

# Cole Schreiner

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## Education

<b>University of California, Santa Cruz</b> <i>Robotics Concentration</i>	<b>2026</b>
<ul style="list-style-type: none"><li>Master of Science in Electrical and Computer Engineering</li></ul>	
<b>University of California, Santa Cruz</b> <i>Graduated with Highest Honors</i>	<b>2025</b>
<ul style="list-style-type: none"><li>Bachelor of Science in Robotics Engineering</li><li>Minor in Electrical Engineering</li></ul>	
<b>El Camino Community College</b> <i>M.E.S.A. Member</i>	<b>2022</b>
<ul style="list-style-type: none"><li>Associate of Science Physics</li><li>Associate of Science Mathematics</li></ul>	

## Technical Skills

**Languages:** Verilog, VHDL, Matlab, C, C++, Java, Python

**Tools and Programs:** AutoDesk, OnShape, SolidWorks, Git, Vivado, LTSpice, Oscilloscopes, 3D Printing, Laser Cutting

**Circuit Theory:** Kirchhoff's Laws, voltage and current division, op-amps, RL and RLC circuits, frequency response, filters, Bode plots, Thevenin/Norton equivalence, analog electronics, and PSpice circuit modeling

**Data Structures:** Trees, Heaps, Binary Search Trees, Graphs, BFS, and DFS

**Engineering:** Statics, Dynamics and kinematic motion of Robots, Feedback Control Systems, VLSI, Microcontroller System Design

## Experience

<b>Palos Verdes Summer Tech Internship</b> <i>Project Lead - Canine Medical Analysis Sensor</i>	<b>June, 2022 – August, 2022</b>
<ul style="list-style-type: none"><li>Designed and developed a medical device to diagnose future mobility issues in dogs by measuring gait variances</li><li>Applied machine learning algorithms to 9-axis IMU telemetry and developed sensor code for efficient data collection and analysis</li><li>Assembled electronics, soldered components, designed in AutoCAD for 3D printed housing, and tested circuitry and software</li><li>Led a team to develop a fully functional prototype</li></ul>	

## Projects

<b>Capstone - Wet-Dry Cyclor (RNA Replicator)</b> <i>Project Director - Origins of Life Simulation Device</i>	<b>June, 2025</b>
<ul style="list-style-type: none"><li><b>Objective:</b> Designed an automated device to simulate prebiotic wet-dry cycling, aiding RNA/DNA polymerization research and enabling cost-effective RNA synthesis for pharmaceutical applications (e.g., siRNA production)</li><li><b>Technical Expertise:</b> Microcontroller programming, feedback control, fluid dynamics, thermal systems, and mechanical design</li><li><b>Software Proficiency:</b> GUI development, automation control, and real-time data analysis</li><li>Collaborated with biomolecular researchers to advance RNA transcription and polymerization, with potential applications in RNA-based therapies such as siRNA</li></ul>	
<b>Professor Piano - <a href="#">[Project Drive]</a></b>	<b>March, 2025</b>
<ul style="list-style-type: none"><li>Designed and developed a wearable piano teaching glove featuring piezoelectric sensors, real-time peak detection, and personalized calibration</li><li>Integrated inertial measurement units (accelerometers and gyroscopes) to capture and analyze user movement, utilizing Euler angles for precise orientation tracking</li><li>Led the integration of I2S audio playback for high-quality sound feedback, enhancing the user experience with immersive, real-time audio feedback</li></ul>	
<b>Mechatronics Robot Competition - <a href="#">[Github + Technical Report]</a></b>	<b>June, 2024</b>
<ul style="list-style-type: none"><li>Directed a team to integrate an embedded state machine design with custom electrical circuits and analog filters to develop a functional robot prototype</li><li>Utilized advanced SolidWorks design techniques to create precise mechanical components and ensure seamless system integration</li><li>Designed, built, and tested the robot under a five-week deadline before competing against 20 teams</li></ul>	