(jw) = \int_{-\infty}^{\infty} x(t) e^{-jw t} dt$$



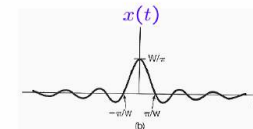
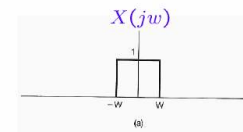
■ Example 4.5:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

$$X(jw) = \int_{-\infty}^{\infty} x(t) e^{-jw t} dt$$

$$\Rightarrow x(t) = \frac{1}{2\pi} \int_{-W}^W e^{jw t} dw$$

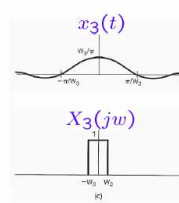
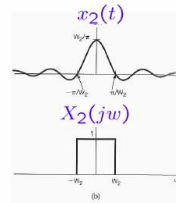
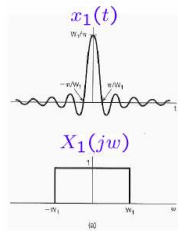
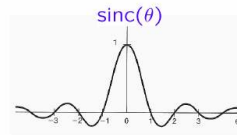
$$= \frac{\sin(Wt)}{\pi t}$$



▪ sinc functions:

$$\text{sinc}(\theta) = \frac{\sin(\pi\theta)}{\pi\theta}$$

$$\frac{\sin(Wt)}{\pi t} = \frac{W}{\pi} \text{sinc}\left(\frac{Wt}{\pi}\right)$$



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▪ Fourier Transform from Fourier Series:

$$X(jw) = 2\pi \delta(w - w_0)$$

$$\Rightarrow x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} 2\pi \delta(w - w_0) e^{jw t} dw$$

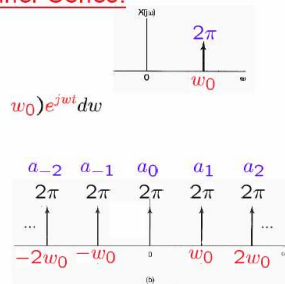
$$= e^{jw_0 t}$$

- more generally,

$$X(jw) = \sum_{k=-\infty}^{+\infty} 2\pi a_k \delta(w - kw_0)$$

$$\Rightarrow x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk w_0 t}$$

Fourier series representation of a periodic signal

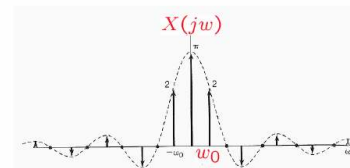


▪ Example 4.6:

$$\dots \Rightarrow a_k = \frac{\sin(k w_0 T_1)}{\pi k}$$

$$\Rightarrow X(jw) = \sum_{k=-\infty}^{+\infty} 2\pi a_k \delta(w - k w_0)$$

$$= \sum_{k=-\infty}^{+\infty} \frac{2 \sin(k w_0 T_1)}{k} \delta(w - k w_0)$$



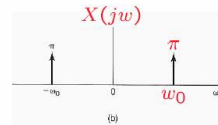
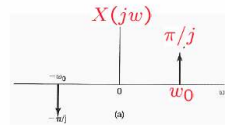
▪ **Example 4.7:**

$$x(t) = \sin(\omega_0 t) = \frac{e^{j\omega_0 t} - e^{-j\omega_0 t}}{2j}$$

$$\Rightarrow a_1 = \frac{1}{2j} \quad a_{-1} = -\frac{1}{2j} \quad a_k = 0, \quad k \neq 1, -1$$

$$x(t) = \cos(\omega_0 t) = \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2}$$

$$\Rightarrow a_1 = \frac{1}{2} \quad a_{-1} = \frac{1}{2} \quad a_k = 0, \quad k \neq 1, -1$$



▪ **Example 4.8:**

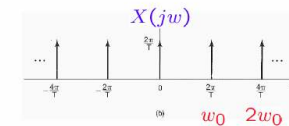
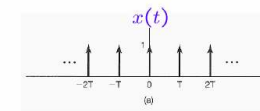
$$x(t) = \sum_{k=-\infty}^{+\infty} \delta(t - kT)$$

$$a_k = \frac{1}{T} \int_{-T/2}^{+T/2} \tilde{x}(t) e^{-jk\omega_0 t} dt$$

$$\Rightarrow a_k = \frac{1}{T} \int_{-T/2}^{+T/2} \delta(t) e^{-jk\omega_0 t} dt = \frac{1}{T}$$

$$X(j\omega) = \sum_{k=-\infty}^{+\infty} 2\pi a_k \delta(\omega - k\omega_0)$$

$$\Rightarrow X(j\omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{+\infty} \delta(\omega - \frac{2\pi}{T}k)$$



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Section	Property
4.3.1	Linearity
4.3.2	Time Shifting
4.3.6	Frequency Shifting
4.3.3	Conjugation
4.3.5	Time Reversal
4.3.5	Time and Frequency Scaling
4.4	Convolution
4.5	Multiplication
4.3.4	Differentiation in Time
4.3.4	Integration
4.3.6	Differentiation in Frequency
4.3.3	Conjugate Symmetry for Real Signals
4.3.3	Symmetry for Real and Even Signals
4.3.3	Symmetry for Real and Odd Signals
4.3.3	Even-Odd Decomposition for Real Signals
4.3.7	Parseval's Relation for Aperiodic Signals

Fourier Transform Pair:

• Synthesis equation: $x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$

• Analysis equation: $X(jw) = \int_{-\infty}^{+\infty} x(t) e^{-jw t} dt$

• Notations:

$$X(jw) = \mathcal{F}\{x(t)\}$$

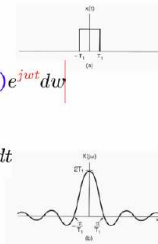
$$\frac{1}{a + jw} = \mathcal{F}\{e^{-at}u(t)\}$$

$$x(t) = \mathcal{F}^{-1}\{X(jw)\}$$

$$e^{-at}u(t) = \mathcal{F}^{-1}\left\{\frac{1}{a + jw}\right\}$$

$$x(t) \xleftrightarrow{\mathcal{F}} X(jw)$$

$$e^{-at}u(t) \xleftrightarrow{\mathcal{F}} \frac{1}{a + jw}$$



Linearity:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

$$X(jw) = \int_{-\infty}^{+\infty} x(t) e^{-jw t} dt$$

$$x(t) \xleftrightarrow{\mathcal{F}} X(jw)$$

$$y(t) \xleftrightarrow{\mathcal{F}} Y(jw)$$

$$\Rightarrow a x(t) + b y(t) \xleftrightarrow{\mathcal{F}} a X(jw) + b Y(jw)$$

Time Shifting:

$$x(t) \xleftrightarrow{\mathcal{F}} X(jw)$$

$$\Rightarrow x(t - t_0) \xleftrightarrow{\mathcal{F}} e^{-jw t_0} X(jw)$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

$$Y(jw) = \int_{-\infty}^{+\infty} x(t - t_0) e^{-jw t} dt$$

$$x(t - t_0) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw(t - t_0)} dw$$

$$= \int_{-\infty}^{+\infty} x(\tau) e^{-jw(\tau + t_0)} d\tau$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} (e^{-jw t_0} X(jw)) e^{jw t} dw$$

$$= e^{-jw t_0} \int_{-\infty}^{+\infty} x(\tau) e^{-jw \tau} d\tau$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

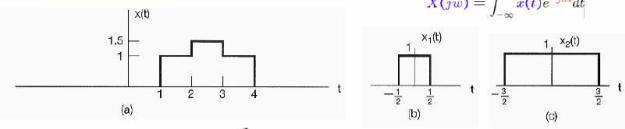
$$X(jw) = \int_{-\infty}^{+\infty} x(t) e^{-jw t} dt$$

Time Shift \rightarrow Phase Shift:

$$\mathcal{F}\{x(t)\} = X(jw) = |X(jw)| e^{j\angle X(jw)}$$

$$\mathcal{F}\{x(t - t_0)\} = e^{-jw t_0} X(jw) = |X(jw)| e^{j[\angle X(jw) - w t_0]}$$

▪ Example 4.9:



$$x(t) = \frac{1}{2}x_1(t - 2.5) + x_2(t - 2.5)$$

$$X_1(jw) = \frac{2 \sin(w/2)}{w}$$

$$X_2(jw) = \frac{2 \sin(3w/2)}{w}$$

$$\Rightarrow X(jw) = e^{-j5w/2} \left\{ \frac{\sin(w/2) + 2 \sin(3w/2)}{w} \right\}$$

▪ Conjugation & Conjugate Symmetry:

$$X(jw) = \int_{-\infty}^{+\infty} x(t)e^{-jw t} dt$$

$$x(t) \xleftrightarrow{\mathcal{F}} X(jw)$$

$$x(t)^* \xleftrightarrow{\mathcal{F}} X^*(-jw)$$

$$\begin{aligned} x(t) &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw \\ &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw \\ &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw \\ &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw \end{aligned}$$

▪ Conjugation & Conjugate Symmetry:

$$x(t) \xleftrightarrow{\mathcal{F}} X(jw)$$

$$x(t)^* \xleftrightarrow{\mathcal{F}} X^*(-jw)$$

$$\bullet x(t) = x^*(t) \Rightarrow X(-jw) = X^*(jw)$$

$$x(t) \text{ is real} \Rightarrow X(jw) \text{ is conjugate symmetric}$$

$$\bullet x(t) = x^*(t) \text{ \& } x(-t) = x(t)$$

$$\Rightarrow X(-jw) = X^*(jw) \text{ \& } X(-jw) = X(jw)$$

$$\Rightarrow X(jw) = X^*(jw)$$

$$x(t) \text{ is real \& even} \Rightarrow X(jw) \text{ are real \& even}$$

$$\bullet x(t) \text{ is real \& odd} \Rightarrow X(jw) \text{ are purely imaginary \& odd}$$

▪ Conjugation & Conjugate Symmetry:

If $x(t)$ is a real function

$$x(t) = \mathcal{E}v\{x(t)\} + \mathcal{O}d\{x(t)\} = x_e(t) + x_o(t)$$

$$\Rightarrow \mathcal{F}\{x(t)\} = \mathcal{F}\{x_e(t)\} + \mathcal{F}\{x_o(t)\}$$

$$\Rightarrow \mathcal{F}\{x_e(t)\} : \text{a real function}$$

$$\Rightarrow \mathcal{F}\{x_o(t)\} : \text{a purely imaginary function}$$

$$x(t) \xleftrightarrow{\mathcal{F}} X(jw)$$

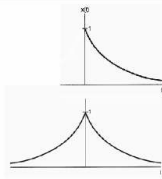
$$\mathcal{E}v\{x(t)\} \xleftrightarrow{\mathcal{F}} \mathcal{R}e\{X(jw)\}$$

$$\mathcal{O}d\{x(t)\} \xleftrightarrow{\mathcal{F}} j \mathcal{I}m\{X(jw)\}$$

▪ Example 4.10:

$$e^{-at}u(t) \xleftrightarrow{\mathcal{F}} \frac{1}{a+jw}$$

$$e^{-a|t|} \xleftrightarrow{\mathcal{F}} ?$$



$$x(t) = e^{-a|t|} = e^{-at}u(t) + e^{at}u(-t)$$

$$= 2 \left[\frac{e^{-at}u(t) + e^{at}u(-t)}{2} \right] = 2\mathcal{E}v\{e^{-at}u(t)\}$$

$$\mathcal{E}v\{e^{-at}u(t)\} \xleftrightarrow{\mathcal{F}} \mathcal{R}e\left\{\frac{1}{a+jw}\right\}$$

$$\mathcal{O}d\{e^{-at}u(t)\} \xleftrightarrow{\mathcal{F}} j\mathcal{I}m\left\{\frac{1}{a+jw}\right\}$$

$$X(jw) = 2\mathcal{R}e\left\{\frac{1}{a+jw}\right\} = \frac{2a}{a^2+w^2}$$

▪ Differentiation & Integration: $X(jw) = \int_{-\infty}^{+\infty} x(t)e^{-jw t} dt$

$$x(t) \xleftrightarrow{\mathcal{F}} X(jw) \quad x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw)e^{jw t} dw$$

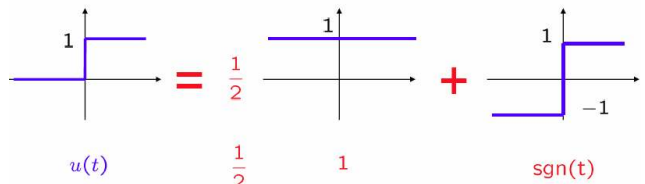
$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

$$\frac{d}{dt}x(t) \xleftrightarrow{\mathcal{F}} jwX(jw)$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

$$\int_{-\infty}^t x(\tau) d\tau \xleftrightarrow{\mathcal{F}} \frac{1}{jw}X(jw) + \pi X(0)\delta(w)$$

dc or average value



$$\frac{1}{2}$$

$$1$$

$$\text{sgn}(t)$$

$$1 \xleftrightarrow{\mathcal{FT}} 2\pi\delta(jw) \quad \text{sgn}(t) \xleftrightarrow{\mathcal{FT}} S(jw)$$

$$\frac{d}{dt}\text{sgn}(t) \xleftrightarrow{\mathcal{FT}} jw S(jw)$$

$$2\delta(t) \xleftrightarrow{\mathcal{FT}} jw S(jw)$$

$$\Rightarrow S(jw) =$$

▪ Example 4.11:

$$x(t) = u(t) \xleftrightarrow{\mathcal{F}} X(jw) = ?$$

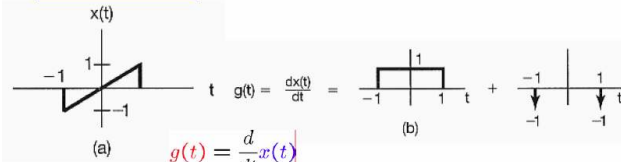
$$g(t) = \delta(t) \xleftrightarrow{\mathcal{F}} G(jw) = 1$$

$$x(t) = \int_{-\infty}^t g(\tau) d\tau \quad X(jw) = \frac{1}{jw}G(jw) + \pi G(0)\delta(w)$$

$$= \frac{1}{jw} + \pi\delta(w)$$

$$\delta(t) = \frac{d}{dt}u(t) \xleftrightarrow{\mathcal{F}} jw \left[\frac{1}{jw} + \pi\delta(w) \right] = 1$$

▪ **Example 4.12:**



$$g(t) = \frac{d}{dt}x(t)$$

$$G(jw) = \frac{2 \sin(w)}{w} - e^{jw} - e^{-jw}$$

$$\Rightarrow X(jw) = \frac{G(jw)}{jw} + \pi G(0)\delta(w)$$

$$= \frac{2 \sin(w)}{jw^2} - \frac{2 \cos(w)}{jw}$$

▪ **Time & Frequency Scaling:** $X(jw) = \int_{-\infty}^{+\infty} x(t)e^{-jw t} dt$

$$x(t) \xleftrightarrow{\mathcal{F}} X(jw)$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw)e^{jw t} dw$$

$$x(at) \xleftrightarrow{\mathcal{F}} \frac{1}{|a|} X\left(\frac{jw}{a}\right)$$

$$\frac{1}{|b|} x\left(\frac{t}{b}\right) \xleftrightarrow{\mathcal{F}} X(jbw)$$

$$x(-t) \xleftrightarrow{\mathcal{F}} X(-jw)$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw)e^{jw t} dw$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\bar{w})e^{j\bar{w} t} d\bar{w}$$

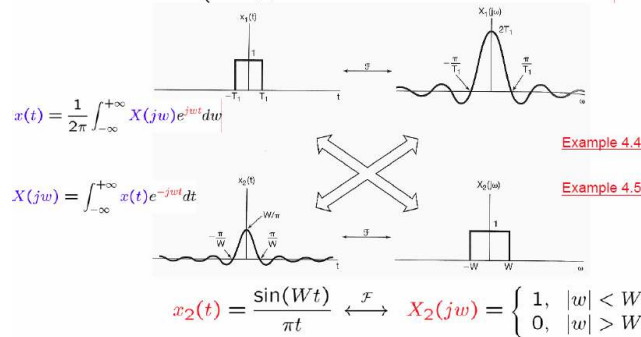
$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\bar{w})e^{j\bar{w} t} d\bar{w}$$

$$= \frac{1}{2\pi} \int_{+\infty}^{-\infty} X(j\bar{w})e^{j\bar{w} t} d\bar{w}$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\bar{w})e^{j\bar{w} t} d\bar{w}$$

