

SEMESTER FIFTH

COURSE AI IN SOFTWARE ENGINEERING (3+0)

COURSE CODE 509

COURSE INSTRUCTOR

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Lecture 01 (Tue)

Feb 21, 23

Chapter 01

Intelligence

Ability to solve the
problem. i.e.: behaviour, learning
ability, action, things
improvement.

Artificial Intelligence (AI)

AI based applications
i.e.: sensor of traffic lights

deeblue
1st application

Domain knowledge \Rightarrow Domain
expert

Natural language processing (NLP)

Anything we do \Rightarrow Intelligence and

then machines can do \Rightarrow Artificial
Intelligence (AI)

Allen Turing (father of Comp. Sci.)
1956, the terms introduce
artificial intelligence.

Evolution \Leftrightarrow (2), 1
many dimensions / fields in AI

Artificial Intelligence in modern
approach

Rumelhart Book

Lecture 02 (Tue)

Feb 28, 23

Artificial Intelligence in
the school of thought

google classroom
code: gmednkp

1. Thinking like a human

How to simulate a human being

Artificial Neural Network

2. Acting like a human → Alan Turing

Alan Turing say the machine
can be intelligent in the 1950's
for the first time and
he proved of his
experiment.

3. Thinking Rationally
right way of thinking

Rational thinking acquire reasoning.

How to built logic

logics

- fuzzy logic
 - Boolean logics
 - Proportional logic
 - Predicted logic
- This is called the reasoning

Aristotal story
laws of thought

Describe the logic of the formally.

Expert system / application

4- Acting Rationally

believer in rational agent

Rational agent is anything which
Optimally achieved proceed input
goal from the environment
& act accordingly

explicit Or Implicit

see outcome & maximize utility

Lecture 03 (Tue)

Mar 07, 23

Agents is anything which receives input (percepts) from environment and act accordingly.

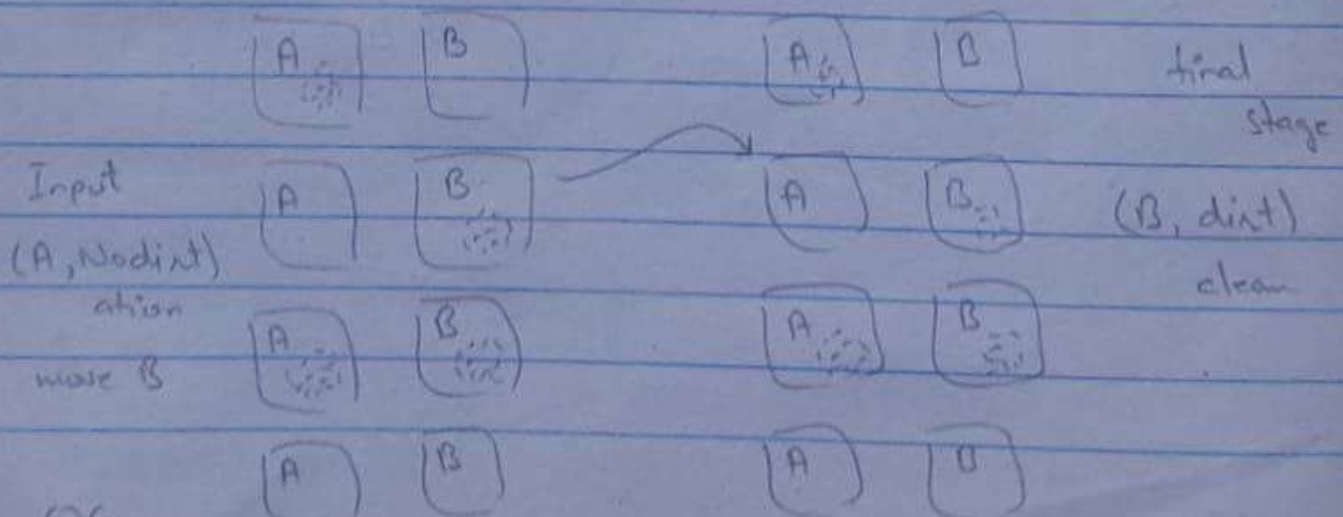
PEAS \rightarrow Performance measure
 \rightarrow environment \rightarrow Actuators \rightarrow Sensors

