Dr. M. Usman Maqbool Bhutta

POSTDOCTORAL FELLOW · DEPARTMENT OF MECHANICAL AND AUTOMATION ENGINEERING, CUHK, HK

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"Roboticist"

Summary.

With the rise of autonomous systems, being a researcher and entrepreneur, my research direction is their deployment to the real world. For any autonomous mode of the robot, a 3D map is essential to navigate and operate at any place. I work to tackle the problems related to scale difference and loop closures for large scale 3D mapping. I've 7+ years of experience specializing in robotics R&D and project management. I previously owned an IT company, and I've been part of several startups since 2011. My full profile can view here (https://usmanmaqbool.github.io/).

Work Experience

RESEARCH (COMPUTER VISION TECHNOLOGIES AND ROBOTICS SYSTEM)

C3 Robotics Laboratory (C3RL), Department of Mechanical and Automation Engineering

CUHK, Hong Kong.

POSTDOCTORAL RESEARCH FELLOW

May. 2021 - Present

- Supervisor: Prof. Darwin Lau, Director of C3 Robotics Laboratory (C3RL), The Chinese University of Hong Kong CUHK, Hong Kong.
- · Research in AR/VR and inspection robotics for construction

I'm working on several projects here

AR/VR: Research in **AR/VR** Platform design, multi-agent mixed reality, assistive prosthetics for the handicapped persons, teleoperated robots, human-robot interaction.

Inspection: Deep learning based research for the robotic presurface inspection for the construction.

Multi-agent collaboration: For indoor vegetation and painting robotics application.

Robotics and Multi-Perception Lab, Robotics Institute

HKUST, HK

PHD

Sep 2016 - Feb 2021

- PhD Supervisor: Prof Ming Liu, Director of Robotics and Multi-Perception Lab (RAM-LAB)
- · Research Contributions as First Author

Place Recognition: Our work makes a leap towards hierarchical deep learning-based place recognition for multiagent SLAM systems. We introduce a probabilistic layer to constrain the local representation along with the global representation of images. The global description of the pre-trained model and the local consistency introduced in our work enables the system to yield good performance at large-scale.

Development Using: MATLAB, Python, Jupyter, Nvidia CUDA, Docker, Deep learning, Matconvnet

Multi-Agent SLAM: I've produced Loop-box for the multi-Agent Direct SLAM Triggered by Single Loop Closure for Large scale semi dense 3D reconstruction /large-scale structure from motion. This work is accepted for publication in IEEE Transactions on Cybernetics (IF= 11+).. Development using: C++ 11, ROS, OpenCV, OpenGV, Paraview, EVO, UGV, LSD-SLAM, Monocular Camera.

SLAM: I've worked mainly for the multi-agent SLAM system. To find the scale difference and excellent relative transformation between difference agents. I've produced PCR-Pro work. This work got best student paper finalist award at IEEE-CYBER 2018.

Development using: C++ 11, ROS, OpenCV, OpenGV, Paraview, EVO, Monocular Camera, Plotly

Automation (Inspection): For smartphone glass inspection, I've introduced Smart-Inspect work. This work is accepted in IROS 2020. The patent is also under-review in the US.

Development using: Python, Jupyter, Nvidia CUDA, K-Means, Docker, Machine learning (ML)

Autonomous Systems Lab (ASL)

ETH Zürich, Switzerland.

Oct. 2019 - Mar. 2020

ACADEMIC GUEST

- Supervisor: Prof. Roland Siegwart, Director of Autonomous Systems Lab (ASL), ETH Zürich, Switzerland.
- Co-Supervisor: Dr. Cesar Dario Cadena Lerma, Senior Researcher at ASL, ETH Zürich, Switzerland.
- Research in Place Recognition: I've worked for making the better place recognition for the better scene understanding. Furthermore, I've also introduced light weight representation of key-frames for better channel utilization.

Development using: MATLAB, Python, Jupyter, Nvidia CUDA, Docker, Deep learning, Matconvnet

Department of Electronics

QAU, Pakistan

MPHIL CANDIDATE

Mar. 2010 - Jun. 2012

- M.Phil. Supervisor: **Prof Hasan Mahmood**, Department of Electronics, QAU.
- Research in Image Processing (CNN): I've introduced CNN-based license plate recognition of Pakistani's Cars. This work has been published in IEEE-ICALIP 2014.

