

# Single input control and Jurdjevic's theorem

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## 1 Jurdjevic and Kupka's Theorem

From Elliott p95 and p117.

**Definition 1** (Strong regularity). *The matrix  $B \in \mathfrak{gl}(n, \mathbb{R})$  is strongly regular if its eigenvalues  $\lambda_k = \alpha_k + i\beta_k$ ,  $k \in 1, \dots, n$  are distinct, including  $2m$  conjugate-complex pairs, and the real parts  $\alpha_1 < \dots < \alpha_{n-m}$  satisfy  $\alpha_i - \alpha_j \neq \alpha_p - \alpha_q$  unless  $i = p$  and  $j = q$ .*

**Theorem 2** (Jurdjevic and Kupka). *Assume that  $\text{Tr}(A) = 0 = \text{Tr}(B)$  and  $B$  is strongly regular. Choose coordinates so that  $B = \text{diag}(\alpha_1, \dots, \alpha_n)$ . If  $A$  satisfies*

$$A_{i,j} \neq 0 \quad \forall i, j \text{ such that } |i - j| = 1, \quad (1)$$

$$A_{1,n}A_{n,1} < 0 \quad (2)$$

*then with  $\Omega = \mathbb{R}$ ,  $\dot{x} = (A + uB)x$  is controllable on  $\mathbb{R}_*^n$ .*

Note that our  $A$  and  $B$  are always traceless. I am wondering about why we are told to diagonalise  $B$ ; I don't think the alphas in the theorem are the same as those in the definition.

## 2 Examples

### 2.1 Example 1

$$A = \begin{pmatrix} 0 & a & 0 & x \\ b & 0 & c & 0 \\ 0 & d & 0 & e \\ y & 0 & f & 0 \end{pmatrix} = \begin{pmatrix} 0 & a & 0 & c \\ b & 0 & c & 0 \\ 0 & d & 0 & -b \\ d & 0 & -a & 0 \end{pmatrix} = \begin{pmatrix} 0 & 2 & 0 & -3 \\ 4 & 0 & -3 & 0 \\ 0 & 5 & 0 & -4 \\ 5 & 0 & -2 & 0 \end{pmatrix} \quad (3)$$

$xy < 0$ . The letters are non zero.

The above is recursive.

$$A = \begin{pmatrix} 0 & a & 0 & c \\ b & 0 & c & 0 \\ 0 & d & 0 & -b \\ d & 0 & -a & 0 \end{pmatrix} = \begin{pmatrix} 0 & 7 & 0 & -3 \\ 7 & 0 & -3 & 0 \\ 0 & 5 & 0 & -7 \\ 5 & 0 & -7 & 0 \end{pmatrix} \quad (4)$$

This example has all real eigenvalues. If we construct B such that this cannot be made imag. then we are OK....

$$B = \begin{pmatrix} a+ib & 0 & 0 & 0 \\ 0 & a-ib & 0 & 0 \\ 0 & 0 & c+id & 0 \\ 0 & 0 & 0 & c-id \end{pmatrix} = \begin{pmatrix} 2+i3 & 0 & 0 & 0 \\ 0 & 2-i3 & 0 & 0 \\ 0 & 0 & -2+i3 & 0 \\ 0 & 0 & 0 & -2-i3 \end{pmatrix} \quad (5)$$

The eigenvalues are all distinct and  $a - c$  are not equal to any other real parts subtracted.

What I want is an example such that a compact drift field is not constructible. Presumably no point trying in 1 mode because of Wu's theorem.

$$A + uB = \begin{pmatrix} u(2+i3) & 7 & 0 & -3 \\ 7 & u(2-i3) & -3 & 0 \\ 0 & 5 & u(-2+i3) & -7 \\ 5 & 0 & -7 & u(-2-i3) \end{pmatrix} \quad (6)$$

This example is not recursive for  $u = 1$ . I need to show that this is never recursive for any value of  $u$ . On MATLAB I find that there are values of  $u$  for which this has imaginary eigenvalues.

So trying for a more general example

$$A = \begin{pmatrix} 0 & a & 0 & c \\ b & 0 & c & 0 \\ 0 & d & 0 & -b \\ d & 0 & -a & 0 \end{pmatrix} = \begin{pmatrix} 0 & 7 & 0 & -3 \\ 7 & 0 & -3 & 0 \\ 0 & 5 & 0 & -7 \\ 5 & 0 & -7 & 0 \end{pmatrix} \quad (7)$$

So what I want is to construct some Hamiltonian matrix  $A + uB$  satisfying all the condition on  $A$  and  $B$  such that there is no value of  $u$  that will give it imaginary eigenvalues. If there is then we could just set this as our drift field. I want to construct a controllable counter-example to Alessio's conjecture.

## 2.2 Master equation

General  $A$  matrix:

$$A = \begin{pmatrix} a & b & c & d \\ e & f & d & h \\ k & l & -a & -e \\ l & g & -b & -f \end{pmatrix} \quad (8)$$

such that  $b, d, e, l \neq 0$  and  $dl < 0$ . (note that without these conditions this is just a general Hamiltonian matrix).

General  $B$  matrix:

$$B = \begin{pmatrix} x + iy & 0 & 0 & 0 \\ 0 & x - iy & 0 & 0 \\ 0 & 0 & -x + iy & 0 \\ 0 & 0 & 0 & -x - iy \end{pmatrix}. \quad (9)$$

General  $A + uB$  matrix:

$$A = \begin{pmatrix} a + u(x + iy) & b & c & d \\ e & f + u(x - iy) & d & h \\ k & l & -a + u(-x + iy) & -e \\ l & g & -b & -f + u(-x - iy) \end{pmatrix}. \quad (10)$$

I would like the eigenvalue equations of  $A + uB$ . From this my question is: are there values of  $a, b, c, d, e, f, g, h, k, l, x, y$  such that there is no value of  $u$  to make the eigenvalue expression less than 0. I can have this function in matlab and then have a load of inputs so I can play around. Ensuring that I stick to the few conditions: that some can't be zero and the  $dl$  condition.