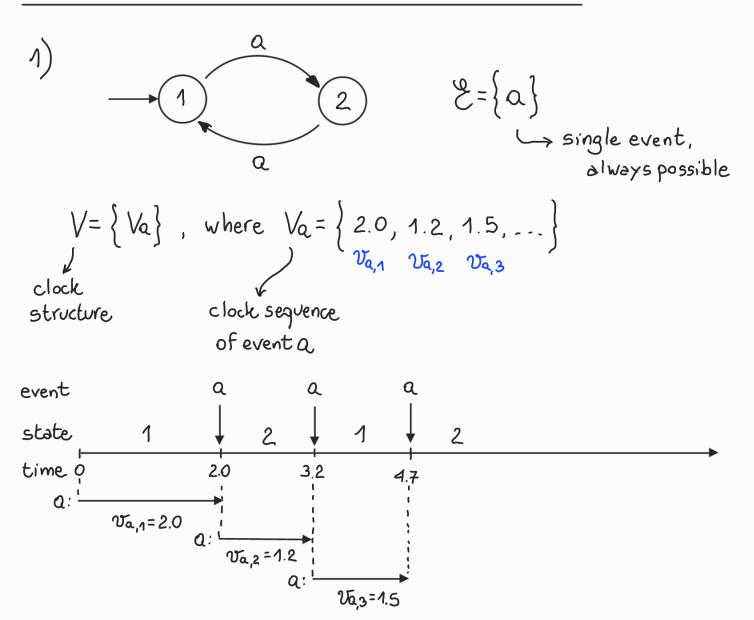
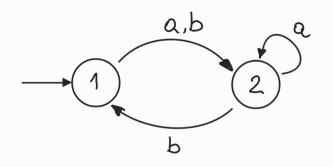
BASIC EXAMPLES OF EVENT TIMING DYNAMICS

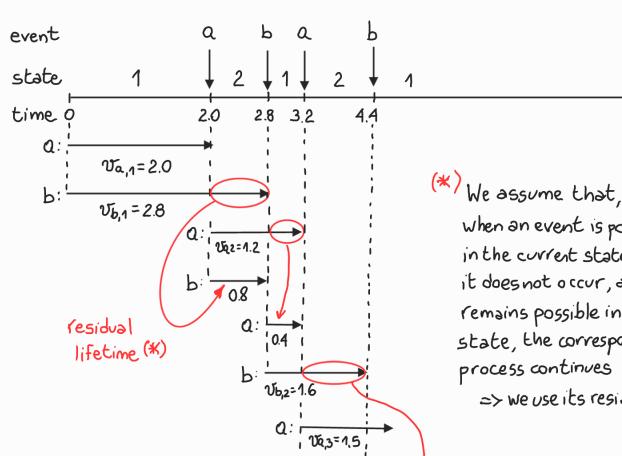


- · Event a is activated at times t=0, 2, 3.2
- · Event a occurs at times t= 2, 3.2, 4.7



$$V = \{ Va, Vb \}$$
 where $Va = \{ 2.0, 1.2, 1.5, ... \}$

$$V_b = \left\{ 2.8, 1.6, 3.0, \dots \right\}$$
 $V_{b,1} \quad V_{b,2} \quad V_{b,3}$



- when an event is possible in the current state, it does not occur, and it remains possible in the next state, the corresponding process continues
 - => we use its residual lifetime

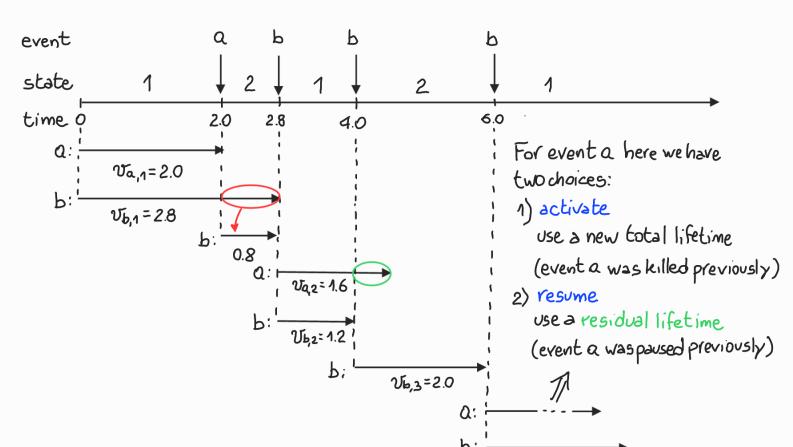
- · Event a is activated at times t=0,2,3.2
- · Event a occurs at times t= 2, 3.2
- · Event b is activated at times t=0, 2.8
- · Event b occurs at times t= 2.8, 4.4

$$\frac{a,b}{2}$$

$$V = \{ Va, Vb \}$$
 where $V_{0} = \{ 2.0, 1.6, 1.5, \dots \}$

$$V_b = \left\{ 2.8, 1.2, 2.0, 1.6, \dots \right\}$$
 $V_{b,1}$ $V_{b,2}$ $V_{b,3}$ $V_{b,4}$

Vb,4=1.6



Thoosing 1) or 2) depends on the particular system.

Assume we choose 1).

- · Event a is activated at times t=0,28,60
- · Event a occurs at time t=2.0

- · Event a is killed at time t=4.0
- Assume we choose 2).
- · Event a is activated at times t=0,28
- · Event a occurs at time t=2.0
- · Event a is paused at time t= 4.0
- · Event a is resumed at time t=6.0

For event b:

- · Event b is activated at times t=0, 2.8, 4.0, 6.0
- Event b occurs at times t = 2.8, 4.0, 6.0

Keeping the previous examples in mind, we are ready to write down a basic algorithm implementing the event timing dynamics (under some assumptions...)

Some additional definitions and notations are useful to this purpose

DEFINITION: the score of evente at timet, denoted ne(t), is the number of total lifetimes of evente used up to time t.