

1. Description

1.1. Project

Project Name	2024.02
Board Name	NUCLEO-F746ZG
Generated with:	STM32CubeMX 6.10.0
Date	02/25/2024

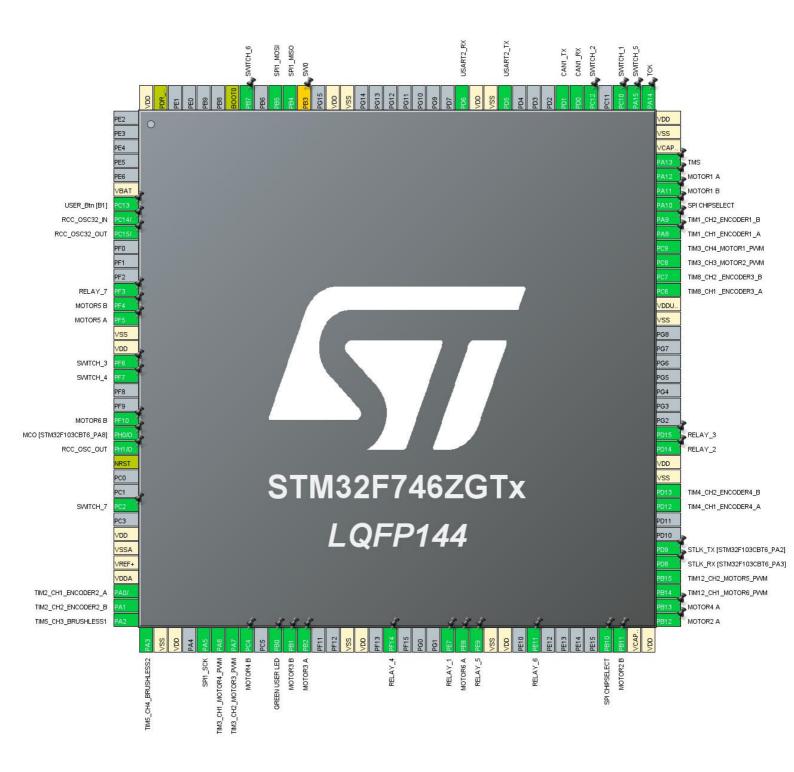
1.2. MCU

MCU Series	STM32F7
MCU Line	STM32F7x6
MCU name	STM32F746ZGTx
MCU Package	LQFP144
MCU Pin number	144

1.3. Core(s) information

Core(s)	Arm Cortex-M7

2. Pinout Configuration



3. Pins Configuration

Pin Number	Pin Name	Pin Type	Alternate	Label
LQFP144	(function after		Function(s)	
	reset)		、 /	
6	VBAT	Power		
7	PC13	I/O	GPIO_EXTI13	USER_Btn [B1]
8	PC14/OSC32_IN	I/O	RCC_OSC32_IN	
9	PC15/OSC32_OUT	I/O	RCC_OSC32_OUT	
13	PF3 *	I/O	GPIO_Output	RELAY_7
14	PF4 *	I/O	GPIO_Output	MOTOR5 B
15	PF5 *	I/O	GPIO_Output	MOTOR5 A
16	VSS	Power		
17	VDD	Power		
18	PF6 *	I/O	GPIO_Input	SWITCH_3
19	PF7 *	I/O	GPIO_Input	SWITCH_4
22	PF10 *	I/O	GPIO_Output	MOTOR6 B
23	PH0/OSC_IN	I/O	RCC_OSC_IN	MCO [STM32F103CBT6_PA8]
24	PH1/OSC_OUT	I/O	RCC_OSC_OUT	
25	NRST	Reset		
28	PC2 *	I/O	GPIO_Input	SWITCH_7
30	VDD	Power		
31	VSSA	Power		
32	VREF+	Power		
33	VDDA	Power		
34	PA0/WKUP	I/O	TIM2_CH1	TIM2_CH1_ENCODER2_A
35	PA1	I/O	TIM2_CH2	TIM2_CH2_ENCODER2_B
36	PA2	I/O	TIM5_CH3	TIM5_CH3_BRUSHLESS1
37	PA3	I/O	TIM5_CH4	TIM5_CH4_BRUSHLESS2
38	VSS	Power		
39	VDD	Power		
41	PA5	I/O	SPI1_SCK	
42	PA6	I/O	TIM3_CH1	TIM3_CH1_MOTOR4_PWM
43	PA7	I/O	TIM3_CH2	TIM3_CH2_MOTOR3_PWM
44	PC4 *	I/O	GPIO_Output	MOTOR4 B
46	PB0 *	I/O	GPIO_Output	GREEN USER LED
47	PB1 *	I/O	GPIO_Output	MOTOR3 B
48	PB2 *	I/O	GPIO_Output	MOTOR3 A
51	VSS	Power		
52	VDD	Power		

