

Information theory notes
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- 1 - Basis of Information theory.

Information theory, alongside data compression, have a key role in modern CS. The former defines a set of theoretical tools, usefull to understand the limitations of what is computable; the latter allows to reduce the amount of space required (in terms of bits) without losing information.

- 1.1 - Shannon's Entropy.

When talking about information we all have a general notion of what it represents, but can we define it formally? And also, is there a way to measure information?

The first to answer these questions was *Claude Shannon*, by many considered the father of modern information theory. In [1] Shannon analyzes various communication systems: from the discrete noiceless one to the continous noisy one. A general structure of these systems is shown in *Figure 1*.

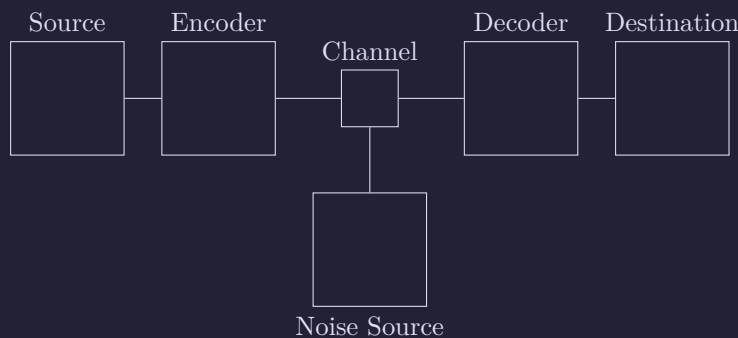


Figure 1: Diagram of a general communication system.

- The *Source* or, more precisely, the *Information Source* refers to some entity (a human, a computer, etc) that produces messages.
- The *Encoder* encodes the messages coming from the source, and transmits them trough the channel. .
- The *channel* is the physical mean trough which the messages are transmitted.
- The *Decoder* has the opposite role of the *Encoder*.
- The *Destination* is the entity to which the messages are meant for.

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Remark. What follows in this section, and the those following, refers just to the discrete noiseless case. We also assume the source to be memoryless, meaning that each symbol produced is independent from the previous one.

Let S be a source of information. Let Σ be the alphabet of symbols used by the source, and for each symbols let $p_i = \Pr(S = \sigma_i)$ at any given time. What we are looking for is some function H , if it exists, that measures the uncertainty we have about S .

As we will show in *Section 1.1.1*, the only form H can assume is the following:

$$H = -K \sum_{i=1}^n p_i \log_b p_i. \quad (1)$$

We define $H(S)$ to be the *entropy* of S . Formally, the entropy measures the average amount of information stored in each symbol of the source output. Thus, we can define the information as the quantity of uncertainty lost, once the outcome of a given event is known.

- 1.1.1 - Entropy: an axiomatic definition.

In *Section 1.1* we said that the only form H can assume is the one in *Equation (1)*. The reason behind this, though one may use different approaches (eg. the connection with the entropy in quantum mechanics), is the way entropy is defined axiomatically.

Axiom. Let H be a measure of uncertainty of a source S , then H must satisfy the following properties.

1. H must be a continuous function of the probabilities. Meaning that if $H(S) = H(p_1, \dots, p_n)$, then H is continuous in $[0, 1]$.
2. $H_2\left(\frac{1}{2}, \frac{1}{2}\right) = 1$.
3. If τ is a permutation of the probabilities, then $H(\tau) = H_n(p_1, \dots, p_n)$. Meaning that, H must not care of the order of the probabilities.
4. If $A(n) = H_n\left(\frac{1}{n}, \dots, \frac{1}{n}\right)$, then H is monotonically increasing. Equally probable events imply greater uncertainty.
5. If a choice can be divided into k consecutive ones, then the original value of H must be the weighted sum of the new H . Meaning that

$$H_n(p_1, \dots, p_n) = H_{n-k+1}(p_1 + \dots + p_k, p_{k+1}, \dots, p_n) \\ + (p_1 + \dots + p_k)H_k\left(\frac{p_1}{p_1 + \dots + p_k}, \dots, \frac{p_k}{p_1 + \dots + p_k}\right).$$

Note. In this context, by event we refer to the symbol produced by the source at a given time.

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Theorem (Theorem 2, [1]). *The only function H that satisfies the above axioms, has the form of Equation (1).*

Proof Let's show how Equation (1) satisfies all the axioms.

