Recorded at time: 98.356 world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (98.356 sec old) Buffer length: 0.000 sec panda_arm_link0 Broadcaster: /robot_state_publisher Average rate: 50.847 Hz Most recent transform: 98.340 (0.016 sec old) Buffer length: 1.180 sec panda_arm_link1 Broadcaster: /robot_state_publisher Average rate: 50.847 Hz Most recent transform: 98.340 (0.016 sec old) Buffer length: 1.180 sec panda_arm_link2 Broadcaster: /robot_state_publisher Average rate: 50.847 Hz Most recent transform: 98.340 (0.016 sec old) Buffer length: 1.180 sec panda_arm_link3 Broadcaster: /robot_state_publisher Average rate: 50.847 Hz Most recent transform: 98.340 (0.016 sec old) Buffer length: 1.180 sec panda_arm_link4 Broadcaster: /robot_state_publisher Average rate: 50.847 Hz Most recent transform: 98.340 (0.016 sec old) Buffer length: 1.180 sec panda_arm_link5 Broadcaster: /robot_state_publisher Average rate: 50.847 Hz Most recent transform: 98.340 (0.016 sec old) Buffer length: 1.180 sec panda_arm_link6 Broadcaster: /robot_state_publisher Average rate: 50.847 Hz Most recent transform: 98.340 (0.016 sec old) Buffer length: 1.180 sec panda_arm_link7 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (98.356 sec old) Buffer length: 0.000 sec

panda_arm_link8

view_frames Result