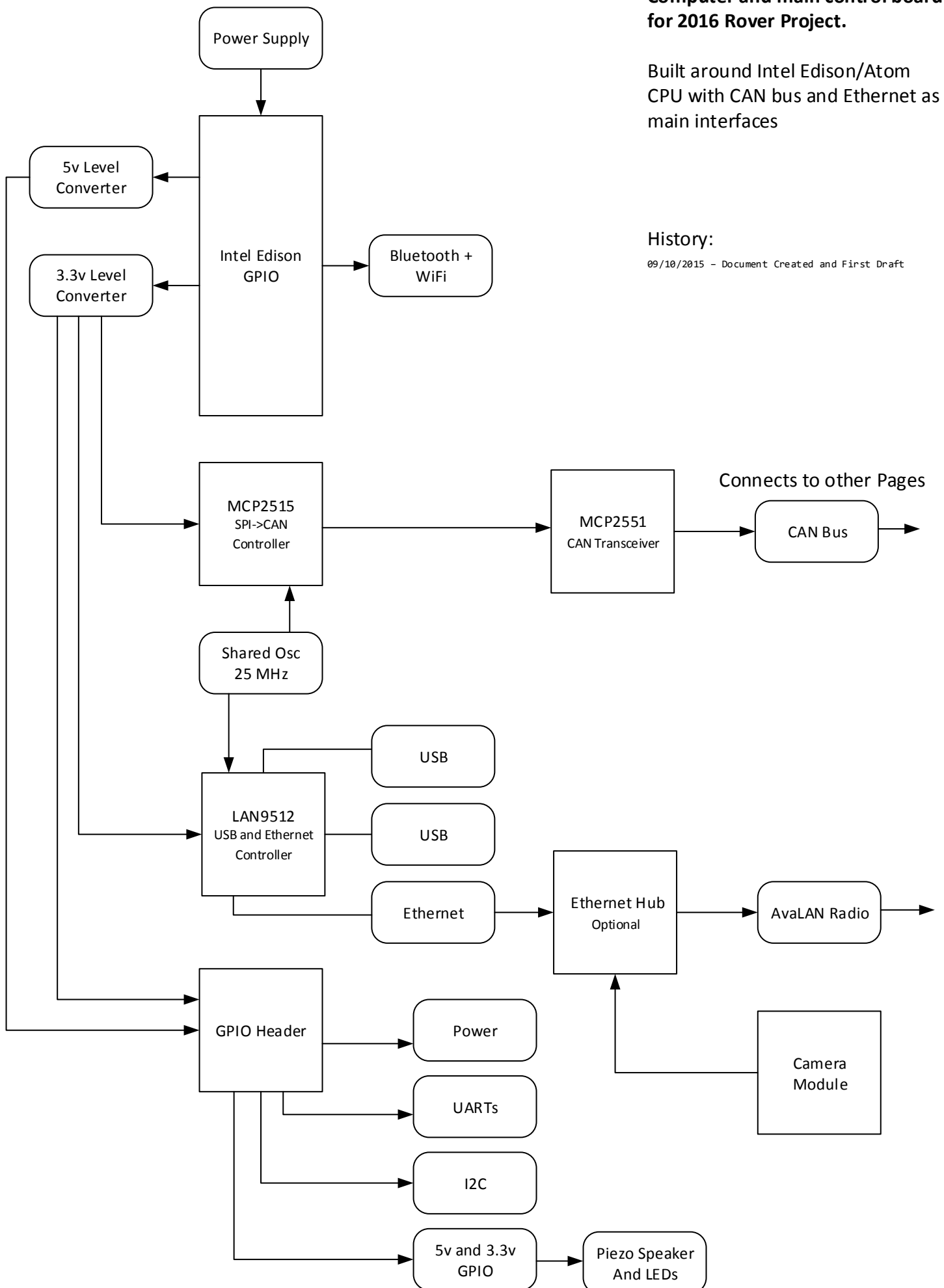


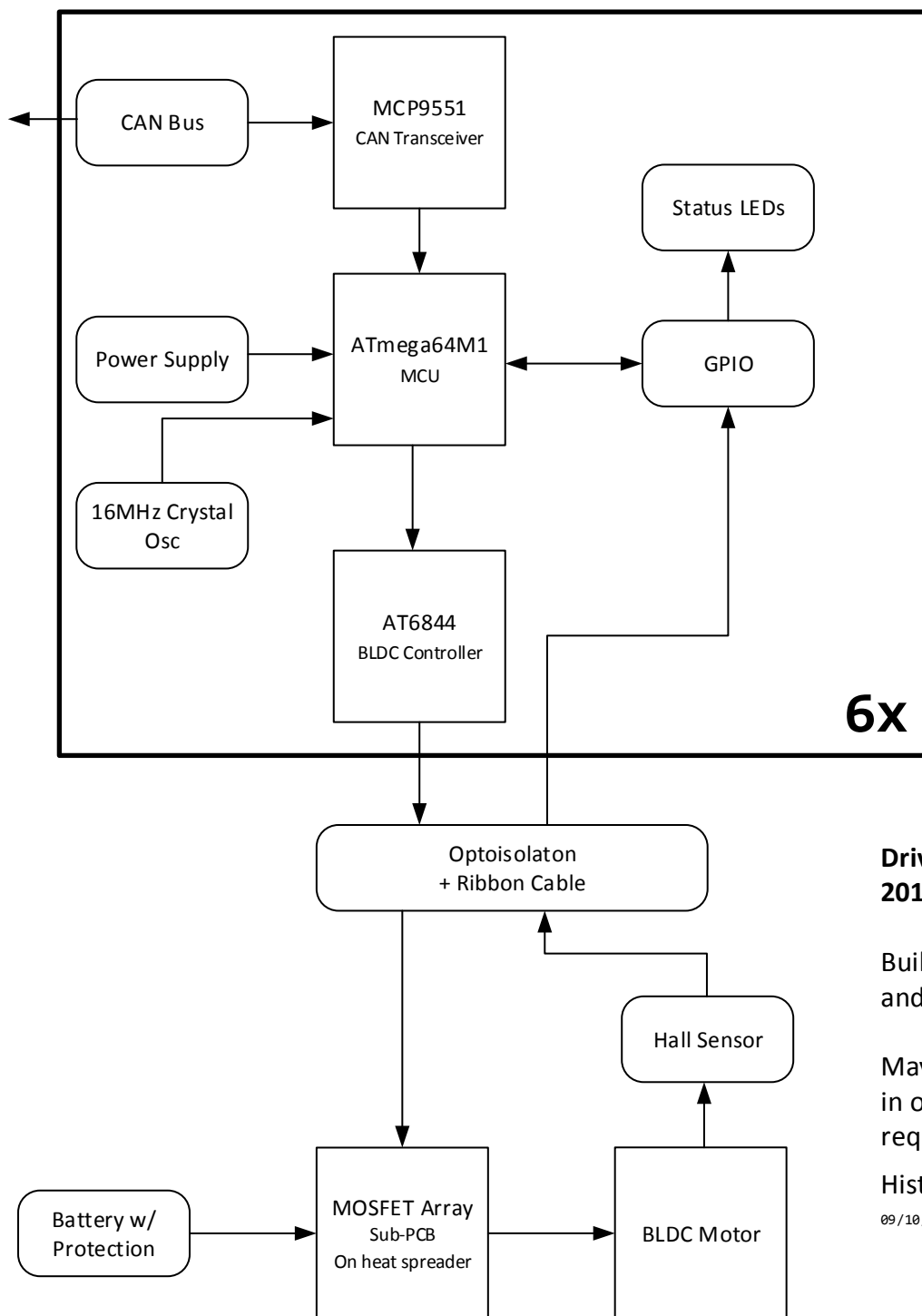
## Computer and main control board for 2016 Rover Project.

Built around Intel Edison/Atom  
CPU with CAN bus and Ethernet as  
main interfaces

### History:

09/10/2015 - Document Created and First Draft





### Drive Motor Control board for 2016 Rover Project.

Built around AT6844 Controller and ATmega64M1 MCU

May need 6x of the above module in order to meet all the requirements of the BLDC control

#### History:

09/10/2015 - Document Created and First Draft