view_frames Result Recorded at time: 76.312 world Broadcaster: /robot_state_publisher Broadcaster: /turtle_tf_broadcaster Average rate: 10000.000 Hz Average rate: 1000.946 Hz Most recent transform: 76.301 (0.011 sec old) Most recent transform: 0.000 (76.312 sec old) Buffer length: 0.000 sec Buffer length: 2.115 sec panda_arm_link0 camera_link_optical Broadcaster: /robot_state_publisher Average rate: 50.472 Hz Most recent transform: 76.305 (0.007 sec old) Buffer length: 2.120 sec panda_arm_link1 Broadcaster: /robot_state_publisher Average rate: 50.472 Hz Most recent transform: 76.305 (0.007 sec old) Buffer length: 2.120 sec panda_arm_link2 Broadcaster: /robot_state_publisher Average rate: 50.472 Hz Most recent transform: 76.305 (0.007 sec old) Buffer length: 2.120 sec panda_arm_link3 Broadcaster: /robot_state_publisher Average rate: 50.472 Hz Most recent transform: 76.305 (0.007 sec old) Buffer length: 2.120 sec panda_arm_link4 Broadcaster: /robot_state_publisher Average rate: 50.472 Hz Most recent transform: 76.305 (0.007 sec old) Buffer length: 2.120 sec panda_arm_link5 Broadcaster: /robot_state_publisher Average rate: 50.472 Hz Most recent transform: 76.305 (0.007 sec old) Buffer length: 2.120 sec panda_arm_link6 Broadcaster: /robot_state_publisher Average rate: 50.472 Hz Most recent transform: 76.305 (0.007 sec old) Buffer length: 2.120 sec panda_arm_link7 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (76.312 sec old) Buffer length: 0.000 sec panda_arm_link8