INDUSTRY AND ENTREPRENEURSHIP

Lisee Technology Corporation Limited

Central. HK

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COO

Jan 2018 - Jan 2021

- Won funding support for company \mid TSSSU Support HK\$ 300,000 (Jun 19 May 20).
- Indoor Navigation for Libray using Lisee Technology | PCF Support HK\$ 160,000 (Jun 18 May 19).

Friends Corporate Technologies

Islamabad PK Feb 2013 - Aug 2015

50+ Projects | Electronics/ Electrical Engineering, R&D, image processing, Web Applications Development, MVC Applications

Federal Government of Pakistan

Islamabad, PK

Dec 2009 - Mar 2010

SCIENTIFIC OFFICER May 2012 - Feb 2013

Electronics/ Electrical Engineering, R&D, image processing

Server4Sale, LLC **Islamabad**, PK

PHP DEVELOPER

Php web application development for Joomla and Zend frameworks.

ACADEMIC

Department of Computer Science BZU-Sahiwal, Pakistan

LECTURER (VISITING) Feb 2016 - Jun 2016

Teaching MCS and BS-CS courses

GPGC Sahiwal, Pakistan

Department of Physics

Oct. 2015 - May. 2016

Teaching BS physics (Electronics related courses + Labs + Projects)

Department of Electronics OAU, Pakistan

INSTRUCTER Aug. 2010 - Dec. 2010

'PHP Web Development' (a short course) offered in Department of Electronics, Quaid-i-Azam University, Islamabad, Pakistan.

Education

Ph.D. in Robotics and AI at RAM-LAB, Robotics Institute

HKUST, Hong Kong

DEPARTMENT OF ELECTRONIC & COMPUTER ENGINEERING, THE HONG KONG UNIVERSITY OF SCIENCE AND TECHNOLOGY

Sep. 2016 - Feb. 2021

- PhD Supervisor: Prof Ming Liu, Director of Robotics and Multi-Perception Lab (RAM-LAB)
- Exchange Supervisor: Prof. Roland Siegwart, Director of Autonomous Systems Lab (ASL), ETH Zürich, Switzerland.
- Exchange Co-Supervisor: Dr. Cesar Dario Cadena Lerma, Senior Researcher at ASL, ETH Zürich, Switzerland.
- Got PEEF CCMS PhD scholarship from Pakistan and overseas research award (ORA).
- Research: Multi-Agent SLAM System, Place Recognition, Autonomous Car and Deep Learning for automation industry. Hand on experience on RGB-D 3D recontruction, Multi-view stereo, python and C++ development experience, multi-threaded coding.3D mesh registration, paraview and parameterizations. Moreover, I've deep understanding of data structures and algorithms. Experience with software development on Linux open-source stack. Calculus, linear algebra and geometry related courses have been taken.

M.Phil. in Electronics **QAU**, Pakistan

DEPARTMENT OF ELECTRONICS, QUAID-I-AZAM UNIVERSITY, ISLAMABAD, PAKISTAN.

Mar. 2010 - Jun. 2012

- M.Phil. Supervisor: Prof Hasan Mahmood, Department of Electronics, QAU.
- · Research: Signal and Image Processing
- Grade: A

M.Sc. in Electronics **QAU**, Pakistan

DEPARTMENT OF ELECTRONICS, QUAID-I-AZAM UNIVERSITY, ISLAMABAD, PAKISTAN.

Mar. 2010 - Jun. 2012

- 2nd position in batch
- Projects: completed 9+ projects related to C++, Verilog/HDL and Micro-controller programming.

B.Sc. in Mathematics and Physics

BZU, Pakistan

BAHAUDDIN ZAKARIYA UNIVERSITY, MULTAN PAKISTAN

Mar. 2010 - Jun. 2012

Grade: 1st Division

Presentation

POSTERS PRESENTATION

Teaching and Learning Innovation Expo 2021

CUHK, Hong Kong

Jul. 2021

- · 'Mixed Reality in Hands-On Learning of Robotics' by Xinyan Zhao, Sabrina Lam, M. Usman M. Bhutta, Darwin Lau and Jimmy Lee.
- 'Online Robotics Laboratory Framework for Interactive and Group Hands-On Learning' by Ken Hui, Ken Kwok, M. Usman M. Bhutta, Darwin Lau and Jimmy Lee.

