Mercury Introduction

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Why?

System performance – Distributed decision making



- ATM system is complex, with many different actors
 - Airlines
 - Crew (flight)
 - Airports (arrival managers, departure managers)
 - Network Manager
 - •
- Actors make decisions through the day with various objectives in mind
 - Local objectives optimisation
 - Cooperation but also competition

System performance – Distributed decision making

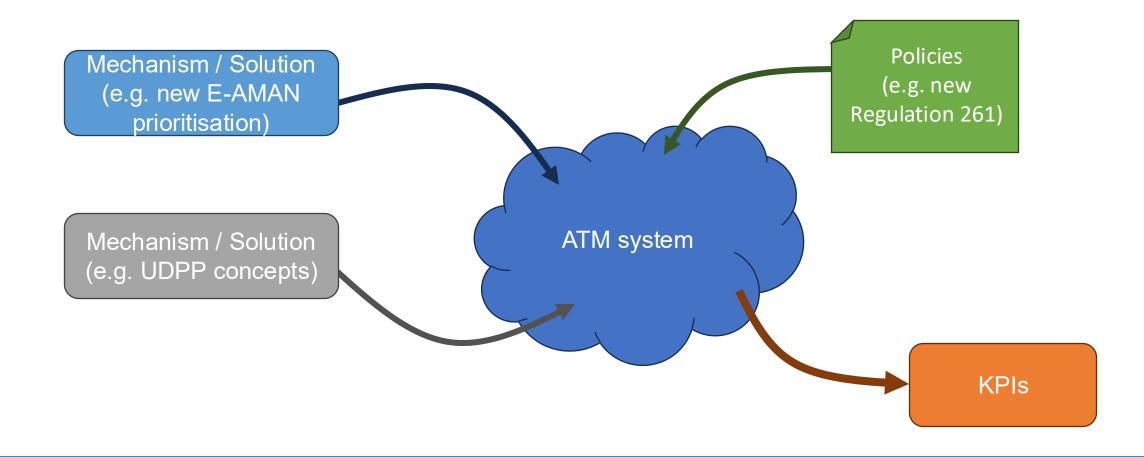


• Network Manager, ANSPs... try to provide capacity but, Airlines making decisions on how to manage their flights, passengers...

System performance – Distributed decision making

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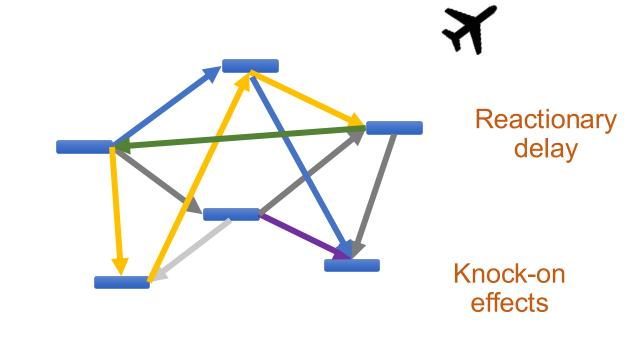
Changes in behaviour due to changes in mechanisms (Solutions) and policies



Modelling not only flights



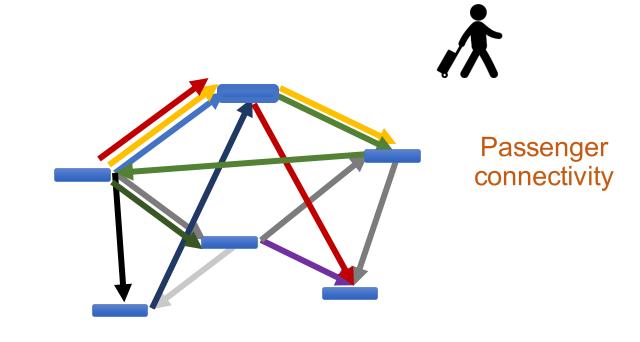
Different stakeholders = > different system perception



Modelling not only flights



Different stakeholders = > different system perception



Modelling not only flights



Different stakeholders = > different system perception

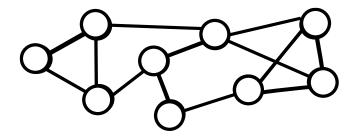
Reactionary delay



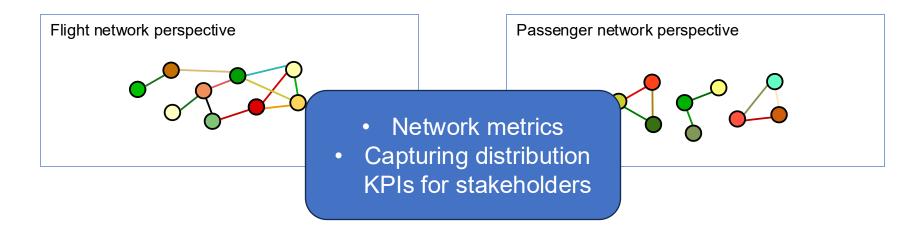
Passenger



Passenger connectivity







Stakeholders' decision shape the system



Actors have different objectives

- E-AMAN
 - Maintain runway capacity
 - Maximise throughput
 - Reduce holdings
 - ...
- DMAN
 - Maintain runway capacity
 - ...

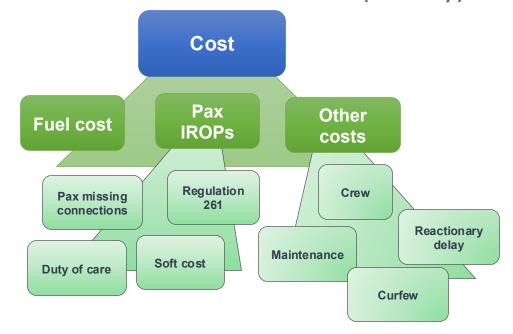
- Network Manager
 - Maintain network capacity
 - Prioritise flights
 - •
- Airlines
 - Keep operations running smoothly
 - Keep delays to a minimum
 - Avoid extra costs
 - ...
- ...

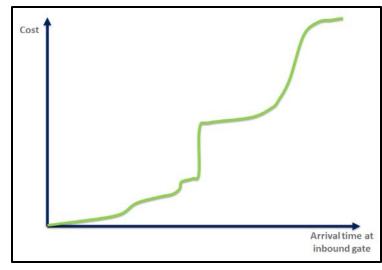
Distributed information which is not shared!

Stakeholders' decision shape the system



- Airlines are (mostly) cost minimization driven
 - Day(s) prior to operations airlines plan their flights
 - During the day of operations perform actions to maintain flight flows (and passengers)
 - Decisions are cost-driven (mostly)





- Non-linear
- Difficult to estimate
- Subject to uncertainties

Stakeholders' decision shape the system



- Airlines are (mostly) cost minimization driven
 - Day(s) prior to operations airlines plan their flights
 - During the day of operations perform actions to maintain flight flows (and passengers)

Plight plan selection

Flight prioritisation in ATFM regulations

Plight trajectory adjustment

Wait for passengers



Requirements and Capabilities

Mercury





Radar

DMAN

Flight

APOC

Terminal

https://github.com/UoW-ATM/Mercury

E-AMAN

- Flight and passenger mobility model
 - Agent-based model
 - Describing main components of ATM system
 - Tracking individual flights and passengers
 - Multimodality and door-to-door estimation capabilities
 - 1 day of operations at ECAC level (27k flights, 3M pax)
 - Developed in various European projects over 10 years
 - Open source