Modelling

Example:- Eight possible world

initial state

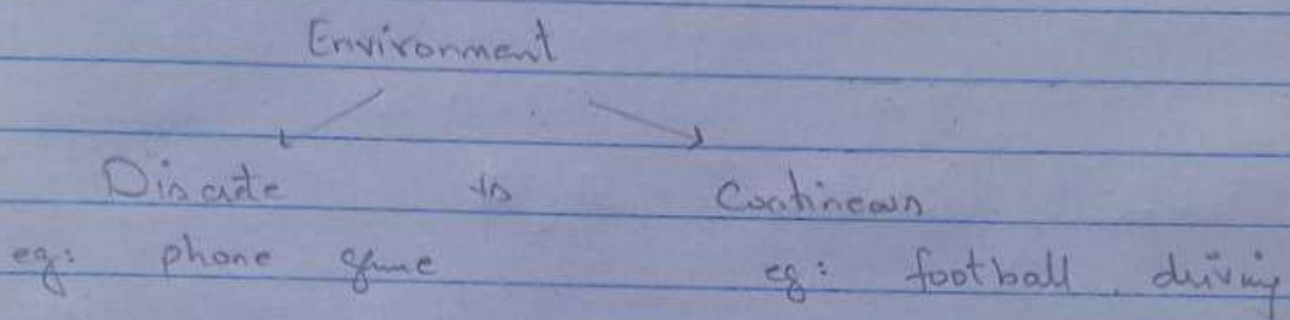
VCA (Vacuum cleaner Agent)



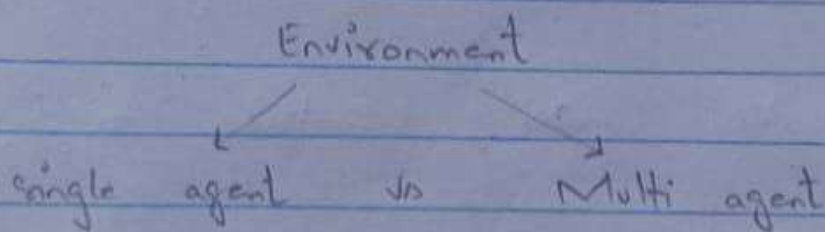
06

This problem is Deterministic problem known as state space

spot the all areas is known as state space graph.



Dangerous (non-Observable) environment



fully Observable vs partially observable

Problantic vs stochastic

probability vary
with time eg:

Static vs dynamic traffic at 4pm etc

(stand still) (changes)

eg: chess game

eg: road / football

Traffic Controller Agent

PEAS

no deadlocks

Efficiency management or optimal
Performance ^{measure}: time of the agent is
quickly.

Environment: road, zebra crossing, vehicles

Actuators: signal lights (Control to light)

Sensors: frequency identify

PEAS of on-mand vehicles

Performance measure : save driving No
traffic rule violation / accurate speed.

Environment : road , vehicle , zebra
crossing.

Actuators : steering , brake

Sensors : Distance , optical brake
sensor , infrared camera

Agents deal in fixed environment

Type of Agents (Next class)

Agent types

- Simple reflex agent (Sensors)
- Model Based reflex agent
- Goal based agent
- Utility Based agent
- Learning based agent

