

**NALAIYA THIRAN PROJECT BASED LEARNING ON  
PROFESSIONAL READINESS FOR INNOVATION, EMPLOYABILITY  
AND ENTREPRENEURSHIP**



**PREVENTION BY PREDICTION**

**PROJECT TITLE: Natural Disaster Intensity Analysis and Classification  
using Artificial Intelligence**

**TEAM ID: PNT2022TMID27942**

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## **ABSTRACT**

A natural disaster is "the negative impact following an actual occurrence of natural hazard in the event that it significantly harms a community". It can cause loss of life or damage property. The severity of the damage depends on the affected population's resilience and on the infrastructure available. Some of the natural disasters are cyclone, wildfire, earthquake and floods. There are many prediction methods to predict the occurrence of natural disaster, yet the level of damage due to disaster has not been reduced. Many deep learning techniques have been applied by various researchers to detect and classify natural disasters to overcome losses in ecosystems, but detection of natural disasters still faces issues due to the complex and imbalanced structures of images. To tackle this problem, we have developed a multilayered deep convolutional neural network model that classifies the natural disaster and a reinforcement learning based model that tells the action to be performed based on the intensity of disaster . The model separates the key frames from the video for processing. The deployed CNN model works with an accuracy of 85.4% and the Reinforcement Learning models have lower deviation values ranging from minimum of '0' to maximum of '5'. This model is self –sufficient and can produce more efficient results in a longer run. The predictions has high accuracy rate and this model will be highly useful in real time.

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## **1. INTRODUCTION**

### ***1.1 Project Inspiration***

A natural disaster is characterized by the abnormal intensity of a natural agent (flood, mudslide, earthquake, avalanche, drought) when the usual measures to be taken to prevent this damage were not able to prevent their emergence or were not able to be taken. Natural Disasters are catastrophic events that result from any of the Earth's natural phenomena. These can range from floods and hurricanes to tsunamis and earthquakes. The Earth, over its 4.54 billion-year history, has seen many natural disasters. Some of these disasters have led to several mass extinctions and drastic repercussions for various surviving species. A natural disaster can be defined as: "A major event brought about by the natural processes of the Earth that causes widespread destruction to the environment and loss of life." A natural hazard often precedes a natural disaster.

The world is racked by disasters, some of which are awful yet controllable. Natural disasters, for instance, can be sudden events which cause significant destruction to property and lives. They can happen naturally, or humans can cause them. The emergency management process is essential to fix the damages caused by these catastrophes. With the process of disaster management, it is possible to limit the damage, and the dangers of the incident can be managed. The process is targeted at warding off disasters and reducing the consequences of events that cannot be avoided.

### ***1.2 Purpose***

There is no common system to help emergency responders measure the impact of natural disasters, to determine the proper allocation of resources, and to expedite mitigation processes. Therefore, a nation's ability to manage extreme events, including natural disasters and other perils, is difficult when there is no consistent method or mutual understanding among emergency management systems of different countries at all levels: international, continental, regional, national, provincial, and local. Therefore, a common severity classification system for all types of natural disasters for all stakeholder groups is required to understand, communicate, and educate the public on the nature of natural disasters.

## **2. LITERATURE SURVEY**

### ***2.1 Existing Problem***

Natural disasters not only disturb the human ecological system but also destroy the properties and critical infrastructures of human societies and even lead to permanent change in the ecosystem. Disaster can be caused by naturally occurring events such as earthquakes, cyclones, floods, and wildfires. Many deep learning techniques have been applied by various researchers to detect and classify natural disasters to overcome losses in ecosystems, but detection of natural disasters still faces issues due to the complex and imbalanced structures of images.

### ***2.2 References***

S NO	TITLE OF THE PAPER	AUTHOR	YEAR	METHODOLOGY
1	Hurricane Damage Detection using Machine Learning and Deep Learning Techniques: A Review	Swapandeep Kaur et al	2021	High volume data of social media and satellite imagery are analysed for damage detection of natural disasters using machine learning and deep learning techniques.
2	Natural Disasters Intensity Analysis and Classification Based on Multispectral Images Using Multi-Layered Deep on Multispectral Images Using Multi-Layered Deep Convolutional Neural Network	Muhammad Aamir, Tariq Ali, Muhammad Irfan, Ahmad Shaf, Muhammad Zeeshan Azam, Adam Glowacz, Frantisek Brumercik, Witold Glowacz, Samar Alqhtani and Saifur Rahman	2021	The proposed multi-layered deep convolutional neural network method works in two blocks of convolutional neural networks. The first block detects the occurrence of a natural disaster and the second defines the intensity of the natural disaster.

3	Disaster Intensity-Based Selection of Training Samples for Remote Sensing Building Damage Classification	Luis Moya , Christian Geiß , Member, IEEE, Masakazu Hashimoto, Erick Mas , Shunichi Koshimura , and Günter Strunz	2021	For the detection of severely damaged buildings a procedure that is based on the automatic selection of training samples for learning and calibrating the standard support vector machine classifier is and the use of two regularization parameters to define the support vectors.
4	Artificial Intelligence for Natural Hazards Risk Analysis:Potential, Challenges, and Research Needs	Seth Guikema	2020	This article is on artificial intelligence, machine learning, and statistical methods used for natural hazard risk assessment .
5	Deep Learning Benchmarks and Datasets for Social Media Image Classification for Disaster Response	Firoj Alam, Ferda Ofli, Muhammad Imran, Tanvirul Alam, Umair Qazi	2020	New datasets for disaster type detection, and informativeness classification, and damage severity assessment are proposed with benchmarking several state-of-the-art deep learning models and achieve promising results.
6	International Journal of Geo-Information,MDPI Journals	Huan Ning et al.	2020	For the detection of flood images obtained from social media, a CNN was developed. when more flooding images were available
7	Forest fire image recognition based on convolutional neural network	Wang Yuanbin, Dang Langfei, Ren Jieying	2019	To detect fire automatically, a forest fire image recognition method based on convolutional neural networks ,based on adaptive pooling method shows better performance and high

				recognition rate.
8	International Journal of Digital Earth, Taylor and Francis	Muham med Ali Sit et al.	2019	In order to identify content and time-related context of social media data related to the disasters, Deep learning, spatial temporal analysis and natural language processing were used.
9	Progress in Disaster Science, Elsevier	Brett W Robertson et al.	2019	On the basis of urgency and time period, images were classified using Multilayer perceptron and VGG-16 CNN network
10	Neural Computing and Applications, Springer	Muham mad Dawood et al.	2019	Satellite images of hurricane were used to determine hurricane intensity using deep CNN method in an automatic manner.
11	MDPI journal Applied Science	Yundong Li et al.	2019	Damage caused to buildings during Hurricane Sandy during the year 2012 was detected using a deep learning method that is Single shot Multi-box detector by the use of aerial images.
12	ISPRS Annals of the Photogrammetry, Remote Sensing and Spatial Information Sciences, Volume IV-2, 2018	Dwarte et al.	2018	Flood severity was detected using Gated Recurrent Unit (GRU) - Convolutional Neural network(CNN).

13	IEEE Transactions on Image Processing	Ritesh Pradhan et al.	2018	Tropical cyclones occurrence during 1998-2012 was studied and the intensity of hurricanes were estimated using deep convolutional neural network.
14	Journal of Applied Remote Sensing	Yundong Li et al.	2018	Damage occurred during Hurricane Sandy in the year 2012 was determined using semi-supervised deep learning system applied on aerial images of the disaster.
15	Springer International Publishing AG, part of Springer Nature 2018	German Novikov et al.	2018	Damage caused by the wildfires in California in 2017 was determined by deep learning using satellite images.

## 2.3 Problem Statement

A **natural disaster** is "the negative impact following an actual occurrence of natural hazard in the event that it significantly harms a community". A natural disaster can cause loss of life or damage property. The severity of the damage depends on the affected population's resilience and on the infrastructure available. Some examples of the natural disasters are cyclone, wildfire, earthquake and floods. There are many prediction methods to predict the occurrence of natural disaster, yet the level of damage due to disaster couldn't be lowered.

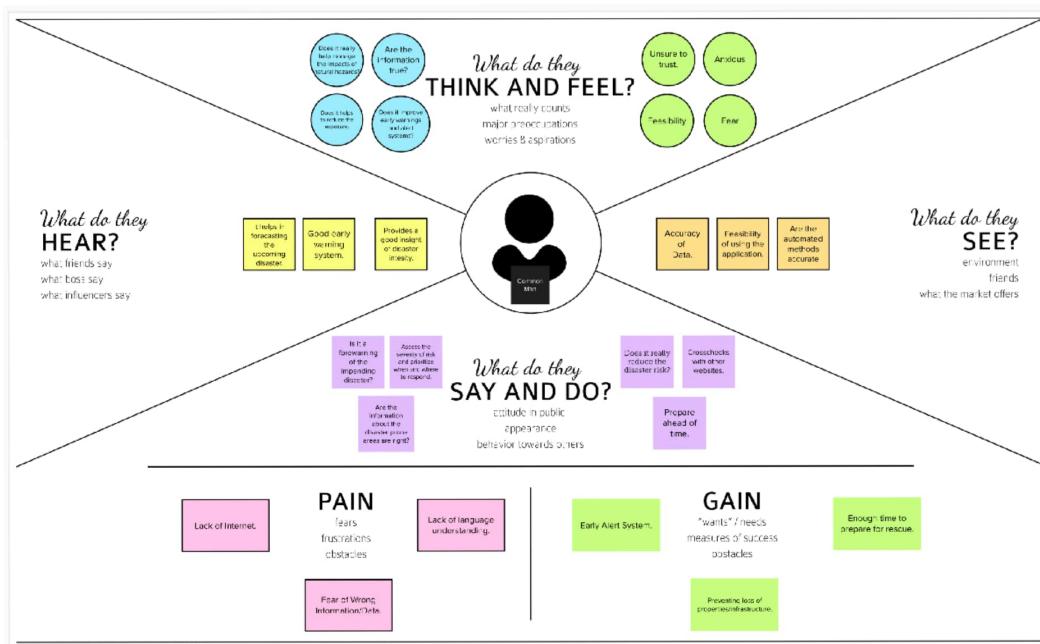
*How efficiently might we classify and analyse the risk of a Natural Disaster???*



