Lecture 7 Memory Management

Operating Systems

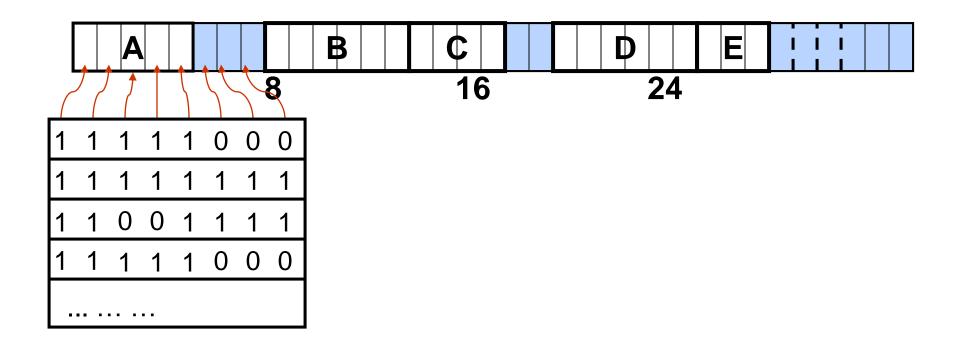
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How to keep track of Memory

- We need to keep track of
 - □ Allocated memory
 - □ Free memory
- Memory management with bitmaps
- Memory management with linked lists

Memory management with bitmaps

- Memory is divided up into allocation units
 - □ Few words
 - □ Or several kilobytes



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Memory management with bitmaps

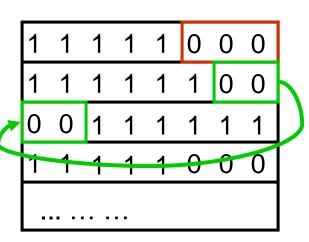
- Size of allocation unit is important
- Smaller allocation unit
 - Larger bitmap required
- Larger allocation unit
 - Smaller bitmap required
 - More memory will be wasted
 - If the process size is not an exact multiple of the allocation unit

Memory management with bitmaps

- To bring a k unit process in memory
- Search for a k run consecutive 0 bits in the map
- Search can be slow
- Since, k run may cross word boundaries

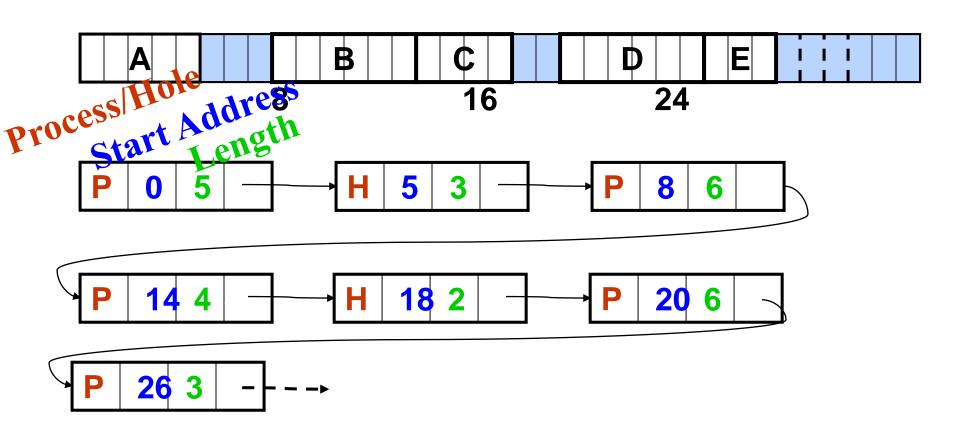
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Find run of length = 3
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Find run of length = 4



Memory management with Linked Lists

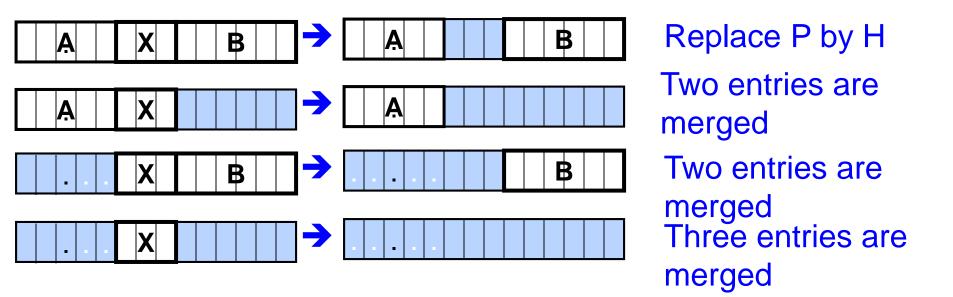
- Linked list of memory segments
 - □ Free segments → Holes
 - □ Allocated segments → Processes



Memory management with Linked Lists

- Segment list is sorted by addresses
- Sorting helps in updating the list, when a process is swapped out or exits
- A process usually has two neighbors

Updating the list requires



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- Several algorithms for allocating memory with linked list
- FIRST FIT:
 - □ Scan the segment list, until
 - □ A hole large enough is found
 - □ Split the hole into two pieces (if not exact match)
 - □ One for the new process
 - □ One for the unused memory
- The algorithm is fast since it searches as little as possible

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Memory Allocation with Linked Lists

NEXT FIT

- Works the same as First Fit, except,
- Does not always start searching from the beginning
- □ Rather starts searching the list, from where it left last time
- Simulations show, that gives no better performance than First Fit

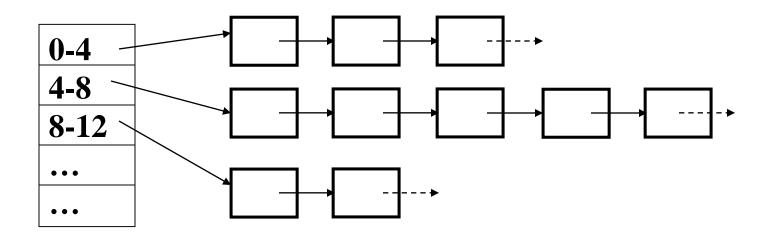
- BEST FIT
 - □ Search the entire list
 - ☐ Take the smallest hole that is adequate
- Best Fit tries to find the hole closest to the size
- Slower than First Fit
 - □ Every time has to search the entire list
- But still results in more memory wastage
 - □ Tends to fill up memory, with tiny useless holes
 - ☐ First Fit generates larger holes on the average

WORST FIT

- □ Take the largest hole available
- □ So that, the hole broken off will be large enough to be useful
- What if the larger holes left by worst fit are not useful
- □ → more memory wasted than Best Fit

- Search time of all the four algorithms can be improved by
- Keeping separate lists for Process and Holes
- While allocating memory only have to search the lists of holes
- DRAWBACK:
 - Problem while deallocating memory
 - □ A node from the process list has to be inserted in the hole list

- The Hole list can be kept sorted by size
- As soon as a hole that fits is found, no more searching is required
- Another improvement can be,
 - Maintain different lists for different sizes of holes
 - QUICK FIT



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- QUICK FIT
- Finding a hole of required size is extremely fast
- DRAWBACK:
 - When a process terminates/swapped out
 - ☐ Finding the neighbor to see whether the merge is possible
 - □ If merge is not done, then sooner memory will be fragmented into large holes