

# PROJECT 1

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## Annex C

### Prediction Function for CNN

#### Importing useful Libraries

```
In [22]: import cv2 as cv
import matplotlib.pyplot as plt
import numpy as np
```

#### Loading the trained parameters and reshaping them as per model.

In this model, there are 08 parameters:

- 1) f1- filters of first layer (10 filters)
- 2) f2- filters of 2nd layer (10 filters)
- 3) w3- weight matrix in fc layer
- 4) w4- weight matrix in fc layer
- 5) b1- bias terms for first convolution
- 6) b2- bias terms for first convolution
- 7) b3- bias for first hidden layer
- 8) b4- bias for 2nd hidden layer

```
In [24]: f1 = np.loadtxt("filter1.txt").reshape(10, 1,5,5)
f2 = np.loadtxt("filter2.txt").reshape(10, 10,5,5)
w3 = np.loadtxt("weight3.txt").reshape(96,4410)
w4 = np.loadtxt("weight4.txt").reshape(8,96)
b1 = np.loadtxt("bias1.txt").reshape(10, 1)
b2 = np.loadtxt("bias2.txt").reshape(10, 1)
b3 = np.loadtxt("bias3.txt").reshape(96,1)
b4 = np.loadtxt("bias4.txt").reshape(8,1)
```

#### Checking shapes of parameters

```
In [25]: print("f1=", f1.shape)
print("f2=", f2.shape)
print("w3=", w3.shape)
print("w4=", w4.shape)
print("b1=", b1.shape)
print("b2=", b2.shape)
print("b3=", b3.shape)
print("b4=", b4.shape)
```

```
f1= (10, 1, 5, 5)
f2= (10, 10, 5, 5)
w3= (96, 4410)
w4= (8, 96)
b1= (10, 1)
```

```
b2= (10, 1)
b3= (96, 1)
b4= (8, 1)
```

## Creating a list of paramters

```
In [26]: parameters= [f1, f2, w3, w4, b1, b2, b3, b4]
```

## Prediction Function

```
In [27]: def Prediction_Function(image, label, parameters, conv_stride, pool_filter, pool_stride):
first_convolution = scratch_convolution(image, f1, b1, conv_stride)
first_convolution[first_convolution<=0] = 0
pooled1 = scratch_maxpool(first_convolution, pool_filter, pool_stride)
second_convolution = scratch_convolution(first_convolution, f2, b2, conv_stride)
second_convolution[second_convolution<=0] = 0
pooled2 = scratch_maxpool(second_convolution, pool_filter, pool_stride)
(nf2, dim2, _) = pooled2.shape
fully_connected = pooled2.reshape((nf2 * dim2 * dim2, 1))
z = w3.dot(fully_connected) + b3
z[z<=0] = 0
output = w4.dot(z) + b4
probs = scratch_softmax(output)
loss = scratch_CrossEntropyLoss(probs, label)
return probs, np.argmax(probs), loss
```

## Defining functions needed for CNN prediction function.

```
In [28]: def scratch_convolution(image, filter, bias, stride=1):
(no_of_filters, number_of_channels_f, f, _) = filter.shape
number_of_channels, image_dim, _ = image.shape
out_dim = int((image_dim - f)/stride)+1
assert number_of_channels == number_of_channels_f
convolved = np.zeros((no_of_filters,out_dim,out_dim))
#moving window over image
for curr_filter in range(no_of_filters):
    curr_y = out_y = 0
    while curr_y + f <= image_dim:
        curr_x = out_x = 0
        while curr_x + f <= image_dim:
            convolved[curr_filter, out_y, out_x] = np.sum(filter[curr_filter] * image
            curr_x += stride
            out_x += 1
            curr_y += stride
            out_y += 1
        return convolved
```

```
In [29]: def scratch_maxpool(image, filter=2, stride=2):
number_of_channels, h_prev, w_prev = image.shape
height = int((h_prev - filter)/stride)+1
width = int((w_prev - filter)/stride)+1
downsampled = np.zeros((number_of_channels, height, width))
#moving window over image
for i in range(number_of_channels):
    curr_y = out_y = 0
    while curr_y + filter <= h_prev:
        curr_x = out_x = 0
        while curr_x + filter <= w_prev:
            downsampled[i, out_y, out_x] = np.max(image[i, curr_y:curr_y+filter, curr_x:curr_x+filter])
            curr_x += stride
            out_x += 1
            curr_y += stride
```

```

        out_y += 1
    return downsampled

```

```

In [30]: def scratch_softmax(scores):
          out = np.exp(scores)
          return out/np.sum(out)
          def scratch_CrossEntropyLoss(probs, label):
              return -np.sum(label * np.log(probs))

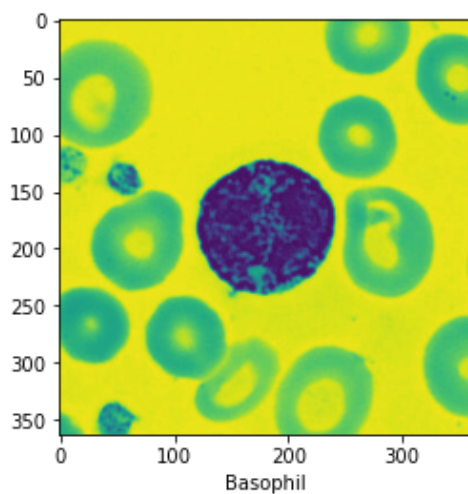
```

## Loading a test image from given dataset

```

In [31]: image= cv.imread("BA_47.jpg",0)
          plt.imshow(image)
          plt.xlabel("Basophil")
          image= cv.resize(image,(50,50),interpolation = cv.INTER_AREA)
          image=np.reshape(image, (1,50,50))

```



## Finding loss and probability using trained parameters

```

In [53]: Probabilities,Label,Loss = Prediction_Function(image, label=6, parameters = parameters, co

```

```

In [54]: print("Probabilities:",Probabilities)
          print("Predicted Label:",Label)
          print("Loss:",Loss)

```

```

Probabilities: [[9.61201676e-07]
 [8.20710788e-07]
 [8.76255410e-08]
 [9.15658616e-07]
 [1.20106748e-07]
 [5.91051855e-07]
 [9.36971976e-01]
 [6.30245274e-02]]
Predicted Label: 6
Loss: 546.7654344830379

```

```

In [ ]:

```

```

In [ ]:

```