§ 5.1 线性微分方程组解的 存在唯一性定理

Existence & Uniqueness Theorems of Linear ODEs

本节要求/Requirements/

- > 掌握高阶线性微分方程与线性微分方程组的关系。
- > 理解线性微分方程组解的存在唯一性定理。
- > 熟练掌握解的逐次逼近序列的构造方法。

5.1.1 记号与定义/Symbol and Definition/

一阶微分方程组

$$\begin{cases} x'_{1} = f_{1}(t, x_{1}, x_{2}, \dots, x_{n}) \\ x'_{2} = f_{2}(t, x_{1}, x_{2}, \dots, x_{n}) \\ \dots \\ x'_{n} = f_{n}(t, x_{1}, x_{2}, \dots, x_{n}) \end{cases}$$

初值条件
$$x_1(t_0) = \eta_1, x_2(t_0) = \eta_2, \dots, x_n(t_0) = \eta_n$$

一阶线性微分方程组

$$\begin{cases} x_1' = a_{11}(t)x_1 + a_{12}(t)x_2 + \dots + a_{1n}(t)x_n + f_1(t) \\ x_2' = a_{21}(t)x_1 + a_{22}(t)x_2 + \dots + a_{2n}(t)x_2 + f_2(t) \\ \dots \\ x_n' = a_{n1}(t)x_1 + a_{n2}(t)x_2 + \dots + a_{nn}(t)x_n + f_n(t) \end{cases}$$
...(5.1)

$$a_{ij}(t)$$
, $f_i(t)$ $i, j = 1, 2, \dots, n$ 在[a, b]上连续

$$\mathbf{A}(t) = \begin{bmatrix} a_{11}(t) & a_{12}(t) & \cdots & a_{1n}(t) \\ a_{21}(t) & a_{22}(t) & \cdots & a_{2n}(t) \\ \cdots & \cdots & \cdots & \cdots \\ a_{n1}(t) & a_{n2}(t) & \cdots & a_{nn}(t) \end{bmatrix}$$
(5.2)

$$f(t) = \begin{bmatrix} f_1(t) \\ f_2(t) \\ \vdots \\ f_n(t) \end{bmatrix} \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \frac{d\mathbf{x}}{dt} = \mathbf{x}' = \begin{bmatrix} x'_1 \\ x'_2 \\ \vdots \\ x'_n \end{bmatrix} \dots (5.3)$$

$$\frac{dx}{dt} = x' = A(t)x + f(t) \qquad \dots (5.4)$$

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$$\boldsymbol{B}(t) = \begin{bmatrix} b_{11}(t) & b_{12}(t) & \cdots & b_{1n}(t) \\ b_{21}(t) & b_{22}(t) & \cdots & b_{2n}(t) \\ \vdots & & & \vdots \\ b_{n1}(t) & b_{n2}(t) & \cdots & b_{nn}(t) \end{bmatrix} \qquad \boldsymbol{u}(t) = \begin{bmatrix} u_1(t) \\ u_2(t) \\ \vdots \\ u_n(t) \end{bmatrix}$$

在区间 $a \le t \le b$ 可定义矩阵与向量函数

$$\mathbf{B}(t) = (b_{ij}(t))_{n \times n}$$
 $\mathbf{u}(t) = (u_1(t), u_2(t), \dots, u_n(t))^T$

连续: $b_{ij}(t)$ $u_i(t)$ 在区间 $a \le t \le b$ 连续。

可微: $b_{ij}(t)$ $u_i(t)$ 在区间 $a \le t \le b$ 可微。

$$\mathbf{B}'(t) = (b'_{ij}(t))_{n \times n}$$
 $\mathbf{u}'(t) = (u'_1(t), u'_2(t), \dots, u'_n(t))^T$

可积: $b_{ij}(t)$ $u_i(t)$ 在区间 $a \le t \le b$ 可积。

$$\int \boldsymbol{B}(t)dt = \left(\int b_{ij}(t)dt\right)_{n \times n}$$

$$\int \boldsymbol{u}(t)dt = \left(\int u_1(t)dt, \int u_2(t)dt, \dots, \int u_n(t)dt\right)^T$$

1)
$$(A(t) + B(t))' = A'(t) + B'(t)$$

 $(u(t) + v(t))' = u'(t) + v'(t)$

2)
$$(\mathbf{A}(t) \cdot \mathbf{B}(t))' = \mathbf{A}'(t)\mathbf{B}(t) + \mathbf{A}(t)\mathbf{B}'(t)$$