▪ **Duality:**

$$x_1(t) = \begin{cases} 1, & |t| < T_1 \\ 0, & |t| > T_1 \end{cases} \xleftrightarrow{\mathcal{F}} X_1(jw) = \frac{2 \sin(wT_1)}{w}$$



Example 4.4

Example 4.5

▪ **Duality:**

$$X(jw) = \int_{-\infty}^{+\infty} x(t)e^{-jw t} dt$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw)e^{jw t} dw$$

$$B(s) = \int_{-\infty}^{+\infty} A(\tau)e^{-js\tau} d\tau$$

$$A(\tau) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} B(s)e^{js\tau} ds$$

$$B(-s) = \int_{-\infty}^{+\infty} A(\tau)e^{js\tau} d\tau$$

$$A(s) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} B(\tau)e^{js\tau} d\tau$$

$$A(-s) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} B(\tau)e^{-js\tau} d\tau$$

▪ Duality:

$$\begin{aligned}
 x(t) &\xleftrightarrow{\mathcal{F}} X(jw) \\
 x(t-t_0) &\xleftrightarrow{\mathcal{F}} e^{-jw t_0} X(jw) \\
 \frac{d}{dt} x(t) &\xleftrightarrow{\mathcal{F}} jw X(jw) \\
 \int_{-\infty}^t x(\tau) d\tau &\xleftrightarrow{\mathcal{F}} \frac{1}{jw} X(jw) + \pi X(0) \delta(w) \\
 -jtx(t) &\xleftrightarrow{\mathcal{F}} \frac{d}{dw} X(jw) \\
 e^{jw_0 t} x(t) &\xleftrightarrow{\mathcal{F}} X(j(w-w_0)) \\
 -\frac{1}{jt} x(t) + \pi x(0) \delta(t) &\xleftrightarrow{\mathcal{F}} \int_{-\infty}^w X(\eta) d\eta
 \end{aligned}$$

▪ Parseval's relation:

$$\begin{aligned}
 x(t) &\xleftrightarrow{\mathcal{F}} X(jw) \\
 \Rightarrow \int_{-\infty}^{+\infty} |x(t)|^2 dt &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(jw)|^2 dw \\
 \int_{-\infty}^{+\infty} |x(t)|^2 dt &= \int_{-\infty}^{+\infty} x(t) x^*(t) dt \\
 &= \int_{-\infty}^{+\infty} x(t) \left[\frac{1}{2\pi} \int_{-\infty}^{+\infty} X^*(jw) e^{-jw t} dw \right] dt \\
 &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X^*(jw) \left[\int_{-\infty}^{+\infty} x(t) e^{-jw t} dt \right] dw \\
 &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(jw)|^2 dw
 \end{aligned}$$

$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$
 $X(jw) = \int_{-\infty}^{+\infty} x(t) e^{-jw t} dt$

- Representation of Aperiodic Signals: the Continuous-Time Fourier Transform
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- The Multiplication Property
- Systems Characterized by Linear Constant-Coefficient Differential Equations

▪ Convolution Property:

$$\begin{aligned}
 &\begin{array}{c} x(t) \\ \xrightarrow{\mathcal{F}} \\ X(jw) \end{array} \quad \begin{array}{c} h(t) \\ \xrightarrow{\mathcal{F}} \\ H(jw) \end{array} \quad \begin{array}{c} y(t) \\ \xrightarrow{\mathcal{F}} \\ Y(jw) \end{array} \\
 y(t) = x(t) * h(t) &\xleftrightarrow{\mathcal{F}} Y(jw) = X(jw) H(jw) \\
 &= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau
 \end{aligned}$$

▪ Multiplication Property:

$$\begin{aligned}
 &\begin{array}{c} s(t) \\ \xrightarrow{\mathcal{F}} \\ S(j\theta) \end{array} \quad \begin{array}{c} p(t) \\ \downarrow \\ \otimes \end{array} \quad \begin{array}{c} r(t) \\ \xrightarrow{\mathcal{F}} \\ R(jw) \end{array} \\
 r(t) = s(t)p(t) &\xleftrightarrow{\mathcal{F}} R(jw) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S(j\theta) P(j(w-\theta)) d\theta
 \end{aligned}$$

▪ From Superposition (or Linearity):

$$\begin{aligned}
 x(t) &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{j\omega t} dw \\
 &= \lim_{w_0 \rightarrow 0} \frac{1}{2\pi} \sum_{k=-\infty}^{+\infty} X(jkw_0) e^{jk\omega_0 t} w_0 \\
 &\quad \frac{1}{2\pi} \sum_{k=-\infty}^{+\infty} X(jkw_0) e^{jk\omega_0 t} w_0 \quad \xrightarrow{\text{Linear System}} \quad \frac{1}{2\pi} \sum_{k=-\infty}^{+\infty} X(jkw_0) H(jkw_0) e^{jk\omega_0 t} w_0 \\
 &\quad H(jkw_0) = \int_{-\infty}^{\infty} h(t) e^{-jk\omega_0 t} dt \\
 y(t) &= \lim_{w_0 \rightarrow 0} \frac{1}{2\pi} \sum_{k=-\infty}^{+\infty} X(jkw_0) H(jkw_0) e^{jk\omega_0 t} w_0 \\
 &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) H(jw) e^{j\omega t} dw
 \end{aligned}$$

▪ From Superposition (or Linearity):

$$\frac{1}{2\pi} \sum_{k=-\infty}^{+\infty} X(jkw_0) e^{jk\omega_0 t} w_0 \rightarrow \frac{1}{2\pi} \sum_{k=-\infty}^{+\infty} X(jkw_0) H(jkw_0) e^{jk\omega_0 t} w_0$$

$$y(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) H(jw) e^{j\omega t} dw$$

$$\text{Since } y(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} Y(jw) e^{j\omega t} dw$$