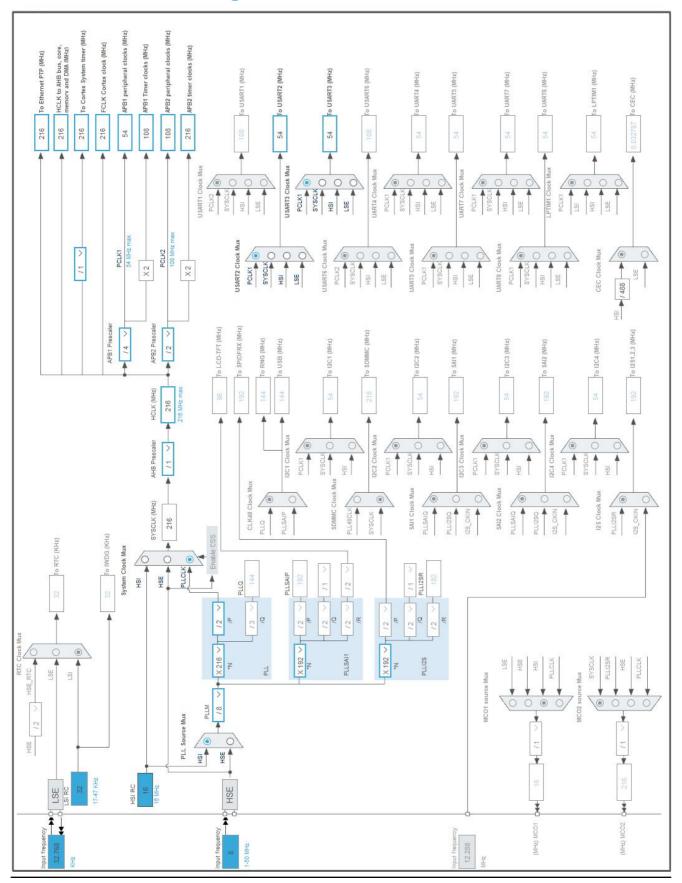
Pin Number	Pin Name	Pin Type	Alternate	Label
LQFP144	(function after		Function(s)	
	reset)			
54	PF14 *	I/O	GPIO_Output	RELAY_4
58	PE7 *	I/O	GPIO_Output	RELAY_1
59	PE8 *	I/O	GPIO_Output	MOTOR6 A
60	PE9 *	I/O	GPIO_Output	RELAY_5
61	VSS	Power		
62	VDD	Power		
64	PE11 *	I/O	GPIO_Output	RELAY_6
69	PB10 *	I/O	GPIO_Output	SPI CHIPSELECT
70	PB11 *	I/O	GPIO_Output	MOTOR2 B
71	VCAP_1	Power		
72	VDD	Power		
73	PB12 *	I/O	GPIO_Output	MOTOR2 A
74	PB13 *	I/O	GPIO_Output	MOTOR4 A
75	PB14	I/O	TIM12_CH1	TIM12_CH1_MOTOR6_PW M
76	PB15	I/O	TIM12_CH2	TIM12_CH2_MOTOR5_PW M
77	PD8	I/O	USART3_TX	STLK_RX [STM32F103CBT6_PA3]
78	PD9	I/O	USART3_RX	STLK_TX [STM32F103CBT6_PA2]
81	PD12	I/O	TIM4_CH1	TIM4_CH1_ENCODER4_A
82	PD13	I/O	TIM4_CH2	TIM4_CH2_ENCODER4_B
83	VSS	Power		
84	VDD	Power		
85	PD14 *	I/O	GPIO_Output	RELAY_2
86	PD15 *	I/O	GPIO_Output	RELAY_3
94	VSS	Power		
95	VDDUSB	Power		
96	PC6	I/O	TIM8_CH1	TIM8_CH1 _ENCODER3_A
97	PC7	I/O	TIM8_CH2	TIM8_CH2 _ENCODER3_B
98	PC8	I/O	TIM3_CH3	TIM3_CH3_MOTOR2_PWM
99	PC9	I/O	TIM3_CH4	TIM3_CH4_MOTOR1_PWM
100	PA8	I/O	TIM1_CH1	TIM1_CH1_ENCODER1_A
101	PA9	I/O	TIM1_CH2	TIM1_CH2_ENCODER1_B
102	PA10 *	I/O	GPIO_Output	SPI CHIPSELECT
103	PA11 *	I/O	GPIO_Output	MOTOR1 B
104	PA12 *	I/O	GPIO_Output	MOTOR1 A
105	PA13	I/O	SYS_JTMS-SWDIO	TMS
106	VCAP_2	Power		

