

Date: 31<sup>st</sup> May 2019



To whomsoever it might concern

CERTIFICATE

This is to certify that **Uthiralakshmi S (119005122)**, pursuing Final Year **B. Tech Electrical and Electronics Engineering** from **SASTRA DEEMED UNIVERSITY, THANJAVUR, TAMIL NADU, INDIA** has successfully completed the project, entitled "**Predicting object dynamics from image sequences: a precursor to autonomous object manipulation**" done as a part of Internship in a research project looking at Intelligent Robot Manipulation approaches at **Lincoln Centre for Autonomous Systems, University of Lincoln, Lincoln, United Kingdom** from **1<sup>st</sup> January 2019 to 31<sup>st</sup> May**.

In the course of project, she has learned various concepts of Neural networks and Machine learning. She has learned and applied concepts of ROS framework. She has worked with Gazebo and Vrep simulation environments for manipulating a robot to perform pushing and grasping actions. She has worked on training neural networks to predict image sequences. She was very hardworking, enthusiastic and dedicated towards the work.

A handwritten signature in black ink, appearing to read "Harit".

Harit Pandya  
Research Fellow  
Lincoln Centre for Autonomous Systems  
University of Lincoln  
Lincoln LN6 7TS  
United Kingdom