improvement complex environment
update knowledge based

Utility quantitative

reflex action

state space

known

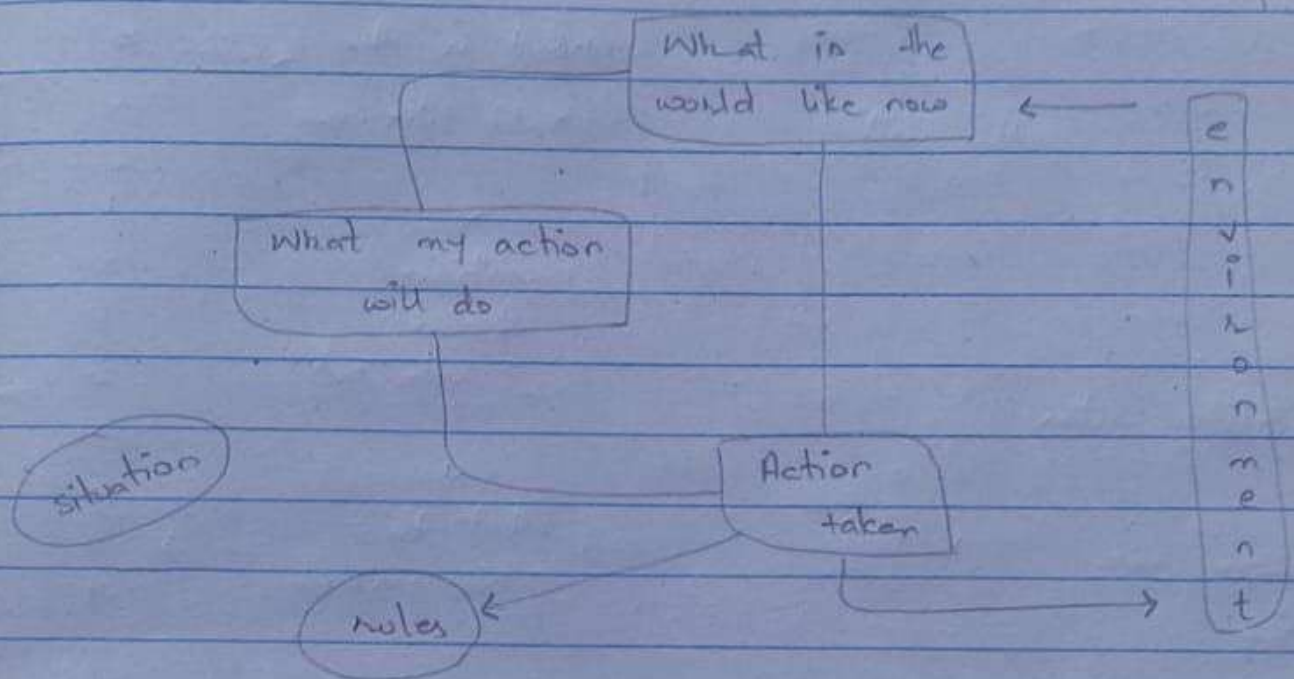
Agent

Model Based

world → states



Percept



Problem imp state

- Initial state
- Goal formation / test

- Implicit goal.
- Explicit goal.

Example

7	6	5
4	3	2
1	0	

goal

path cost

Utility rules

2	7	3
6	0	1
4	5	

change every
time

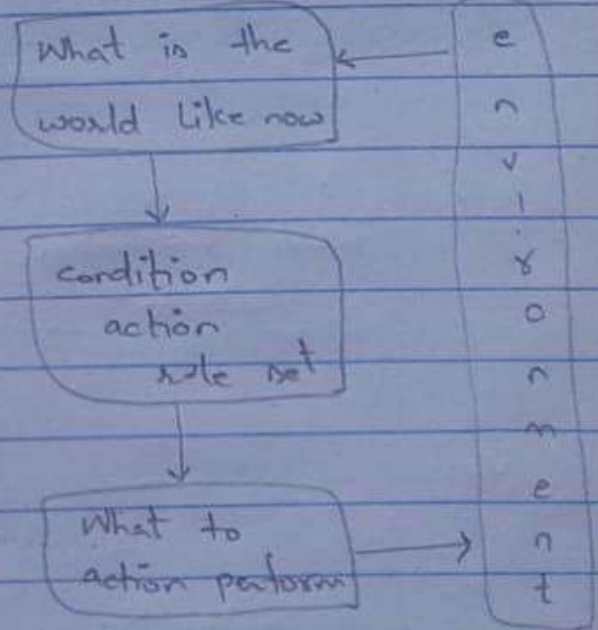
critic

Problem solving

Simple reflex

Agent

Percept



Lecture 05 (Tue)

May 02, 23

Chapter no 07, 08, & 09

logical Agents

Aristotle
represent a
logic

logic (reasoning)
is a language → formation
two types
Syntax Semantics

How you create
syntaxes

How you interpreted
the syntaxes

facts / rules
build in the system

Or
Meaning of
Sentence

KB (knowledge based)

- Domain specific knowledge
- Inference engine

first form of logic

Propositional form of logic

symbols : P, Q, R, S 7 bi conditional

$\Leftrightarrow, \wedge, \vee, \neg, \Rightarrow$

left Δ right

$P \Rightarrow Q$

True	False
$\underbrace{\hspace{1.5cm}}$	
False	

Possible models Or Possible
world Or possibilities

Symbol grows model 2^n

7 symbol \Rightarrow model 2^7

Grid

1,4	2,4	3,4	4,4
1,3 W	2,3 W?	3,3	4,3
1,2 A ₅	2,2 A ₃	3,2 W ₃	4,2
1,1 ↑	2,1	3,1	4,1
A →	A(B)	P?	

Agent task to travel and
caught the
treasure

Pit₀ ^{slit} Breeze (Pit)

wumpus ^{6/6} adjacent

Smell (wumpus)

PEAS Input precepta glitter
(treasure)

$$\{(1,1), \neg B, \neg S, \neg G\} \quad 1+1+1+1$$

$T(N_0)$

$$\{(2,1), B, \neg S, \neg G\}$$

$$\{(1,2), \neg B, \neg G, S\}$$

$$\{(2,2), \neg B, S, \neg G\} \Rightarrow \text{Risk } 50\% \quad 50\%$$

There is a pit in $(3,1) \Rightarrow P(3,1)$

$$P(2,2) \vee P(3,1)$$

$$B(2,2) \Rightarrow P(2,2) \vee P(3,1)$$

$$S(1,2) \Rightarrow W(2,2) \vee W(1,3)$$

$$P(3,1)$$

$$\neg P(1,1)$$

Use 5 distinct symbols

$$2^5 = 32$$

Lecture 02

Feb 23, 24

Artificial Intelligence (AI)

Ability to think / learn
+ form decision or opinion.

udacity website

think like human

Act like human

think rational Act rational

lecture

May 10, 24

Artificial Intelligence

Types of Agents

P	Performance	Simple Reflex Agent
E	Environment	
A	Act	
S	Sensor	if the change occurs

Model based Reflex agent

maintain history + simple reflex agent

Generative AI based model

Goal based reflex agent

Modern world

learning based agent

agent means feed or define

Q. p # 02

Types of Environment

Environment Types