Pin Number LQFP144	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
107	VSS	Power		
108	VDD	Power		
109	PA14	I/O	SYS_JTCK-SWCLK	TCK
110	PA15 *	I/O	GPIO_Input	SWITCH_5
111	PC10 *	I/O	GPIO_Input	SWITCH_1
113	PC12 *	I/O	GPIO_Input	SWITCH_2
114	PD0	I/O	CAN1_RX	
115	PD1	I/O	CAN1_TX	
119	PD5	I/O	USART2_TX	
120	VSS	Power		
121	VDD	Power		
122	PD6	I/O	USART2_RX	
130	VSS	Power		
131	VDD	Power		
133	PB3 **	I/O	SYS_JTDO-SWO	SW0
134	PB4	I/O	SPI1_MISO	
135	PB5	I/O	SPI1_MOSI	
137	PB7 *	I/O	GPIO_Input	SWITCH_6
138	воото	Boot		
143	PDR_ON	Reset		
144	VDD	Power		

^{*} The pin is affected with an I/O function

^{**} The pin is affected with a peripheral function but no peripheral mode is activated

4. Clock Tree Configuration



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5. Software Project

5.1. Project Settings

Name	Value
Project Name	2024.02.24 manual robot code
Project Folder	C:\Users\urtna\STM32CubeIDE\workspace_1.14.0\2024.02.24 manual robot
Toolchain / IDE	STM32CubeIDE
Firmware Package Name and Version	STM32Cube FW_F7 V1.17.1
Application Structure	Advanced
Generate Under Root	Yes
Do not generate the main()	No
Minimum Heap Size	0x200
Minimum Stack Size	0x400

5.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	No
Backup previously generated files when re-generating	No
Keep User Code when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power	No
consumption)	
Enable Full Assert	No

5.3. Advanced Settings - Generated Function Calls

Rank	Function Name	Peripheral Instance Name
1	SystemClock_Config	RCC
2	MX_GPIO_Init	GPIO
3	MX_DMA_Init	DMA
4	MX_CAN1_Init	CAN1
5	MX_TIM1_Init	TIM1
6	MX_TIM2_Init	TIM2
7	MX_TIM4_Init	TIM4
8	MX_TIM5_Init	TIM5
9	MX_TIM8_Init	TIM8
10	MX_TIM12_Init	TIM12
11	MX_USART3_UART_Init	USART3

Rank	Function Name	Peripheral Instance Name
12	MX_SPI1_Init	SPI1
13	MX_USART2_UART_Init	USART2
14	MX_TIM6_Init	TIM6
15	MX_TIM3_Init	TIM3