IEEE/RSJ International Conference on Intelligent Robots and Systems [IROS, 2020]

Las Vegas, USA

PRESENTOR AS AUTHOR

SEPTEMBER 7, 2021

Oct. 2020

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• Introduced Smart-Inspect for the micro scale localization and classification of smartphone glass defects for industrial automation.

PRESENTER AS COO LISEE TECHNOLOGY CORPORATION COMPANY LIMITED, HONG KONG.

Jan. 2019

• Introduced Lisee technology in front of selection committee panel and won TSSSU 2019-20 funding of the amount of HK\$300,000.

IEEE Int. Conf. on CYBER Technology in Automation, Control, and Intelligent Systems [IEEE-CYBER 2018]

Tianjin, China

• Introduced PCR-Pro for the estimation of information matrix and scale difference for pose graph SLAM.

IET-Young Professionals Exhibition and Competition (IET-YPEC) 2018

CityU, Hong Kong

Presenter as COO Lisee Technology Corporation Company Limited, Hong Kong.

Jul. 2018

Jul. 2018

• Introduced Lisee technology at IET-YPEC 2018.

Campus Challenge @ HKUST Transportation

HKUST, Hong Kong

PRESENTER AS PARTICIPENT

PRESENTOR AS AUTHOR

May 2018

HKUST got 80+ proposals for this compeitions, and arranged a roadshow. My proposal got selected for the audiance award after getting maximum votes.

Best Student Paper Finalist Award, IEEE Int. Conf. on CYBER Technology in Automation, Control, and

High Tech Innovation and Entrepreneurship

HKUST, Hona Kond

PRESENTER AS ENTREPRENEUR

Dec. 2017

Tianjin, China

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• Introduced my study related to the flying cars.

World First Youth Robotics Developemnt Forum 2017

Shangri-La Shenzhen, China.

PRESENTER AS AUTHOR.

Nov. 2017

• Introduced my work related to multi-agent SLAM system.

Honors & Awards ____

Intelligent Systems

INTERNATIONAL

July, 2018

May, 2017 Completion Award, The Graduate Teaching Assistant Training, HKUST Dec, 2016 Best External Award, Robotics and Multi-Perception Lab, HKUST Nov, 2016 Completion Award, Author Workshop, Elsevier Publishing Campus DOMESTIC Sep 2016 CCMS PhD Scholarship, Won Chief Minister Marit Scholarship (CCMS) scholarship award by Punjab Government (PEEF), Pakistan for pursuing my PhD studies at HKUST, HK Sep 2013 Participant, Painting for peace (Pakistan-India-Afghanistan) event, a part of the Harmony initiative Apr 2013 Participant, Case Spark in business plan competition Apr 2013 Participant, Case EPICA Apr 2013 Participant, How to be a Better Playwright Workshop by PNCA and US Embassay Pakistan Oct 2012 Participant, Punjab Youth Festival Oct 2011 Participant, Int'l Youth Conference and Festival Sep 2011 Participant, Asian Youth Conference and Peace Festival Apr 2011 Completion Award, Acting and Directing Theater Workshop by PNCA and US Embassay Pakistan Dec 2011 Participant, National Drama Festival Dec 2010 Instuctor of short Course, PHP Web Development' at the Department of Electronics, QAU Apr 2013 Completion Award, Running River Rafting course by Adventure Foundation of Pakistan	
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Apr 2013 Completion Award , Running River Rafting course by Adventure Foundation of Pakistan	Islamabad, PK
	Islamabad, PK
Apr 2013 Completion Award , Paragliding course by QAU Adventure Club	Mansehra, PK
	Islamabad, PK
Dec 2008 Award of Honor , Finance Secretary of Electronics Student Society (ESS) at QAU	Islamabad, PK

Academic Activities

TC. Referee Service, IEEE Transactions on Cybernetics 2020, -21 ICRA Referee Service, IEEE/RSJ International Conference on Robotics and Automation 2021, -20 Referee Service, IEEE/RSJ RA-L and International Conference on Robotics and Automation **IROS** 2021,-20, -19, -18 Spr 2020, Spr 2019, HKUST, HK Teaching Assistant, EESM 5547 - Multimedia Signal Processing Spr 2018 Referee Service, IEEE International Conference on Automation Science and Engineering 2019 HKUST, HK Teaching Assistant, ELEC4820 - Medical Imaging Fall 2018 Spr 2017 HKUST, HK Teaching Assistant, ELEC 1010 - Electronic and Information Technology

