Write a simple function in MATLAB, with the name  $cflip\_bee()$  that implements circular flipping of an input array x.

Check your function for different lengths of input and values of N.

#### **SOLUTION TASK 1:**

# Required Code:

```
function y = cflip_bee(x,N)
x=[1,2,3,4];
N=6;
%where x = input array
% N = the number of points for circular flipping (DFT points)
%y = output that should be Modulo N circularly flipped version of x
if(N>length(x))
    x1 = [x, zeros(1, N-length(x))];
end

y = [x1(1), x1(length(x1):-1:2)];
return y;
```

# REQUIRED OUTPUTS:

```
Example I
>> z=cflip_bee([1,2,3,4,6,7,4],2)

z =

1  0  0  4  3  2

Example 2
>> z=cflip_bee([1,2,3,4],6)
|
z =

1  0  0  4  3  2
```

# Implementation of Circular Shifting

Write a function in MATLAB, with the name  $cshift\_bee()$  that implements circular shifting of an input array x. The format of the function should be

```
REQUIRED CODE:
function y = cshift_bee(x,r,N)
x1=x
if(N>length(x))

x1 = [x, zeros(1, N-length(x))];
end
if (r<=0)
y = [x1((length(x1)+r+1):length(x1)), x1(1:(length(x1)+r))];
else
y = [x1(r+1:length(x1)), x1(1:r)];
end</pre>
```

Verify your result for different values of x, r, and N.

# Implementation of Circular Convolution

Write a function in MATLAB, with the name  $cconv\_bee()$  that implements circular convolution of an input array x with an array h.

The format of the function should be

Required Code:

```
function y = cconv bee(x,h,N)
%where x, h = input arrays
% N = the number of DFT points
%y = N point output of circular convolution
if(N>length(x))
x = [x, zeros(1, N-length(x))]
end
if(N>length(h))
h = [h, zeros(1, N-length(h))]
%h will remain intact and make matrix of impulse h
end
flippled h=cflip bee(h,N)
flipped matrix=zeros(N,N)
for i=\overline{0}:N-1
     temp vector=cshift bee(flippled h,-i,N)
     flipped_matrix(i+1,:) = temp_vector
 end
 %now time for matrix multiplication
my result=transpose(flipped matrix*transpose(x))
% cconv bee([1,1,1,1,1,1],[1,1,1,1,1,1,1],11]
end
```

#### **OUTPUTS**:

Test your result on some values of x, h and N and compare your results with the MATLAB built-in function cconv().

```
>> cconv_bee([1,1,1],[1,1,1],5)
my_result =
             3 2 1
        2
>> conv([1,1,1],[1,1,1])
ans =
    1
      2 3 2
>>
2<sup>nd</sup> Example
>> cconv_bee([1,2,1],[1,0,1],5)
my result =
      2 2 2 1
>> conv([1,2,1],[1,0,1])
ans =
      2 2 2 1
```

**a.** Write a code for implementing Overlap and Add Method.

## REQUIRED CODE

```
function y = add_method_conv(x,h,L)
%x input signal
%h filter signal (impulse response)
%L chunks size of x divisions into smaller inpu signals
step one --> finding individual outputs of chunks of x[n]
remainder=mod(x, L)
if remainder==0
   total\_chunks=length(x)/L
   last fraction=0
   total\_chunks=floor(length(x)/L)+1
   last_fraction=1
total chunks
my chunks array=zeros(total chunks,L)
for i=0:total_chunks-1
   if(i==total chunks-1 && last fraction==1)
       %means last chunk needs padding
        disp('camehere')
       temp single chunk=[x(i*L+1:length(x)),zeros(1,L-length(x(i*L+1:length(x))))];
```

```
my_chunks_array(i+1,:)=temp_single_chunk;
    else
        temp single chunk=x(i*L+1:i*L+L);
        my_chunks_array(i+1,:)=temp_single_chunk;
         disp('camehere')
    end
end
%now next step , we will convolving each chunk with the filter's response
chunks convolved matrix=zeros(total chunks, L+length(h)-1)
for i=1:total_chunks
    single chunk convolved=cconv bee(my chunks array(i,:),h,L+length(h)-1);
    chunks convolved matrix(i,:)=single chunk convolved;
end
chunks convolved matrix
%now last step, adding all the outputs together
final ans=[]
for i=1:total chunks
   if i==1
        final ans=chunks convolved matrix(i,:);
   else
        temp=chunks convolved matrix(i,:)
        temp common points addition=final ans(length(final ans)-
length(h) +2:length(final ans)) + temp(1:length(h) -1)
        final_ans=[final_ans(1:length(final_ans)-
length(h)+1), temp common points addition, temp(length(h):length(temp))]
    end
   final ans
end
```