1. Power Consumption Calculator report

1.1. Microcontroller Selection

Series	STM32F7
Line	STM32F7x6
мси	STM32F746ZGTx
Datasheet	DS10916_Rev4

1.2. Parameter Selection

Temperature	25
Vdd	3.3

1.3. Battery Selection

Battery	Alkaline(9V)
Capacity	625.0 mAh
Self Discharge	0.3 %/month
Nominal Voltage	9.0 V
Max Cont Current	200.0 mA
Max Pulse Current	0.0 mA
Cells in series	1
Cells in parallel	1

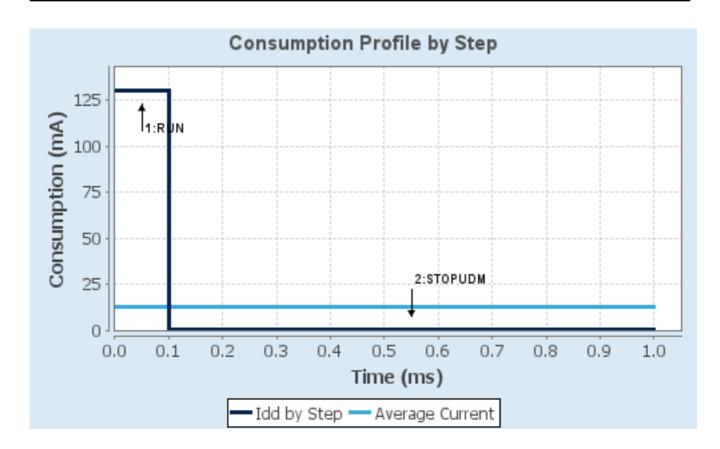
1.4. Sequence

Ston	Cton4	Ston 2
Step	Step1	Step2
Mode	RUN	STOP UDM (Under Drive)
Vdd	3.3	3.3
Voltage Source	Battery	Battery
Range	Scale1-High	No Scale
Fetch Type	ITCM/FLASH/REGON	n/a
CPU Frequency	216 MHz	0 Hz
Clock Configuration	HSE PLL	Regulator LP Flash-PwrDwn
Clock Source Frequency	4 MHz	0 Hz
Peripherals		
Additional Cons.	0 mA	0 mA
Average Current	130 mA	100 μΑ
Duration	0.1 ms	0.9 ms
DMIPS	462.0	0.0
Ta Max	87.84	104.99
Category	In DS Table	In DS Table

1.5. Results

Sequence Time	1 ms	Average Current	13.09 mA
Battery Life	1 day, 23 hours	Average DMIPS	462.24005
			DMIPS

1.6. Chart



2. Peripherals and Middlewares Configuration

2.1. CAN1

mode: Activated

2.1.1. Parameter Settings:

Bit Timings Parameters:

Prescaler (for Time Quantum) 16

Time Quantum 296.2962962963 *

Time Quanta in Bit Segment 1 1 Time
Time Quanta in Bit Segment 2 1 Time
Time for one Bit 888 *

Baud Rate 1125000 *

ReSynchronization Jump Width 1 Time

Basic Parameters:

Time Triggered Communication Mode

Automatic Bus-Off Management

Disable

Automatic Wake-Up Mode

Disable

Automatic Retransmission

Disable

Receive Fifo Locked Mode

Disable

Transmit Fifo Priority

Disable

Advanced Parameters:

Operating Mode Normal

2.2. RCC

High Speed Clock (HSE): BYPASS Clock Source

Low Speed Clock (LSE): Crystal/Ceramic Resonator

2.2.1. Parameter Settings:

System Parameters:

VDD voltage (V) 3.3

Flash Latency(WS) 7 WS (8 CPU cycle)

RCC Parameters:

HSI Calibration Value 16

TIM Prescaler Selection Disabled

HSE Startup Timout Value (ms) 100

LSE Startup Timout Value (ms) 5000

Power Parameters:

Power Over Drive Enabled

Power Regulator Voltage Scale Power Regulator Voltage Scale 1

2.3. SPI1

Mode: Full-Duplex Master

2.3.1. Parameter Settings:

Basic Parameters:

Frame Format Motorola

Data Size 8 Bits *

First Bit LSB First *

Clock Parameters:

Prescaler (for Baud Rate) 128 *

Baud Rate 843.75 KBits/s *

Clock Polarity (CPOL) High *
Clock Phase (CPHA) 2 Edge *

Advanced Parameters:

CRC Calculation Disabled NSS Signal Type Software

2.4. SYS

Debug: Serial Wire

Timebase Source: SysTick

2.5. TIM1

Combined Channels: Encoder Mode

2.5.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 0
Counter Mode Up
Counter Period (AutoReload Register - 16 bits value) 65535
Internal Clock Division (CKD) No Division

Repetition Counter (RCR - 16 bits value) 0

auto-reload preload Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)
Trigger Event Selection TRGO2	Reset (UG bit from TIMx_EGR)
Encoder:	
Encoder Mode	Encoder Mode TI1 and TI2 *
Parameters for Channel 1	
Polarity	Falling Edge *
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
Parameters for Channel 2	
Polarity	Falling Edge *
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
2.6. TIM2	
Combined Channels: Encoder Mo	da
	ue
2.6.1. Parameter Settings:	
Counter Settings:	
Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value)	65535 *
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable
Trigger Output (TRGO) Parameters:	Disable
Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)
Encoder:	Trease (OG Sit Holli Think_EGIV)
Encoder Mode	5 1
	Encoder Mode TI1 and TI2 *
Parameters for Channel 1	
Polarity	Falling Edge *
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
Parameters for Channel 2	
Polarity	Falling Edge *
IC Selection	Direct

Prescaler Division Ratio No division

Input Filter 0

2.7. TIM3

Channel1: PWM Generation CH1 Channel2: PWM Generation CH2 Channel3: PWM Generation CH3 Channel4: PWM Generation CH4

2.7.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)

Counter Mode

Counter Period (AutoReload Register - 16 bits value)

Internal Clock Division (CKD)

auto-reload preload

1686 *

Up

127 *

No Division

Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit) Disable (Trigger input effect not delayed)

Trigger Event Selection TRGO Reset (UG bit from TIMx_EGR)

PWM Generation Channel 1:

Mode PWM mode 1

Pulse (16 bits value) 0

Output compare preload Enable
Fast Mode Disable
CH Polarity High

PWM Generation Channel 2:

Mode PWM mode 1

Pulse (16 bits value) 0
Output compare preload Enable
Fast Mode Disable
CH Polarity High

PWM Generation Channel 3:

Mode PWM mode 1

Pulse (16 bits value) 0

Output compare preload Enable

Fast Mode Disable

CH Polarity High

PWM Generation Channel 4:

Mode PWM mode 1

Pulse (16 bits value) 0

Output compare preload Enable
Fast Mode Disable
CH Polarity High

2.8. TIM4

Combined Channels: Encoder Mode

2.8.1. Parameter Settings:

Counter Settings:	
Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	65535
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable
Trigger Output (TRGO) Parameters:	
Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)
Encoder:	
Encoder Mode	Encoder Mode TI1 and TI2 *
Parameters for Channel 1	
Polarity	Falling Edge *
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
Parameters for Channel 2	
Polarity	Falling Edge *
IC Selection	Direct
Prescaler Division Ratio	No division

0

2.9. TIM5

Input Filter

Channel3: PWM Generation CH3 Channel4: PWM Generation CH4

2.9.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 21600-1 *

Counter Mode Up

Counter Period (AutoReload Register - 32 bits value) 100-1 *

Internal Clock Division (CKD) No Division auto-reload preload Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit) Disable (Trigger input effect not delayed)

Trigger Event Selection TRGO Reset (UG bit from TIMx_EGR)

PWM Generation Channel 3:

Mode PWM mode 1

Pulse (32 bits value) 0
Output compare preload Enable

Fast Mode Disable CH Polarity High

PWM Generation Channel 4:

Mode PWM mode 1

Pulse (32 bits value) 0

Output compare preload Enable

Fast Mode Disable

CH Polarity High

2.10. TIM6

mode: Activated

2.10.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 1000-1 *

Counter Mode Up

Counter Period (AutoReload Register - 16 bits value) 840-1 *

auto-reload preload Disable

Trigger Output (TRGO) Parameters:

Trigger Event Selection Reset (UG bit from TIMx_EGR)

2.11. TIM8

Combined Channels: Encoder Mode

2.11.1. Parameter Settings:

Counter Settings:	
Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	65535
Internal Clock Division (CKD)	No Division
Repetition Counter (RCR - 16 bits value)	0
auto-reload preload	Disable
Trigger Output (TRGO) Parameters:	
Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)
Trigger Event Selection TRGO2	Reset (UG bit from TIMx_EGR)
Encoder:	
Encoder Mode	Encoder Mode TI1 and TI2 *
Parameters for Channel 1	
Polarity	Falling Edge *
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
Parameters for Channel 2	
Polarity	Falling Edge *
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
2.12. TIM12	
Channel1: PWM Generation CH1	
Channel2: PWM Generation CH2	
2.12.1. Parameter Settings:	
Countar Sattings	
Counter Settings:	
Prescaler (PSC - 16 bits value)	1686 *
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value)	127 *
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

PWM Generation Channel 1:

Mode

PWM mode 1

Pulse (16 bits value) 0

Output compare preload Enable

Fast Mode Disable

CH Polarity High

PWM Generation Channel 2:

Mode PWM mode 1

Pulse (16 bits value) 0

Output compare preload Enable

Fast Mode Disable

CH Polarity High

2.13. USART2

Mode: Asynchronous

2.13.1. Parameter Settings:

Basic Parameters:

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

Advanced Parameters:

Data Direction Receive and Transmit

Over Sampling 16 Samples
Single Sample Disable

Advanced Features:

Auto Baudrate Disable TX Pin Active Level Inversion Disable **RX Pin Active Level Inversion** Disable Disable **Data Inversion** TX and RX Pins Swapping Disable Overrun Enable Enable DMA on RX Error MSB First Disable

2.14. USART3

Mode: Asynchronous

2.14.1. Parameter Settings:

Basic Parameters:

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

Advanced Parameters:

Data Direction Receive and Transmit

Over Sampling 16 Samples
Single Sample Disable

Advanced Features:

Auto Baudrate Disable TX Pin Active Level Inversion Disable Disable **RX Pin Active Level Inversion** Data Inversion Disable TX and RX Pins Swapping Disable Enable Overrun DMA on RX Error Enable MSB First Disable

* User modified value

3. System Configuration

3.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
CAN1	PD0	CAN1_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
	PD1	CAN1_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
RCC	PC14/OSC3 2_IN	RCC_OSC32_IN	n/a	n/a	n/a	
	PC15/OSC3 2_OUT	RCC_OSC32_O UT	n/a	n/a	n/a	
	PH0/OSC_I N	RCC_OSC_IN	n/a	n/a	n/a	MCO [STM32F103CBT6_PA8]
	PH1/OSC_O UT	RCC_OSC_OUT	n/a	n/a	n/a	
SPI1	PA5	SPI1_SCK	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
	PB4	SPI1_MISO	Alternate Function Push Pull	Pull-up *	Very High	
	PB5	SPI1_MOSI	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
SYS	PA13	SYS_JTMS- SWDIO	n/a	n/a	n/a	TMS
	PA14	SYS_JTCK- SWCLK	n/a	n/a	n/a	TCK
TIM1	PA8	TIM1_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM1_CH1_ENCODER1_ A
	PA9	TIM1_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM1_CH2_ENCODER1_ B
TIM2	PA0/WKUP	TIM2_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM2_CH1_ENCODER2_ A
	PA1	TIM2_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM2_CH2_ENCODER2_ B
TIM3	PA6	TIM3_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM3_CH1_MOTOR4_PW M
	PA7	TIM3_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM3_CH2_MOTOR3_PW M
	PC8	TIM3_CH3	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM3_CH3_MOTOR2_PW M
	PC9	TIM3_CH4	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM3_CH4_MOTOR1_PW M