Network Manager

Computation requirements

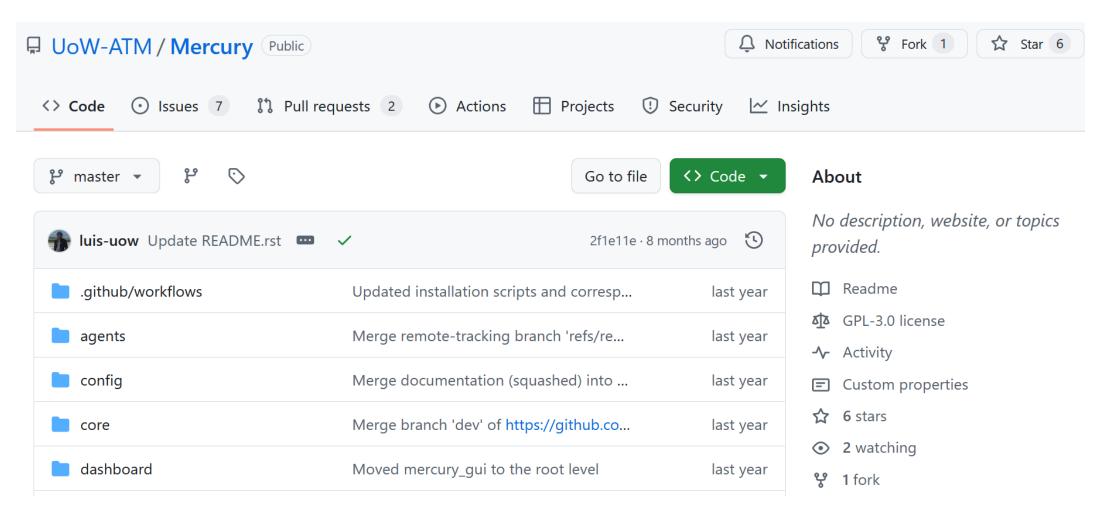
- 1 day of operations simulation (ECAC region ~27K flights, ~3.4M pax):
 - ~ 8GB RAM
 - ~25 minutes baseline scenario (Intel i7-4790 @3.60GHz)
- **Individual low-level metrics** for different stakeholders

Mercury





https://github.com/UoW-ATM/Mercury



Requirements



- Model main actors in ATM
- Model channels of propagation of delay (flight and passengers) and cost
- Evaluate Mechanisms / Solutions on
 - E-AMAN
 - Dynamic cost indexing + waiting for passenger strategies
 - Flight prioritization for ATFM regulations

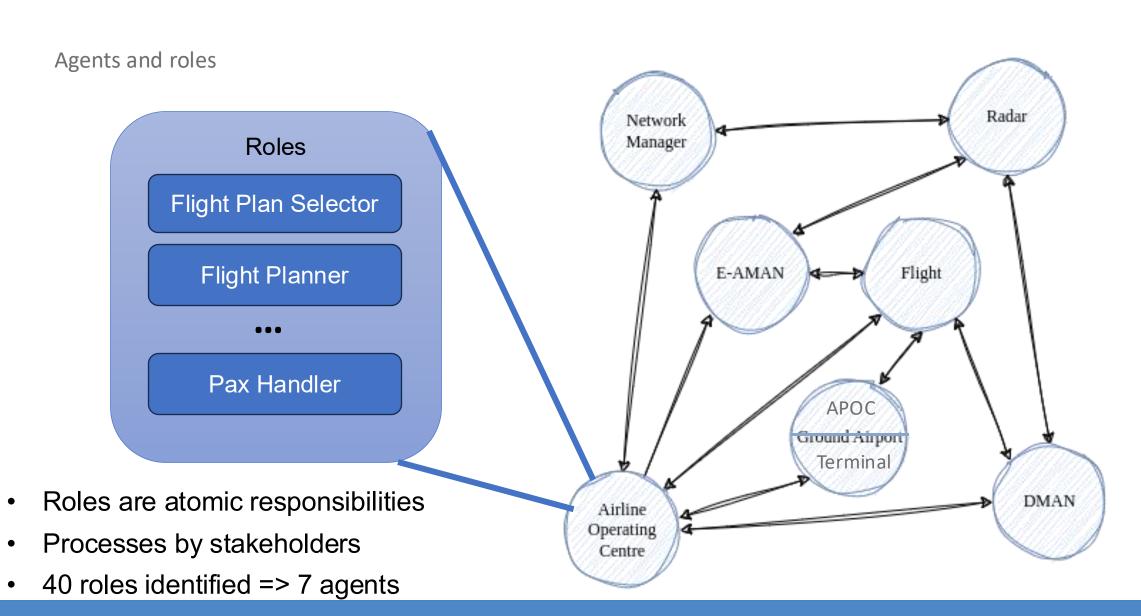
- Need trade-off fuel and time in trajectory
- Need estimation of cost of delay at different points



Design Approach

GAIA methodology





Messaging, events and interactions



Agent type	Roles
Airline Operating Centre	Airline Flight Planner, Dynamic Cost Index Computer, Passenger Reallocation, Turnaround Operations, Airline Passenger Handler, Flight Plan Selector
Flight	Aircraft Departing Handler, Departure Slot Requester, Flight Plan Constraint Updater, Flight Plan Updater, Flight Arrival Information Provider, Ground Arrival Handler, Operate Trajectory, Potential Delay Recovery Provider
Airport Operating Centre	Ground Handler, Taxi-out Estimator, Taxi-Out Provider, Taxi-In Provider
E-AMAN	Strategic Arrival Queue Builder, Arrival Queue Planned Updater, Arrival Cancellation Handler, Flight In AMAN Handler, Arrival Planner Provider, Arrival Tactical Provider, Slot Assigner, Arrival Planner Provider Queue, Arrival Tactical Provider Queue

- Agents react to
 - Changes in the environment (events)
 - Messages from other agents



Communication and Simulation

Communication and simulation



- Messaging, events and interactions
 - Discrete-event simulator
 - Roles are triggered by events with might trigger interaction (messages) with other agents
 - Concurrence is possible
 - Events can be generated, modified, cancelled (as needed)
 - Events track main operational milestones:
 - Flight plan submission
 - Push-back
 - Take-off
 - •
 - Use of resources (e.g. aircraft)



Events



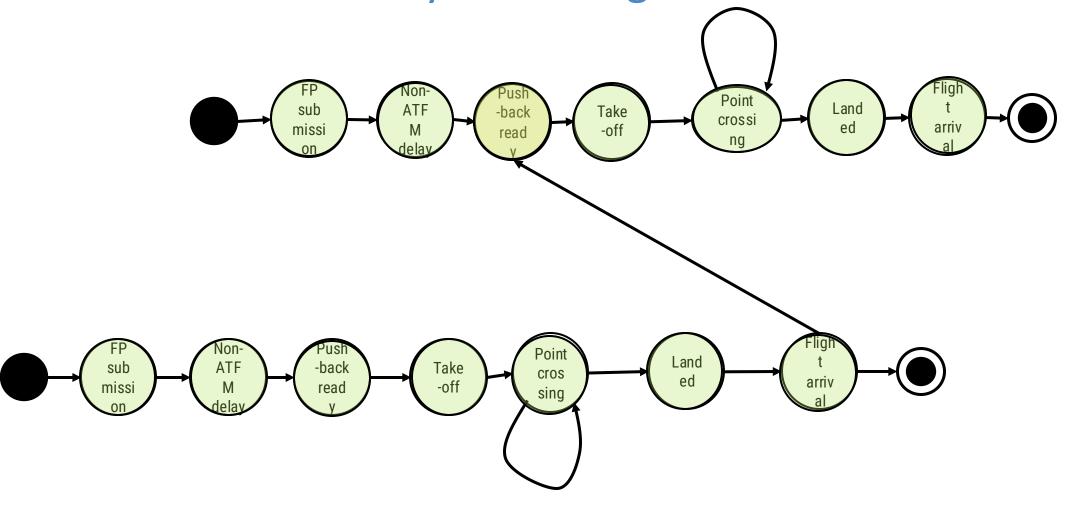
Events: main operational milestones (9 key events)

Event	Short description
FP submission	First submission of flight plan for a flight. This is normally triggered 3 h before the flight SOBT.
Delay estimation	AOC checks the status of the flight and a random non-ATFM delay is drawn. This is normally triggered 1 h before the flight EOBT.
Passenger check	AOC checks which passengers are not ready to board their flights, 5 min before EOBT.
Pushback ready	Aircraft is ready to push-back. The flight requests a departure slot.
Pushback	The flight is off-block and begins taxi-out. Connecting passengers which are not boarded are rebooked.
Take-off	The flight begins an "operate trajectory" activity which integrates the trajectory between pre-defined waypoints in the flight plan (with stochastic noise).
Flight Crossing Point	A waypoint is crossed by the flight during its trajectory execution. This type of event triggered by the flight and captured by the Radar for the broadcast the position of the flight to interested parties in the model.
Landing	The flight reaches its final trajectory point. It begins taxi-in.
Flight Arrival	The flight arrives at the gate. Turnaround and connecting passenger processes begin.

