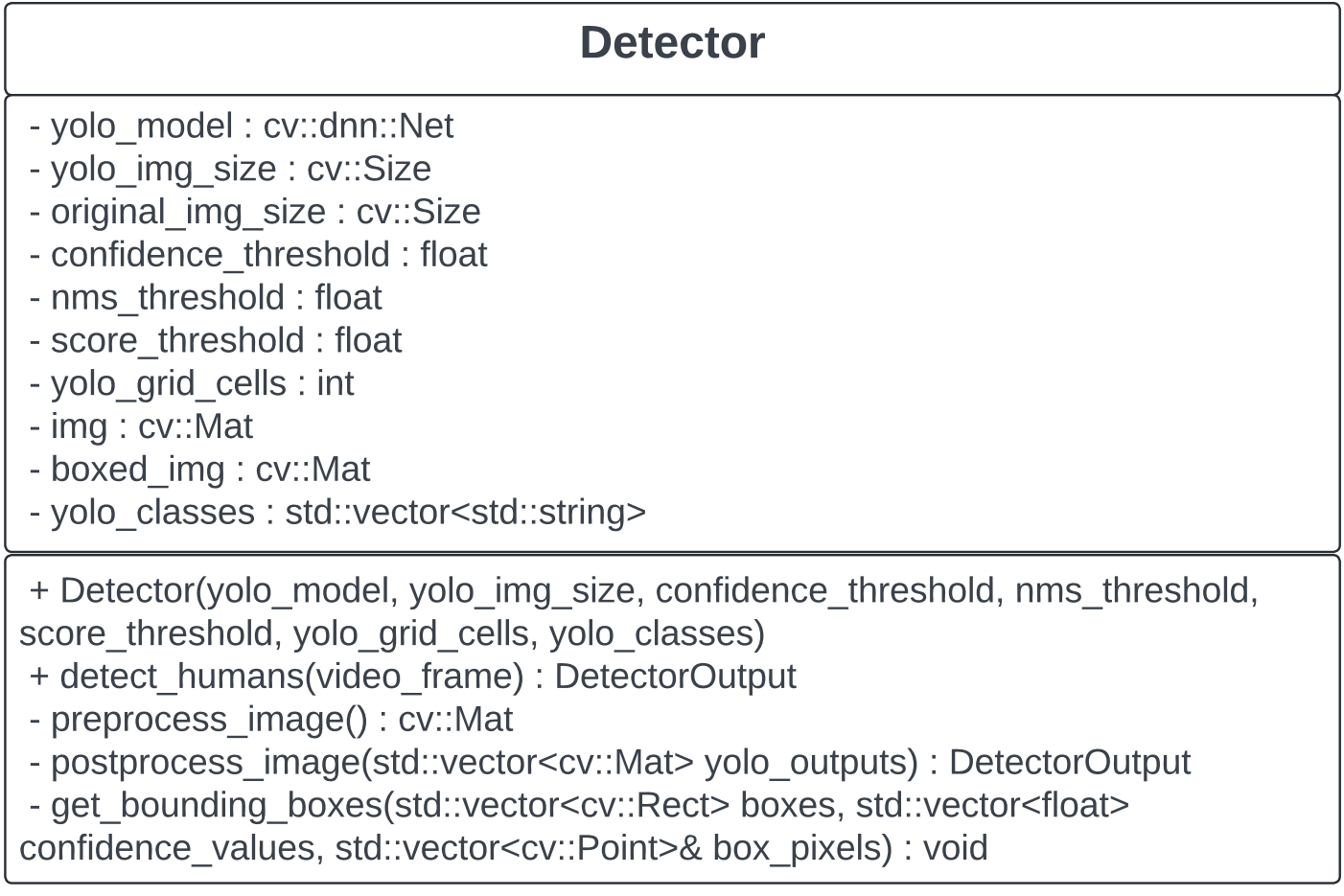
Detector
- yolo_model : cv::dnn::Net
- yolo_img_size : cv::Size
- original_img_size : cv::Size
- confidence_threshold : float
- nms_threshold : float
- score_threshold : float
- yolo_grid_cells : int
- img : cv::Mat
- boxed_img : cv::Mat
- yolo_classes : std::vector<std::string>
+ Detector(yolo_model, yolo_img_size, confidence_threshold, nms_threshold, score_threshold, yolo_grid_cells, yolo_classes)
+ detect_humans(video_frame) : DetectorOutput
- preprocess_image() : cv::Mat
- postprocess_image(std::vector<cv::Mat> yolo_outputs) : DetectorOutput
- get_bounding_boxes(std::vector<cv::Rect> boxes, std::vector<float> confidence_values, std::vector<cv::Point>& box_pixels) : void