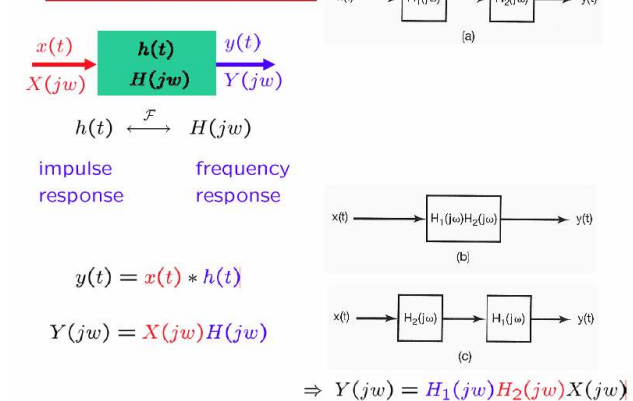
$$\Rightarrow Y(jw) = X(jw) H(jw)$$

$$y(t) = x(t) * h(t) \xleftrightarrow{\mathcal{F}} Y(jw) = X(jw) H(jw)$$

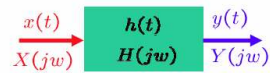
▪ From Convolution Integral:

$$\begin{aligned}
 x(t) &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{j\omega t} dw \\
 X(jw) &= \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \\
 x(t-t_0) &\xleftrightarrow{\mathcal{F}} e^{-j\omega t_0} X(jw) \\
 y(t) &= \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau \\
 \Rightarrow Y(jw) &= \mathcal{F}\{y(t)\} = \int_{-\infty}^{+\infty} \left[\int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau \right] e^{-j\omega t} dt \\
 &= \int_{-\infty}^{+\infty} x(\tau) \left[\int_{-\infty}^{+\infty} h(t-\tau) e^{-j\omega t} dt \right] d\tau \\
 &= \int_{-\infty}^{+\infty} x(\tau) \left[e^{-j\omega \tau} H(jw) \right] d\tau \\
 &= H(jw) \int_{-\infty}^{+\infty} x(\tau) e^{-j\omega \tau} d\tau \\
 \Rightarrow Y(jw) &= H(jw) X(jw)
 \end{aligned}$$

▪ Equivalent LTI Systems:



▪ Example 4.15: Time Shift



$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

$$X(jw) = \int_{-\infty}^{\infty} x(t) e^{-jw t} dt$$

$$x(t - t_0) \xrightarrow{F} e^{-jw t_0} X(jw)$$

$$h(t) = \delta(t - t_0)$$

$$\Rightarrow H(jw) = e^{-jw t_0}$$

$$Y(jw) = H(jw)X(jw)$$

$$= e^{-jw t_0} X(jw)$$

$$\Rightarrow y(t) = x(t - t_0)$$

▪ Examples 4.16 & 17: Differentiator & Integrator

$$y(t) = \frac{d}{dt} x(t) \Rightarrow Y(jw) = jw X(jw)$$

$$\Rightarrow H(jw) = jw$$

$$y(t) = \int_{-\infty}^t x(\tau) d\tau \Rightarrow h(t) = u(t) \quad \text{impulse response}$$

$$\Rightarrow H(jw) = \frac{1}{jw} + \pi \delta(w)$$

$$\Rightarrow Y(jw) = H(jw)X(jw)$$

$$= \frac{1}{jw} X(jw) + \pi \delta(w) X(jw)$$

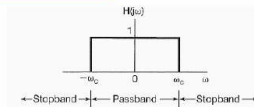
$$= \frac{1}{jw} X(jw) + \pi \delta(w) X(0)$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

$$X(jw) = \int_{-\infty}^{\infty} x(t) e^{-jw t} dt$$

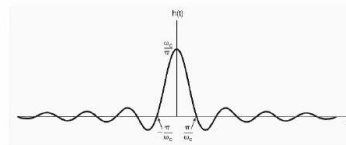
▪ Example 4.18: Ideal Lowpass Filter

$$H(jw) = \begin{cases} 1, & |w| < w_c \\ 0, & |w| > w_c \end{cases}$$



$$\Rightarrow h(t) = \frac{1}{2\pi} \int_{-w_c}^{+w_c} e^{jw t} dw$$

$$= \frac{\sin(w_c t)}{\pi t}$$



$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

$$X(jw) = \int_{-\infty}^{\infty} x(t) e^{-jw t} dt$$

▪ Filter Design:

$$H(jw) = \int_{-\infty}^{\infty} h(t) e^{-jw t} dt$$

$$y(t) = h(t) * x(t)$$

$$= \int_{-\infty}^{\infty} h(t - \tau) x(\tau) d\tau$$

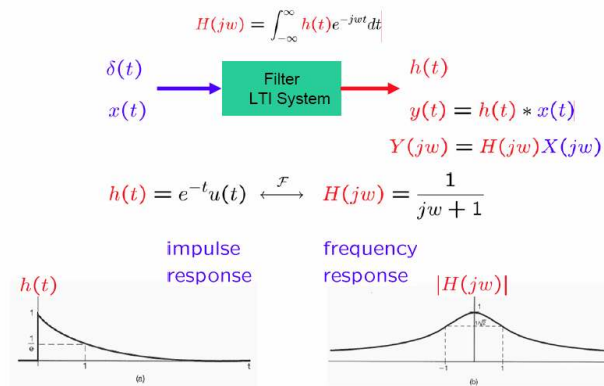
$$H(jw) = \int_{-\infty}^{\infty} h(t) e^{-jw t} dt$$

$$X(jw) = \int_{-\infty}^{\infty} x(t) e^{-jw t} dt$$

$$\Rightarrow Y(jw) = H(jw)X(jw)$$

$$\Rightarrow y(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} Y(jw) e^{jw t} dw$$