Discrete event simulation

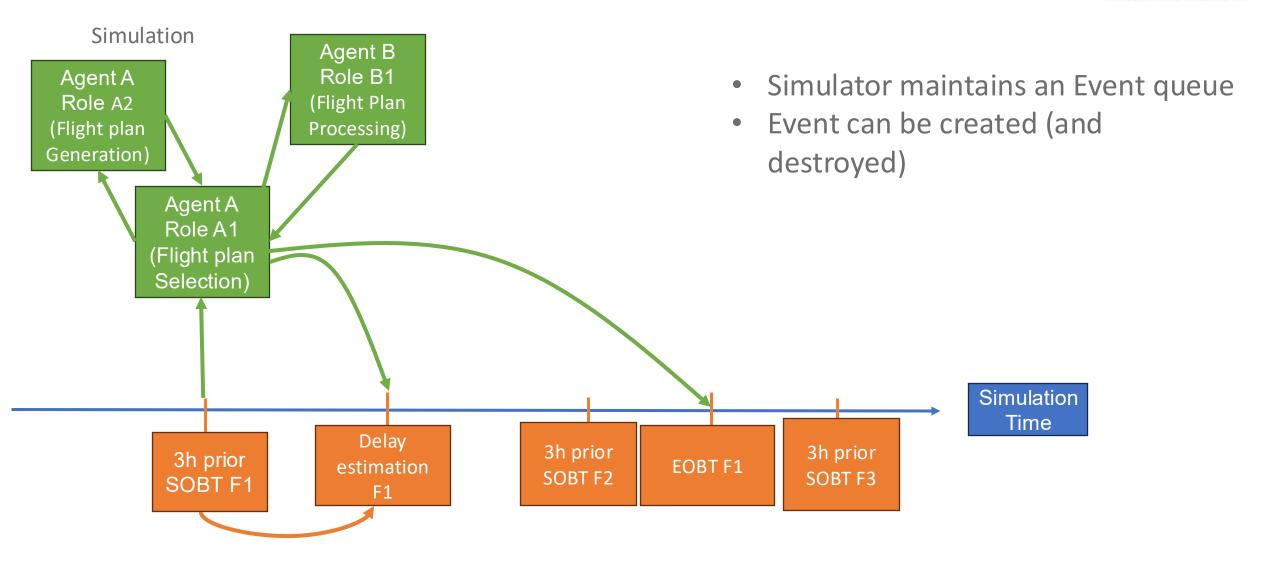
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Reactionary modelling



