

Lab 02: Plotting in MATLAB

EE232: Signals & Systems

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1 Plots

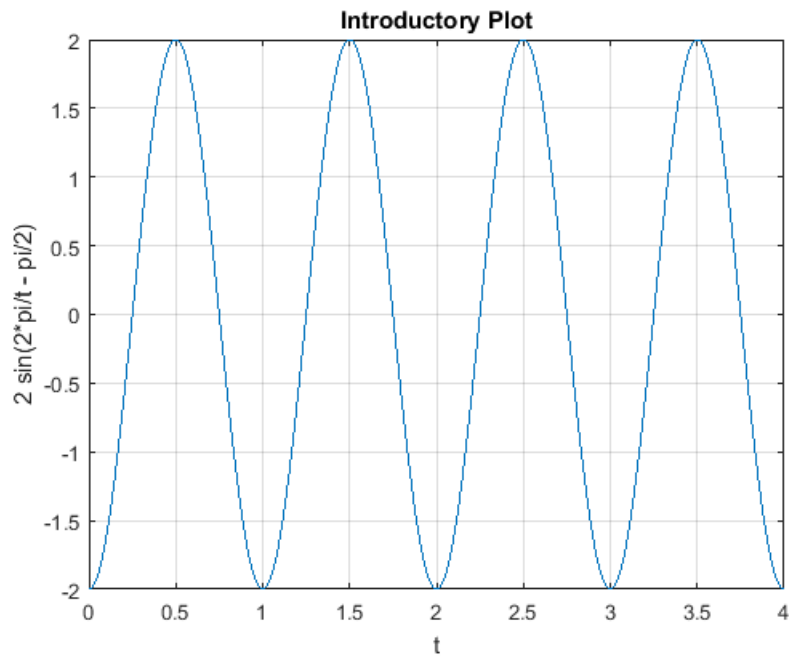
1.1 Equation

$$X = 2 \sin(2\pi t - \frac{\pi}{2})$$

1.2 MATLAB Code

```
t_i = 0;  
t_f = 4;  
  
t = t_i : (t_f - t_i) / 1000 : t_f;  
x = 2 .* sin(2 * pi * t - pi/2);  
  
plot(t, x);  
title('Introductory Plot');  
xlabel('t');  
ylabel('2 sin(2*pi/t - pi/2)');  
grid on;
```