3)
$$(A(t) \cdot u(t))' = A'(t)u(t) + A(t)u'(t)$$

定义1 设A(t) 是区间 $a \le t \le b$ 上的连续 $n \times n$ 矩阵,

f(t) 是区间 $a \le t \le b$ 上的连续 n 维向量,方程组

$$\frac{dx}{dt} = x' = A(t)x + f(t) \qquad (5.4)$$

在某区间 $\alpha \le t \le \beta$ ([α , β] \subset [a,b]) 的解就是向量

u(t) 在区间 $\alpha \le t \le \beta$ 上连续且满足

$$\mathbf{u}'(t) = \mathbf{A}(t)\mathbf{u}(t) + \mathbf{f}(t)$$

定义2 初值问题(Cauchy Problem)

$$\begin{cases} \frac{d\mathbf{x}}{dt} = \mathbf{x}' = \mathbf{A}(t)\mathbf{x} + f(t) \\ \mathbf{x}(t_0) = \mathbf{\eta} \end{cases}$$
(5.5)

的解就是方程组(5.4)在包含 t_0 的区间 $\alpha \le t \le \beta$

上的解u(t), 使得 $u(t_0) = \eta$

例1 验证向量
$$u(t) = \begin{bmatrix} e^{-t} \\ -e^{-t} \end{bmatrix}$$
 是初值问题

$$\boldsymbol{x'} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \boldsymbol{x} \qquad \boldsymbol{x}(0) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

在区间 $-\infty < t < +\infty$ 上的解。

$$\mathbf{p} \qquad \mathbf{u}'(t) = \begin{bmatrix} -e^{-t} \\ e^{-t} \end{bmatrix}, \qquad \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} e^{-t} \\ -e^{-t} \end{bmatrix} = \begin{bmatrix} -e^{-t} \\ e^{-t} \end{bmatrix}$$

$$\boldsymbol{u}(0) = \begin{bmatrix} e^0 \\ -e^0 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

因此 u(t) 是给定初值问题的解。

5.1.2 n 阶线性微分方程与一阶线性微分方程组等价

例1
$$x'' + p(t)x' + q(t)x = f(t)$$

解 $\Rightarrow x_1 = x, \quad x_2 = x',$
 $x'_1 = x' = x_2$
 $x'_2 = x'' = -p(t)x' - q(t)x + f(t)$
 $\begin{cases} x'_1 = x_2 \\ x'_2 = -q(t)x_1 - p(t)x_2 + f(t) \end{cases}$
 $x' = \begin{bmatrix} 0 & 1 \\ -q(t) & -p(t) \end{bmatrix} x + \begin{bmatrix} 0 \\ f(t) \end{bmatrix}$

$$x(t_0) = \eta_1, x'(t_0) = \eta_2$$

$$x'' + p(t)x' + q(t)x = f(t) \qquad \text{im} \mathbb{E} \quad x = \varphi_1(t)$$

$$\varphi_1''(t) + p(t)\varphi_1'(t) + q(t)\varphi_1(t) = f(t)$$

$$\begin{bmatrix} \varphi_1'(t) \\ \varphi_2'(t) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -q(t) & -p(t) \end{bmatrix} \begin{bmatrix} \varphi_1(t) \\ \varphi_2(t) \end{bmatrix} + \begin{bmatrix} 0 \\ f(t) \end{bmatrix} \quad x = \begin{bmatrix} \varphi_1(t) \\ \varphi_2(t) \end{bmatrix}$$

$$= \begin{bmatrix} \varphi_2(t) \\ -q(t)\varphi_1(t) - p(t)\varphi_2(t) + f(t) \end{bmatrix} \quad \text{for } x = \begin{bmatrix} 0 & 1 \\ -q(t) & -p(t) \end{bmatrix} x + \begin{bmatrix} 0 \\ f(t) \end{bmatrix}$$

$$x^{(n)} + a_1(t)x^{(n-1)} + \dots + a_{n-1}(t)x' + a_n(t)x = f(t)$$

$$\Rightarrow x_1 = x, x_2 = x', x_3 = x'', \dots, x_n = x^{(n-1)}$$

$$x_1' = x' = x_2$$

$$x_2' = x'' = x_3$$

$$x'_{n-1} = x^{(n-1)} = x_n$$

$$\begin{cases} x'_1 = x' = x_2 \\ x'_2 = x'' = x_3 \\ \dots \\ x'_{n-1} = x^{(n-1)} = x_n \\ x'_n = x^{(n)} = -a_n(t)x_1 - a_{n-1}(t)x_2 - \dots - a_1(t)x_n + f(t) \end{cases}$$

$$\mathbf{x}' = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & 1 \\ -a_n(t) & -a_{n-1}(t) & \cdots & -a_2(t) & -a_1(t) \end{bmatrix} \mathbf{x} + \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ f(t) \end{bmatrix}$$