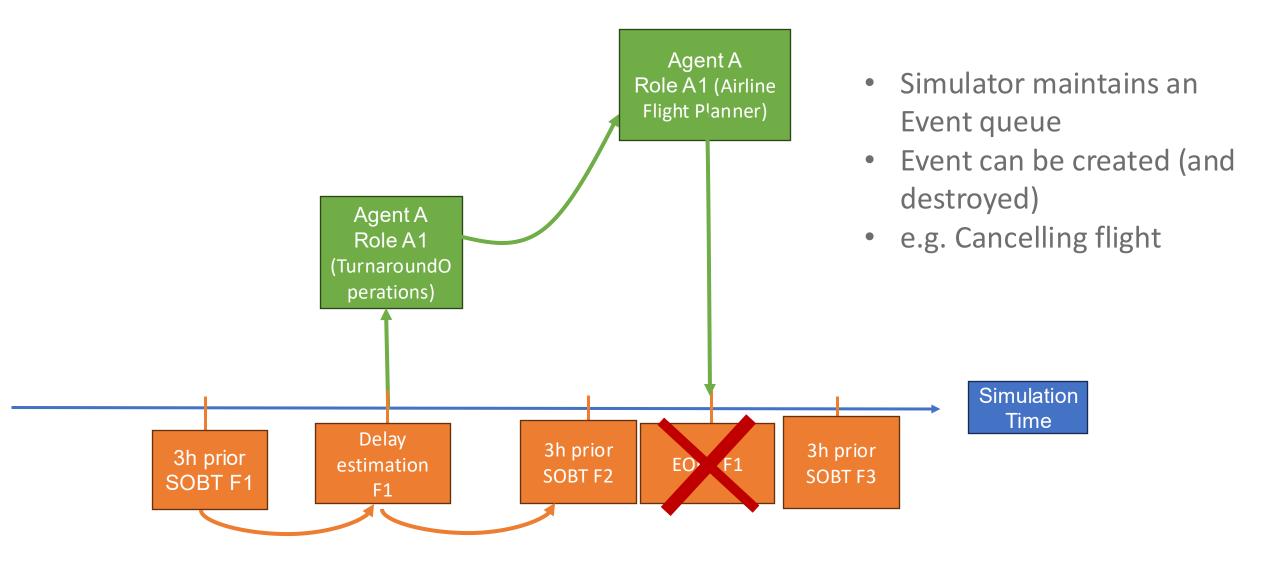
Simulation – Events principle





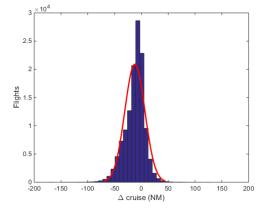
Simulation – Events principle



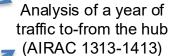


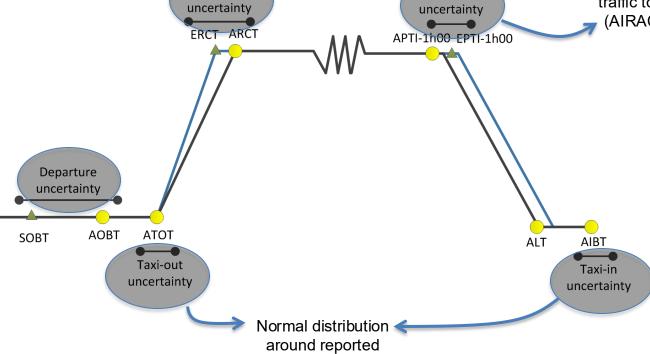
Uncertainty modelling

Climb









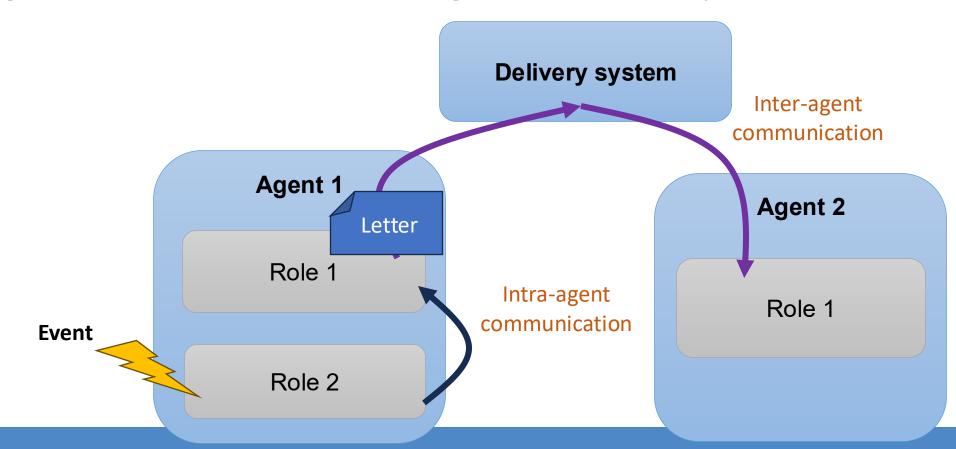
values

Cruise

Inter and intra agents communication

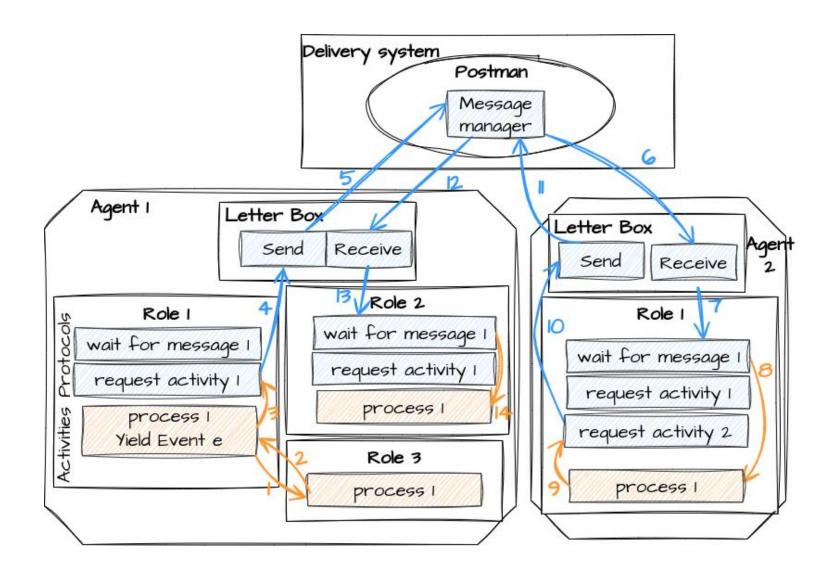


- Communications
 - Inter-agents: two agents interacting (messaging system)
 - Intra-agents: two roles within the same agent (direct memory access)