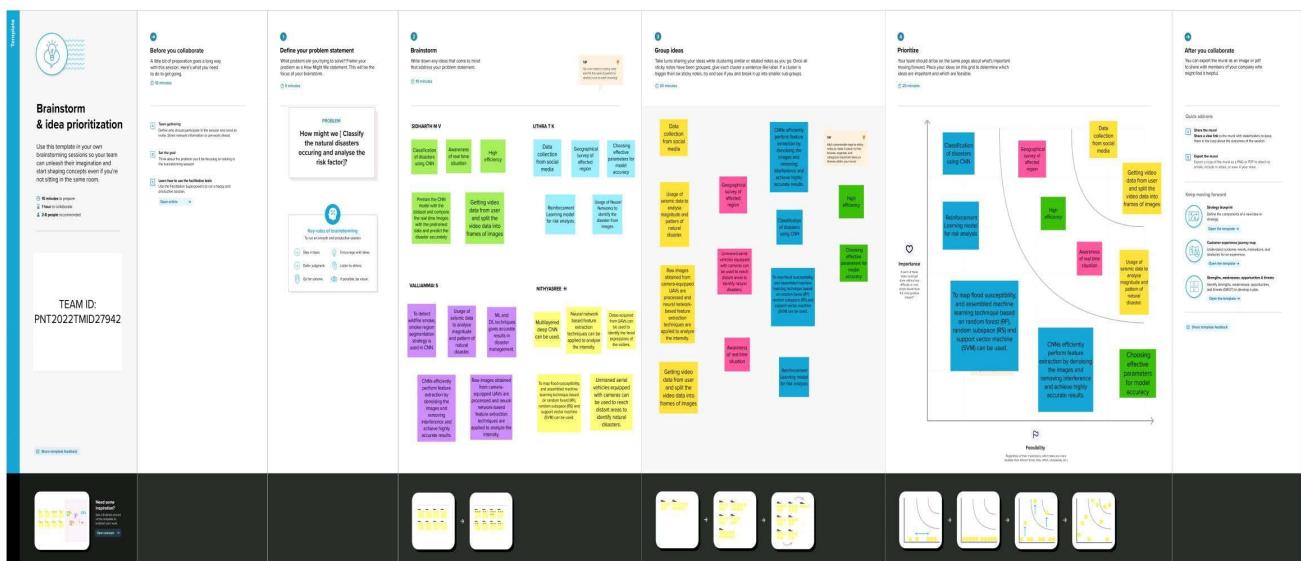
What is the problem?	Occurrence of natural disaster
Who does the problem affects?	Environment and all of its constituents such as human beings, plants, animals and infrastructures & economy
When the problem occurs?	Extreme climate conditions, human carelessness, seismic movements and greenhouse effect
Where does the problem occur?	Coastal regions, over populated regions
Why it is important to fix the problem?	To save the lives of living things, maintain ecological balance and financial security, forecast awareness, less losses due to damage

### 3. IDEATION & PROPOSED SOLUTION

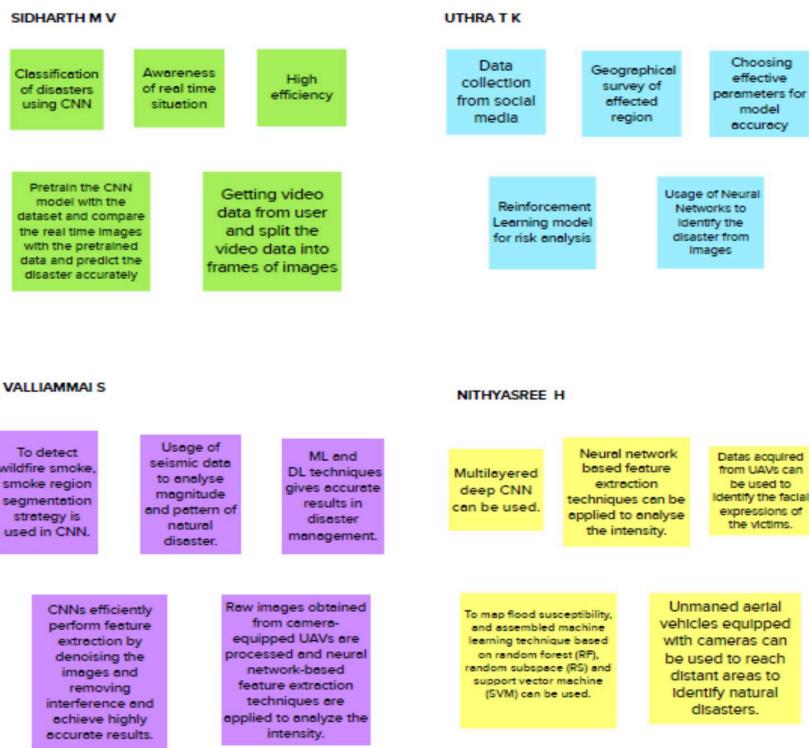
#### 3.1 Empathy Map Canvas



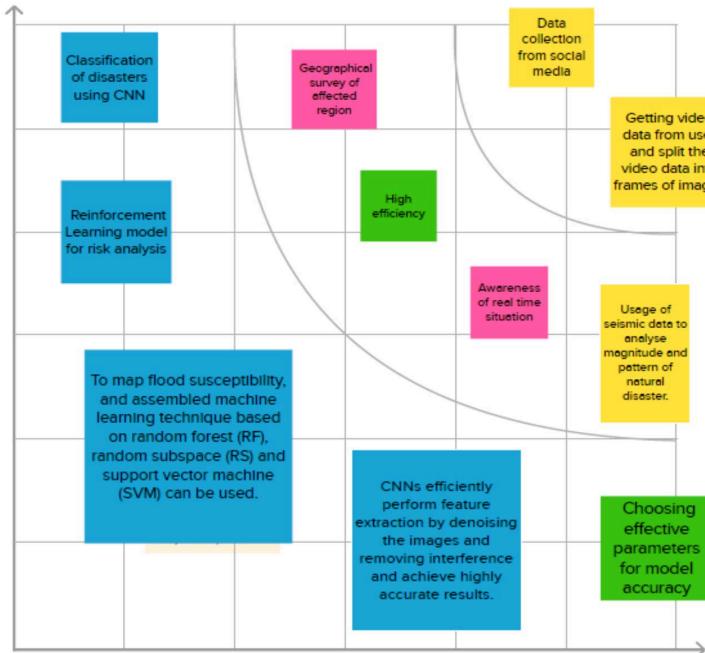
#### 3.2 Ideation & Brainstorming



## ● Brainstorming



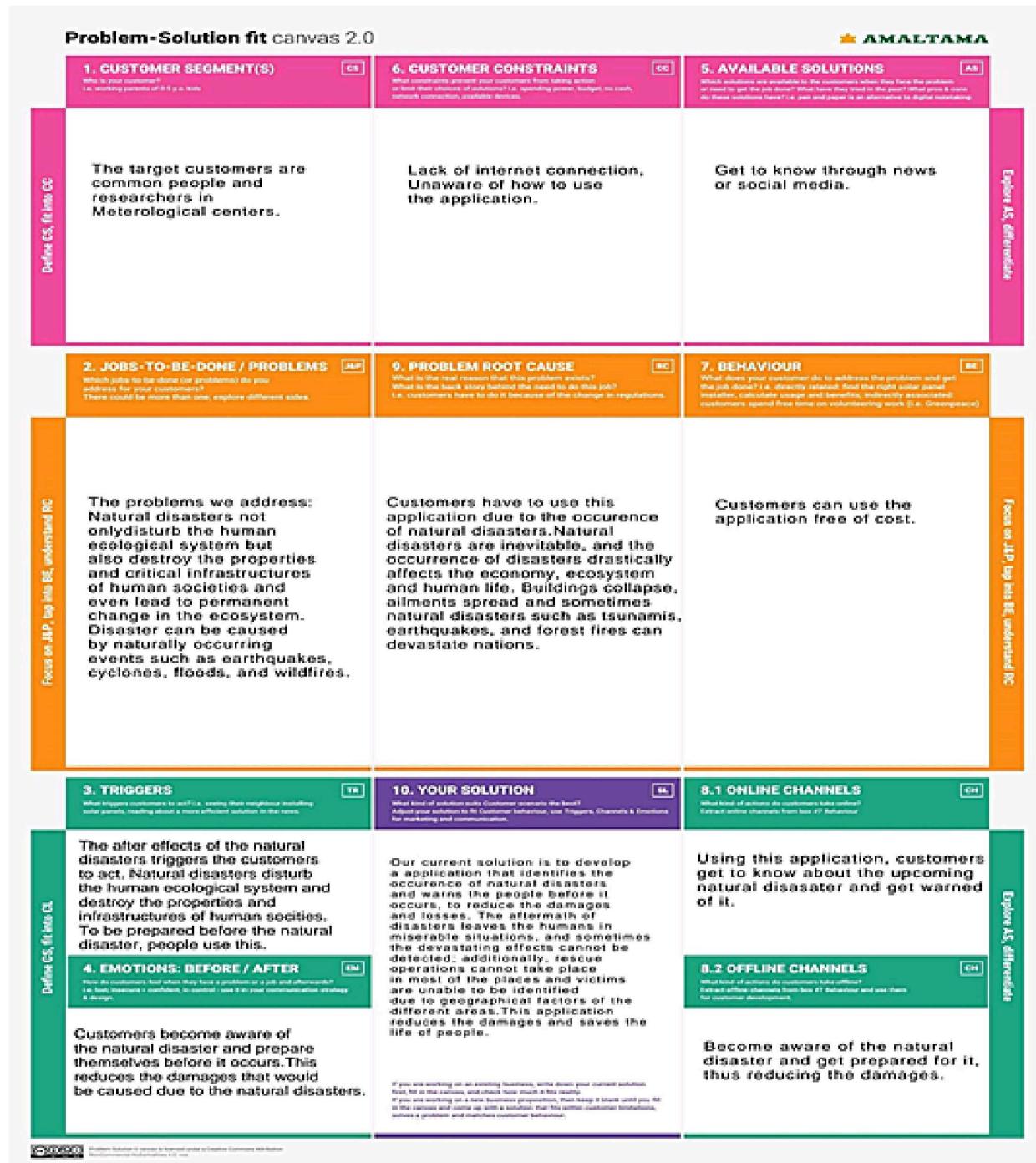
## ● Prioritize ideas



### **3.3 Proposed Solution**

<b>S.No.</b>	<b>Parameter</b>	<b>Description</b>
1	Problem Statement (Problem to be solved)	Classify and identify the occurring natural disaster and analyse its risk factor.
2	Idea / Solution description	Usage of AI-based multilayer network model for identification of the disaster.
3	Novelty / Uniqueness	Usage of self-sufficient AI model based on reinforcement learning for risk analysis.
4	Social Impact / Customer Satisfaction	It helps the user to know the risk factor at his location and mitigation suggestions support.
5	Business Model (Revenue Model)	It is a cheap software with affordable minimum requirements.
6	Scalability of the Solution	Better accuracy in intensity analysis and risk factor with mitigation measures is evaluated using this model.

