Linear Algebra

DEFINITION 1 A set of two or more vectors in a real inner product space is said to be *orthogonal* if all pairs of distinct vectors in the set are orthogonal. An orthogonal set in which each vector has norm 1 is said to be *orthonormal*.

EXAMPLE 1 An Orthogonal Set in R³

Let
$$\mathbf{v}_1 = (0, 1, 0), \quad \mathbf{v}_2 = (1, 0, 1), \quad \mathbf{v}_3 = (1, 0, -1)$$

and assume that R^3 has the Euclidean inner product.

It follows that the set of vectors $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is orthogonal since

$$\langle \mathbf{v}_1, \mathbf{v}_2 \rangle = \langle \mathbf{v}_1, \mathbf{v}_3 \rangle = \langle \mathbf{v}_2, \mathbf{v}_3 \rangle = 0.$$

EXAMPLE 2 Constructing an Orthonormal Set

The Euclidean norms of the vectors in Example 1 are

$$\|\mathbf{v}_1\| = 1$$
, $\|\mathbf{v}_2\| = \sqrt{2}$, $\|\mathbf{v}_3\| = \sqrt{2}$

Consequently, normalizing \mathbf{u}_1 , \mathbf{u}_2 , and \mathbf{u}_3 yields

$$\mathbf{u}_{1} = \frac{\mathbf{v}_{1}}{\|\mathbf{v}_{1}\|} = (0, 1, 0),$$

$$\mathbf{u}_{2} = \frac{\mathbf{v}_{2}}{\|\mathbf{v}_{2}\|} = \left(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}\right),$$

$$\mathbf{u}_{3} = \frac{\mathbf{v}_{3}}{\|\mathbf{v}_{3}\|} = \left(\frac{1}{\sqrt{2}}, 0, -\frac{1}{\sqrt{2}}\right)$$

We leave it for you to verify that the set $S = \{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is orthonormal by showing that

$$\langle \mathbf{u}_1, \mathbf{u}_2 \rangle = \langle \mathbf{u}_1, \mathbf{u}_3 \rangle = \langle \mathbf{u}_2, \mathbf{u}_3 \rangle = 0$$

and $\|\mathbf{u}_1\| = \|\mathbf{u}_2\| = \|\mathbf{u}_3\| = 1$

In an inner product space, a basis consisting of orthonormal vectors is called an *orthonormal basis*, and a basis consisting of orthogonal vectors is called an *orthogonal basis*.

A familiar example of an orthonormal basis is the standard basis for \mathbb{R}^n with the Euclidean inner product:

$$\mathbf{e}_1 = (1, 0, 0, \dots, 0), \quad \mathbf{e}_2 = (0, 1, 0, \dots, 0), \dots, \quad \mathbf{e}_n = (0, 0, 0, \dots, 1)$$

EXAMPLE 3 An Orthonormal Basis for P_n

Recall that the standard inner product of the polynomials

$$\mathbf{p} = a_0 + a_1 x + \dots + a_n x^n$$
 and $\mathbf{q} = b_0 + b_1 x + \dots + b_n x^n$

is
$$\langle \mathbf{p}, \mathbf{q} \rangle = a_0 b_0 + a_1 b_1 + \dots + a_n b_n$$

and the norm of **p** relative to this inner product is

$$\|\mathbf{p}\| = \sqrt{\langle \mathbf{p}, \mathbf{p} \rangle} = \sqrt{a_0^2 + a_1^2 + \dots + a_n^2}$$

You should be able to see from these formulas that the standard basis

$$S = \left\{1, x, x^2, \dots, x^n\right\}$$

is orthonormal with respect to this inner product.

Coordinates Relative to Orthonormal Bases

One way to express a vector **u** as a linear combination of basis vectors

$$S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$$

is to convert the vector equation

$$\mathbf{u} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_n \mathbf{v}_n$$

to a linear system and solve for the coefficients c_1, c_2, \ldots, c_n .

However, if the basis happens to be orthogonal or orthonormal, then the following theorem shows that the coefficients can be obtained more simply by computing appropriate inner products.