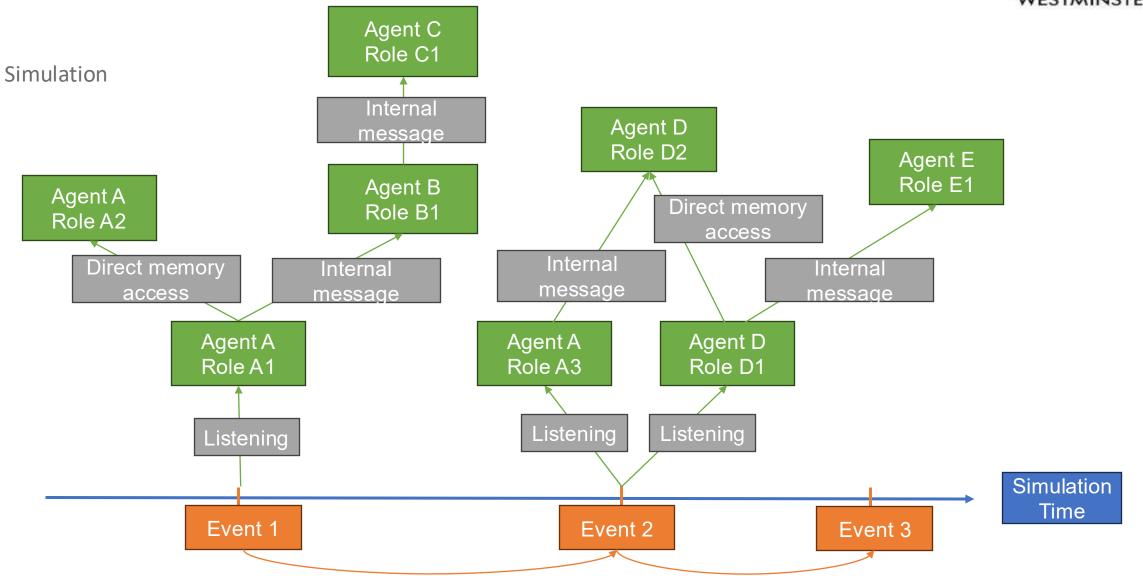
Internal communication



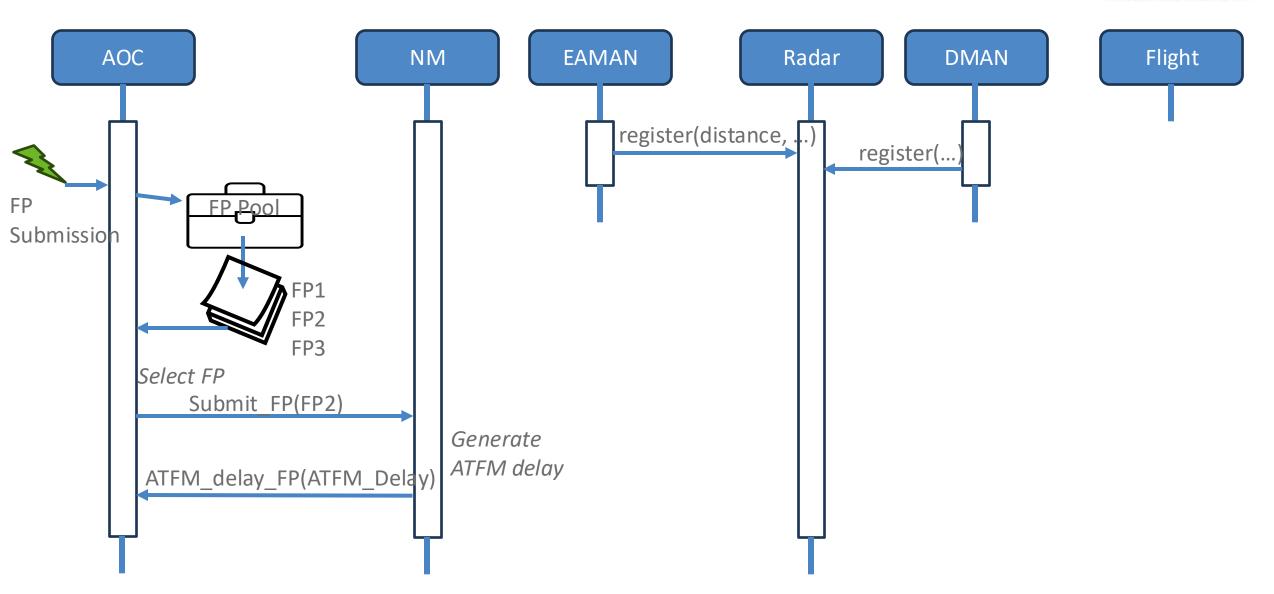


Events with communications

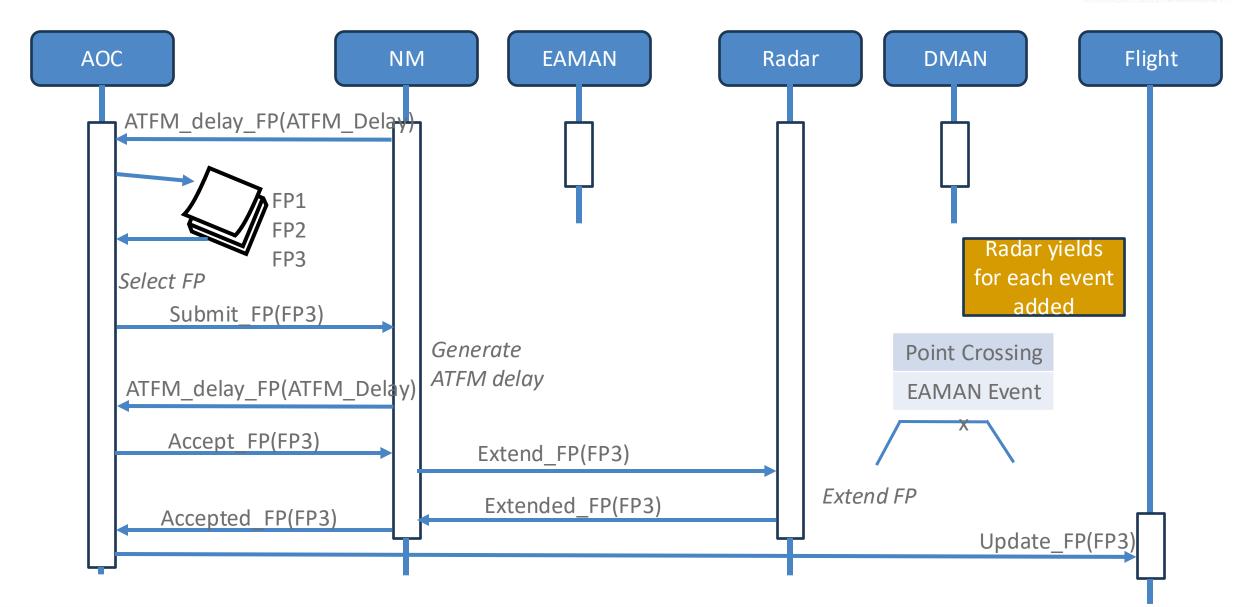




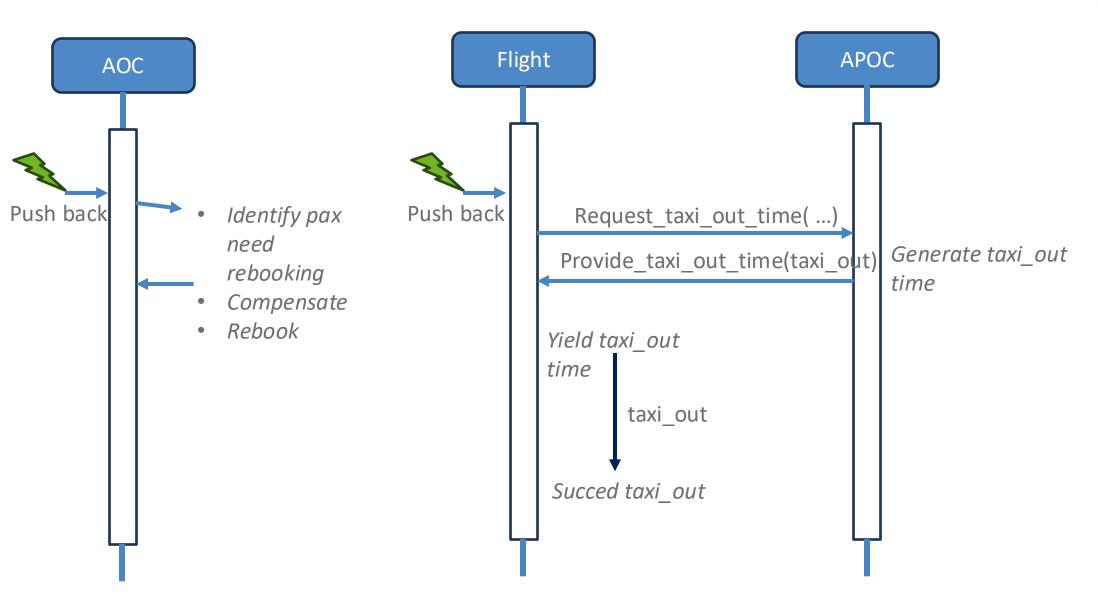


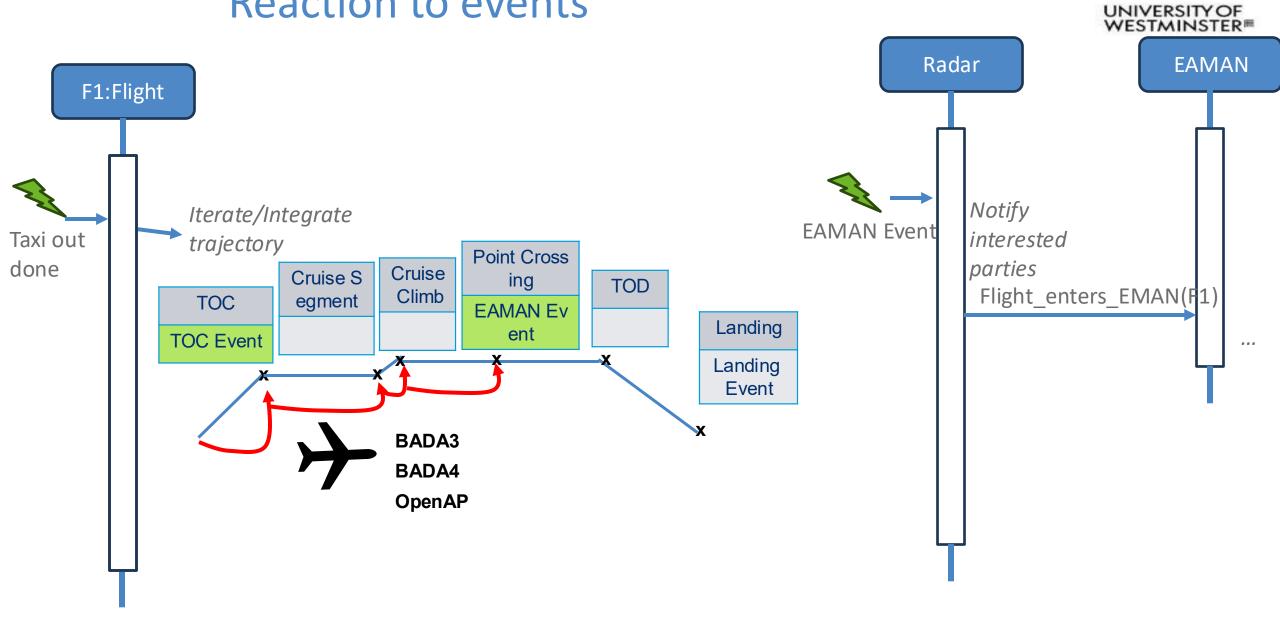






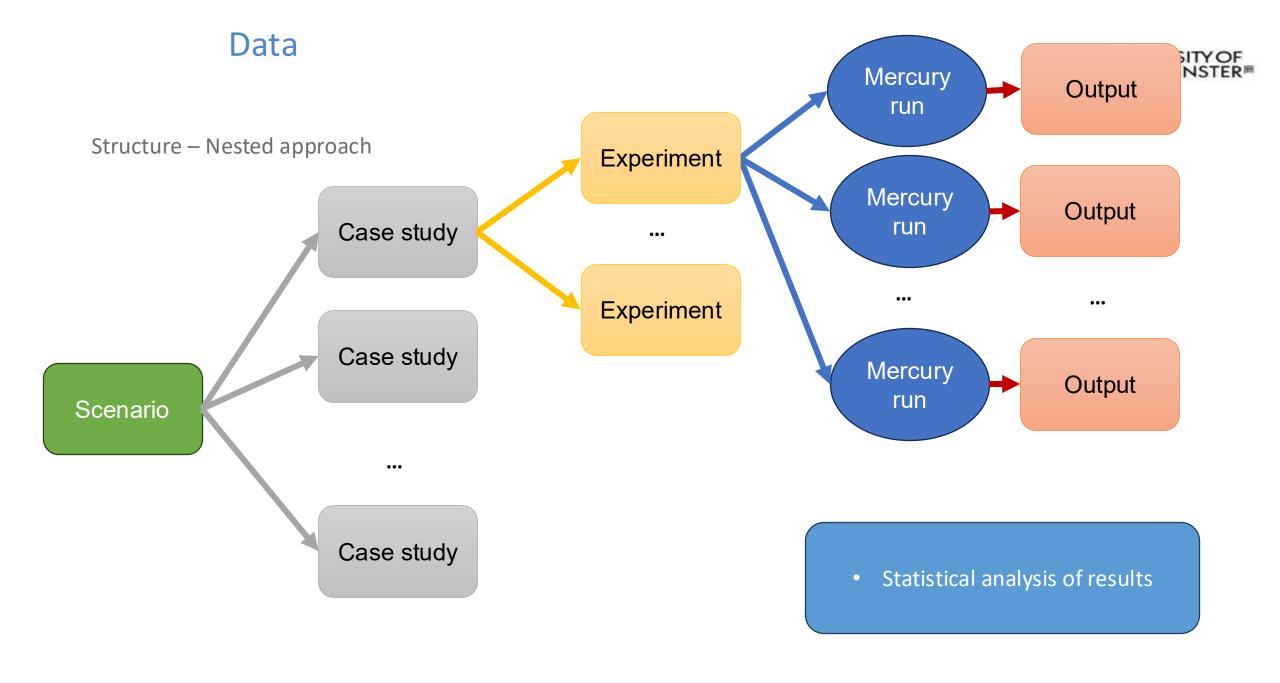








Scenarios / Case Study / Experiments





- Scenario
- All possible flights (and pax) for a given period and region
- Information required to simulate ATM operations

E.g.