### 3.4 Problem Solution fit



## **4. REQUIREMENT ANALYSIS**

### ***4.1 Functional requirement***

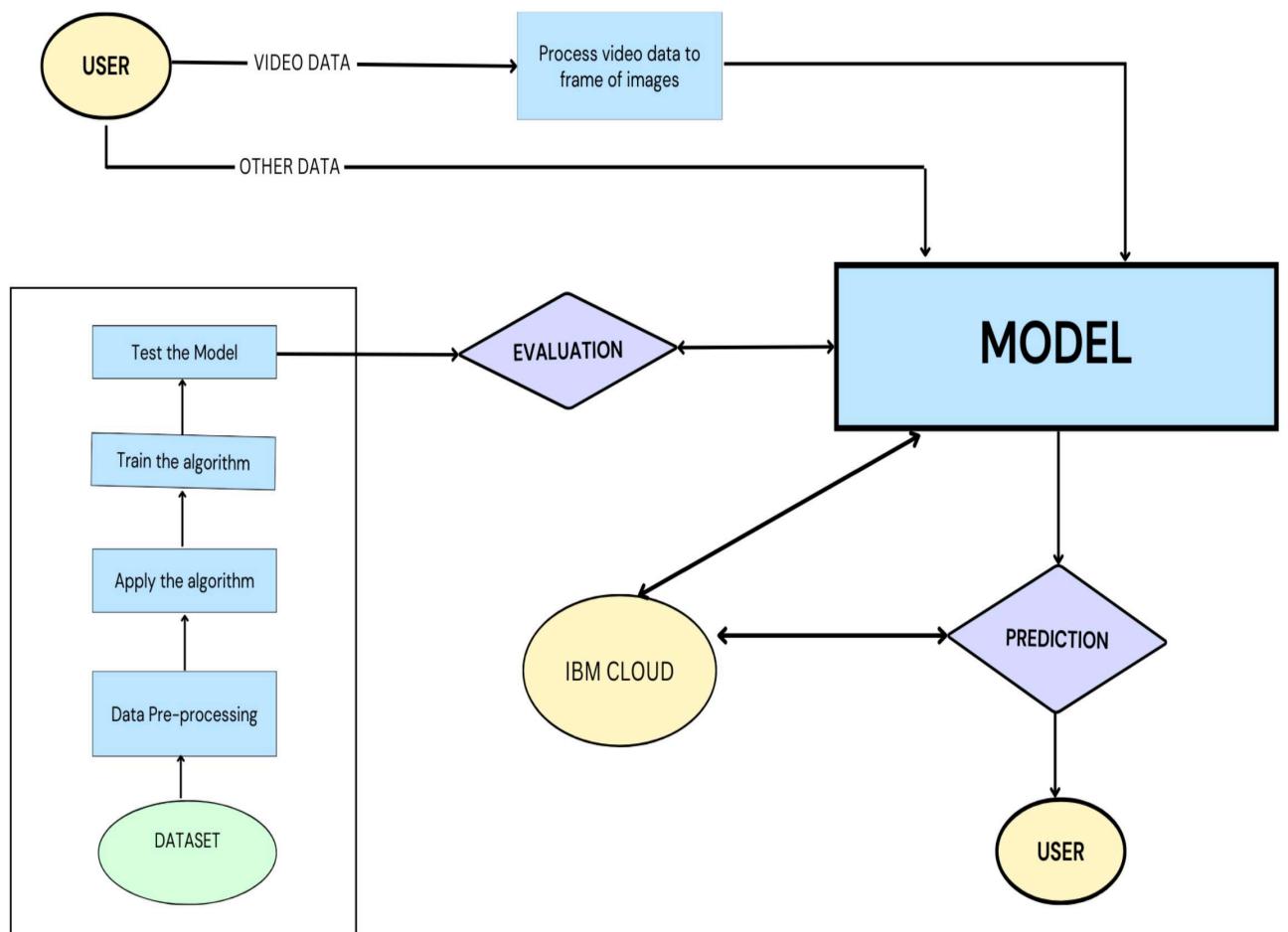
<b>FR No.</b>	<b>Functional Requirement (Epic)</b>	<b>Sub Requirement (Story / Sub-Task)</b>
FR-1	User Registration	Registration through Form ,Registration through Gmail, Registration through LinkedIN
FR-2	User Confirmation	Confirmation via Email Confirmation via OTP
FR-3	Access to the location	Turn on the location.
FR-4	Input	Video feed from the camera.
FR-5	Processing	Processing the images and videos based on the available datas.
FR-6	Output	Alerts about the intensity of the disaster.

### ***4.2 Non-Functional requirements***

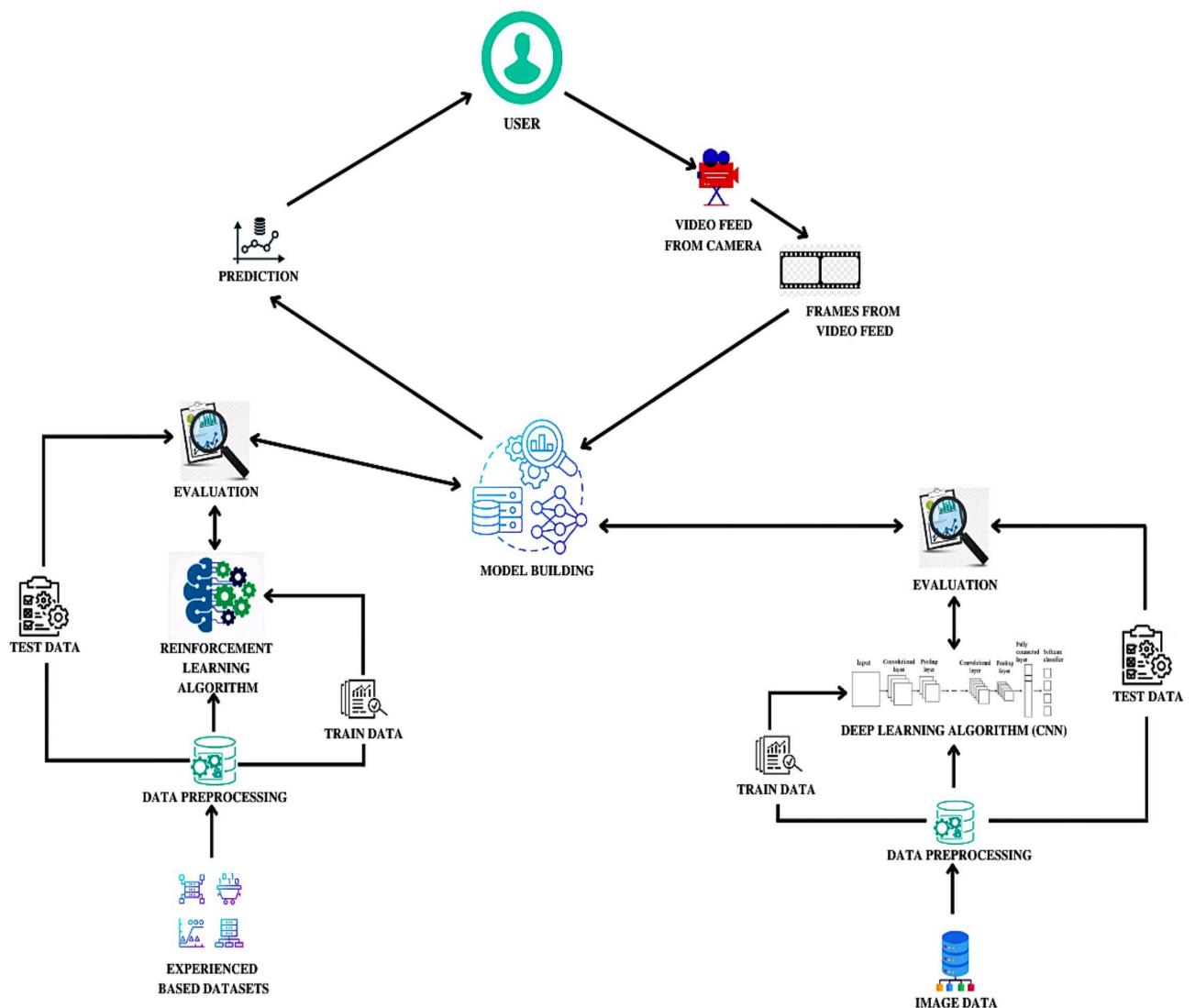
<b>FR No.</b>	<b>Non-Functional Requirement</b>	<b>Description</b>
NFR1	<b>Usability</b>	Can be used if there is proper internet connection and input.
NFR2	<b>Security</b>	Users must change the initially assigned login password immediately after the first successful login. Moreover, the initial should never be reused.
NFR3	<b>Reliability</b>	Gives accurate information and can be used any time.
NFR4	<b>Performance</b>	Good user experience and ease of operating the application. Latency is very low.
NFR5	<b>Availability</b>	The application is available all the time and can be accessed at any time.
NFR6	<b>Scalability</b>	Assesses the highest workloads. The application is scalable enough to support 1,000,000 visits at the same time while maintaining optimal performance.