1. From axiom 5 we have $A(nm) = A(n) + A(m)$. Let's note in fact that:

$$\begin{aligned} A(nm) &= H_{nm} \left(\frac{1}{nm}, \dots, \frac{1}{nm} \right) \\ &= H_{nm-n+1} \left(\frac{1}{m}, \frac{1}{nm}, \dots, \frac{1}{nm} \right) + \frac{1}{m} H_n \left(\frac{1}{n}, \dots, \frac{1}{n} \right) \\ &\underbrace{= \dots =}_{m \text{ times}} H_{nm-nm+m} \left(\frac{1}{m}, \dots, \frac{1}{m} \right) + H_n \left(\frac{1}{n}, \dots, \frac{1}{n} \right) \\ &= A(m) + A(n). \end{aligned}$$

2. From the previous point, we also have that $A(n^k) = kA(n)$, for any n, k .
3. Let us consider some r big enough such that $\exists k : 2^k \leq n^r < 2^{k+1}$. It follows that

$$k \log_b 2 \leq r \log_b n < (k+1) \log_b 2.$$

Let's divide everything by $r \log_b 2$, we now have

$$\frac{k}{r} \leq \log_2 n < \frac{k+1}{r} \implies \left| \log_2 n - \frac{k}{r} \right| < \frac{1}{r}.$$

From axiom 4 follows $A(2^k) \leq A(n^r) < A(2^{k+1})$, which means that $kA(2) \leq rA(n) < (k+1)A(2)$. From a similar reasoning as before, we get

$$\left| \frac{A(n)}{A(2)} - \frac{k}{r} \right| < \frac{1}{r} \implies A(n) \approx \frac{A(2)}{\log_b 2} \log_b n$$

since $A(n)/A(2) \approx \log_b n$. Thus, $A(n) = c \log_b n$.

4. Suppose $p \in \mathbb{Q} \iff p = \frac{r}{s}, r \leq s$. Then we have

$$\begin{aligned} A(s) &= H_s \left(\frac{1}{s}, \dots, \frac{1}{s} \right) \\ &= H_{s-r+1} \left(\frac{r}{s}, \frac{1}{s}, \dots, \frac{1}{s} \right) + \frac{r}{s} H_r \left(\frac{1}{r}, \dots, \frac{1}{r} \right) \\ &= \dots = H_2 \left(\frac{r}{s}, 1 - \frac{r}{s} \right) + \frac{s-r}{s} A(s-r) + \frac{r}{s} A(s). \end{aligned}$$

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From the previous point, we can conclude that

$$A(n) = -c[(1-p)\log_b(1-p) + p\log_b p].$$

Also, since \mathbb{Q} is dense in \mathbb{R} and H is continuous, we can extend what above to any $p \in \mathbb{R}$.

5. Lastly, Equation (1) can be easily proved by induction on n . ■

The proof we provide is merely a sketch. See [1] (Appendix 2) for a detailed proof.

- 1.2 - Encoding of a source and Sardinas-Patterson algorithm.

Let's now focus our attention onto the source itself. In general, the alphabet these use may not be suitable for transmission, for some reason or another. For this particular reason, a *encoder* is used to convert the source alphabet, to a new one, which is more suitable for transmission. On the receiving side, a *decoder* is used to convert back to the original alphabet. This process is called *source encoding/decoding*.

Formally, given a source S defined on some alphabet, and X a new alphabet, called *input alphabet*, we define a function $C : S \rightarrow X$ that maps sequences of symbols of S to sequences of symbols in X . A sequence of symbols in X is called a *codeword*.

Before we consider specific types of *codes*, let us consider the general case. Let's C be a generic mapping from a source S to some new alphabet X . Since we have not imposed any condition on C , one may define it in such a way that two, or more, source symbols share the same codeword. It is easy to observe that, in doing so, the decoded message may not be correct or even unique.

Example. Let's consider the code shown below. How would we de-

Source	Code
s_1	0
s_2	11
s_3	01
s_4	11

code the text 000111? We have two possibilities: either as $s_1s_1s_3s_2$ or as $s_1s_1s_3s_4$. As said before, the decoded message might not be unique. Also, unless the context is given, there's no way to know which one is correct.

From the above example, we can conclude that a "good" code must encode each source symbol with a unique codeword. We call such codes *non-singular codes*.

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- 1.2.1 - Uniquely decodable codes (UD).

One may think that non-singular codes are enough, but in most cases they are not. In fact, it might happen that a codeword is prefix of another, making the decode process tedious.