THEOREM 6.3.2

(a) If $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is an orthogonal basis for an inner product space V, and if \mathbf{u} is any vector in V, then

$$\mathbf{u} = \frac{\langle \mathbf{u}, \mathbf{v}_1 \rangle}{\|\mathbf{v}_1\|^2} \mathbf{v}_1 + \frac{\langle \mathbf{u}, \mathbf{v}_2 \rangle}{\|\mathbf{v}_2\|^2} \mathbf{v}_2 + \dots + \frac{\langle \mathbf{u}, \mathbf{v}_n \rangle}{\|\mathbf{v}_n\|^2} \mathbf{v}_n$$
(3)

(b) If $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is an orthonormal basis for an inner product space V, and if \mathbf{u} is any vector in V, then

$$\mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \dots + \langle \mathbf{u}, \mathbf{v}_n \rangle \mathbf{v}_n \tag{4}$$

Proof (a)

Since $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is a basis for V, every vector \mathbf{u} in V can be expressed in the form

$$\mathbf{u} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_n \mathbf{v}_n$$

We will complete the proof by showing that

$$c_i = \frac{\langle \mathbf{u}, \mathbf{v}_i \rangle}{\|\mathbf{v}_i\|^2}$$
 for $i = 1, 2, \dots, n$.

$$\langle \mathbf{u}, \mathbf{v}_i \rangle = \langle c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_n \mathbf{v}_n, \mathbf{v}_i \rangle$$

$$\langle \mathbf{u}, \mathbf{v}_i \rangle = c_1 \langle \mathbf{v}_1, \mathbf{v}_i \rangle + c_2 \langle \mathbf{v}_2, \mathbf{v}_i \rangle + \dots + c_n \langle \mathbf{v}_n, \mathbf{v}_i \rangle$$

Since S is an orthogonal set, all of the inner products in the last equality are zero except the ith, so we have

$$\langle \mathbf{u}, \mathbf{v}_i \rangle = c_i \langle \mathbf{v}_i, \mathbf{v}_i \rangle = c_i \|\mathbf{v}_i\|^2$$

Solving this equation for c_i yields (5), which completes the proof.

Proof (b) In this case, $\|\mathbf{v}_1\| = \|\mathbf{v}_2\| = \cdots = \|\mathbf{v}_n\| = 1$, so Formula

$$\mathbf{u} = \frac{\langle \mathbf{u}, \mathbf{v}_1 \rangle}{\|\mathbf{v}_1\|^2} \mathbf{v}_1 + \frac{\langle \mathbf{u}, \mathbf{v}_2 \rangle}{\|\mathbf{v}_2\|^2} \mathbf{v}_2 + \dots + \frac{\langle \mathbf{u}, \mathbf{v}_n \rangle}{\|\mathbf{v}_n\|^2} \mathbf{v}_n$$

simplifies to
$$\mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \cdots + \langle \mathbf{u}, \mathbf{v}_n \rangle \mathbf{v}_n$$

basis $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is

$$(\mathbf{u})_S = \left(\frac{\langle \mathbf{u}, \mathbf{v}_1 \rangle}{\|\mathbf{v}_1\|^2}, \frac{\langle \mathbf{u}, \mathbf{v}_2 \rangle}{\|\mathbf{v}_2\|^2}, \dots, \frac{\langle \mathbf{u}, \mathbf{v}_n \rangle}{\|\mathbf{v}_n\|^2}\right)$$

and relative to an orthonormal basis $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is

$$(\mathbf{u})_S = (\langle \mathbf{u}, \mathbf{v}_1 \rangle, \langle \mathbf{u}, \mathbf{v}_2 \rangle, \dots, \langle \mathbf{u}, \mathbf{v}_n \rangle)$$

EXAMPLE 5 A Coordinate Vector Relative to an Orthonormal Basis

Let $\mathbf{v}_1 = (0, 1, 0), \quad \mathbf{v}_2 = \left(-\frac{4}{5}, 0, \frac{3}{5}\right), \quad \mathbf{v}_3 = \left(\frac{3}{5}, 0, \frac{4}{5}\right)$

It is easy to check that $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is an orthonormal basis for R^3 with the Euclidean inner product.