Skills_

Robotics and Computer Vision Ubuntu, ROS, PCL, Docker, Catkin, OpenCV, OpenGV, Ceres Solver, g2o, Libpointmatcher

Machine Learning / Deep Learning Jupyter, Pytorch, Tensorflow, Keras, CUDA

Programming Python, C/C++, Matlab, git, LaTeX, FPGA, Verilog

Web mkdocs, Hugo, Jekyll, PHP, MYSQL

Languages English, Urdu

Research Publication

Why-So-Deep: Image Correspondence Verification by Probabilistic Spatial Landmarks **Elevation for Visual Place Recognition**

M Usman Maqbool Bhutta*, Yuxiang Sun, Darwin Lau and Ming Liu

Submitted

Loop-box: Multi-Agent Direct SLAM Triggered by Single Loop Closure for Large Scale Mapping

M Usman Maqbool Bhutta*, Manohar Kuse, Rui Fan, Yanan Liu and Ming Liu

IEEE Transactions on Cybernetics (IF: 11+)

Smart-Inspect: Micro Scale Localization and Classification of Smart Phone Glass Defects for Industrial Automation

M Usman Maqbool Bhutta*, Shoaib Aslam, Peng Yun, Jianhao JIAO and Ming Liu

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2020)

Multiple Lane Detection Algorithm Based on Optimised Dense Disparity Map Estimation

Han Ma, Yixin Ma, Jianhao Jiao, M Usman Maqbool Bhutta, Mohammud Junaid Bocus, Lujia Wang, Ming Liu and Rui

Fan

Accepted in IEEE International Conference on Imaging Systems and Techniques (IST 2018)

PCR-Pro: 3D Sparse and Different Scale Point Clouds Registration and Robust Estimation of Information Matrix For Pose Graph SLAM

M USMAN MAQBOOL BHUTTA* AND MING LIU

Presented in IEEE Int. Conf. on CYBER Technology in Automation, Control, and Intelligent Systems (IEEE-CYBER 2018), and won Best Student Paper Finalist Award.

An intelligent approach for robust detection and recognition of multiple color and font styles automobiles license plates: A feature-based algorithm

M Usman Maqbool Bhutta*, Hasan Mahmood, and Haroon Malik

Published in IEEE International Conference on Audio, Language and Image Processing (ICALIP 2014).

Efficient Reset Design Techniques

QAMAR, ZOHA, BUSHRA YASEEN, AND USMAN MAQBOOL

Published in Science International Lahore

Patent .

Semi-Supervised Learning Approach for Smart Phone Glasses Defect Inspection

Muhammad Usman Maqbool Bhutta, Jianhao Jiao, Peng Yun, Yuan Wang, Xuebin Sun, Ming Liu

U.S. Provisional Patent Application No. 62/974,937, Filing Date 01/06/2020.

Automatic Surface Defect Detection System for Smart Phone Glass Based on Deep Learning

Yuan Wang, Jianhao Jiao, Peng Yun, Muhammad Usman Maqbool Bhutta, Xuebin Sun, Ming Liu

U.S. Provisional Patent Application No. 62/974,938, Filing Date 01/06/2020.

Journal Paper

Submitted

Journal Paper

Oct 2020

Conference Paper

Oct 2020

Conference Paper

Dec 2018

Conference Paper

Jul 2018

Conference Paper

Jan 2015

Journal Paper

2015

US Patent

US Patent

Jan 2020

Jan 2020



Prof Darwin Lau

ASSISTANT PROFESSOR · DIRECTOR OF C3 ROBOTICS LAB (C3RL), DEPARTMENT OF MECHANICAL AND AUTOMATION ENGINEERING, THE CHINESE UNIVERSITY OF HONG KONG, HK.

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Prof Ming Liu

 $Associate\ Professor\ \cdot\ Director\ of\ Robotics\ and\ Multi-Perception\ Lab\ (RAM-LAB),\ Department\ of\ Electronic\ and\ Computer\ Enginneering,\ HKUST,\ HK.$

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Dr. Cesar Dario Cadena Lerma

Senior Researcher $\,\cdot\,$ ASL, ETH Zürich, Switzerland (+41) (0) 44 633-8803

Postdoc Supervisor

darwinlau@cuhk.edu.hk

Ph.D. Supervisor

eelium@ust.hk

Exchange Co-Supervisor cesarcadena.lerma@gmail.com