▪ Filter Design:



▪ Example 4.19:

$x(t) \xrightarrow{\text{Filter LTI System}} y(t)$
 $h(t) = e^{-at}u(t), \quad a > 0 \Rightarrow H(jw) = \frac{1}{a + jw}$
 $x(t) = e^{-bt}u(t), \quad b > 0 \Rightarrow X(jw) = \frac{1}{b + jw}$
 $\Rightarrow Y(jw) = H(jw)X(jw) = \frac{1}{a + jw} \frac{1}{b + jw}$
 if $a \neq b$

$$= \frac{1}{b-a} \left[\frac{1}{a + jw} - \frac{1}{b + jw} \right]$$

▪ Example 4.19:

if $a \neq b$ $Y(jw) = \frac{1}{b-a} \left[\frac{1}{a + jw} - \frac{1}{b + jw} \right]$
 $\Rightarrow y(t) = \frac{1}{b-a} [e^{-at}u(t) - e^{-bt}u(t)]$
 if $a = b$ $Y(jw) = \frac{1}{(a + jw)^2}$
 since $e^{-at}u(t) \xleftrightarrow{\mathcal{F}} \frac{1}{a + jw}$
 and $t e^{-at}u(t) \xleftrightarrow{\mathcal{F}} j \frac{d}{dw} \left[\frac{1}{a + jw} \right] = \frac{1}{(a + jw)^2}$
 $\Rightarrow y(t) = t e^{-at}u(t)$

▪ Example 4.20:

$H(jw) = \int_{-\infty}^{\infty} h(t)e^{-jwt} dt$
 $x(t) = \frac{\sin(w_i t)}{\pi t} \xrightarrow{\text{Filter LTI System}} y(t) = ?$
 $h(t) = \frac{\sin(w_c t)}{\pi t}$
 $\Rightarrow Y(jw) = H(jw)X(jw)$
 $\Rightarrow X(jw) = \begin{cases} 1, & |w| \leq w_i \\ 0, & \text{otherwise} \end{cases}$
 $\Rightarrow H(jw) = \begin{cases} 1, & |w| \leq w_c \\ 0, & \text{otherwise} \end{cases}$
 $\Rightarrow Y(jw) = \begin{cases} 1, & |w| \leq w_0 \\ 0, & \text{otherwise} \end{cases}$ where $w_0 = \min(w_c, w_i)$
 $\Rightarrow y(t) = \begin{cases} \frac{\sin(w_c t)}{\pi t}, & w_c \leq w_i \\ \frac{\sin(w_i t)}{\pi t}, & w_i \leq w_c \end{cases}$

$X(jw)$
 $H(jw)$

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Convolution & Multiplication:

$$y(t) = x(t) * h(t) \xleftrightarrow{\mathcal{F}} Y(j\omega) = X(j\omega)H(j\omega)$$

$$= \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau$$

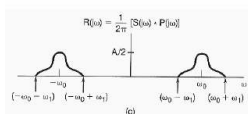
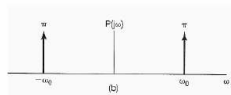
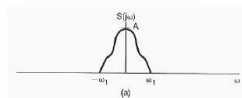
$$r(t) = s(t)p(t) \xleftrightarrow{\mathcal{F}} R(j\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S(j\theta)P(j(\omega-\theta))d\theta$$

Multiplication of One Signal by Another:

- Scale or modulate the amplitude of the other signal
- Modulation



Example 4.21:



$$r(t) = s(t)p(t)$$

$$s(t) \xleftrightarrow{\mathcal{F}} S(j\omega)$$

$$p(t) \xleftrightarrow{\mathcal{F}} P(j\omega)$$

$$p(t) = \cos(\omega_0 t)$$

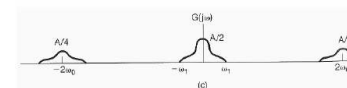
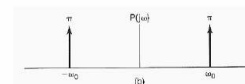
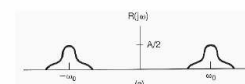
$$P(j\omega) = \pi\delta(\omega - \omega_0) + \pi\delta(\omega + \omega_0)$$

$$R(j\omega) = \frac{1}{2\pi} [S(j\omega) * P(j\omega)]$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} S(j\theta)P(j(\omega - \theta))d\theta$$

$$= \frac{1}{2} S(j(\omega - \omega_0)) + \frac{1}{2} S(j(\omega + \omega_0))$$

Example 4.22:



$$g(t) = r(t)p(t)$$

$$r(t) \xleftrightarrow{\mathcal{F}} R(j\omega)$$

$$p(t) \xleftrightarrow{\mathcal{F}} P(j\omega)$$

$$p(t) = \cos(\omega_0 t)$$

$$G(j\omega) = \frac{1}{2\pi} [R(j\omega) * P(j\omega)]$$

▪ **Example 4.23:**

$$x(t) = \frac{\sin(t) \sin(t/2)}{\pi t^2}$$

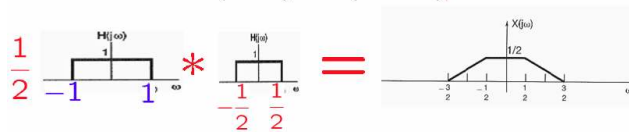
$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) e^{j\omega t} d\omega$$

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$X(j\omega) = \int_{-\infty}^{\infty} \frac{\sin(t) \sin(t/2)}{\pi t^2} e^{-j\omega t} dt$$