- All flights and pax for a day of operation in Europe (27k flights, 3.8M pax)
- Distributions for probability delay (High, Medium, Low) from historical data analysis

- ...

- Case study
- All possible flights (and pax) for a given period and region
- Information required to simulate ATM operations

E.g.

- All flights and pax for a day of operation in Europe (27k flights, 3.8M pax)
- Distributions for probability delay (High, Medium, Low) from historical data analysis

- ...

- Experiment
- Iteration on parameters to evaluate case study
 E.g.
- Cost of fuel from 0.1 to 0.7 EUR/Kg

...

Key data exploration



Give some input data.

Choose a scenario.

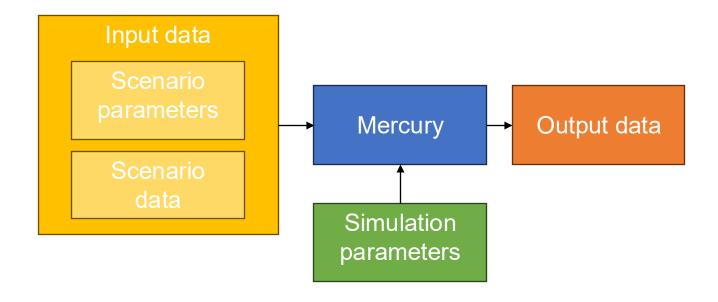
Choose case study (opt.).

Choose some parameters to set or sweep (opt.)

Choose number of iteration (by default only 1).

Run.

Get results: summarised and detailed.



Data sample **Zenodo**

https://zenodo.org/records/1138 4379

Key data exploration



In config/mercury_config.py: how the simulation should run

 Scenario parameters in input folder: what the simulation should run

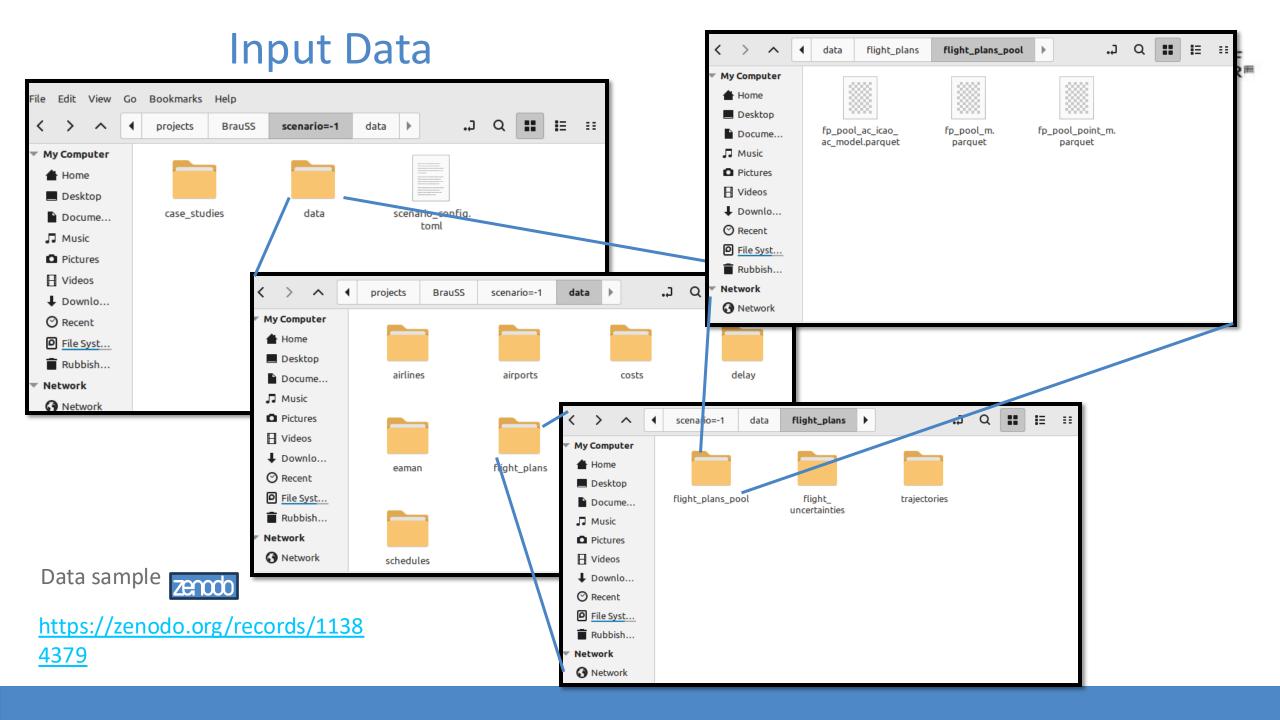
```
[paras.modules]
modules_to_load = ['CM']
path = 'modules'
[paras.airlines]
non_ATFM_delay_loc = 0.0
compensation_uptake = 0.11
delay_estimation_lag = 60
threshold_swap = 100.0
heuristic_knock_on_factor = 1.8
smoothness_fp = 200.0
fp_anchor = 0.3
#extra_climb_tweak = 2.
cancel_cascade_curfew = false
```

Input Data

```
scenario_config.toml ×
[infol
scenario id = -1
description = "Anonymised test scenario - 1k flights"
[data]
    [data.scenario]
    input scenario = 'scenario'
    [data.delay]
    input delay paras = 'delay parameters'
    [data.network manager]
   input atfm delay = 'iedf atfm static'
    input atfm prob = 'prob atfm static'
    input regulation at airport days = 'regulation at airport days static'
   input atfm regulation at airport = 'regulation at airport static'
   input atfm regulation at airport manual = 'regulation at airport manual'
    [data.costs]
    input soft cost = 'soft cost delay static'
    input_compensation = 'passenger compensation static'
    input doc = 'duty of care static'
    input non pax cost = 'non pax delay static'
    input non pax cost fit = 'non pax delay fit static'
    input cost curfews = 'curfew non pax costs'
    input estimated cost curfews = 'curfew costs estimated'
    [data.pax]
    input itinerary = 'pax itineraries'
    [data.airports]
    input airport = 'airport info static'
    input mtt = 'mtt static'
   input_airport_modif = 'airport modif cap'
        [data.airports.curfew]
        icao airport name = 'icao'
        curfew airport name = 'arrival curfew start'
        input airport curfew = 'airports curfews times'
        input curfew extra time = 'airports extra time curfews'
        input airports with curfews = 'airports with curfews'
        input airports curfew2 = 'airport curfew'
```