Example. Let's consider the following codes. How should we decode

Source	Code
s_1	0
s_2	1
s_3	01
s_4	11

the string 000111? Once again, we have many possibilities: for example $s_1s_1s_3s_2s_2$ or $s_1s_1s_3s_4$. Additionally, unless context is given, we don't know which one is correct.

We say that a code is UD if and only each sequence of codewords corresponds to at most one sequence of source symbols.

From this definition, two questions follow:

- How we construct such codes?
- How can we check whether a given code is UD or not?

The next section focus on the second question, we'll then answer the first.

- 1.2.2 - Sardinas-Patterson algorithm.

The *Sardinas-Patterson* algorithm provides a way to check whether a code C , is UD or not. Conceptually the algorithm, and the theorem from which it derives, are based on the following remark: consider a string that is the concatenation of codewords. If we try to construct two distinct factorization, each word in of the factorization is either part of a word in the other factorization, or it starts with a prefix that is suffix of a word in the other factorization. Hence, a code is non-UD if it happens that a suffix is itself a codeword.

As stated before the algorithm is based on a theorem, given below.

Theorem 1.1. Given C a code on an alphabet Σ , consider the sets S_0, S_1, \dots such that:

- $S_0 = C$
- $S_i = \{\omega \in \Sigma^* | \exists \alpha \in S_0, \exists \beta \in S_{i-1} : \alpha = \beta\omega \vee \beta = \alpha\omega\}$

then necessary and sufficient condition for C to be UD is that, $\forall n > 0, S_0 \cap S_n = \emptyset$.

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Therefore, the algorithm has three halt conditions:

- $\forall i > 0, S_0 \cap S_i \neq \emptyset$ the the code is not UD.
- $\forall i > 0, S_i = \emptyset$ then the code is UD.
- $\forall i, j > 0, S_i = S_j$ then the code is UD.

Example. Let's consider the following code: $C = \{a, c, ad, abb, bad, deb, bbcde\}$. Is it UD? Applying Sardinas-Patterson, step by step we get the following:

Iter 1. Let $\alpha_0 = ab, \alpha_1 = abb$ and $\beta_0 = \beta_1 = a$ then, $S_1 = \{d, bb\}$.

Iter 2. Let $\alpha_0 = deb, \alpha_1 = bbcde$ and $\beta_0 = d, \beta_1 = bb$ then, $S_2 = \{eb, cde\}$.

Iter 3. Let $\alpha_0 = c$ and $\beta = cde$ then, $S_3 = \{de\}$.

Iter 4. Let $\alpha_0 = deb$ and $\beta = de$ then, $S_4 = \{b\}$.

Iter 5. Let $\alpha_0 = bad$ and $\beta = b$ then, $S_5 = \{ad\}$.

From the above steps (summarised in *Table 1*), follows that the code is not UD since $S_0 \cap S_5 = \{ab\} \neq \emptyset$.

S_0	S_1	S_2	S_3	S_4	S_5
a	d	eb			
c					
ad					
abb	bb	cde	de	b	ab
bad					
deb					
bbcde					

Table 1: Steps of Sardinas-Patterson for the code C .

Exercise 1.1. Apply the Sardinas-Patterson algorithm to the following codes:

- $C_0 = \{a, b, cd, abb, abcd\}$
- $C_1 = \{0, 01, 100, 11001, 01011\}$
- $C_2 = \{010, 0001, 0110, 11000, 00011, 00110, 11110, 101011\}$

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- 1.2.3 - Prefix codes.

Let's look back at the example of *Section 1.2.1*. Given the codewords $\{0, 1, 01, 11\}$ for the source symbol s_1, s_2, s_3, s_4 respectively, how should we decode the string 000111? As said before, unless some context is given, we can't be sure.

Then what's the issue? Essentially, even though to each source symbol is assigned a distinct codeword, these are not prefix-free, meaning that some of the codewords are prefix of others (eg. the codeword for s_1 is prefix of the codeword for s_3). From what just stated, a natural solution to the problem is to define codes that are prefix-free. One can also prove that, prefix-free (or simply prefix) codes are also instantaneous (each source symbol can be decoded without reading further in the string).

Theorem. Let C be a prefix-free code, then C is UD.

Proof It follows from *Theorem 1.1*. ■

Section 1 - REFERENCES

References

- [1] Claude Shannon. “A Mathematical Theory of Communication”. In: *Bell System Technical Journal* 27 (1948).

Section 1 - Acronyms

Acronyms

UD uniquely decodable codes. 6–8