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
TIM4	PD12	TIM4_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM4_CH1_ENCODER4_ A
	PD13	TIM4_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM4_CH2_ENCODER4_ B
TIM5	PA2	TIM5_CH3	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM5_CH3_BRUSHLESS1
	PA3	TIM5_CH4	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM5_CH4_BRUSHLESS2
TIM8	PC6	TIM8_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM8_CH1 _ENCODER3_A
	PC7	TIM8_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM8_CH2 _ENCODER3_B
TIM12	PB14	TIM12_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM12_CH1_MOTOR6_P WM
	PB15	TIM12_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	TIM12_CH2_MOTOR5_P WM
USART2	PD5	USART2_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
	PD6	USART2_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
USART3	PD8	USART3_TX	Alternate Function Push Pull	Pull-up *	Very High	STLK_RX [STM32F103CBT6_PA3]
	PD9	USART3_RX	Alternate Function Push Pull	Pull-up *	Very High	STLK_TX [STM32F103CBT6_PA2]
Single Mapped Signals	PB3	SYS_JTDO- SWO	n/a	n/a	n/a	SW0
GPIO	PC13	GPIO_EXTI13	External Interrupt Mode with Rising edge trigger detection	No pull-up and no pull-down	n/a	USER_Btn [B1]
	PF3	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	RELAY_7
	PF4	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR5 B
	PF5	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR5 A
	PF6	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	SWITCH_3
	PF7	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	SWITCH_4
	PF10	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR6 B
	PC2	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	SWITCH_7
	PC4	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR4 B
	PB0	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	GREEN USER LED
	PB1	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR3 B
	PB2	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR3 A
	PF14	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	RELAY_4
	PE7	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	RELAY_1
	PE8	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR6 A

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
	PE9	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	RELAY_5
	PE11	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	RELAY_6
	PB10	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	SPI CHIPSELECT
	PB11	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR2 B
	PB12	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR2 A
	PB13	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR4 A
	PD14	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	RELAY_2
	PD15	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	RELAY_3
	PA10	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	SPI CHIPSELECT
	PA11	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR1 B
	PA12	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR1 A
	PA15	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	SWITCH_5
	PC10	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	SWITCH_1
	PC12	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	SWITCH_2
	PB7	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	SWITCH_6

3.2. DMA configuration

DMA request	Stream	Direction	Priority
USART3_RX	DMA1_Stream1	Peripheral To Memory	High *
USART3_TX	DMA1_Stream3	Memory To Peripheral	High *
USART2_RX	DMA1_Stream5	Peripheral To Memory	High *
USART2_TX	DMA1_Stream6	Memory To Peripheral	High *

USART3_RX: DMA1_Stream1 DMA request Settings:

Mode: Circular *
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable *
Peripheral Data Width: Byte
Memory Data Width: Byte

USART3_TX: DMA1_Stream3 DMA request Settings:

Mode: Normal
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable *
Peripheral Data Width: Byte

Peripheral Data Width: Byte Memory Data Width: Byte

USART2_RX: DMA1_Stream5 DMA request Settings:

Mode: Circular *
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable *
Peripheral Data Width: Byte
Memory Data Width: Byte

USART2_TX: DMA1_Stream6 DMA request Settings:

