view_frames Result

Recorded at time: 33.584

base_link

Broadcaster: /robot_state_publisher
Average rate: 10.667 Hz
Most recent transform: 33.488 (0.096 sec old)
Buffer length: 1.500 sec

link_1

Broadcaster: /robot_state_publisher
Average rate: 10.667 Hz
Most recent transform: 33.488 (0.096 sec old)
Buffer length: 1.500 sec

link_2

Broadcaster: /robot_state_publisher
Average rate: 10.667 Hz
Most recent transform: 33.488 (0.096 sec old)
Buffer length: 1.500 sec

link_3

Broadcaster: /robot_state_publisher
Average rate: 10.667 Hz
Most recent transform: 33.488 (0.096 sec old)
Buffer length: 1.500 sec

link_4

Broadcaster: /robot_state_publisher
Average rate: 10.667 Hz
Most recent transform: 33.488 (0.096 sec old)
Buffer length: 1.500 sec

link_5

Broadcaster: /robot_state_publisher
Average rate: 10.667 Hz
Most recent transform: 33.488 (0.096 sec old)
Buffer length: 1.500 sec

link_6

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (33.584 sec old)
Buffer length: 0.000 sec

tool0

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (33.584 sec old)
Buffer length: 0.000 sec

Broadcaster: /link1_broadcaster
Average rate: 10.599 Hz
Most recent transform: 33.684 (-0.100 sec old)
Buffer length: 1.604 sec

kinect

link_depthtf