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```
[data.flight plans.en route wind]
    [data.airports.taxi]
                                                           input iedf wind static = 'iedf wind static old1409'
    input taxi in = 'taxi in static'
                                                           wind type = 'LIKE \"%%seament%%\"'
    input taxi out = 'taxi out static'
[data.eaman]
input eaman = 'eaman definition' # table name
[data.airlines]
input airline = 'airline static' # table name
[data.schedules]
input schedules = 'flight schedule' # table name
[data.flight plans]
    [data.flight plans.crco]
    #CRCO if computing FPs
    input crco charges = 'crco charges static old1409'
    input crco vat = 'crco vat static old1409'
    input crco fix = 'crco fix static old1409'
    input overfly = 'crco overfly static old1409'
    input crco weight = 'crco weight static old1409'
    [data.flight plans.routes] # Not used, directly flight plans
    input route pool = 'route pool'
    input route pool has airspace = 'route pool has airspace static'
    input airspace = 'airspace static'
    [data.flight_plans.trajectories] # Not used, directly flight plans
    input trajectory pool = 'trajectory pool'
    input trajectory segments = 'trajectory segment' # missing
    [data.flight plans.flight plans pool]
    input fp pool = 'fp pool m'
    input fp pool point = 'fp pool point m'
    input fp pool ac icao ac model = 'fp pool ac icao ac model' # relations|
    [data.flight plans.flight uncertainties]
    input flight uncertainties = 'flight uncertainties static'
    input extra cruise if dci = 'increment cruise dci static'
```



Output Data



Pax

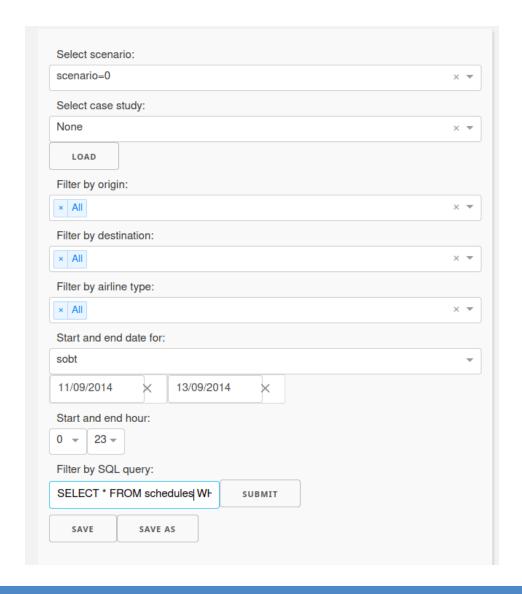
_id	initial_sobt	final_sibt	initial_aobt	final_aibt	modified_itinerary	tot_arriv
61	2019-09-06 15:35:00	2019-09-06 20:50:00	2019-09-06 19:47:24.380680	2019-09-07 07:27:00.000000	True	
157	2019-09-06 14:20:00	2019-09-06 19:35:00	2019-09-06 14:51:11.188765	2019-09-07 07:32:00.000000	True	
170	2019-09-06 04:40:00	2019-09-06 10:49:00	2019-09-06 04:55:49.318364	2019-09-06 10:49:00.000000	False	
186	2019-09-06 07:20:00	2019-09-06 11:45:00	2019-09-06 08:08:58.684235	2019-09-06 12:47:00.000000	True	
201	2019-09-06 05:05:00	2019-09-06 09:46:00	2019-09-06 05:10:18.836478	2019-09-06 09:46:00.000000	False	

tot_arrival_delay	connecting_pax	final_destination_reached	multimodal	missed_air2rail	missed_rail2air	ground_mobility_time
637	'False	True	True	True	False	67.49