1.3 MATLAB Output



2 Intersecting Plots

2.1 Equations

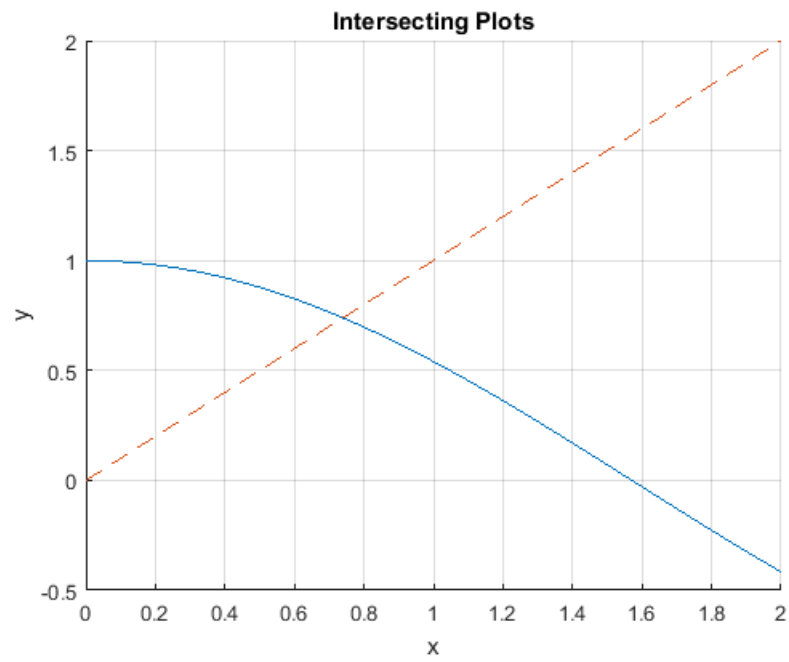
$$y = \cos x$$

$$y = x$$

2.2 MATLAB Code

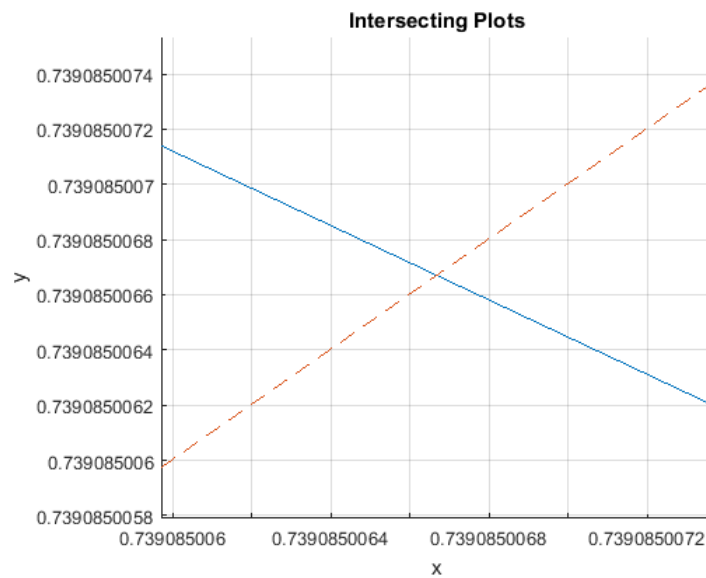
```
x_i = 0;  
x_f = 2;  
  
x = linspace(x_i, x_f, 1000);  
y_1 = cos(x);  
y_2 = x;  
  
hold on;  
plot(x,y_1);  
plot(x,y_2, '--');  
title('Intersecting Plots');  
xlabel('x');  
ylabel('y');  
grid on;
```

2.3 MATLAB Output



2.4 Intersection Point

Intersection point after zooming in, can be observed to be 0.739 .



3 Subplots

3.1 Equations

$$y = \frac{\sin x}{x}$$
$$u = \frac{1}{(x-1)^2} + x$$
$$v = \frac{x^2 + 1}{x^2 - 4}$$
$$z = \frac{(10-x)^{\frac{1}{3}} - 1}{(4-x^2)^{\frac{1}{2}}}$$

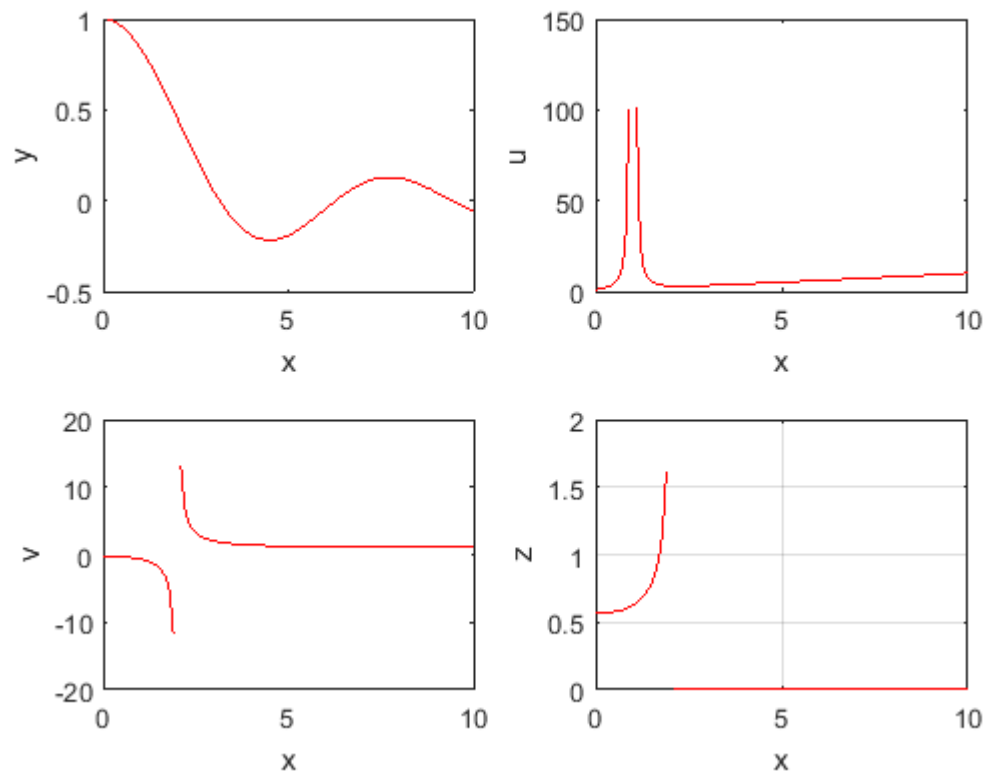
3.2 MATLAB Code

```
x = 0:0.1:10;

y = sin(x) ./ x;
u = (1 ./ (x - 1).^2) + x;
v = (x.^2 + 1) ./ (x.^2 - 4);
z = ((10 - x).^(1/3) - 1) ./ ((4 - x.^2).^(1/2));

subplot(2,2,1);
plot(x,y,'r');
xlabel('x');
ylabel('y');
subplot(2,2,2);
plot(x,u,'r');
xlabel('x');
ylabel('u');
subplot(2,2,3);
plot(x,v,'r');
xlabel('x');
ylabel('v');
subplot(2,2,4);
plot(x,z,'r');
xlabel('x');
ylabel('z');
grid on;
```

3.3 MATLAB Output



3.3.1 Warnings

Warning: Imaginary parts of complex X and/or Y arguments ignored