## 5. PROJECT DESIGN

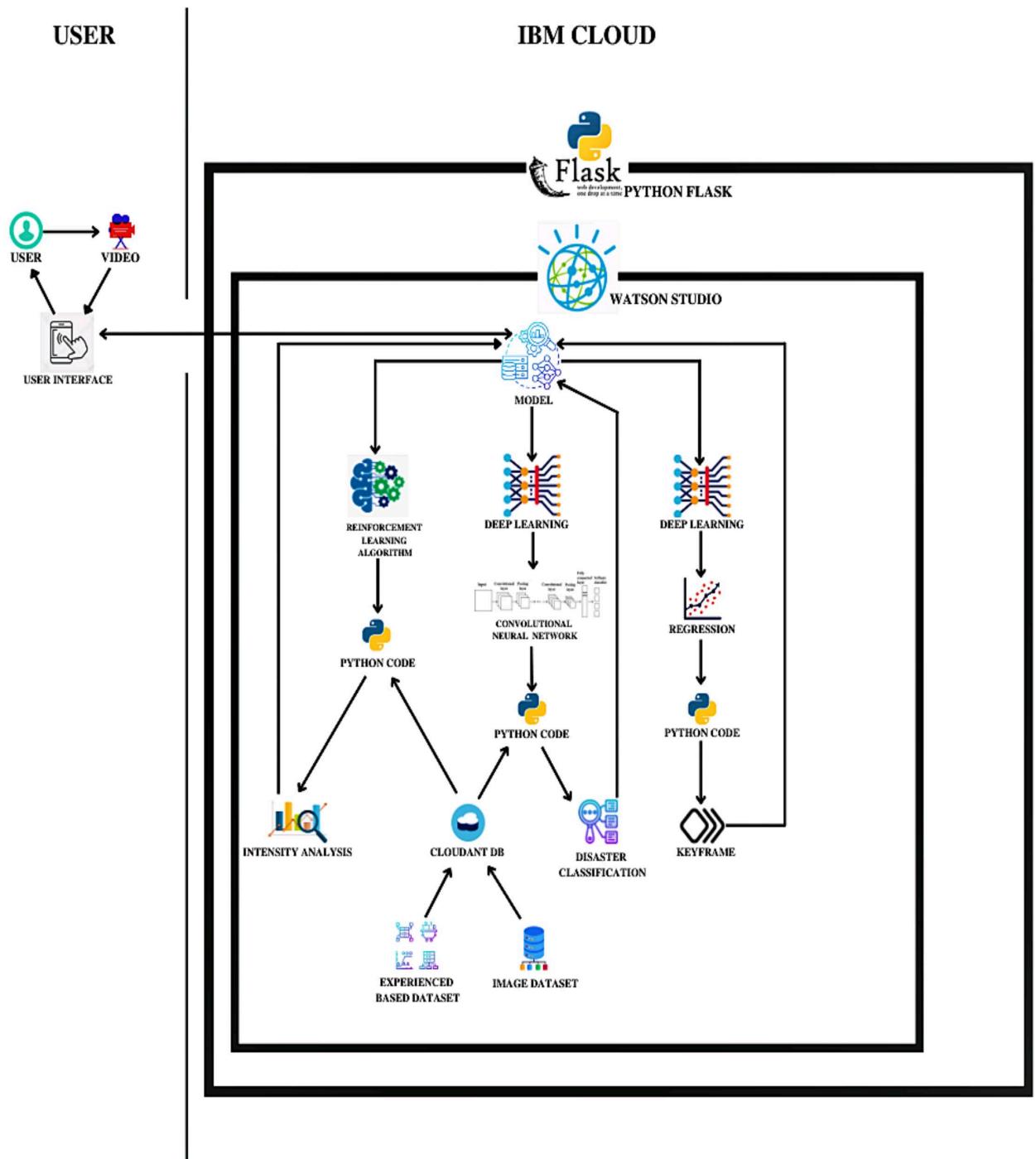
### 5.1 Data Flow Diagrams



## 5.2 Solution Architecture



### 5.3 Technical Architecture



## 5.4 User Stories

User Type	Functional Requirement (Epic)	User Story Number	User Story / Task	Acceptance criteria	Priority	Release
Customer (Mobile user)	Registration	USN-1	As a user, I can register for the application by entering my email, password and confirming my password.	I can access my account / dashboard	High	Sprint-1
		USN-2	As a user, I will receive confirmation email once I have registered for the application	I can receive confirmation email & click confirm	High	Sprint-1
		USN-3	As a user, I will receive confirmation OTP once I have registered for the application	I can enter the OTP & click confirm	Low	Sprint-2
		USN-4	As a user, I can register for the application through Gmail	I can access my account / dashboard	Medium	Sprint-1
		USN-5	As a user, I can register for the application through LinkedIn	I can access my account / dashboard	Medium	Sprint-3
	Login	USN-6	As a user, I can log into the application by entering email & password	I can access my account / dashboard	High	Sprint-1
	Dashboard	USN-7	As a user, I can access the information and services provided in the dashboard	I can access my dashboard	High	Sprint-2
Customer (Web user)	Login	USN-8	As a user, I can login to the web application and access my dashboard	I can access my account / dashboard using the registered login credentials	High	Sprint-1
Customer Care Executive	Help desk	USN-9	As a user, I can get the help from customer care	I can reach out to the help desk if there is any grievances	Medium	Sprint-3
Administrator	Management	USN-10	As an administrator, I can collect new datasets and keep the model trained	I can collect and train model with new dataset	Medium	Sprint-3
		USN-11	As an administrator, I can update the features of the application	I can feature to the application	Medium	Sprint-3
		USN-12	As an administrator, I can collect the data of user and maintain user history	I can maintain details of the user such as name, gmail, location etc	High	Sprint-1

		USN-13	As an administrator, I can maintain 3rd - party services	I can maintain services such as GPS etc	Medium	Sprint-2
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## **6. PROJECT PLANNING & SCHEDULING**

### ***6.1 Sprint Planning & Estimation***

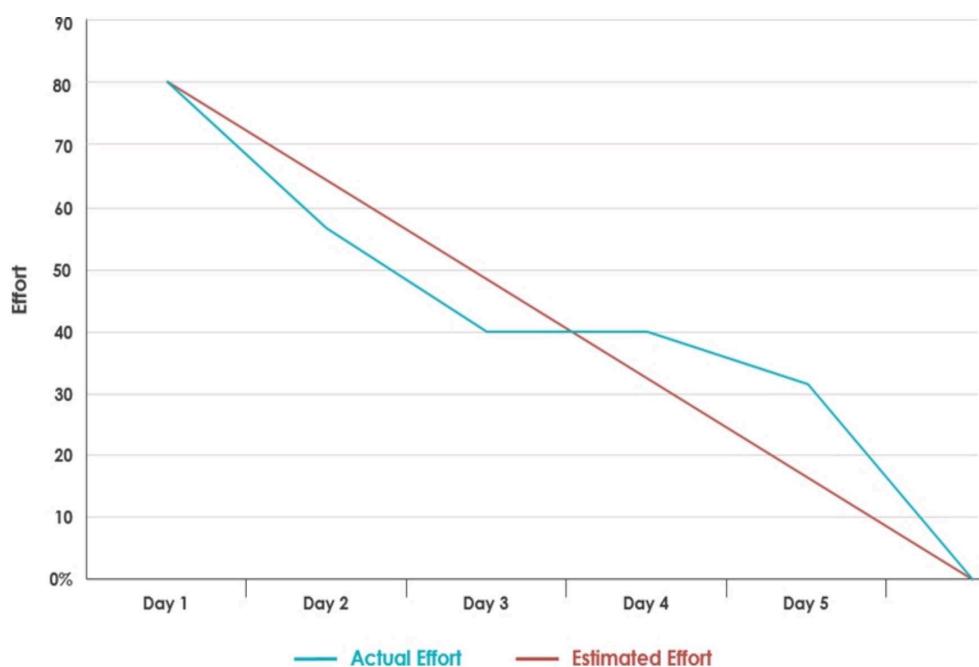
Sprint	Functional Requirement (Epic)	User Story Number	User Story / Task	Story Points	Priority	Team Members
Sprint-3	Registration	USN-1	As a user, I can register for the website by entering my email, password, and confirming my password.	1	High	Nithyasree, Valliammai
Sprint-3		USN-2	As a user, I will receive confirmation email once I have registered for the application.	1	High	Nithyasree, Valliammai
Sprint-3		USN-3	As a user, I can register for the application through mobile number.	2	Medium	Nithyasree, Valliammai
Sprint-3		USN-4	As a user, I will receive confirmation SMS (OTP)	2	Medium	Nithyasree, Valliammai
Sprint-3	Login	USN-5	As a user, I can log into the application by entering email & password.	1	High	Nithyasree, Valliammai
Sprint-3		USN-6	As a user, I can upload image/video.	2	Medium	Nithyasree, Uthra
Sprint-3		USN-7	As a user, I get predicted output.	1	High	Nithyasree, Uthra
Sprint-3		USN-8	As a user, I can logout of the website.	3	Low	Nithyasree, Sidharth
Sprint-3		USN-9	As a developer, I can collect data and maintain user history.	3	Low	Sidharth, Nithyasree
Sprint-1	HTML pages	USN-10	As a developer, Build registration page using HTML	1	High	Uthra
Sprint-1		USN-11	As a developer, Build login page using HTML	1	High	Uthra

Sprint-1		USN-12	As a developer, Build home page using HTML	1	High	Uthra, Sidharth
Sprint-2		USN-13	As a developer, Build upload page using HTML	1	High	Uthra, Sidharth
Sprint-2		USN-14	As a developer, Build redirecting pages using HTML	3	Low	Uthra, Sidharth
Sprint-2		USN-15	As a developer, Build analysis report page using HTML	1	High	Uthra, Sidharth
Sprint-1		USN-16	As a developer, Build logout page using HTML	2	Medium	Uthra
Sprint-3		USN-17	As a developer, Getting access to location from user.	1	High	Nithyasree
Sprint-1	Dashboard	USN-18	As a developer, Build dashboard page using HTML	1	High	Uthra, Sidharth
Sprint-1		USN-19	As a developer, collect dataset to train and test model.	1	High	Uthra, Sidharth, Nithyasree, Valliammai
Sprint-1	Image preprocessing	USN-20	As a developer, import imagedatagenerator library to perform image augmentation	2	Medium	Sidharth, Nithyasree
Sprint-1		USN-21	As a developer, configure imagedatagenerator library to augment images	2	Medium	Sidharth
Sprint-1		USN-22	As a developer, applying imagedatagenerator library to trainset and testset images	1	High	Sidharth
Sprint-2	Model building	USN-23	As a developer, Train-test and save model.	1	High	Uthra, Sidharth
Sprint-2	Application building	USN-24	As a developer, Build python code.	1	High	Nithyasree, Uthra
Sprint-3		USN-25	As a developer, Run the application.	1	High	Nithyasree, Sidharth
Sprint-4	Cloud integration	USN-26	As a developer, Integrate the application with IBM cloud.	1	High	Nithyasree, Valliammai
Sprint-4		USN-27	As a developer, Train the model on IBM	1	High	Uthra,