Mode: Normal

Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable *

Peripheral Data Width: Byte
Memory Data Width: Byte

3.3. NVIC configuration

3.3.1. NVIC

Interrupt Table	Enable	Preenmption Priority	SubPriority	
Non maskable interrupt	true	0	0	
Hard fault interrupt	true	0	0	
Memory management fault	true	0	0	
Pre-fetch fault, memory access fault	true	0	0	
Undefined instruction or illegal state	true	0	0	
System service call via SWI instruction	true	0	0	
Debug monitor	true	0	0	
Pendable request for system service	true	0	0	
System tick timer	true	0	0	
DMA1 stream1 global interrupt	true	0	0	
DMA1 stream3 global interrupt	true	0	0	
DMA1 stream5 global interrupt	true	0	0	
DMA1 stream6 global interrupt	true	0	0	
TIM1 capture compare interrupt	true	0	0	
TIM2 global interrupt	true	0	0	
TIM4 global interrupt	true	0	0	
USART2 global interrupt	true	0	0	
USART3 global interrupt	true	0	0	
TIM6 global interrupt, DAC1 and DAC2 underrun error interrupts	true	0	0	
PVD interrupt through EXTI line 16	unused			
Flash global interrupt	unused			
RCC global interrupt		unused		
CAN1 TX interrupts		unused		
CAN1 RX0 interrupts		unused		
CAN1 RX1 interrupt		unused		
CAN1 SCE interrupt		unused		
TIM1 break interrupt and TIM9 global interrupt		unused		
TIM1 update interrupt and TIM10 global interrupt	unused			
TIM1 trigger and commutation interrupts and TIM11 global interrupt	unused			
TIM3 global interrupt	unused			
SPI1 global interrupt	unused			
EXTI line[15:10] interrupts	unused			
TIM8 break interrupt and TIM12 global interrupt				
TIM8 update interrupt and TIM13 global interrupt	unused			
TIM8 trigger and commutation interrupts and		unused		

Interrupt Table	Enable	Preenmption Priority	SubPriority
TIM14 global interrupt			
TIM8 capture compare interrupt		unused	
TIM5 global interrupt		unused	
FPU global interrupt		unused	

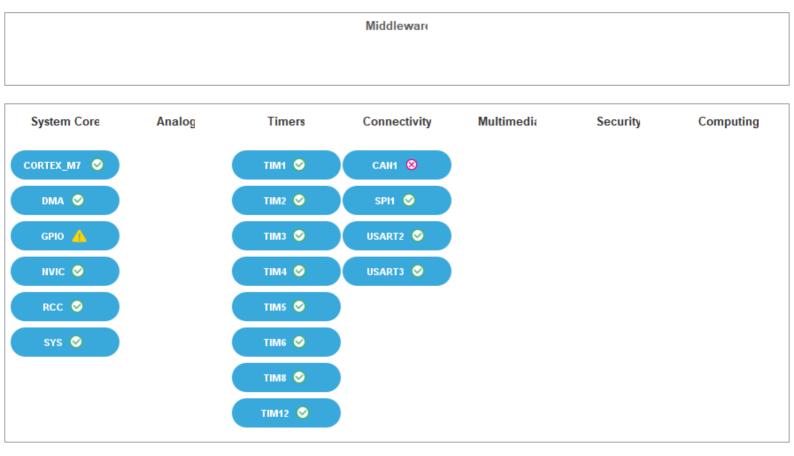
3.3.2. NVIC Code generation

Enabled interrupt Table	Select for init sequence ordering	Generate IRQ handler	Call HAL handler
Non maskable interrupt	false	true	false
Hard fault interrupt	false	true	false
Memory management fault	false	true	false
Pre-fetch fault, memory access fault	false	true	false
Undefined instruction or illegal state	false	true	false
System service call via SWI instruction	false	true	false
Debug monitor	false	true	false
Pendable request for system service	false	true	false
System tick timer	false	true	true
DMA1 stream1 global interrupt	false	true	true
DMA1 stream3 global interrupt	false	true	true
DMA1 stream5 global interrupt	false	true	true
DMA1 stream6 global interrupt	false	true	true
TIM1 capture compare interrupt	false	true	true
TIM2 global interrupt	false	true	true
TIM4 global interrupt	false	true	true
USART2 global interrupt	false	true	true
USART3 global interrupt	false	true	true
TIM6 global interrupt, DAC1 and DAC2 underrun error interrupts	false	true	true

^{*} User modified value

4. System Views

- 4.1. Category view
- 4.1.1. Current



5. Docs & Resources

Type Link

BSDL files https://www.st.com/resource/en/bsdl_model/stm32f7_bsdl.zip

IBIS models https://www.st.com/resource/en/ibis_model/stm32f7_ibis.zip

System View https://www.st.com/resource/en/svd/stm32f7-svd.zip

Description

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