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# Linear Algebra

# Linear Independence

**DEFINITION 1** If  $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$  is a set of two or more vectors in a vector space  $V$ , then  $S$  is said to be a ***linearly independent set*** if no vector in  $S$  can be expressed as a linear combination of the others. A set that is not linearly independent is said to be ***linearly dependent***.

**THEOREM 4.3.1** A nonempty set  $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$  in a vector space  $V$  is linearly independent if and only if the only coefficients satisfying the vector equation

$$k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + \cdots + k_r\mathbf{v}_r = \mathbf{0}$$

are  $k_1 = 0, k_2 = 0, \dots, k_r = 0$ .

► **EXAMPLE Linear Independence of the Standard Unit Vectors in  $R^3$**

consider the standard unit vectors  $\mathbf{v}_1 = (1, 0, 0),$

$$\mathbf{v}_2 = (0, 1, 0),$$

$$\mathbf{v}_3 = (0, 0, 1)$$

To prove linear independence we must show that the only coefficients satisfying the vector equation

$$k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + k_3\mathbf{v}_3 = \mathbf{0}$$

are

$$k_1 = 0, k_2 = 0, k_3 = 0.$$

This becomes evident by writing this equation in its component form

$$k_1(1,0,0) + k_2(0,1,0) + k_3(0,0,1) = (0,0,0)$$

$$(k_1, k_2, k_3) = (0,0,0)$$

$$\Rightarrow k_1 = 0, k_2 = 0, k_3 = 0.$$

The most basic linearly independent set in  $R^n$  is the set of standard unit vectors

$$\mathbf{e}_1 = (1, 0, 0, \dots, 0), \quad \mathbf{e}_2 = (0, 1, 0, \dots, 0), \dots, \quad \mathbf{e}_n = (0, 0, 0, \dots, 1)$$

## ► EXAMPLE 2 Linear Independence in $R^3$

Determine whether the vectors

$$\mathbf{v}_1 = (1, -2, 3), \quad \mathbf{v}_2 = (5, 6, -1), \quad \mathbf{v}_3 = (3, 2, 1)$$

are linearly independent or linearly dependent in  $R^3$ .

### **Solution**

The linear independence or dependence of these vectors is determined by whether the vector equation

$$k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + k_3\mathbf{v}_3 = \mathbf{0} \tag{1}$$

can be satisfied with coefficients that are not all zero.

To see whether this is so, let us rewrite (1) in the component form

$$k_1(1, -2, 3) + k_2(5, 6, -1) + k_3(3, 2, 1) = (0, 0, 0)$$

Equating corresponding components on the two sides yields the homogeneous linear system

$$\begin{aligned} k_1 + 5k_2 + 3k_3 &= 0 \\ -2k_1 + 6k_2 + 2k_3 &= 0 \\ 3k_1 - k_2 + k_3 &= 0 \end{aligned}$$

Thus, our problem reduces to determining whether this system has nontrivial solutions.

## Solving the above system of equations for $k_1, k_2$ & $k_3$ using Gauss elimination method

The augmented matrix is given by

$$\tilde{A} = \begin{pmatrix} \textcolor{blue}{1} & 5 & 3 & 0 \\ \textcolor{red}{-2} & 6 & 2 & 0 \\ \textcolor{red}{3} & -1 & 1 & 0 \end{pmatrix} \begin{matrix} R_1 \\ R_2 \\ R_3 \end{matrix}$$

Pivot element Pivot Row

$$= \begin{pmatrix} 1 & 5 & 3 & 0 \\ 0 & \textcolor{blue}{16} & 8 & 0 \\ 0 & \textcolor{red}{-16} & -8 & 0 \end{pmatrix} \begin{matrix} R_1 \\ R_2 \rightarrow R_2 + 2R_1 \\ R_3 \rightarrow R_3 - 3R_1 \end{matrix}$$

$$R_2 = \begin{matrix} -2 & 6 & 2 & 0 \end{matrix}$$

$$2R_1 = \begin{matrix} 2 & 10 & 6 & 0 \end{matrix}$$

$$\tilde{A} = \begin{pmatrix} 1 & 5 & 3 & 0 \\ 0 & \textcolor{blue}{16} & 8 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{matrix} R_1 \\ R_2 \\ R_3 \rightarrow R_3 + R_2 \end{matrix}$$