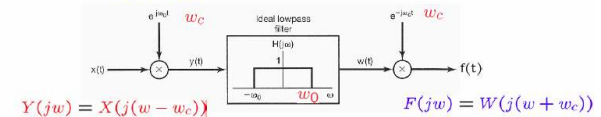
$$= \pi \left(\frac{\sin(t)}{\pi t} \right) \left(\frac{\sin(t/2)}{\pi t} \right)$$

$$\Rightarrow X(j\omega) = \frac{1}{2} \mathcal{F} \left\{ \frac{\sin(t)}{\pi t} \right\} * \mathcal{F} \left\{ \frac{\sin(t/2)}{\pi t} \right\}$$



▪ **Bandpass Filter Using Amplitude Modulation:**

$$e^{j\omega_c t} \xleftrightarrow{\mathcal{F}} 2\pi\delta(\omega - \omega_c)$$



$$Y(j\omega) = X(j(\omega - \omega_c))$$

$$F(j\omega) = W(j(\omega + \omega_c))$$

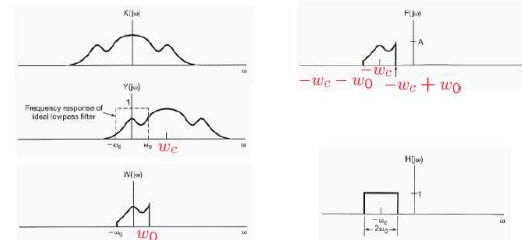


TABLE 4.1 PROPERTIES OF THE FOURIER TRANSFORM

Section	Property	Aperiodic signal	Fourier transform
		$x(t)$	$X(j\omega)$
		$y(t)$	$Y(j\omega)$
4.3.1	Linearity	$ax(t) + by(t)$	$aX(j\omega) + bY(j\omega)$
4.3.2	Time Shifting	$x(t - t_0)$	$e^{-j\omega t_0} X(j\omega)$
4.3.6	Frequency Shifting	$e^{j\omega_0 t} x(t)$	$X(j(\omega - \omega_0))$
4.3.3	Conjugation	$x^*(t)$	$X^*(-j\omega)$
4.3.5	Time Reversal	$x(-t)$	$X(-j\omega)$
4.3.5	Time and Frequency Scaling	$x(at)$	$\frac{1}{ a } X\left(\frac{j\omega}{a}\right)$
4.4	Convolution	$x(t) * y(t)$	$X(j\omega)Y(j\omega)$
4.5	Multiplication	$x(t)y(t)$	$\frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\theta)Y(j(\omega - \theta))d\theta$
4.3.4	Differentiation in Time	$\frac{d}{dt}x(t)$	$j\omega X(j\omega)$
4.3.4	Integration	$\int_{-\infty}^t x(\tau)d\tau$	$\frac{1}{j\omega} X(j\omega) + \pi\delta(\omega)$
4.3.6	Differentiation in Frequency	$tx(t)$	$j\frac{d}{d\omega} X(j\omega)$
4.3.3	Conjugate Symmetry for Real Signals	$x(t)$ real	$\begin{cases} X(j\omega) = X^*(-j\omega) \\ \Re\{X(j\omega)\} = \Re\{X(-j\omega)\} \\ \Im\{X(j\omega)\} = -\Im\{X(-j\omega)\} \end{cases}$
4.3.3	Symmetry for Real and Even Signals	$x(t)$ real and even	$X(j\omega)$ real and even
4.3.3	Symmetry for Real and Odd Signals	$x(t)$ real and odd	$X(j\omega)$ purely imaginary and odd
4.3.3	Even-Odd Decomposition for Real Signals	$x_e(t) = \frac{1}{2}(x(t) + x(-t))$ [x(t) real]	$\Re\{X(j\omega)\}$
		$x_o(t) = \frac{1}{2}(x(t) - x(-t))$ [x(t) real]	$j\Im\{X(j\omega)\}$
4.3.7	Parseval's Relation for Aperiodic Signals	$\int_{-\infty}^{\infty} x(t) ^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) ^2 d\omega$	

TABLE 4.2 BASIC FOURIER TRANSFORM PAIRS

Signal	Fourier transform	Fourier series coefficients (if periodic)
$\sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t}$	$2\pi \sum_{k=-\infty}^{+\infty} a_k \delta(\omega - k\omega_0)$	a_k
$e^{j\omega_0 t}$	$2\pi\delta(\omega - \omega_0)$	$a_1 = 1$ $a_k = 0$, otherwise
$\cos \omega_0 t$	$\pi[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$	$a_1 = a_{-1} = \frac{1}{2}$ $a_k = 0$, otherwise
$\sin \omega_0 t$	$\frac{\pi}{j}[\delta(\omega - \omega_0) - \delta(\omega + \omega_0)]$	$a_1 = -a_{-1} = \frac{1}{2j}$ $a_k = 0$, otherwise
$x(t) = 1$	$2\pi\delta(\omega)$	$a_0 = 1$, $a_k = 0$, $k \neq 0$ (this is the Fourier series representation for any choice of $T > 0$)
Periodic square wave		
$x(t) = \begin{cases} 1, & t < T_1 \\ 0, & T_1 < t \leq \frac{T}{2} \end{cases}$	$\sum_{k=-\infty}^{+\infty} \frac{2 \sin k\omega_0 T_1}{k} \delta(\omega - k\omega_0)$	$\frac{\omega_0 T_1}{\pi} \text{sinc} \left(\frac{k\omega_0 T_1}{\pi} \right) = \frac{\sin k\omega_0 T_1}{k\pi}$
and $x(t + T) = x(t)$		