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$$\begin{cases} x^{(n)} + a_1(t)x^{(n-1)} + \dots + a_{n-1}(t)x' + a_n(t)x = f(t) \\ x(t_0) = \eta_1, x'(t_0) = \eta_2, \dots, x^{(n-1)}(t_0) = \eta_n \end{cases}$$

$$\psi(t) \leftarrow \psi'(t)$$

$$\vdots$$

$$\psi^{(n-1)}(t)$$

$$\mathbf{x}' = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & 1 \\ -a_n(t) & -a_{n-1}(t) & \cdots & -a_2(t) & -a_1(t) \end{bmatrix} \mathbf{x} + \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ f(t) \end{bmatrix} \quad \mathbf{x}(t_0) = \begin{bmatrix} \eta_1 \\ \eta_2 \\ \vdots \\ \eta_n \end{bmatrix} = \boldsymbol{\eta}$$
.....(5.7)

例2 将初值问题 $\begin{cases} x'' + 3tx' - 5t^2x = \sin t \\ x(0) = 0 \quad x'(0) = 1 \end{cases}$

化为与之等价的一阶方程组的初值问题。

例3 将下列方程组化为高阶方程

$$\boldsymbol{x'} = \begin{bmatrix} 0 & 1 \\ 1 & -1 \end{bmatrix} \boldsymbol{x}$$

解

$$\begin{cases} x_1' = x_2 & x_2'' = x_1' - x_2' = x_2 - x_2' \\ x_2' = x_1 - x_2 & x_2'' + x_2' - x_2 = 0 \end{cases}$$

注意: 不是所有方程组都可化为高阶方程

$$\begin{cases} x_1' = x_1 \\ x_2' = x_2 \end{cases}$$

5.1.3 存在唯一性定理

初值问题(Cauchy Problem)

$$\begin{cases} \frac{d\mathbf{x}}{dt} = \mathbf{x}' = \mathbf{A}(t)\mathbf{x} + \mathbf{f}(t) \\ \mathbf{x}(t_0) = \mathbf{\eta} \end{cases}$$
(5.5)

定理1 如果A(t)是 $n \times n$ 矩阵,f(t)是n 维列向量,它们都在区间 $a \le t \le b$ 上连续,则对于区间 $a \le t \le b$ 上的任何数 t_0 及任一常数向量

$$x(t_0) = \begin{bmatrix} \eta_1 \\ \eta_2 \\ \vdots \\ \eta_n \end{bmatrix} = \eta$$
 方程组(5.5)存在唯一解 $\varphi(t)$ 定义于整个区间 $a \le t \le b$ 上,且满足初始多

定义于整个区间 $a \le t \le b$ 上,且满足初始条件 $\mathbf{x}(t_0) = \boldsymbol{\eta}$

现取 $\varphi_0(t) = \eta$,构造皮卡逐步逼近向量函数序列:

$$\begin{cases} \boldsymbol{\varphi}_0(t) = \boldsymbol{\eta} \\ \boldsymbol{\varphi}_k(t) = \boldsymbol{\eta} + \int_{t_0}^t [\boldsymbol{A}(s)\boldsymbol{\varphi}_{k-1}(s) + \boldsymbol{f}(s)] ds, \end{cases}$$

$$a \le t \le b$$
 $k = 1, 2, \cdots$

向量函数 $\varphi_k(t)$ 称为(5.4)的第 k 次近似解。

例4 求方程组的初值问题

$$\frac{d\mathbf{x}}{dt} = \mathbf{x}' = \begin{pmatrix} 1 & 0 \\ -1 & 1 \end{pmatrix} \mathbf{x} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \qquad \mathbf{x}(0) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