Express the vector $\mathbf{u} = (1, 1, 1)$ as a linear combination of the vectors in S, and find the coordinate vector $(\mathbf{u})_S$.

$$\langle \mathbf{u}, \mathbf{v}_1 \rangle = 1$$
, $\langle \mathbf{u}, \mathbf{v}_2 \rangle = -\frac{1}{5}$, and $\langle \mathbf{u}, \mathbf{v}_3 \rangle = \frac{7}{5}$

Therefore, by Theorem 6.3.2 we have

$$\mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \cdots + \langle \mathbf{u}, \mathbf{v}_n \rangle \mathbf{v}_n$$

$$\mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \langle \mathbf{u}, \mathbf{v}_3 \rangle \mathbf{v}_3$$

$$\mathbf{u} = \mathbf{v}_1 - \frac{1}{5}\mathbf{v}_2 + \frac{7}{5}\mathbf{v}_3$$

that is,

$$(1, 1, 1) = (0, 1, 0) - \frac{1}{5}(-\frac{4}{5}, 0, \frac{3}{5}) + \frac{7}{5}(\frac{3}{5}, 0, \frac{4}{5})$$

Thus, the coordinate vector of \mathbf{u} relative to S is

$$(\mathbf{u})_S = (\langle \mathbf{u}, \mathbf{v}_1 \rangle, \langle \mathbf{u}, \mathbf{v}_2 \rangle, \langle \mathbf{u}, \mathbf{v}_3 \rangle) = (1, -\frac{1}{5}, \frac{7}{5})$$

EXAMPLE 6 An Orthonormal Basis from an Orthogonal Basis

(a) Show that the vectors

$$\mathbf{w}_1 = (0, 2, 0), \quad \mathbf{w}_2 = (3, 0, 3), \quad \mathbf{w}_3 = (-4, 0, 4)$$

form an orthogonal basis for R^3 with the Euclidean inner product, and use that basis to find an orthonormal basis by normalizing each vector.

(b) Express the vector $\mathbf{u} = (1, 2, 4)$ as a linear combination of the orthonormal basis vectors obtained in part (a).

Solution (a) The given vectors form an orthogonal set since

$$\langle \mathbf{w}_1, \mathbf{w}_2 \rangle = 0, \quad \langle \mathbf{w}_1, \mathbf{w}_3 \rangle = 0, \quad \langle \mathbf{w}_2, \mathbf{w}_3 \rangle = 0$$

It follows that these vectors are linearly independent and hence form a basis for \mathbb{R}^3 . We calculate the norms of \mathbf{w}_1 , \mathbf{w}_2 , and \mathbf{w}_3 and then obtain the orthonormal basis

$$\mathbf{v}_1 = \frac{\mathbf{w}_1}{\|\mathbf{w}_1\|} = \frac{1}{2} (0, 2, 0) = (0, 1, 0),$$

$$\mathbf{v}_2 = \frac{\mathbf{w}_2}{\|\mathbf{w}_2\|} = \frac{1}{3\sqrt{2}} (3, 0, 3) = \left(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}\right),$$

$$\mathbf{v}_3 = \frac{\mathbf{w}_3}{\|\mathbf{w}_3\|} = \frac{1}{4\sqrt{2}} (-4, 0, 4) = \left(-\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}\right)$$

Solution (b) It follows from $\mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \cdots + \langle \mathbf{u}, \mathbf{v}_n \rangle \mathbf{v}_n$ that

$$\mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \langle \mathbf{u}, \mathbf{v}_3 \rangle \mathbf{v}_3$$

We obtain

$$\langle \mathbf{u}, \mathbf{v}_1 \rangle = (1, 2, 4) \cdot (0, 1, 0) = 2$$

$$\langle \mathbf{u}, \mathbf{v}_2 \rangle = (1, 2, 4) \cdot \left(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}} \right) = \frac{5}{\sqrt{2}}$$

$$\langle \mathbf{u}, \mathbf{v}_3 \rangle = (1, 2, 4) \cdot \left(-\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}} \right) = \frac{3}{\sqrt{2}}$$

and hence that

$$(1, 2, 4) = 2(0, 1, 0) + \frac{5}{\sqrt{2}} \left(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}} \right) + \frac{3}{\sqrt{2}} \left(-\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}} \right)$$

THANK YOU