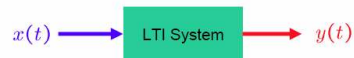
$\sum_{n=-\infty}^{\infty} \delta(t - nT)$	$\frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta\left(\omega - \frac{2\pi k}{T}\right)$	$a_k = \frac{1}{T}$ for all k
$x(t) \begin{cases} 1, & t < T_1 \\ 0, & t > T_1 \end{cases}$	$\frac{2 \sin \omega T_1}{\omega}$	—
$\frac{\sin Wt}{\pi t}$	$X(j\omega) = \begin{cases} 1, & \omega < W \\ 0, & \omega > W \end{cases}$	—
$\delta(t)$	1	—
$u(t)$	$\frac{1}{j\omega} + \pi \delta(\omega)$	—
$\delta(t - t_0)$	$e^{-j\omega t_0}$	—
$e^{-\sigma t} u(t), \operatorname{Re}\{\sigma\} > 0$	$\frac{1}{a + j\omega}$	—
$te^{-\sigma t} u(t), \operatorname{Re}\{\sigma\} > 0$	$\frac{1}{(a + j\omega)^2}$	—
$\frac{t^{n-1}}{(n-1)!} e^{-\sigma t} u(t), \operatorname{Re}\{\sigma\} > 0$	$\frac{1}{(a + j\omega)^n}$	—

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- Systems Characterized by Linear Constant-Coefficient Differential Equations

▪ A useful class of CT LTI systems:

$$a_N \frac{d^N y(t)}{dt^N} + a_{N-1} \frac{d^{N-1} y(t)}{dt^{N-1}} + \dots + a_1 \frac{dy(t)}{dt} + a_0 y(t) = b_M \frac{d^M x(t)}{dt^M} + b_{M-1} \frac{d^{M-1} x(t)}{dt^{M-1}} + \dots + b_1 \frac{dx(t)}{dt} + b_0 x(t)$$

$$\sum_{k=0}^N a_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M b_k \frac{d^k x(t)}{dt^k}$$



$$Y(j\omega) = X(j\omega)H(j\omega) \quad H(j\omega) = \frac{Y(j\omega)}{X(j\omega)}$$

$$\mathcal{F} \left\{ \sum_{k=0}^N a_k \frac{d^k y(t)}{dt^k} \right\} = \mathcal{F} \left\{ \sum_{k=0}^M b_k \frac{d^k x(t)}{dt^k} \right\}$$

$$\sum_{k=0}^N a_k \mathcal{F} \left\{ \frac{d^k y(t)}{dt^k} \right\} = \sum_{k=0}^M b_k \mathcal{F} \left\{ \frac{d^k x(t)}{dt^k} \right\}$$

$$\sum_{k=0}^N a_k (j\omega)^k Y(j\omega) = \sum_{k=0}^M b_k (j\omega)^k X(j\omega)$$

$$Y(j\omega) \left[\sum_{k=0}^N a_k (j\omega)^k \right] = X(j\omega) \left[\sum_{k=0}^M b_k (j\omega)^k \right]$$

$$\Rightarrow H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{\sum_{k=0}^M b_k (j\omega)^k}{\sum_{k=0}^N a_k (j\omega)^k} = \frac{b_M (j\omega)^M + \dots + b_1 (j\omega) + b_0}{a_N (j\omega)^N + \dots + a_1 (j\omega) + a_0}$$

▪ Examples 4.24 & 4.25:

$$\frac{dy(t)}{dt} + ay(t) = x(t) \Rightarrow H(j\omega) = \frac{1}{j\omega + a}$$

$$(j\omega)Y(j\omega) + aY(j\omega) = X(j\omega) \Rightarrow h(t) = e^{-at}u(t)$$

$$\frac{d^2y(t)}{dt^2} + 4\frac{dy(t)}{dt} + 3y(t) = \frac{dx(t)}{dt} + 2x(t)$$

$$\Rightarrow H(j\omega) = \frac{(j\omega) + 2}{(j\omega)^2 + 4(j\omega) + 3} = \frac{(j\omega + 2)}{(j\omega + 1)(j\omega + 3)}$$

$$= \frac{1/2}{j\omega + 1} + \frac{1/2}{j\omega + 3}$$

$$\Rightarrow h(t) = \frac{1}{2}e^{-t}u(t) + \frac{1}{2}e^{-3t}u(t)$$

▪ Example 4.26:

$$x(t) = e^{-t}u(t) \xrightarrow{\text{LTI System}} y(t) = ???$$

$$H(j\omega) = \frac{(j\omega + 2)}{(j\omega + 1)(j\omega + 3)}$$

$$\Rightarrow Y(j\omega) = X(j\omega)H(j\omega)$$

$$= \left[\frac{1}{j\omega + 1} \right] \left[\frac{j\omega + 2}{(j\omega + 1)(j\omega + 3)} \right]$$

$$= \frac{j\omega + 2}{(j\omega + 1)^2(j\omega + 3)}$$

$$= \frac{\frac{1}{4}}{j\omega + 1} + \frac{\frac{1}{2}}{(j\omega + 1)^2} - \frac{\frac{1}{4}}{j\omega + 3}$$

$$\Rightarrow y(t) = \left[\frac{1}{4}e^{-t} + \frac{1}{2}te^{-t} - \frac{1}{4}e^{-3t} \right] u(t)$$

Signals & Systems (Chap 1)

LTI & Convolution (Chap 2)

Bounded/Convergent

Periodic

FS
(Chap 3)

- CT
- DT

Aperiodic

FT

- CT (Chap 4)
- DT (Chap 5)

Unbounded/Non-convergent

LT

- CT (Chap 9)

zT

- DT (Chap 10)

Time-Frequency (Chap 6)

Communication (Chap 8)

CT-DT (Chap 7)

Control (Chap 11)