## **REQUIRED OUTPUTS:**

```
>> add_method_conv([1,2,3,4,5,6,2,3],[5,4,2,1],2)
final ans =
    5
         14
              25
                    37
                                    48
                                          40
                                               22
                                                      8
                                                           3
                         49
                            61
                                                                0
                                                                      0
>> conv([1,2,3,4,5,6,2,3],[5,4,2,1])
ans =
    5
         14
            25
                 37 49
                               61
                                    48
                                          40
                                               22
                                                           3
```

# **b.** Write a code for implementing Overlap Save Method. REOURIED CODE

```
function y = add method overlap convolve (x, h, L)
%remember this method works when L>length(h)
%step one , getting required chunks , but this time we will use while loop
%and break by force
breaking_loop=1;
my chunks array=[];
tracking index=1;
%padd zeros to input signal of size p-1
x=[zeros(1, length(h)-1), x];
while (breaking loop==1)
    if(length(x(tracking index:length(x)))<L)</pre>
        disp('came in if ')
        x=[x, zeros(1, L-length(x(tracking index:length(x))))];
        my chunks array=[my chunks array;x(tracking index:tracking index+L-
1)];
        tracking_index= (tracking index+L-1) - length(h)+1;
        breaking loop=0
        disp('came in if ')
    else
        disp('came in else')
        my_chunks_array=[my_chunks array;x(tracking index:tracking index+L-
1)];
        tracking index=tracking index+1;
        tracking index= (tracking index+L-1) - length(h)+1;
        tracking index;
    end
    if(tracking index+L-1==length(x))
my chunks array=[my chunks array;x(tracking index:tracking index+L-1)];
            breaking loop=0;
    end
%now to find convolution for each chunk of input signal but L point
z=size(my chunks array);
z=z(1);
convolved chunk matrix=[];
for i=1:z
    single chunk convolved=cconv bee(my chunks array(i,:),h,L);
```

```
convolved_chunk_matrix=[convolved_chunk_matrix;single_chunk_convolved];
end
%now discarding the first p-1 points of each convolved_input_chunk vector
discarded_p_minus_1_matrix=[];
for i=1:z
discarded_p_minus_1_matrix=[discarded_p_minus_1_matrix;convolved_chunk_matrix(i,length(h):L)];
end
%now concatinating into single vector
final_ans=[];
for i=1:z
    final_ans=[final_ans,discarded_p_minus_1_matrix(i,:)]
end
```

c. Compare the results of both against each other and against the direct convolution of whole length x.

#### COMPARISION BETWEEN ALL THREE IMPLEMENTATIONS

Implement the two block convolution methods but this time using the MATLAB functions fft() and ifft().

Now instead of using the previous built  $cconv\_bee(x,h,N)$  function , we will get the convolution results using the new implemented function ,

linear\_conv\_using\_fft(x,h,N) which uses the FFT to compute the convolution between two signals.

The code for this function is given as:

```
function y = linear_conv_using_fft(x,h,N)
if(N>length(x))
x = [x, zeros(1, N-length(x))];
end
if(N>length(h))
h = [h, zeros(1, N-length(h))];
end
x_FFT=fft(x);
h_FFT=fft(h);
dot_product=x_FFT.*h_FFT;
y=ifft(dot_product);
end
```

We have now, just replaced the function of  $cconv\_bee(x,h,N)$  with this above function in both overlap add , add and overlap save method. And we have verified the results, and they are exactly same as answers obtained from previous implementations.

## Verification of results:

(Each convolution block function uses the FFT implemented function for calculating the convolutions)