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$$R_2 + 2R_1 = \begin{matrix} 0 & 16 & 8 & 0 \end{matrix}$$


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Rewriting as system of equations, we get

$$k_1 + 5k_2 + 3k_3 = 0$$

$$16k_2 + 8k_3 = 0$$

$$R_3 = \begin{matrix} 3 & -1 & 1 & 0 \end{matrix}$$

$$-3R_1 = \begin{matrix} -3 & -15 & -9 & 0 \end{matrix}$$


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$$R_3 - 3R_1 = \begin{matrix} 0 & -16 & -8 & 0 \end{matrix}$$


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Rewriting as system of equations, we get

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$$k_1 + 5k_2 + 3k_3 = 0 \text{ ----- (1)}$$

$$16k_2 + 8k_3 = 0 \text{ ----- (2)}$$

Let  $k_3 = t$  (since  $k_3$  is arbitrary), from (1) and (2) we get

$$k_3 = t$$

$$k_2 = -\frac{1}{2}t$$

$$k_1 = -\frac{1}{2}t$$

This shows that the system has nontrivial solutions and hence that the vectors are linearly dependent.

## Method 2:

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A second method for establishing the linear dependence is to take advantage of the fact that the coefficient matrix

$$A = \begin{bmatrix} 1 & 5 & 3 \\ -2 & 6 & 2 \\ 3 & -1 & 1 \end{bmatrix}$$

is square and compute its determinant.

The  $\det(A) = 0$ , it follows that the above system of equations has nontrivial solution. **Therefore, the given vectors are linearly dependent.**

### Note:

Because we have established that the vectors  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ , and  $\mathbf{v}_3$  are linearly dependent, at least one of them is a linear combination of the others, for example,

$$\mathbf{v}_3 = \frac{1}{2}\mathbf{v}_1 + \frac{1}{2}\mathbf{v}_2$$

### ► EXAMPLE Linear Independence of Polynomials

Determine whether the polynomials

$$\mathbf{p}_1 = 1 - x, \quad \mathbf{p}_2 = 5 + 3x - 2x^2, \quad \mathbf{p}_3 = 1 + 3x - x^2$$

are linearly dependent or linearly independent in  $P_2$ .

#### **Solution**

The linear independence or dependence of these vectors is determined by whether the vector equation

$$k_1\mathbf{p}_1 + k_2\mathbf{p}_2 + k_3\mathbf{p}_3 = \mathbf{0}$$

can be satisfied with coefficients that are not all zero.

Now, rewriting above equation in its polynomial form gives

$$k_1(1 - x) + k_2(5 + 3x - 2x^2) + k_3(1 + 3x - x^2) = 0$$

or, equivalently,

$$(k_1 + 5k_2 + k_3) + (-k_1 + 3k_2 + 3k_3)x + (-2k_2 - k_3)x^2 = 0$$

Since this equation must be satisfied by all  $x$  in  $(-\infty, \infty)$ , each coefficient must be zero



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Thus, the linear dependence or independence of the given polynomials hinges on whether the following linear system has a nontrivial solution:

$$\begin{aligned}k_1 + 5k_2 + k_3 &= 0 \\ -k_1 + 3k_2 + 3k_3 &= 0 \\ -2k_2 - k_3 &= 0\end{aligned}$$

We leave it for you to show that this linear system has nontrivial solutions either by solving it directly or by showing that the coefficient matrix has determinant zero.

Thus, the set  $\{\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3\}$  is linearly dependent.

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THANK YOU