的二次近似解。

$$\boldsymbol{\varphi}_1(t) = \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \int_0^t \left\{ \begin{pmatrix} 1 & 0 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} dt$$

$$= \int_{0}^{t} {0 \choose 1} dt = {0 \choose t}$$

$$\varphi_{2}(t) = \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \int_{0}^{t} \left\{ \begin{pmatrix} 1 & 0 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ t \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} dt$$

$$= \int_{0}^{t} {0 \choose t+1} dt$$

$$= \begin{pmatrix} 0 \\ \frac{1}{2}t^2 + t \end{pmatrix}$$

5.1.4 简单方程组的消元法

例5 求解方程组
$$x' = \begin{bmatrix} 3 & -2 \\ 2 & -1 \end{bmatrix} x$$

$$\begin{cases} x'_1 = 3x_1 - 2x_2 \\ x'_2 = 2x_1 - x_2 \end{cases}$$

关键:保留一个未知函数,消掉另一个未知函数

$$x_{1} = \frac{1}{2}(x'_{2} + x_{2}) \qquad x'_{1} = \frac{1}{2}(x''_{2} + x'_{2})$$

$$\frac{1}{2}(x''_{2} + x'_{2}) = \frac{3}{2}(x'_{2} + x_{2}) - 2x_{2} \qquad x''_{2} - 2x'_{2} + x_{2} = 0$$

$$x_{2}'' - 2x_{2}' + x_{2} = 0$$

$$x_{1} = \frac{1}{2}(x_{2}' + x_{2})$$

$$x_{2}(t) = (c_{1} + c_{2}t)e^{t}$$

$$x_{1}(t) = \frac{1}{2}[(c_{1} + c_{2} + c_{2}t)e^{t} + (c_{1} + c_{2}t)e^{t}]$$

$$x_{1}(t) = \frac{1}{2}(2c_{1} + c_{2} + 2c_{2}t)e^{t}$$

方程组的解为

$$\begin{cases} x_1(t) = \frac{1}{2}(2c_1 + c_2 + 2c_2t)e^t \\ x_2(t) = (c_1 + c_2t)e^t \end{cases}$$

例6 求解方程组

$$\frac{dx}{dt} = y$$

$$\frac{dy}{dt} = \frac{y^2}{x}$$

 \mathbf{M} : 保留一个未知函数 x,消掉另一个未知函数 y

$$\frac{d^2x}{dt^2} = \frac{dy}{dt}$$

$$\frac{dp}{dt} = \frac{1}{x}p^2$$

$$\frac{d^2x}{dt^2} = \frac{1}{x}(\frac{dx}{dt})^2$$

$$\frac{dp}{dx}\frac{dx}{dt} = \frac{1}{x}p^2$$

$$\frac{dx}{dt} = p$$

$$p\frac{dp}{dx} - \frac{1}{x}p^2 = 0$$

$$p\frac{dp}{dx} - \frac{1}{x}p^{2} = 0$$

$$p = 0, \quad \frac{dp}{dx} - \frac{1}{x}p = 0$$

$$\begin{cases}
x = c_{2}e^{c_{1}t} \\
y = c_{1}c_{2}e^{c_{1}t}
\end{cases}$$

$$p = c_{1}x$$

$$\frac{dy}{dt} = 0$$

$$\frac{dy}{dt} = 0$$

$$\frac{dy}{dt} = 0$$

$$\frac{dy}{dt} = 0$$

$$y = c_{1}c_{2}e^{c_{1}t}$$

$$y = 0$$

$$\frac{dx}{dt} = c_{1}x$$

$$\begin{cases}
x = c_{2}e^{c_{1}t} \\
y = c_{1}c_{2}e^{c_{1}t}
\end{cases}$$

$$\begin{cases}
x = c_{2}e^{c_{1}t} \\
y = c_{1}c_{2}e^{c_{1}t}
\end{cases}$$

练习:

1 P.184 2 (b)

2 求方程组的初值问题

$$\frac{d\mathbf{x}}{dt} = \mathbf{x'} = \begin{pmatrix} 1 & 0 \\ -2 & 1 \end{pmatrix} \mathbf{x} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \qquad \mathbf{x}(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

的二次近似解。

求下列方程组的解

$$\begin{cases} \frac{dx}{dt} = y \\ \frac{dy}{dt} = x \end{cases} \qquad \begin{cases} \frac{dx}{dt} = y + 1 \\ \frac{dy}{dt} = -x + \frac{1}{\sin t} \end{cases}$$

作业: P.184 第2(c), 3题。

$$\begin{cases} \frac{dx}{dt} + y = \cos t \\ \frac{dy}{dt} + x = \sin t \end{cases} \begin{cases} \frac{dx}{dt} = y + z \\ \frac{dy}{dt} = z + x \\ \frac{dz}{dt} = x + y \end{cases}$$

$$\begin{cases} \frac{dx}{dt} = y + z \\ \frac{dy}{dt} = z + x \\ \frac{dz}{dt} = x + y \end{cases}$$