# Dijkstra's Algorithm with Time Complexity Analysis

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Algorithm 1 Dijkstra(G, w, s)
 1: Input: Graph G = (V, E), weight function w, source vertex s
 2: Output: Shortest path distances d[v] for all v \in V
 3: function Initialize-Single-Source(G, s)
        for all v \in V do
             d[v] \leftarrow \infty
                                                                                          ▶ Set initial distances to infinity
 5:
             \pi[v] \leftarrow \text{NIL}
                                                                                                         ▷ No predecessor yet
 6:
 7:
        end for
        d[s] \leftarrow 0
                                                                                           ▷ Distance to the source is zero
 9: end function
10: Initialize-Single-Source(G, s)
                                                                                                                          \triangleright \mathcal{O}(V)
11: S \leftarrow \emptyset
                                                                      ▷ Set of vertices whose shortest paths are found
12: Q \leftarrow \emptyset
                                                                                                              ▶ Priority queue
13: for all u \in V do
        Insert u into Q with key d[u]
                                                                                              \triangleright \mathcal{O}(\log V) for each insertion
15: end for
16: while Q \neq \emptyset do
        u \leftarrow \text{Extract-Min}(Q)
                                                                                                                     \triangleright \mathcal{O}(\log V)
17:
        S \leftarrow S \cup \{u\}
18:
19:
        for all v \in G.Adj[u] do
                                                                                               \triangleright Iterate over neighbors of u
             Relax(u, v, w)
20:
             if Relax decreases d[v] then
21:
                 Decrease-Key(Q, v, d[v])
                                                                                                                     \triangleright \mathcal{O}(\log V)
22:
             end if
23:
        end for
25: end while
```

## **Functions Used**

 $\mathbf{Relax}(u, v, w)$ :

- **Description:** Updates d[v] and  $\pi[v]$  if a shorter path to v is found via u.
- Steps:

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- If d[v] > d[u] + w(u, v), set d[v] = d[u] + w(u, v) and \pi[v] = u.
```

• Time Complexity:  $\mathcal{O}(1)$  per edge.

## Extract-Min(Q):

- Description: Retrieves and removes the vertex with the smallest key from the priority queue.
- Time Complexity:  $\mathcal{O}(\log V)$  using a binary heap.

## Decrease-Key(Q, v, d[v]):

- **Description:** Updates the key of vertex v in the priority queue to d[v].
- Time Complexity:  $\mathcal{O}(\log V)$  using a binary heap.

## Time Complexity Analysis

- 1. Initialization (Lines 1–5):
  - Initialize-Single-Source takes  $\mathcal{O}(V)$ .
  - Inserting all vertices into the priority queue takes  $\mathcal{O}(V \log V)$ .

# 2. Main Loop (Lines 6-12):

- ullet The while loop runs at most |V| times since each vertex is extracted once.
- Extract-Min takes  $\mathcal{O}(\log V)$  per iteration, so total  $\mathcal{O}(V \log V)$ .
- For each vertex u, relaxing all adjacent edges involves  $\mathcal{O}(\log V)$  for each Decrease-Key operation. Over all vertices, this sums to  $\mathcal{O}(E\log V)$ .

# Overall Time Complexity:

$$\mathcal{O}(V \log V + E \log V) = \mathcal{O}((V + E) \log V)$$

**Note:** In a connected graph,  $E \ge V - 1$ , so this simplifies to  $\mathcal{O}(E \log V)$ .