Time complexity: Classes P and NP 204213 Theory of Computation

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Outline

- Review
- Relationship among models
- The class P
- The class NP

The class NP

Terminology

- worst-case analysis, average-case analysis
- running time, time complexity
- asymptotic notations: big-O, little-O

Time complexity class

Definition

Let $t: \mathcal{N} \to \mathcal{R}^+$ be a function. Define the **time complexity** class, TIME(t(n)), to be the collection of all languages that are decidable by an O(t(n)) time Turing machine.

Multitape TM's and single-tape TM's

Theorem 1

Let t(n) be a function, where $t(n) \ge n$. Then every t(n) time multitape TM has a equivalent $O(t^2(n))$ -time single-tape TM.

Proof (sketch)

• Let M be a k-tape TM. We'll simulate M on a single-tape TM S.

Relationship among models

- The contents of the other tape (not input tape) have total length of O(t(n)). (why?)
- Thus, time to simulate each step in M is O(n) + O(t(n)).
- There are O(t(n)) steps; thus the running time is $O(t(n) \times (n+t(n)) = O(t^2(n))$, since t(n) > n.

Nondeterministic TM's

Definition

The running time of a nondeterministic TM N is a function $f: \mathcal{N} \to \mathcal{N}$, where f(n) is the maximum number of steops that N uses on any branch of its computation on any input of length n.

Nondeterministic TM's

Theorem 2

Let t(n) be a function, where t(n) > n. Then, every t(n)-time nondeterministic TM has an equivalent $2^{O(t(n))}$ -time deterministic TM.

Differences in models

- At most polynomial difference between multi-tape TM's and single-tape TM's.
- At most exponential difference between nondeterministic TM's and deterministic TM's.

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- They also vary a lot. So, it doesn't really make sense to say just "they are equivalence".
- Since there are many models of TM's, can we group them? And how?

- Single-tape deterministic TM's
- Multi-tape deterministic TM's
- Nondeterministic TM's

- Single-tape deterministic TM's
- Multi-tape deterministic TM's
- Nondeterministic TM's
- Real computers

Grouping by relationship of power

- Single-tape deterministic TM's, Multi-tape deterministic TM's and Real computers
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Grouping by relationship of power

- Single-tape deterministic TM's, Multi-tape deterministic TM's and Real computers
- Nondeterministic TM's
 - Consider a brute-force search algorithm. How fast is it?

Definition of class P

Definition

P is the class of languages that are decidable in polynomial time on a deterministic single-tape TM. In other words,

$$P = \bigcup_{k} TIME(n^{k}).$$

Practicality

Are brute-force algorithms practical?

Practicality

Are brute-force algorithms practical? Can we avoid them?

Problems in P: Path

 $PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph } \}$ that has a directed path from s to t }.

Theorem 3

 $PATH \in \mathbf{P}$

Problems in P: Relprime

 $RELPRIME = \{\langle x, y \rangle \mid x \text{ and } y \text{ are relatively prime} \}.$

Theorem 4

 $RELPRIME \in \mathbf{P}$

Search problems

In many cases, we **do not** know how to avoid brute-force search algorithms.

Hamiltonian path

- A Hamiltonian path is a path that goes through each node exacly once.
- Let

$$HAMPATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph} \}$$

that has a directed Hamiltonian path from s to t .

Can you decide HAMPATH quickly?

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 - How fast are those checking procedures?
 - How can they be fast? They just **check!**. They also have hints.

Let's abstract those checking procedures out.

Definition

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Notes

- We call c a certificate.
- For polynomial time verifiers, the certificates can only have polynomial-length (in terms of the length of w).

Definition

NP is the class of languages that have polynomial time verifiers.