			Cloud.			Sidharth, Nithyasree,
Sprint-4		USN-28	As a developer, Upload datasets to Cloudant DB	3	Low	Sidharth, Valliammai
Sprint-4		USN-29	As a developer, Fetch data from Cloudant DB to perform manipulations on code	2	Medium	Nithyasree, Valliammai
Sprint-4		USN-30	As a developer, Get feedback from the user	1	High	Valliammai
Sprint-4		USN-31	As a developer, update features on website	3	Low	Uthra, Nithyasree
Sprint-4		USN-32	As a developer, work on bugs	2	Medium	Sidharth, Valliammai
Sprint-4		USN-33	As a developer, track the progress of team using JIRA Software	1	High	Sidharth
Sprint-4	Analysis	USN-34	As a developer, perform user acceptance test	1	High	Sidharth, Valliammai
Sprint-4		USN-35	As a developer, performance testing is done to check the efficiency of the code	1	High	Uthra, Valliammai
Sprint-4		USN-36	As a developer, collect & analyse testcase report	1	High	Uthra, Nithyasree
Sprint-4		USN-37	As a developer, Submitting the overall project report	1	High	Uthra, Sidharth

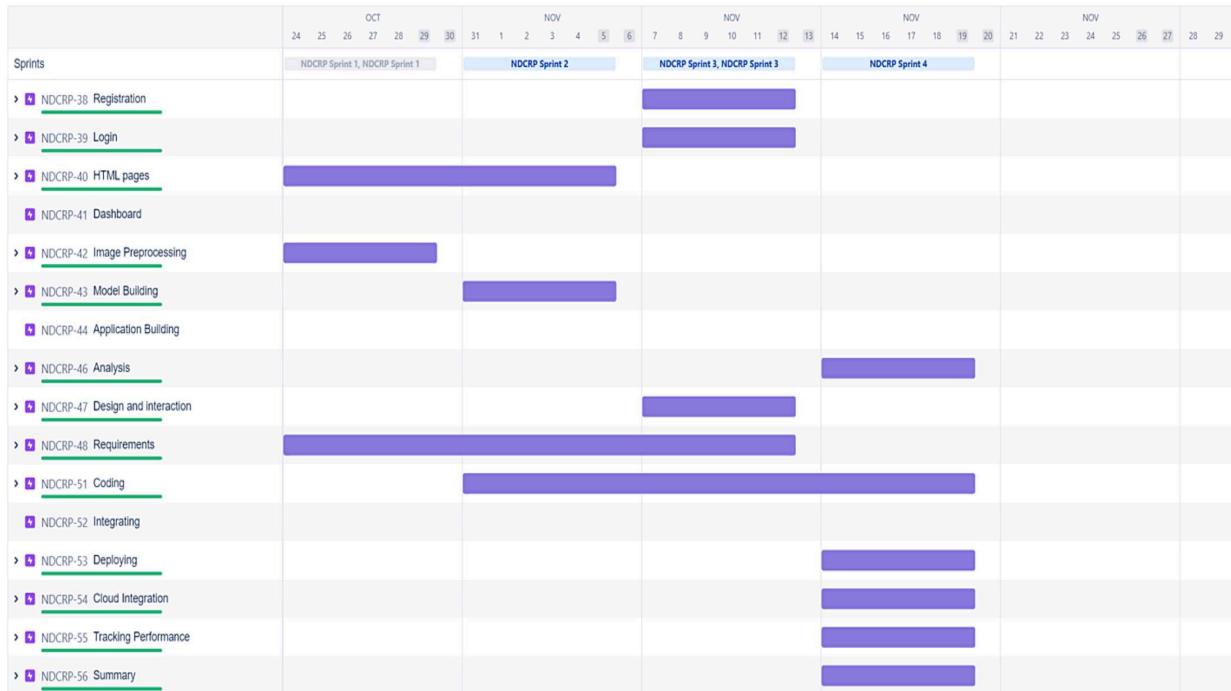
## 6.2 Sprint Delivery Schedule

Sprint	Total Story Points	Duration	Sprint Start Date	Sprint End Date (Planned)	Story Points Completed (as on Planned End Date)	Sprint Release Date (Actual)
Sprint-1	20	6 Days	24 Oct 2022	29 Oct 2022	20	29 Oct 2022
Sprint-2	20	6 Days	31 Oct 2022	05 Nov 2022	20	05 Nov 2022
Sprint-3	20	6 Days	07 Nov 2022	12 Nov 2022	20	12 Nov 2022
Sprint-4	20	6 Days	14 Nov 2022	19 Nov 2022	20	19 Nov 2022



## 6.3 Reports from JIRA

### Road Map



The screenshot shows the Jira Software interface with the following details:

- Project:** Natural Disasters Intensity Analysis and Classification using AI
- Module:** Backlog
- Sprints:**
  - NDCRP Sprint 2:** 31 Oct – 5 Nov (6 issues)
    - NDCRP-21 As a developer, Build upload page using HTML [HTML PAGES]
    - NDCRP-50 As a developer, Build python code for risk analysis. [CODING]
    - NDCRP-25 As a developer, Build python code for image classification. [CODING]
    - NDCRP-24 As a developer, Train-test and save model [MODEL BUILDING]
    - NDCRP-22 As a developer, Build redirecting pages using HTML [HTML PAGES]
    - NDCRP-23 As a developer, Build analysis report page using HTML [HTML PAGES]
  - NDCRP Sprint 4:** 14 Nov – 19 Nov (13 issues)
    - NDCRP-37 As a developer, Submitting the overall project report [SUMMARY]
    - NDCRP-29 As a developer, Fetch data from Cloudant DB to perform manipulations on code [DEPLOYING]
- Status:** Complete sprint (for both sprints)
- Search Bar:** Type here to search

Jira Software - Projects / Natural Disasters Intensity Analysis and Classification using AI

Roadmap

Planning: Roadmap

Development: Code

You're in a team-managed project

Type here to search

Sprints	NOV	DEC	JAN '23
NDCRP-38 Registration	Nov 1-15	Nov 16-30	
NDCRP-39 Login	Nov 1-15	Nov 16-30	
NDCRP-40 HTML pages	Nov 1-15	Nov 16-30	
NDCRP-41 Dashboard	Nov 1-15	Nov 16-30	
NDCRP-42 Image Preprocessing	Nov 1-15	Nov 16-30	
NDCRP-43 Model Building	Nov 1-15	Nov 16-30	
NDCRP-44 Application Building	Nov 1-15	Nov 16-30	
NDCRP-46 Analysis	Nov 1-15	Nov 16-30	
NDCRP-47 Data interaction	Nov 1-15	Nov 16-30	

Search: Q Search

Give feedback Share Export View settings

Quickstart

15:38 16-11-2022

Jira Software - Projects / Natural Disasters Intensity Analysis and Classification using AI

All sprints

Planning: Board

Development: Code

You're in a team-managed project

Type here to search

TO DO 2 ISSUES	IN PROGRESS 3 ISSUES	REVIEW 4 ISSUES	DONE 30 ISSUES
As a user, I can logout of the website. <b>LOGIN</b> NDCRP-8	As a developer, Get feedback from the user. <b>ANALYSIS</b> NDCRP-30	As a developer, work on bugs. <b>ANALYSIS</b> NDCRP-32	As a user, I can register for the website by entering my email, password, and confirming my password. <b>REGISTRATION</b> NDCRP-1
As a developer, Build logout page using HTML. <b>HTML PAGES</b> NDCRP-20	As a developer, Getting access to location from user. <b>REQUIREMENTS</b> NDCRP-10	As a developer, Train the model on IBM Cloud. <b>DEPLOYING</b> NDCRP-27	As a developer, Submitting the overall project report. <b>SUMMARY</b> NDCRP-37
As a developer, Build upload page using HTML. <b>HTML PAGES</b> NDCRP-21	As a developer, Fetch data from Cloudant DB to perform manipulations on code <b>DEPLOYING</b> NDCRP-29	As a developer, I can collect data.	As a developer, Upload datasets to Cloudant DB <b>DEPLOYING</b> NDCRP-28

Search: Q Search

Complete sprint Insights

GROUP BY None

Quickstart

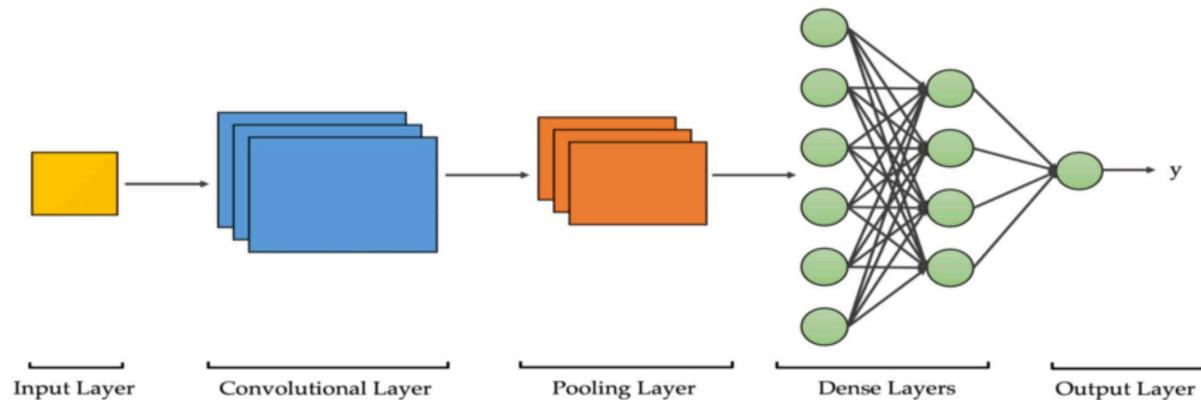
15:34 16-11-2022

## **7. CODING & SOLUTIONING**

### **7.1 Feature 1 ( Convolutional Neural Network )**

Feature Overview:

A Convolutional Neural Network or CNN is a type of artificial neural network, which is widely used for image/object recognition and classification. Deep Learning thus recognizes objects in an image by using a CNN. CNNs are playing a major role in diverse tasks/functions like image processing problems, computer vision tasks like localization and segmentation, video analysis, to recognize obstacles in self-driving cars, as well as speech recognition in natural language processing.



```
#-----Import libraries
```

```
import tensorflow
from tensorflow import keras
from keras import Sequential
from keras.layers import Convolution2D, MaxPooling2D, Flatten, Dense, Dropout
from keras.preprocessing.image import ImageDataGenerator as idm
import numpy as np
import warnings
warnings.filterwarnings('ignore')
```

```
#-----Mount google drive
```

```

from google.colab import drive
drive.mount('/content/drive')

#-----Unzip dataset
pwd
ls
cd /content/drive/MyDrive/IBM_DATASET/
ls
!unzip training_set.zip

#-----Configure and apply imagedatagenerator
#Configure train_datagen
train_datagen = idm(rescale=1./255, zoom_range=0.2, horizontal_flip=True,
vertical_flip=False)
#Configure test_datagen
test_datagen = idm(rescale=1./255)
Xtrain =
train_datagen.flow_from_directory('/content/drive/MyDrive/IBM_DATASET/tr
ain_set',target_size=(76, 76), batch_size=100, class_mode='categorical',
color_mode = "rgb")
Xtest =
test_datagen.flow_from_directory('/content/drive/MyDrive/IBM_DATASET/tes
t_set',target_size=(76, 76), batch_size=100, class_mode='categorical',
color_mode = "rgb")

#-----Display class indices
Xtrain.class_indices
Xtest.class_indices

#-----Create Model
#Defining model
model=Sequential()

#-----Build and Configure model
#Convolution Layer 1

```

```

model.add(Convolution2D(32, (3, 3), activation='relu', input_shape=(76, 76, 3
)))
model.add(MaxPooling2D(pool_size=(2, 2)))
#Convolution Layer 2
model.add(Convolution2D(32, (3, 3), activation='relu', input_shape=(76, 76, 3
)))
model.add(MaxPooling2D(pool_size=(2, 2)))
#Convolution Layer 3
model.add(Convolution2D(64, (3, 3), activation='relu', input_shape=(76, 76, 3
)))
model.add(MaxPooling2D(pool_size=(2, 2)))
#Convolution Layer 4
model.add(Convolution2D(64, (3, 3), activation='relu', input_shape=(76, 76, 3
)))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Flatten())
model.add(Dense(300, activation='relu'))
model.add(Dense(150, activation='relu'))
model.add(Dense(3, activation='softmax'))

#-----Model Summary
model.summary()

#-----Compile the model
model.compile(optimizer='adam', loss='categorical_crossentropy', metrics=
['accuracy'])

#-----Train Model
#Model fitting - training and validation
history = model.fit_generator(Xtrain, steps_per_epoch= len(Xtrain),
epochs=15, validation_data=Xtest, validation_steps= len(Xtest))

#-----Test Model
from tensorflow.keras.preprocessing import image

test_img=image.load_img('/content/drive/MyDrive/IBM_DATASET/test_set/Ea

```

```

rthquake/Copy of 22.jpg',target_size=(76,76))

test_img

x=image.img_to_array(test_img)
x=np.expand_dims(x, axis=0)
predicted=np.argmax(model.predict(x))
Prediction_category=['Cyclone', 'Earthquake', 'Flood']
Prediction_category[predicted]

#-----Save Model
model.save('CNN_Model_for_Disaster_Classification.h5')

#-----Plot Accuracy graph
# importing dependencies to plot the graph
import matplotlib.pyplot as plt
import seaborn as sns
import cv2
#Training and Validation Accuracy Plots
epochs_range = range(15)

plt.figure(figsize=(6,6))
plt.plot(epochs_range, history.history['accuracy'], label='Training Accuracy')
plt.plot(epochs_range, history.history['val_accuracy'], label='Validation Accuracy')
plt.legend()
plt.title('Training and Testing Accuracy')
plt.show()

#-----Plot Loss graph
#Training and Validation Loss Plot
plt.figure(figsize=(6,6))
plt.plot(epochs_range, history.history['loss'], label='Training Loss')
plt.plot(epochs_range, history.history['val_loss'], label='Validation Loss')
plt.legend()

```

```

plt.title('Training and Testing Loss')
plt.show()

#-----Confusion Matrix

from sklearn.metrics import classification_report, confusion_matrix
y_pred = model.predict_generator(Xtest, 500 // 100)
y_pred = np.argmax(y_pred, axis=1)
print('Confusion Matrix')
print(confusion_matrix(Xtest.classes, y_pred))

#-----Classification Report

print('Classification Report')
target_names = ['Cyclone', 'Earthquake', 'Flood']
print(classification_report(Xtest.classes, y_pred,
target_names=target_names))

```

This CNN model has comparatively more layers (i.e. 3 layers) which increases the efficiency of the model to classify accurately and the capacity of the model gets increased as the number of layers get increased. The image input is processed through the different network layers of the model and the class of which image belongs to is been predicted. Here we have 3 classes: Cyclone, Flood , Earthquake. The model predicts and reports any one of the class.

## **7.2 Feature 2 ( Key Frame Separation Model)**

Feature Overview:

In accessing large collections of digitized videos, it is often difficult to find both the appropriate video file and the portion of the video that is of interest. We use keyframes to summarize videos, and to provide access points into them . Hence, the classification becomes more accurate.

```

#-----Mount google drive

from google.colab import drive
drive.mount('/content/drive')

```

```

#-----Import Dependencies

import os
import cv2
import subprocess

#-----Function

def get_frame_types(video_fn):
    command = 'ffprobe -v error -show_entries frame=pict_type -of
default=noprint_wrappers=1'.split()
    out = subprocess.check_output(command + [video_fn]).decode()
    frame_types = out.replace('pict_type=', '').split()
    return zip(range(len(frame_types)), frame_types)

def save_i_keyframes(video_fn):
    frame_types = get_frame_types(video_fn)
    i_frames = [x[0] for x in frame_types if x[1]=='I']
    if i_frames:
        basename = os.path.splitext(os.path.basename(video_fn))[0]
        cap = cv2.VideoCapture(video_fn)
        for frame_no in i_frames:
            cap.set(cv2.CAP_PROP_POS_FRAMES, frame_no)
            ret, frame = cap.read()
            outname = 'Key_frame_'+str(frame_no)+'.jpg'
            cv2.imwrite(outname, frame)
            print (outname)
        cap.release()

    else:
        print ('No I-frames in '+video_fn)

if __name__ == '__main__':
    save_i_keyframes(filename)

```

### **7.3 Feature 3 ( Reinforcement Learning Model )**

#### **Feature Overview:**

Reinforcement learning is an area of Machine Learning. It is about taking suitable action to maximize reward in a particular situation. It is employed by various software and machines to find the best possible behavior or path it should take in a specific situation. Reinforcement learning differs from supervised learning in a way that in supervised learning the training data has the answer key with it so the model is trained with the correct answer itself whereas in reinforcement learning, there is no answer but the reinforcement agent decides what to do to perform the given task. In the absence of a training dataset, it is bound to learn from its experience. The RL process is as follows:

- Observe --> Environment of the Agent
- Decide --> Decision as per Observations
- Act --> Action on the Decision
- Receive --> Getting Rewarded or Penalised as per the Action
- Learn --> from previous Actions and improve
- Iterate --> Repeat the entire process till Success

#### **7.3.1 RL Model for Earthquake**

```
#-----Mount google drive
from google.colab import drive
drive.mount('/content/drive')

#-----Read data
df=pd.read_csv( path)

#-----Plot Earthquake prone locations
sns.scatterplot(x='latitude',y='longitude',data=df)
plt.title('Earthquake Prone Locations ')

#-----Import Dependencies
```

```

import gym
from gym import Env
from gym.spaces import Discrete, Box, Dict, Tuple, MultiBinary,
MultiDiscrete
import numpy as np
import random
import os
from stable_baselines3 import PPO
from stable_baselines3.common.vec_env import VecFrameStack
from stable_baselines3.common.evaluation import evaluate_policy

#-----Building an Environment

class EarthquakeEnv(Env):
    def __init__(self):
        # Actions we can take: hide, stay, vacate
        self.action_space = Discrete(3)
        # Plate movement array
        self.observation_space = Box(low=np.array([0]),
high=np.array([100]))
        # Set start magnitude
        self.state = 5 + random.randint(-3,3)
        # Set decision duration
        self.decision_duration = 60

    def step(self, action):
        # Apply action
        # 0 -1 = -1 magnitude
        # 1 -1 = 0
        # 2 -1 = 1 magnitude
        self.state += action -1
        # Reduce decision duration by 1 second
        self.decision_duration -= 1

        # Calculate reward
        if self.state >=5 and self.state <=20:
            reward =1
        else:
            reward =-1
        return self.observation_space.sample(), self.state, reward, {}

```

```

        else:
            reward = -1

        # Check if time is over
        if self.decision_duration <= 0:
            done = True
        else:
            done = False

        # Apply magnitude error
        #self.state += random.randint(-1,1)
        # Set placeholder for info
        info = {}

        # Return step information
        return self.state, reward, done, info

    def render(self):
        # Implement viz
        pass

    def reset(self):
        # Reset magnitude
        self.state = np.array([15 + random.randint(-3,3)]).astype(float)
        # Reset decision duration
        self.decision_duration = 60
        return self.state

env = EarthquakeEnv()
env.observation_space.sample()

#-----Test Environment
episodes = 80
for episode in range(1, episodes+1):
    state = env.reset()
    done = False
    score = 0

```

```

while not done:
    env.render()
    action = env.action_space.sample()
    n_state, reward, done, info = env.step(action)
    score+=reward
    print('Episode:{} Score:{}'.format(episode, score))

-----Train Model
log_path = os.path.join('Training', 'Logs')
model = PPO("MlpPolicy", env, verbose=1, tensorboard_log=log_path)
model.learn(total_timesteps=10000)

-----Save Model
model.save('PPO')
evaluate_policy(model, env, n_eval_episodes=80)

```

The seismic magnitude is initialised '5' and the decision duration being 60sec , for a wrong desicion at that episode for the concerned state, after the action the agent is penalised and gets 59 seconds only for the decision making during the next state.For the correct decision the agent is rewarded +1 sec for decision making. Here the 3 actions are: Hide(-1) , Stay(0) , Evacuate(+1). On a longer run the model becomes self sufficient and improves the decision making during risk.

