





imports


IOperations
O cmd_vel(msg: Twist)



IEvents
⚡ scan: Seq(real)

 TurtleBot
P IOperations
i IEvents
<div>scan: Seq(real)</div>

 Module
<div> <div> <div>scan: Seq(real)</div> <div> <i>ref TurtleBot</i></div> </div> <div> <div></div> <div><i>ref Driving</i></div> </div> </div>

 Twist
linear: Vector3
angular: Vector3

 Vector3
x: real
y: real
z: real

 Driving
R IOperations
<div> <div> <div> stm0</div> <div> <div>R IOperations</div> <div>π lvel: real, avel: real</div> <div>C</div> </div> </div> <div> <div> <div>i /#C</div> <div> <div>Forward</div> <div>entry cmd_vel(Twist(linear = Vector3(x = lvel, y = 0, z = 0), angular = Vector3(x = 0, y = 0, z = avel))))</div> </div> </div> </div> </div>