PRACTICAL 3

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Roll: 26 Batch: A 2

AIM: Write a program to implement Breadth First Search. Take a graph and start/goal node an input. Your job is to find goal node. **Print the total cost and path**

Code:

```
graph= {
    'Arad': [("Zerind",75),("Timisoara",118),("Sibiu",140)],
    'Bucharest' : [("Urziceni", 85), ("Giurgiu", 90), ("Pitesti", 101), ("Fag
    'Craiova' : [("Dobreta", 120), ("Pitesti", 138), ("RV", 146)],
    'Dobreta': [("Mehadia",75),("Craiova",120)],
    'Eforie' : [("Hirsova", 86)],
    'Fagaras': [("Sibiu",99),("Bucharest",211)],
    'Giurgiu' : [("Bucharest",90)],
    'Lugoj' : [("Mehadia",70),("Timisoara",111)],
    'Mehadia' : [("Lugoj",70),("Dobreta",75)],
    'Neamt' : [("Iasi",87)],
    'Oradea' : [("Zerind",71),("Sibiu",151)],
    'Pitesti' : [("RV", 97), ("Bucharest", 101), ("Craiova", 138)],
    'RV' : [("Sibiu", 80), ("Pitesti", 97), ("Craiova",)],
    'Sibiu': [("RV",80),("Fagaras",99),("Oradea",151),("Arad",140)],
    'Urziceni' : [("Bucharest", 85), ("Hirsova", 98), ("Vaslui", 142)],
    'Vaslui' : [("Iasi",92),("Urziceni",142)],
    'Zerind': [("Oradea",71),("Arad",75)]
que=[]
def path (arr,p):
   que.append(arr[p][0])
   p=arr[p][1]
   if (p! = -1):
     path(arr,p)
   exit()
def route():
 c=len(que)
 cost =0
```

```
while (c>0):
     print(que[c-1])
    for n in graph[que[c-1]]:
     if n[0] == que[c-2]:
        cost=cost+n[1]
     c=c-1
  print("Total cost of path is : ")
  return cost
visited=[]
queue=[]
def bfs(visited, graph, start, end):
 arr=[]
  index=-1
  visited.append(start)
  queue.append(start)
  arr.append([start,index])
  while end not in visited:
    m=queue.pop(0)
    print (m, end = " ")
    index+=1
    for neighbour in graph[m]:
      if neighbour[0] not in visited:
        visited.append(neighbour[0])
        queue.append(neighbour[0])
        arr.append([neighbour[0],index])
  path(arr,len(arr)-1)
  print("\nPath from start to end is : ")
  print(route())
print("Following is the Breadth-
First Search (only till goal node is reached): ")
bfs(visited, graph, 'Arad', 'Bucharest')
```

OUTPUT:

```
Following is the Breadth-First Search (only till goal node is reached):
Arad Zerind Timisoara Sibiu Oradea Lugoj RV Fagaras

Path from start to end is:
Arad
Sibiu
Fagaras
Bucharest

Total cost of path is:
450
```