### 7.3.2 RL Model for Flood & Cyclone

```

-----Import Dependencies
import gym
from gym import Env
from gym.spaces import Discrete, Box, Dict, Tuple, MultiBinary,
MultiDiscrete
import numpy as np
import random
import os
from stable_baselines3 import PPO
from stable_baselines3.common.vec_env import VecFrameStack

```

```

from stable_baselines3.common.evaluation import evaluate_policy

#-----Building an Environment

class Water_DisasterEnv(Env):
    def __init__(self):
        # Actions we can take: closed room, stay, vacate
        self.action_space = Discrete(3)
        # Temperature array
        self.observation_space = Box(low=np.array([0]),
high=np.array([100]))
        # Set start rainfall
        self.state = 10 + random.randint(-3, 3)
        # Set decision duration
        self.decision_duration = 60

    def step(self, action):
        # Apply action
        # 0 -1 = -1 rainfall
        # 1 -1 = 0
        # 2 -1 = 1 rainfall
        self.state += action -1
        # Reduce decision duration by 1 minute
        self.decision_duration -= 1

        # Calculate reward
        if self.state >=10 and self.state <=20:
            reward =1
        else:
            reward = -1

        # Check if time is over
        if self.decision_duration <= 0:
            done = True
        else:
            done = False

```

```

# Apply rainfall fluctuations
#self.state += random.randint(-1,1)
# Set placeholder for info
info = {}

# Return step information
return self.state, reward, done, info

def render(self):
    # Implement viz
    pass

def reset(self):
    # Reset rainfall
    self.state = np.array([15 + random.randint(-3,3)]).astype(float)
    # Reset decision duration
    self.decision_duration = 60
    return self.state

env = Water_DisasterEnv()
env.observation_space.sample()

-----Test Environment

episodes = 100
for episode in range(1, episodes+1):
    state = env.reset()
    done = False
    score = 0

    while not done:
        env.render()
        action = env.action_space.sample()
        n_state, reward, done, info = env.step(action)
        score+=reward

    print('Episode:{} Score:{}'.format(episode, score))

-----Train Model

```

```

log_path = os.path.join('Training', 'Logs')
model = PPO("MlpPolicy", env, verbose=1, tensorboard_log=log_path)
model.learn(total_timesteps=20000)

-----Save Model

model.save('PPO')
evaluate_policy(model, env, n_eval_episodes=100)

```

The rainfall measure is initialised '10" and the decision duration being 60sec , for a wrong desicion at that episode for the concerned state, after the action the agent is penalised and gets 59 seconds only for the decision making during the next state. For the correct decision the agent is rewarded +1 sec for decision making. The reward is granted for right decision only when the rainfall measure is between 10 and 20. Here the 3 actions are: Hide(-1) , Stay(0) , Evacuate(+1). On a longer run the model becomes self sufficient and improves the decision making during risk.

## 7.4 Database Schema

Training Image dataset link:

[https://drive.google.com/file/d/1JCI8bDZQNOYdSdCUCJHgUWIRIKvoekfD/view?usp=drive\\_web](https://drive.google.com/file/d/1JCI8bDZQNOYdSdCUCJHgUWIRIKvoekfD/view?usp=drive_web)

Testing Image dataset link:

[https://drive.google.com/file/d/1T34RSRag3M8IS58SqoluGdmXNWnc\\_Ez/view?usp=drive\\_web](https://drive.google.com/file/d/1T34RSRag3M8IS58SqoluGdmXNWnc_Ez/view?usp=drive_web)

CSV files:

[https://drive.google.com/file/d/1Gn55xF2C8IMHleZ6pD5J2UE5FruLhbAQ/view?usp=share\\_link](https://drive.google.com/file/d/1Gn55xF2C8IMHleZ6pD5J2UE5FruLhbAQ/view?usp=share_link)

[https://drive.google.com/file/d/1s37TRvWmFomrG15zEEiEtTW5bvrg-3Gu/view?usp=share\\_link](https://drive.google.com/file/d/1s37TRvWmFomrG15zEEiEtTW5bvrg-3Gu/view?usp=share_link)

## **8. TESTING**

### **8.1 Test Cases**

<https://docs.google.com/spreadsheets/d/132Lf2Efx5a6CRVcB1k07XXoFiXjuPU8gyZgdFevWNw/edit?usp=sharing>

### **8.2 User Acceptance Testing**

#### **1.PURPOSE OF DOCUMENT:**

The purpose of this document is to briefly explain the test coverage and open issues of the project at the time of the release to User Acceptance Testing (UAT).

#### **2.DEFECT ANALYSIS:**

This report shows the number of resolved or closed bugs at each severity level, and how they were resolved.

RESOLUTION	SEVERITY 1	SEVERITY 2	SEVERITY 3	SEVERITY 4	SUBTOTAL
By Design	15	6	4	5	30
Duplicate	0	0	4	1	5
External	2	4	0	1	7
Fixed	20	5	4	10	39
Not Reproduced	0	1	0	0	1
Skipped	0	0	1	0	1
Won't Fix	1	4	3	1	9
<b>Totals</b>	<b>38</b>	<b>20</b>	<b>16</b>	<b>18</b>	<b>92</b>

### **3. TEST CASE ANALYSIS:**

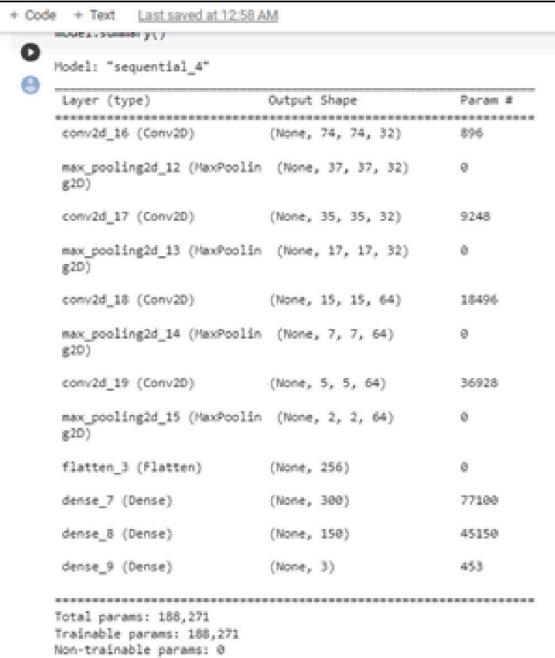
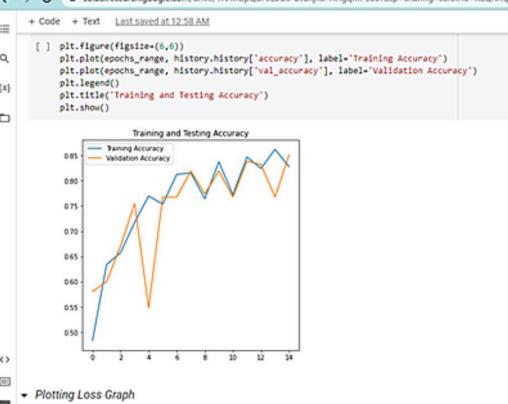
This report shows the number of test cases that have passed, failed, and untested

SECTION	TOTAL CASES	NOT TESTED	FAIL	PASS
Print Engine	5	0	0	5
Client Application	25	0	2	23
Security	3	0	0	3
Exception Reporting	7	0	0	7
Final Report Output	4	0	0	4
Version Control	1	0	0	1

## **9. RESULTS**

### **9.1 Performance Metrics**

- For CNN Model

S.No	Parameter	Screenshot																																																									
1.	Model Summary	 <p>The screenshot shows the output of the <code>model.summary()</code> command for a sequential model named "sequential_4". The output details the architecture and parameter count for each layer:</p> <table border="1"><thead><tr><th>Layer (type)</th><th>Output Shape</th><th>Param #</th></tr></thead><tbody><tr><td>conv2d_16 (Conv2D)</td><td>(None, 74, 74, 32)</td><td>896</td></tr><tr><td>max_pooling2d_12 (MaxPooling2D)</td><td>(None, 37, 37, 32)</td><td>0</td></tr><tr><td>conv2d_17 (Conv2D)</td><td>(None, 35, 35, 32)</td><td>9248</td></tr><tr><td>max_pooling2d_13 (MaxPooling2D)</td><td>(None, 17, 17, 32)</td><td>0</td></tr><tr><td>conv2d_18 (Conv2D)</td><td>(None, 15, 15, 64)</td><td>18496</td></tr><tr><td>max_pooling2d_14 (MaxPooling2D)</td><td>(None, 7, 7, 64)</td><td>0</td></tr><tr><td>conv2d_19 (Conv2D)</td><td>(None, 5, 5, 64)</td><td>36928</td></tr><tr><td>max_pooling2d_15 (MaxPooling2D)</td><td>(None, 2, 2, 64)</td><td>0</td></tr><tr><td>flatten_3 (Flatten)</td><td>(None, 256)</td><td>0</td></tr><tr><td>dense_7 (Dense)</td><td>(None, 300)</td><td>77100</td></tr><tr><td>dense_8 (Dense)</td><td>(None, 150)</td><td>45150</td></tr><tr><td>dense_9 (Dense)</td><td>(None, 3)</td><td>45</td></tr></tbody></table> <p>Total params: 188,271 Trainable params: 188,271 Non-trainable params: 0</p>	Layer (type)	Output Shape	Param #	conv2d_16 (Conv2D)	(None, 74, 74, 32)	896	max_pooling2d_12 (MaxPooling2D)	(None, 37, 37, 32)	0	conv2d_17 (Conv2D)	(None, 35, 35, 32)	9248	max_pooling2d_13 (MaxPooling2D)	(None, 17, 17, 32)	0	conv2d_18 (Conv2D)	(None, 15, 15, 64)	18496	max_pooling2d_14 (MaxPooling2D)	(None, 7, 7, 64)	0	conv2d_19 (Conv2D)	(None, 5, 5, 64)	36928	max_pooling2d_15 (MaxPooling2D)	(None, 2, 2, 64)	0	flatten_3 (Flatten)	(None, 256)	0	dense_7 (Dense)	(None, 300)	77100	dense_8 (Dense)	(None, 150)	45150	dense_9 (Dense)	(None, 3)	45																		
Layer (type)	Output Shape	Param #																																																									
conv2d_16 (Conv2D)	(None, 74, 74, 32)	896																																																									
max_pooling2d_12 (MaxPooling2D)	(None, 37, 37, 32)	0																																																									
conv2d_17 (Conv2D)	(None, 35, 35, 32)	9248																																																									
max_pooling2d_13 (MaxPooling2D)	(None, 17, 17, 32)	0																																																									
conv2d_18 (Conv2D)	(None, 15, 15, 64)	18496																																																									
max_pooling2d_14 (MaxPooling2D)	(None, 7, 7, 64)	0																																																									
conv2d_19 (Conv2D)	(None, 5, 5, 64)	36928																																																									
max_pooling2d_15 (MaxPooling2D)	(None, 2, 2, 64)	0																																																									
flatten_3 (Flatten)	(None, 256)	0																																																									
dense_7 (Dense)	(None, 300)	77100																																																									
dense_8 (Dense)	(None, 150)	45150																																																									
dense_9 (Dense)	(None, 3)	45																																																									
2.	Accuracy	 <p>The screenshot shows a line graph titled "Training and Testing Accuracy" plotted against 34 epochs. The x-axis represents epochs from 0 to 34, and the y-axis represents accuracy from 0.50 to 0.95. The blue line represents Training Accuracy, and the orange line represents Validation Accuracy. Both lines show an overall increasing trend with some fluctuations.</p> <table border="1"><caption>Data extracted from the Accuracy graph</caption><thead><tr><th>Epoch</th><th>Training Accuracy</th><th>Validation Accuracy</th></tr></thead><tbody><tr><td>0</td><td>0.50</td><td>0.55</td></tr><tr><td>2</td><td>0.65</td><td>0.60</td></tr><tr><td>4</td><td>0.75</td><td>0.55</td></tr><tr><td>6</td><td>0.80</td><td>0.80</td></tr><tr><td>8</td><td>0.75</td><td>0.75</td></tr><tr><td>10</td><td>0.85</td><td>0.80</td></tr><tr><td>12</td><td>0.80</td><td>0.85</td></tr><tr><td>14</td><td>0.85</td><td>0.80</td></tr><tr><td>16</td><td>0.80</td><td>0.85</td></tr><tr><td>18</td><td>0.85</td><td>0.80</td></tr><tr><td>20</td><td>0.80</td><td>0.85</td></tr><tr><td>22</td><td>0.85</td><td>0.80</td></tr><tr><td>24</td><td>0.80</td><td>0.85</td></tr><tr><td>26</td><td>0.85</td><td>0.80</td></tr><tr><td>28</td><td>0.80</td><td>0.85</td></tr><tr><td>30</td><td>0.85</td><td>0.80</td></tr><tr><td>32</td><td>0.80</td><td>0.85</td></tr><tr><td>34</td><td>0.85</td><td>0.80</td></tr></tbody></table>	Epoch	Training Accuracy	Validation Accuracy	0	0.50	0.55	2	0.65	0.60	4	0.75	0.55	6	0.80	0.80	8	0.75	0.75	10	0.85	0.80	12	0.80	0.85	14	0.85	0.80	16	0.80	0.85	18	0.85	0.80	20	0.80	0.85	22	0.85	0.80	24	0.80	0.85	26	0.85	0.80	28	0.80	0.85	30	0.85	0.80	32	0.80	0.85	34	0.85	0.80
Epoch	Training Accuracy	Validation Accuracy																																																									
0	0.50	0.55																																																									
2	0.65	0.60																																																									
4	0.75	0.55																																																									
6	0.80	0.80																																																									
8	0.75	0.75																																																									
10	0.85	0.80																																																									
12	0.80	0.85																																																									
14	0.85	0.80																																																									
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18	0.85	0.80																																																									
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22	0.85	0.80																																																									
24	0.80	0.85																																																									
26	0.85	0.80																																																									
28	0.80	0.85																																																									
30	0.85	0.80																																																									
32	0.80	0.85																																																									
34	0.85	0.80																																																									