717	False	True	True	True	False	92.92
C	False	True	True	False	False	97.49
62	False	True	True	True	False	92.59
C	False	True	True	False	False	103.72



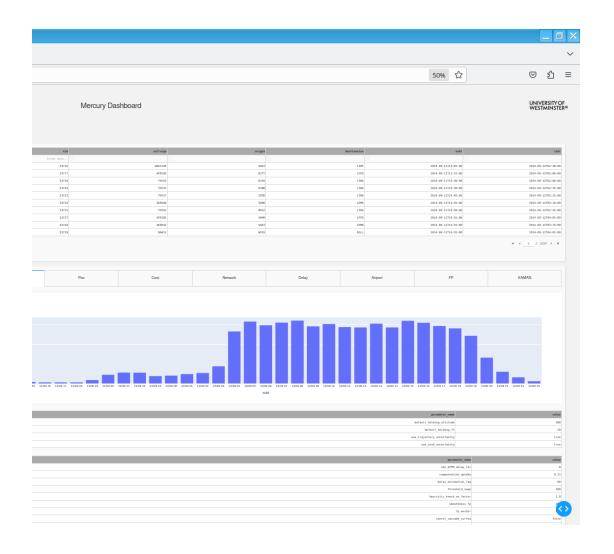


Facilitate manipulation input/output data and configuration



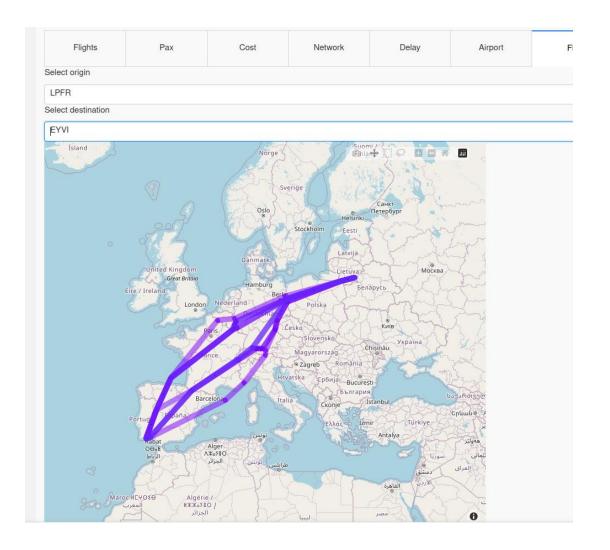


Facilitate manipulation input/output data and configuration



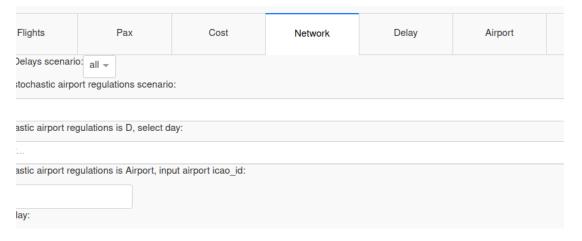


Facilitate manipulation input/output data and configuration

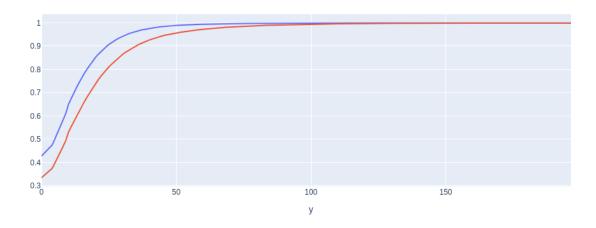




Facilitate manipulation input/output data and configuration



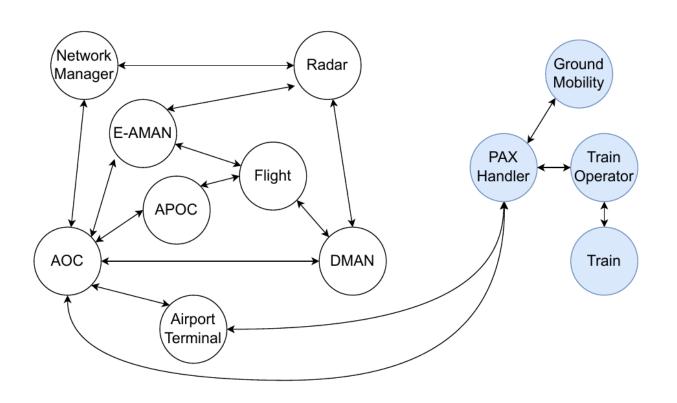
ATFM delay Probability





Extension of Mercury to Multimodality

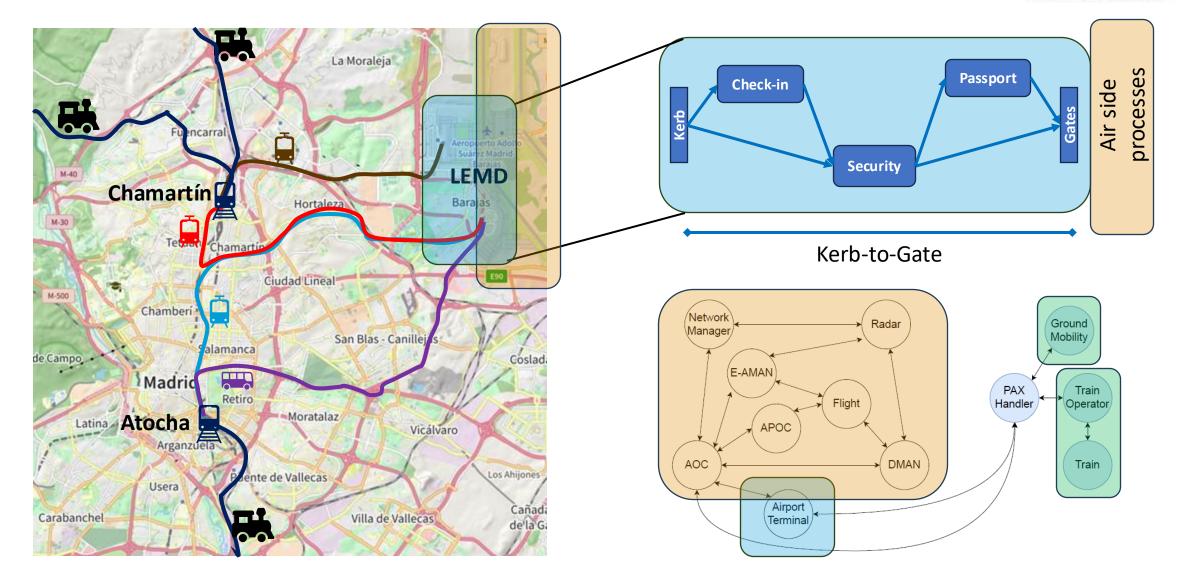




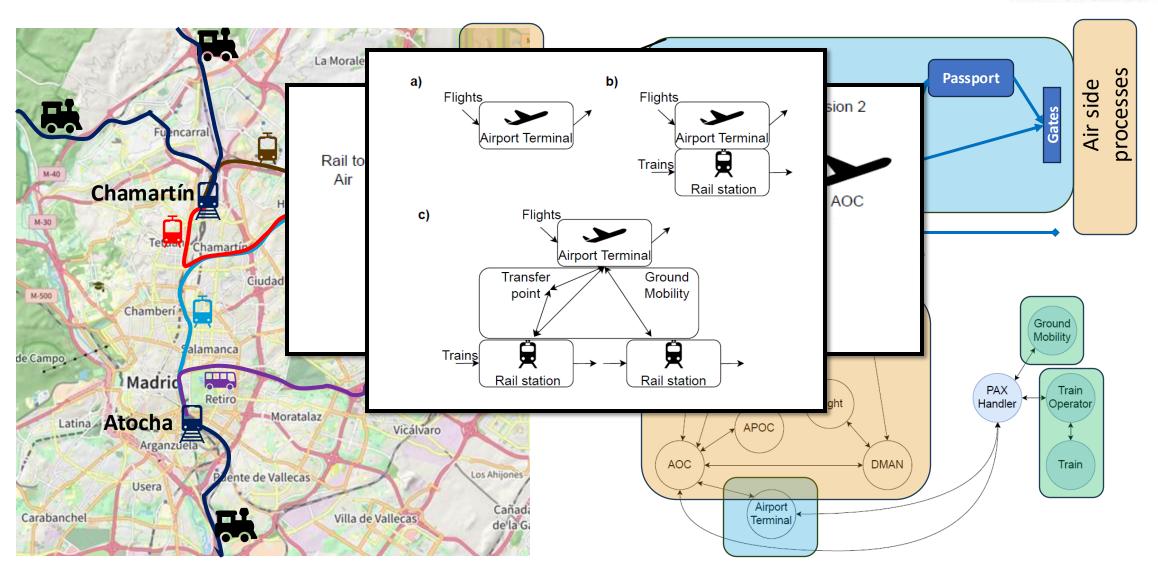
New agents:

Train, Train Operator, Ground Mobility, Passenger Handler.











Example of use of Mercury

Examples use of Mercury



- Evaluate different versions of Dynamic Cost Indexing Waiting for Passengers
- Evaluate different version of E-AMAN
- Evaluate different version of Flight Prioritisation
- Changes of policies (e.g. Regulation 261)
- Behavioural economics aspects with human in the loop simulations
- Multimodal connectivity at hubs

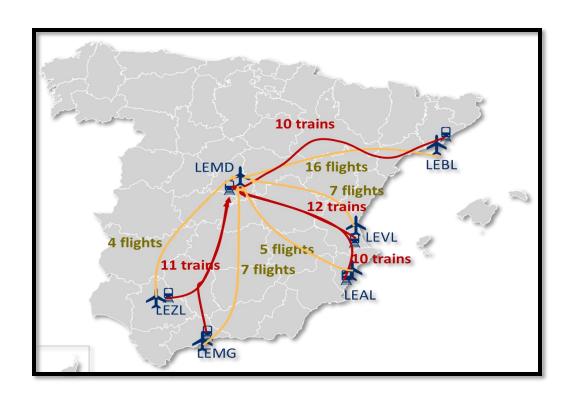
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- 1 day of air traffic on 22nd September 2023 to/from Madrid Barajas (LEMD) (816 flights)
- GTFS dataset from Renfe (154 trains)
- Passenger OD matrix from Aviation Week
- All flights with a rail alternative
 < 2h30 removed (air ban policy)
- OD matrix is disaggregated into the flights and trains





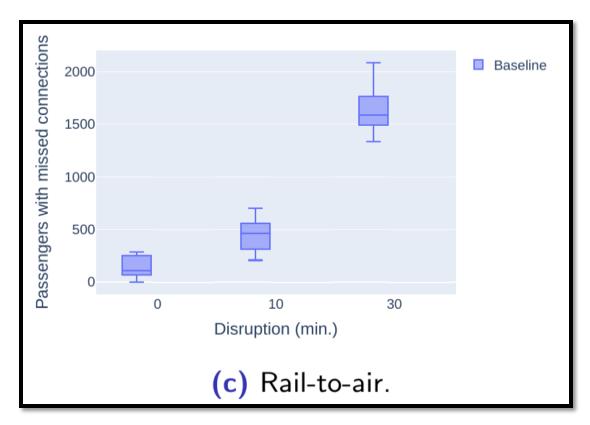
- Out of 90k pax,
- 66.8% are single-flight,
- 18.8% are connecting flight-flight,
- 14.4% are multimodal.

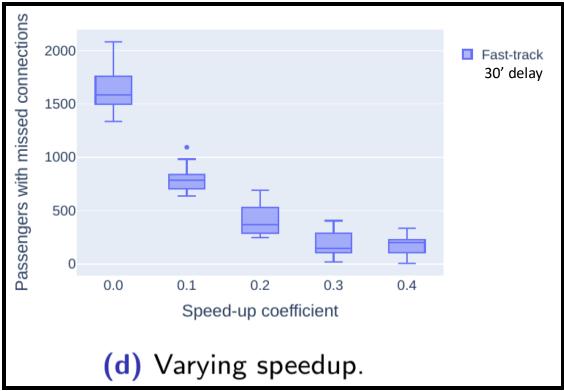


- Fast-track process for pax
 - Speed up Kerb-to-Gate for delayed passengers by a given factor,
 - Affects only rail-air connections
- Disrupted delayed ground mobility (10 30 minutes)



Fast-track for processing passengers







Conclusions

Conclusions





- Multi-agent-based system
- Decisions based on cost estimation
- Event-driven tracking main processes
- Modelling flight and passenger mobility
- Capturing low level indicators (and distributions) for relevant stakeholders
 - Delay, costs, emissions, etc.
- Modular: possible to modify behaviour of element in system
- Open source (and libraries): Python

https://github.com/UoW-ATM/Mercury

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THANK YOU