3.	Loss	<pre>+ Code + Text Last saved at 12:58 AM [ ] plt.figure(figsize=(6,4)) plt.plot(epoch_range, history.history['loss'], label='Training Loss') plt.plot(epoch_range, history.history['val_loss'], label='Validation Loss') plt.legend() plt.title('Training and Testing Loss') plt.show()</pre>
4.	Confusion Matrix	<pre>{x} [ ] #Confuton Matrix and Classification Report Y_pred = model.predict_generator(Xtest,500 // 100) y_pred = np.argmax(Y_pred, axis=1) print('Confusion Matrix') print(confusion_matrix(Xtest.classes, y_pred))  &lt;&gt; WARNING:tensorflow:Your input ran out of data; interrupting training. Make sure that your dataset has at least 500000 elements and consider using the repeat() transform if you want to shuffle the dataset. Confusion Matrix [[20 22 13]  [16 22 12]  [16 14 20]]</pre>
5.	Classification Report	<pre>colab.research.google.com/drive/1fVMGpQuFeL3G6-bvqkRe-ATlgqMPSS0?usp=sharing#scrollTo=8ZF1h8OAtv1m + Code + Text Last saved at 12:58 AM Connect   🔍 ⚙️ 🌐 📁 🌐</pre> <p>Classification Report</p> <pre>{x} [ ] print('Classification Report') target_names = ['Cyclone', 'Earthquake', 'Flood'] print(classification_report(Xtest.classes, y_pred, target_names=target_names))  Classification Report precision    recall    f1-score   support Cyclone       0.38      0.36      0.37      55 Earthquake    0.38      0.44      0.41      50 Flood          0.44      0.40      0.42      50  accuracy           0.40      0.40      0.40      155 macro avg        0.40      0.40      0.40      155 weighted avg     0.40      0.40      0.40      155</pre>

- For RL Model-1 (Earthquake)

S.No.	Parameter	Screenshot
1.	Episode and Score	<pre>[ ] Episode:1 Score:-42 [ ] Episode:2 Score:60 [ ] Episode:3 Score:50 [ ] Episode:4 Score:60 [ ] Episode:5 Score:60 [ ] Episode:6 Score:40 [ ] Episode:7 Score:56 [ ] Episode:8 Score:60 [ ] Episode:9 Score:60 [ ] Episode:10 Score:6 [ ] Episode:11 Score:60 [ ] Episode:12 Score:60 [ ] Episode:13 Score:60 [ ] Episode:14 Score:16 [ ] Episode:15 Score:60 [ ] Episode:16 Score:60 [ ] Episode:17 Score:12 [ ] Episode:18 Score:60 [ ] Episode:19 Score:60 [ ] Episode:20 Score:30 [ ] Episode:21 Score:60 [ ] Episode:22 Score:56 [ ] Episode:23 Score:34 [ ] Episode:24 Score:60 [ ] Episode:25 Score:12 [ ] Episode:26 Score:60 [ ] Episode:27 Score:60 [ ] Episode:28 Score:4 [ ] Episode:29 Score:6 [ ] Episode:30 Score:60 [ ] Episode:31 Score:56 [ ] Episode:32 Score:36 [ ] Episode:33 Score:60 [ ] Episode:34 Score:60 [ ] Episode:35 Score:60 [ ] Episode:36 Score:60 [ ] Episode:37 Score:60 [ ] Episode:38 Score:60 [ ] Episode:39 Score:60 [ ] Episode:40 Score:60 [ ] Episode:41 Score:60 [ ] Episode:42 Score:60 [ ] Episode:43 Score:60 [ ] Episode:44 Score:60 [ ] Episode:45 Score:60 [ ] Episode:46 Score:60 [ ] Episode:47 Score:60</pre>
2.	Evaluation Policy	<pre>[ ] model.save('PPO') [ ] evaluate_policy(model, env, n_eval_episodes=80) (60.0, 0.0)</pre>

- For RL Model-2 (Flood and Cyclone)

S.No.	Parameter	Screenshot
1.	Episode and Score	<pre>[ ] Episode:1 Score:-14 [ ] Episode:2 Score:46 [ ] Episode:3 Score:16 [ ] Episode:4 Score:32 [ ] Episode:5 Score:4 [ ] Episode:6 Score:2 [ ] Episode:7 Score:24 [ ] Episode:8 Score:30 [ ] Episode:9 Score:30 [ ] Episode:10 Score:24 [ ] Episode:11 Score:24 [ ] Episode:12 Score:52 [ ] Episode:13 Score:24 [ ] Episode:14 Score:60 [ ] Episode:15 Score:28 [ ] Episode:16 Score:60 [ ] Episode:17 Score:30 [ ] Episode:18 Score:22 [ ] Episode:19 Score:6 [ ] Episode:20 Score:58 [ ] Episode:21 Score:20 [ ] Episode:22 Score:42 [ ] Episode:23 Score:28 [ ] Episode:24 Score:20 [ ] Episode:25 Score:60 [ ] Episode:26 Score:32 [ ] Episode:27 Score:46 [ ] Episode:28 Score:-14 [ ] Episode:29 Score:60 [ ] Episode:30 Score:-44 [ ] Episode:31 Score:46 [ ] Episode:32 Score:20 [ ] Episode:33 Score:30 [ ] Episode:34 Score:36 [ ] Episode:35 Score:60 [ ] Episode:36 Score:60 [ ] Episode:37 Score:-20</pre>
2.	Evaluation Policy	<pre>[ ] model.save('PPO') [ ] evaluate_policy(model, env, n_eval_episodes=100) (-49.6, 3.730951621235526)</pre>

## **10. ADVANTAGES & DISADVANTAGES**

### ***10.1 Advantages***

- This model supports more accurate classification of the natural disaster.
- It does highly efficient prediction of the type of disaster due to increased capacity.
- It also supports in finding the level of risk and next mitigated action based on the self-sufficiency model.
- The model will be able to guide in selection of the next action to be performed by the user during occurrence of a disaster.

### ***10.2 Disadvantages***

- The scope of the Reinforcement learning model has to be widened to more number of actions which will happen by test and trials on its own in a longer run.
- In real time there will be more number of special cases which takes time to be handled.

## **11. CONCLUSION**

To tackle the problem of prediction of the classification and risk analysis of occurring Natural Disaster more efficiently , we have developed a multi-layered deep convolutional neural network model that classifies the natural disaster and a reinforcement learning based model that tells the action to be performed based on the intensity of disaster . The model separates the key frames from the video for processing. The deployed CNN model works with an accuracy of 85.4% and the Reinforcement Learning models have lower deviation values ranging from minimum of '0' to maximum of '5'. This model is self –sufficient and can produce more efficient results in a longer run. The predictions has high accuracy rate and this model will be highly useful in real time.

## **12. FUTURE SCOPE**

This model can be used by adding more number of layers to increase the model capacity to classify more number of natural disasters most efficiently. The Reinforcement Model will be self- sufficient and thus will add more number of states and actions and will be able to guide more appropriately. This project can be extended for other natural disaster classifications and become more generic world-wide.

## **13. APPENDIX**

### **13.1 Source Code**

<https://github.com/IBM-EPBL/IBM-Project-18936-1659691440/tree/main/Project/Final%20Deliverables/6.%20Deployment/6.1%20DevOps%20code>

### **13.2 GitHub & Project Demo Link**

<https://github.com/IBM-EPBL/IBM-Project-18936-1659691440>

<https://github.com/IBM-EPBL/IBM-Project-18936-1659691440/tree/main/Project/Final%20Deliverables/1.%20Project%20Report>

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**Links:**

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